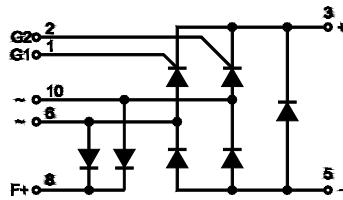


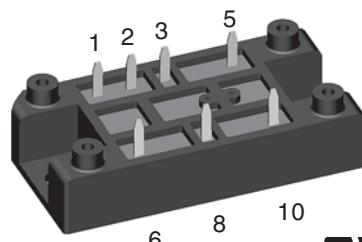
# Half Controlled Single Phase Rectifier Bridge

Including Freewheeling Diode and Field Diodes

$V_{RSM}$	$V_{RRM}$	Type
$V_{DSM}$	$V_{DRM}$	
V	V	
900	800	VHFD 16-08io1
1300	1200	VHFD 16-12io1
1700	1600	VHFD 16-16io1



$V_{RRM} = 800\text{-}1600 \text{ V}$   
 $I_{dAVM} = 21 \text{ A}$



Replacement: VHFD37-08/-12/-16 io1

## Bridge and Freewheeling Diode

Symbol	Conditions	Maximum Ratings		
$I_{dAV}$	$T_H = 85^\circ\text{C}$ , module	16	A	
$I_{dAVM} *$	module	21	A	
$I_{FRMS}, I_{TRMS}$	per leg	15	A	
$I_{FSM}, I_{TSM}$	$T_{VJ} = 45^\circ\text{C}$ ; $V_R = 0 \text{ V}$	150	A	
	$t = 10 \text{ ms}$ (50 Hz), sine $t = 8.3 \text{ ms}$ (60 Hz), sine	170	A	
	$T_{VJ} = T_{VJM}$ $V_R = 0 \text{ V}$	130	A	
	$t = 10 \text{ ms}$ (50 Hz), sine $t = 8.3 \text{ ms}$ (60 Hz), sine	140	A	
$I^{2t}$	$T_{VJ} = 45^\circ\text{C}$ $V_R = 0 \text{ V}$	110	$\text{A}^2\text{s}$	
	$t = 10 \text{ ms}$ (50 Hz), sine $t = 8.3 \text{ ms}$ (60 Hz), sine	120	$\text{A}^2\text{s}$	
	$T_{VJ} = T_{VJM}$ $V_R = 0 \text{ V}$	85	$\text{A}^2\text{s}$	
	$t = 10 \text{ ms}$ (50 Hz), sine $t = 8.3 \text{ ms}$ (60 Hz), sine	80	$\text{A}^2\text{s}$	
$(di/dt)_{cr}$	$T_{VJ} = 125^\circ\text{C}$ $f = 50 \text{ Hz}$ , $t_p = 200 \mu\text{s}$ $V_D = 2/3 V_{DRM}$ $I_G = 0.3 \text{ A}$ , $di_G/dt = 0.3 \text{ A}/\mu\text{s}$	repetitive, $I_T = 50 \text{ A}$ non repetitive, $I_T = 0.5 I_{dAV}$	150	$\text{A}/\mu\text{s}$
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}$ ; $V_{DR} = 2/3 V_{DRM}$ $R_{GK} = \infty$ ; method 1 (linear voltage rise)	1000	V/ $\mu\text{s}$	
$V_{RGM}$		10	V	
$P_{GM}$	$T_{VJ} = T_{VJM}$ $I_T = 0.5 I_{dAVM}$	$t_p = 80 \mu\text{s}$ $t_p = 500 \mu\text{s}$ $t_p = 10 \text{ ms}$	$\leq 10$ $\leq 5$ $\leq 1$	W
$P_{GAVM}$		0.5	W	
$T_{VJ}$		-40...+125	$^\circ\text{C}$	
$T_{VJM}$		125	$^\circ\text{C}$	
$T_{stg}$		-40...+125	$^\circ\text{C}$	
$V_{ISOL}$	50/60 Hz, RMS $I_{ISOL} \leq 1 \text{ mA}$	$t = 1 \text{ min}$ $t = 1 \text{ s}$	3000 3600	V~
$d_s$	Creep distance on surface	12.7	mm	
$d_A$	Strike distance in air	9.4	mm	
$a$	Max. allowable acceleration	50	$\text{m}/\text{s}^2$	
$M_d$	Mounting torque (M5) (10-32 UNF)	2-2.5 18-22	Nm lb.in.	
<b>Weight</b>		35	g	

### Features

- Package with DCB ceramic base plate
- Isolation voltage 3600 V~
- Planar passivated chips
- Blocking voltage up to 1600 V
- Low forward voltage drop
- Leads suitable for PC board soldering
- UL registered E 72873

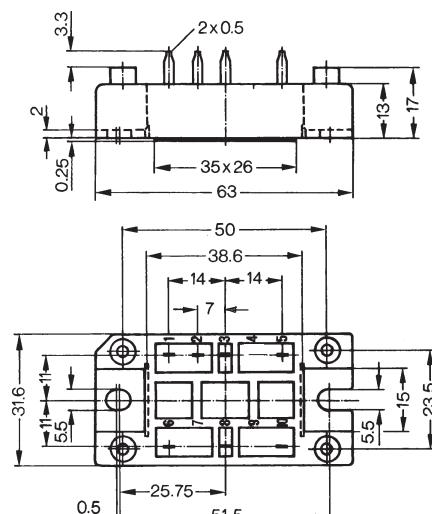
### Applications

- Supply for DC power equipment
- DC motor control

### Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling

### Dimensions in mm (1 mm = 0.0394")



Symbol	Conditions	Characteristic Values		
$I_R, I_D$	$V_R = V_{RRM}; V_D = V_{DRM}$ $T_{VJ} = T_{VJM}$ $T_{VJ} = 25^\circ C$	$\leq 5$	mA	
		$\leq 0.3$	mA	
$V_T, V_F$	$I_T, I_F = 45 A; T_{VJ} = 25^\circ C$	$\leq 2.55$	V	
$V_{TO}$	For power-loss calculations only ( $T_{VJ} = 125^\circ C$ )	1.0	V	
$r_T$		40	$m\Omega$	
$V_{GT}$	$V_D = 6 V;$ $T_{VJ} = 25^\circ C$ $T_{VJ} = -40^\circ C$	$\leq 1.0$	V	
	$T_{VJ} = 25^\circ C$ $T_{VJ} = -40^\circ C$	$\leq 1.2$	V	
$I_{GT}$	$V_D = 6 V;$ $T_{VJ} = 25^\circ C$ $T_{VJ} = -40^\circ C$ $T_{VJ} = 125^\circ C$	$\leq 65$	mA	
	$T_{VJ} = -40^\circ C$	$\leq 80$	mA	
	$T_{VJ} = 125^\circ C$	$\leq 50$	mA	
$V_{GD}$	$T_{VJ} = T_{VJM};$	$V_D = 2/3 V_{DRM}$	$\leq 0.2$	V
$I_{GD}$	$T_{VJ} = T_{VJM};$	$V_D = 2/3 V_{DRM}$	$\leq 5$	mA
$I_L$	$I_G = 0.3 A; t_G = 30 \mu s;$ $di_G/dt = 0.3 A/\mu s;$ $T_{VJ} = 25^\circ C$	$\leq 150$	mA	
	$T_{VJ} = -40^\circ C$	$\leq 200$	mA	
	$T_{VJ} = 125^\circ C$	$\leq 100$	mA	
$I_H$	$T_{VJ} = 25^\circ C; V_D = 6 V; R_{GK} = \infty$	$\leq 100$	mA	
$t_{gd}$	$T_{VJ} = 25^\circ C; V_D = 0.5 V_{DRM}$ $I_G = 0.3 A; di_G/dt = 0.3 A/\mu s$	$\leq 2$	$\mu s$	
$t_q$	$T_{VJ} = 125^\circ C, I_T = 15 A, t_p = 300 \mu s, V_R = 100 V$	typ.	150	$\mu s$
$Q_r$	$di/dt = -10 A/\mu s, dv/dt = 20 V/\mu s, V_D = 2/3 V_{DRM}$		75	$\mu C$
$R_{thJC}$	per thyristor (diode); DC current	2.4	K/W	
	per module	0.6	K/W	
$R_{thJH}$	per thyristor (diode); DC current	3.0	K/W	
	per module	0.75	K/W	

## Field Diodes

Symbol	Conditions	Maximum Ratings	
$I_{FAV}$	$T_H = 85^\circ C$ , per Diode	4	A
$I_{FAVM}$	per diode	4	A
$I_{FRMS}$	per diode	6	A
$I_{FSM}$	$T_{VJ} = 45^\circ C; V_R = 0 V$ $t = 10 ms (50 Hz), sine$ $t = 8.3 ms (60 Hz), sine$	100	A
		110	A
	$T_{VJ} = T_{VJM}$ $V_R = 0 V$ $t = 10 ms (50 Hz), sine$ $t = 8.3 ms (60 Hz), sine$	85	A
		94	A
$I^2t$	$T_{VJ} = 45^\circ C$ $V_R = 0 V$ $t = 10 ms (50 Hz), sine$ $t = 8.3 ms (60 Hz), sine$	50	$A^2s$
		50	$A^2s$
	$T_{VJ} = T_{VJM}$ $V_R = 0 V$ $t = 10 ms (50 Hz), sine$ $t = 8.3 ms (60 Hz), sine$	36	$A^2s$
		37	$A^2s$
$I_R$	$V_R = V_{RRM}$	1	mA
	$T_{VJ} = T_{VJM}$	0.15	mA
	$T_{VJ} = 25^\circ C$		
$V_F$	$I_F = 21 A; T_{VJ} = 25^\circ C$	1.83	V
$V_{TO}$	For power-loss calculations only ( $T_{VJ} = 125^\circ C$ )	0.9	V
$r_T$		50	$m\Omega$
$R_{thJC}$	per diode; DC current	4.4	K/W
$R_{thJH}$	per diode; DC current	5.2	K/W

Data according to IEC 60747 and refer to a single thyristor/diode unless otherwise stated.

\* for resistive load

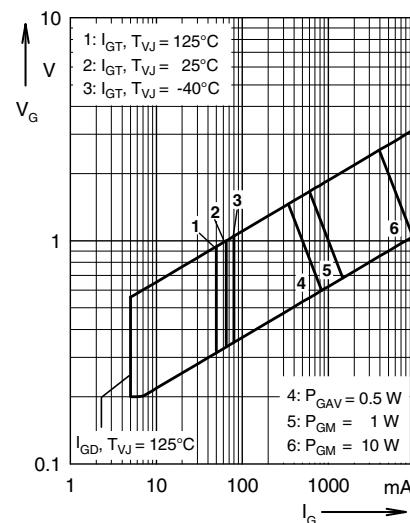


Fig. 1 Gate trigger range

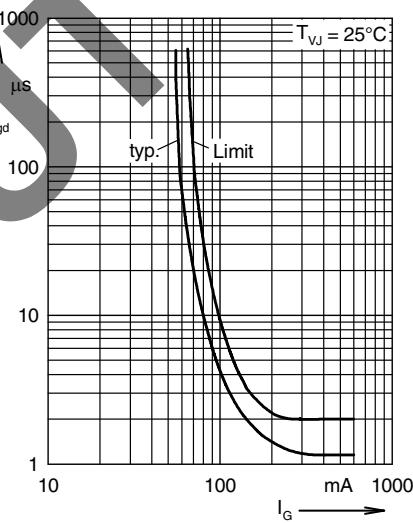


Fig. 2 Gate controlled delay time  $t_{gd}$

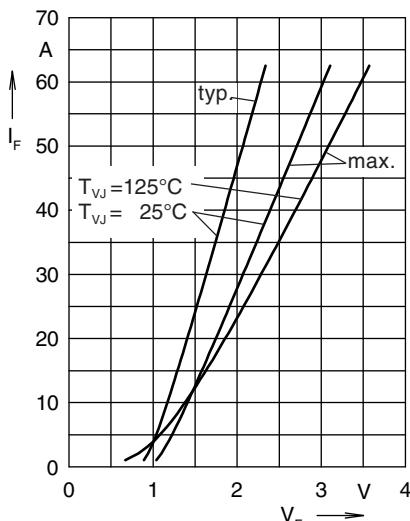


Fig. 3 Forward current vs. voltage drop per diode

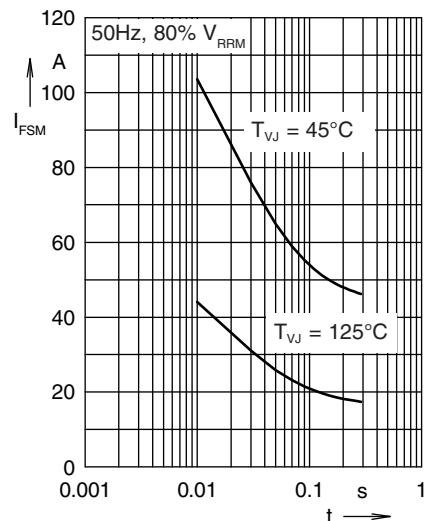


Fig. 4 Surge overload current

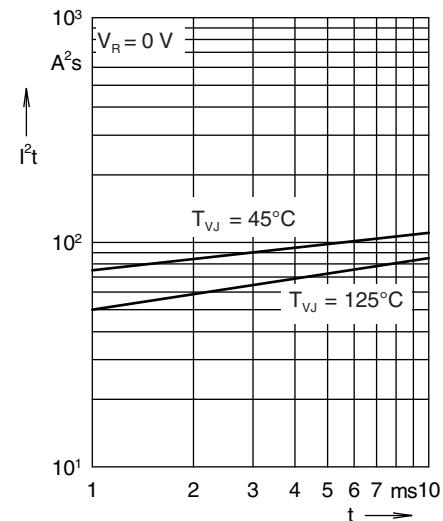


Fig. 5  $I^2t$  versus time per diode

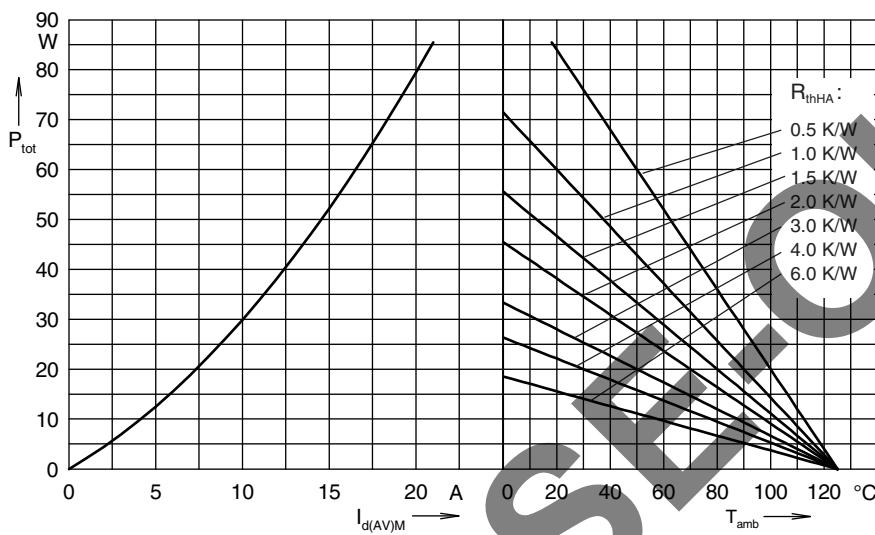


Fig. 6 Power dissipation vs. direct output current and ambient temperature

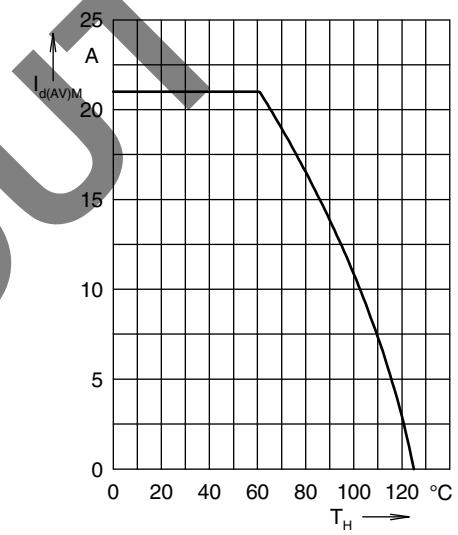


Fig. 7 Max. forward current vs. heatsink temperature

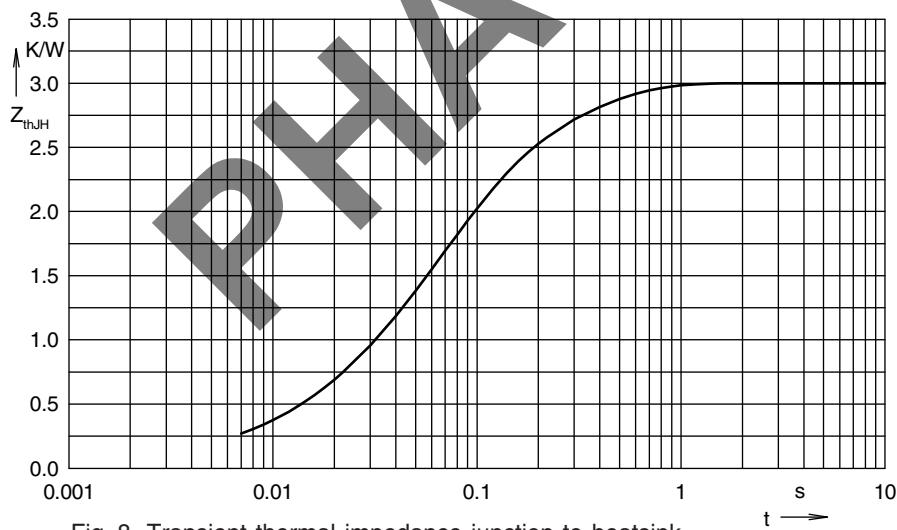


Fig. 8 Transient thermal impedance junction to heatsink

Constants for  $Z_{thJH}$  calculation:

i	$R_{thi}$ (K/W)	$t_i$ (s)
1	0.01	0.008
2	0.4	0.05
3	1.69	0.06
4	0.9	0.25

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