IS31CS8975

MCU with 1KB SRAM and 16Kx16 ECC E-Flash

GENERAL DESCRIPTION

CS8975 is a general-purpose MCU with 16KB Code e-Flash memory with ECC, 1K SRAM with ECC. The embedded flash for code storage has built-in ECC that correct 1-bit error and detect two-bit errs. CPU accesses the e-Flash through program address read and through Flash Controller which can performs software read/write operations of e-Flash.

CPU in CS8975 is 1-T 8051 with enhanced multiplication and division accelerator. There are two clock sources for system, one is a 16MHz/32MHz IOSC (manufacturer calibrated +/- 2%) and another one is 128KHz SOSC. Both clock sources have a clock programmable divider for scaling down the frequency to save power dissipations. The clock selections are combined with flexible power management schemes, including NORMAL, STOP, and SLEEP modes to balance speed and power consumption.

There are T0/T1/T2/T3/T4/T5 timers coupled with CPU and three WDT where WDT1 is clocked by SYSCLK, and WDT2/WDT3 are clocked by a non-stop SOSC. An 8-bit/16-bit checksum and 16-bit CRC accelerator is included. There are EUART/LIN controller and I2C master/Slave controller as well as SPI master/slave controller. The interfaces of these controllers are multiplexed with GPIO pins. Other useful peripherals include a buzzer control, 6 channels of 12-bit PWM, and one channel of 16-bit timer/capture and quadrature decoder.

Analog peripherals include an 11-bit ADC with internal temperature sensor, an 8-bit voltage output DAC, and four analog comparators with programmable threshold. A touch key controller up to 20-bit resolutions is also included. The touch key controller also has shield output capability for moisture immunity. The touch key controller allows sleep mode (under 10uA) and use auto detection for wakeup. The maximum number of key input can be scanned is 11.

CS8975 also provides a flexible means of flash programming that supports ISP and IAP. The protection of data loss is implemented in hardware by access restriction of critical storage segments. The code security is reinforced with sophisticated writer commands and ISP commands. The on-chip break point processor also allows easy debugging which can be integrated with ISP. Reliable power-on-reset circuit and low supply voltage detection allows reliable operations under harsh environments.

Applications

- Touch key applications with high robustness and reliability requirements
- Automotive and appliance

FEATURES

CPU and Memory

- 1-Cycle 8051 CPU core up to 32MHz
- 16-bit Timers T0/T1/T2/T3/T4 and 24-bit T5
- Checksum and CRC accelerator
- WDT1 by SYSCLK, WDT2/WDT3 by SOSC
- Clock fault monitoring
- Up to 6 external interrupts shared with GPIO pins
- Power saving modes – Normal, STOP, and SLEEP modes
- 256B IRAM and 1792B XRAM or 256B IRAM and 768B XRAM with ECC check
- 16KB Code e-Flash with ECC and two 512x16 Information Block
  - Program read with hardware ECC
  - Software read/write direct access 16-bit wide
  - Code security and data loss protection
  - 100K endurance and 10 years retention

Clock Sources

- Internal oscillator at +/- 2% 16MHz/32MHz
  - Spread Spectrum option
- Internal low power oscillator 128KHz
- External clock option

Digital Peripherals

- 6 CH 8/10/12-bit center-aligned PWM controller
  - Trigger interrupt and ADC conversion
  - Output polarity
- One 16-bit Timer/Capture and One 16-bit quadrature decoder
- Buzzer/Melody generator
- One I^2C Master
- One I^2C Slave – also for ISP and debug
- One SPI Master/Slave Controllers
- One EUART1 and one EUART2/LIN

Analog Peripherals

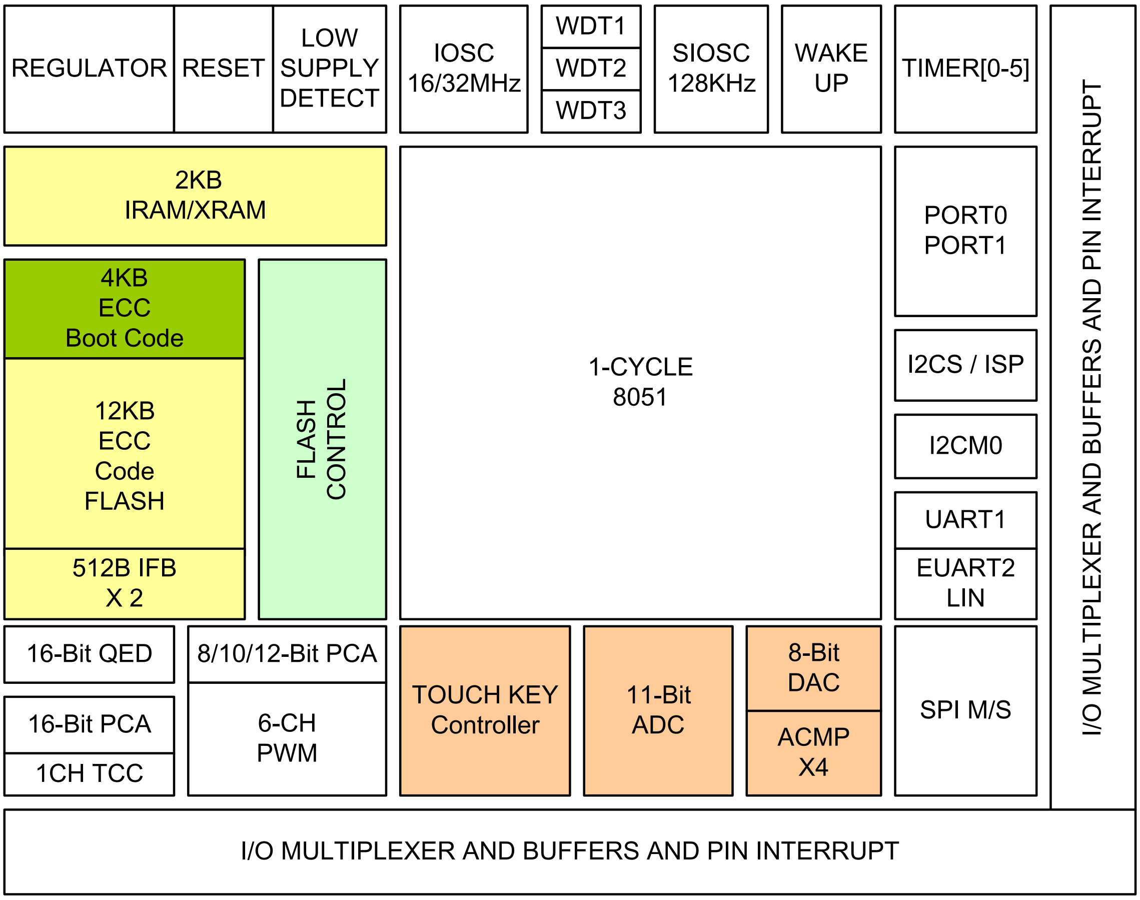
- Capacitance sense touch-key controller scan up to 11 key inputs
  - Shield output for moisture immunity
  - Low power sleep mode wakeup (<5uA).
- 11-Bit SAR ADC with GPIO analog input
  - Temperature sensor and supply measurement
- 8-Bit DAC and four analog comparators
- Power on reset and Low voltage detect (2.3V-4.5V)

Miscellaneous

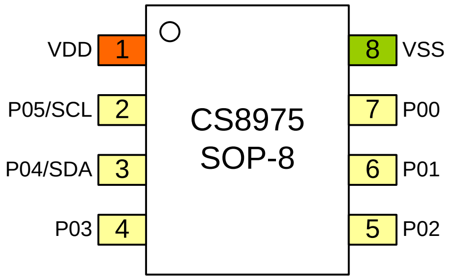
- Up to 12 GPIO pins with multi-function options
  - Configurable IO structure and noise filters
- 2.3V to 5.5V single supply
- Active current < 150uA/MHz in Normal mode
- Low power standby (< 1uA) in SLEEP mode
- Operating temperature -40°C to 85°C
- SOP-8/TSSOP-16 package and RoHS compliant

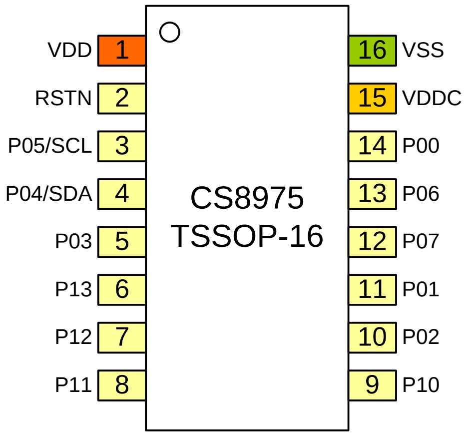
IS31CS8975

BLOCK DIAGRAM



PIN OUT


VDD 1
P05/SCL 2
P04/SDA 3
P03 4
CS8975
SOP-8
8 VSS
7 P00
6 P01
5 P02


VDD 1
RSTN 2
P05/SCL 3
P04/SDA 4
P03 5
P13 6
P12 7
P11 8
CS8975
TSSOP-16
16 VSS
15 VDDC
14 P00
13 P06
12 P07
11 P01
10 P02
9 P10

PIN Description and Multifunction Table

8 PIN	16 PIN	NAME	TYPE	ANIO1	ANIO2	PIN DESCRIPTION
1	1	VDDH	P			Supply Voltage 2.3V to 5.5V
	2	RSTN	IO			Active low reset input with internal 5K Ohm pull-up.
2	3	P05	IO/A	KEY	ADCA	Port 0.5 I/O with multi-function. This pin also defaults to I2CS SCL for ISP
3	4	P04	IO/A	KEY	ADCB	Port 0.4 I/O with multi-function. This pin also defaults to I2CS SDA for ISP
4	5	P03	IO/A	KEY	ADCA	Port 0.3 I/O with multi-function.
	6	P13	IO/A	KEY	CMPTH	Port 1.3 I/O with multi-function.
	7	P12	IO/A	KEY	CMPD	Port 1.2 I/O with multi-function.
	8	P11	IO/A	KEY	CMPC	Port 1.1 I/O with multi-function.
	9	P10	IO/A	KEY	CMPB	Port 1.0 I/O with multi-function.
5	10	P02	IO/A	KEY	CMPA	Port 0.2 I/O with multi-function.
6	11	P01	IO/A	KEY	SHIELD	Port 0.1 I/O with multi-function.
	12	P07	IO/A	KEY	ADCB	Port 0.7 I/O with multi-function.
	13	P06	IO/A	KEY	SHIELD	Port 0.6 I/O with multi-function.
7	14	P00	IO/A	KEYR	DAC	Port 0.0 I/O with multi-function.
	15	VDDC	P/O			Internal 1.5V supply. Connect to external 1.0uF decoupling capacitor.
8	16	VSS	G			VSS

Each GPIO pin can use MFCFG register to select pin functions. The function table is shown as following table.

MFCFG[4-0]	Function NAME	FUNCTION DESCRIPTION
00000	LOW	This force the output to logic low state. Actual output depends on OPOL setting in IOCFG register.
00001	GPIO	8051 GPIO port
00010	SCK	SPI SCK input or output depending SPI MS setting.
00011	SDI	SPI SDI input corresponding to MI or SI depending SPI MS setting.
00100	SDO	SPI SDO output corresponding to MO or SO depending SPI MS setting.
00101	SSN	SPI SSN input or output depending SPI MS setting.
00110	SSCL	I2C Slave SCL I/O
00111	SSDA	I2C Slave SDA I/O
01000	MSCL	I2C Master SCL I/O
01001	MSDA	I2C Master SDA I/O
01010	TX1	EUART1 TX output
01011	RX1	EUART1 RX input
01100	TX2	EUART2/LIN TX output
01101	RX2	EUART2/LIN RX input
01110	BZ	Buzzer/Melody output
01111	XCLK	External system clock input
10000	T0	Timer 0 input
10001	T1	Timer 1 input
10010	T2	Timer 2 input
10011	IDX	Quadrature Encoder IDX (Index) input
10100	PHA	Quadrature Encoder PHA (Phase A) input
10101	PHB	Quadrature Encoder PHA (Phase B) input
10110	XCAPT	TCC (Timer Compare/Capture) Capture Input
10111	TC	TCC (Timer Compare/Capture) Terminal Count output
11000	CC	TCC (Timer Compare/Capture) Compare Count output
11001	PWM0	PWM Channel 0 output
11010	PWM1	PWM Channel 1 output

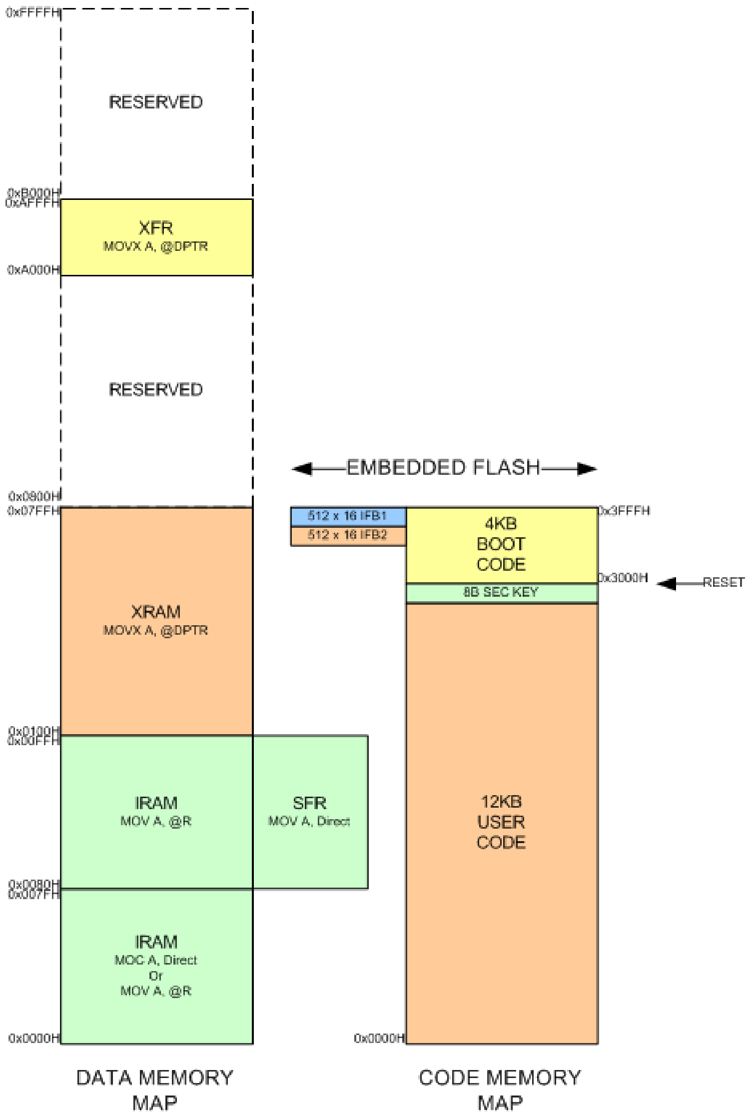
11011	PWM2	PWM Channel 2 output
11100	PWM3	PWM Channel 3 output
11101	PWM4	PWM Channel 4 output
11110	PWM5	PWM Channel 5 output
11111	HIGH	This force the output to logic high state. Actual output depends on OPOL setting in IOCFG register

**** MFCFG[4-0] default is 00000 after reset, thus default state is output logic low.

MEMORY MAP

There are total 256 bytes internal RAM in CS8975, the same as standard 8052. There are total 768 bytes auxiliary RAM allocated in the 8051 extended RAM area at 0x0100h – 0x03FFh. Programs can use "MOVX" instruction to access the XRAM.

There is a 16Kx16 embedded Flash memory for code storage. For CPU program access (Read Only), the lower byte is used for actual access, and the upper byte is used for ECC check. The ECC is performed in nibble bases with each nibble in the high byte corresponds to the nibbles in the low byte. ECC in this case is capable of one-bit correction and two-bit detection for each nibble. This is significantly more robust than 8:5 ECC. ECC check in program access path is in hardware and performed automatically. The embedded Flash can also be accessed through Flash controller. The Flash controller allows both read/write access and is always in 16-bit width with no ECC. For erase operations, the page size of the Flash is in 512x16. There are two 512x16 IFB blocks in the Flash. The first IFB is used for manufacturing and calibration data, and some area as user OTP data. The 2nd IFB is open for user application with no restriction. Also please note there are 8-byte of code security key located at the last of user program space for protection of pirate access of information.



REGISTER MAP SFR (0x80 – 0xFF)

The SFR address map maintains maximum compatibilities to most commonly used 8051 like MCU. The following table shows the SFR address map. Since SFR can be accessed by direct addressing mode, registers of built-in peripherals that require fast access are mostly located in SFR. XFR is mainly used for on-chip peripheral control and configurations.

	0	1	2	3	4	5	6	7
0XF0	B	-			I2CMSA	I2CMCR	I2CMBUF	I2CMTP
0XE0	ACC	-	-	-	-	-	-	-
0XD0	PSW	-	-	-	-	-	-	-
0XC0	-	-	SCON2	I2CMTO	PMR	STATUS	MCON	TA
0XB0	-	SCON1	SCON1X	SFIFO1	SBUF1	SINT1	SBR1L	SBR1H
0XA0	P2	SPICR	SPIMR	SPIST	SPIDATA	SFIFO2	SBUF2	SINT2
0X90	P1	EXIF	WTST	DPX	-	DPX1	-	-
0X80	P0	SP	DPL	DPH	DPL1	DPH1	DPS	PCON
	8	9	A	B	C	D	E	F
0XF8	EXIP	MD0	MD1	MD2	MD3	MD4	MD5	ARCON
0XE8	EXIE		MXAX	-	-	-	-	-
0XD8	WDCON		DPXR	I2CSCON2	I2CSST2	I2CSADR2	I2CSDAT2	-
0XC8	T2CON	TB	RLDL	RLDH	TL2	TH2	ADCCTL	T34CON
0XB8	IP	-	ADCL	ADCH	-	-	-	-
0XA8	IE	ADCCFG	-	-	TL4	TH4	TL3	TH3
0X98			-	ESP	-	ACON	-	WKMASK
0X88	TCON	TMOD	TL0	TL1	TH0	TH1	CKCON	CKSEL

REGISTER MAP XFR (0xA000 – 0xAFFF)

	0	1	2	3	4	5	6	7
A000	REGTRM	IOSCITRM	IOSCVTRM	-	-	-	-	SOSCTRM
A010	LVDCFG	LVDTHD	LVDHYS	-	TSTMON	FLSHVDD	BSTCMD	RSTCMD
A020	FLSHDATL	FLSHDATH	FLSHADL	FLSHADH	FLSHECC	FLSHCMD	ISPCLKF	FLSHPRTC
A030	FLSHPRT0	FLSHPRT1	FLSHPRT2	FLSHPRT3	FLSHPRT4	FLSHPRT5	FLSHPRT6	FLSHPRT7
A040	NTAFRQL	NTAFRQH	NTADUR	NTAPAU	NTBFRQL	NTBFRQH	NTBDUR	NTBPAU
A050	TCCFG1	TCCFG2	TCCFG3	-	TCPRDL	TCPRDH	TCCMPL	TCCMPH
A060	TCCPTRL	TCCPTRH	TCCPTFL	TCCPTFH	-	-	-	-
A070	QECFG1	QECFG2	QECFG3	-	QECNTL	QECNTH	QEMAXL	QEMAXH
	8	9	A	B	C	D	E	F
A008	-	-	-	-	-	PECCCFG	PECCADL	PECCADH
A018	TK3CFGA	TK3CFGB	TK3CFGC	TK3CFGD	TK3HDTYL	TK3HDTYH	TK3LDTYL	TK3LDTYH
A028	TK3BASEL	TK3BASEH	TK3THDL	TK3THDH	TK3PUD	DECCCFG	DECCADL	DECCADH
A038	CMPCFGAB	CMPCFGCD	CMPVTH0	CMPVTH1	DACCFG	CMPST	-	-
A048	BZCFG	NTPOW	NTTU	-	-	-	-	-
A058	-	-	-	-	-	-	-	-
A068	T5CON	TL5	TH5	TT5	-	-	-	-
A078	CCCFG	-	-	-	CCDATA0	CCDATA1	CCDATA2	CCDATA3

	0	1	2	3	4	5	6	7
A080	PWMCFG1	PWMCFG2	PWMCFG3	-	PWM0DTYL	PWM0DTYH	PWM1DTYL	PWM1DTYH
A090	LINCTRL	LINCNTRH	LINCNTRL	LINSBRH	LINSBRL	LININT	LININTEN	-
A0A0	-	-	-	-	-	-	-	-
A0B0	LINTCON	TXDTOL	TXDTOH	RXDTOL	RXDTOH	BSDCLRL	BSDCLRH	BSDWKC
A0C0	-	-	-	-	-	-	-	-
A0D0	-	-	-	-	-	-	-	-
A0E0	BPINTF	BPINTE	BPINTC	BPCTRL	-	-	-	-
A0F0	PC1AL	PC1AH	PC1AT	-	PC2AL	PC2AH	PC2AT	-
	8	9	A	B	C	D	E	F
A088	PWM2DTYL	PWM2DTYH	PWM3DTYL	PWM3DTYH	PWM4DTYL	PWM4DTYH	PWM5DTYL	PWM5DTYH
A098	DBPCIDL	DBPCIDH	DBPCIDT	DBPCNXL	DBPCNXH	DBPCNXT	STEPCTRL	SI2CDBGID
A0A8	-	-	-	-	-	-	-	-
A0B8	BSDACT	-	-	-	-	-	-	-
A0C8	-	-	-	-	-	-	-	-
A0D8	WDT2CF	WDT2L	WDT2H	WDT3CF	WDT3L	WDT3H		
A0E8	-	-	-	-	-	-	-	-
A0F8	-	-	-	-	-	-	-	-

	0	1	2	3	4	5	6	7
A100	IOCFGO00	IOCFGO01	IOCFGO02	IOCFGO03	IOCFGO04	IOCFGO05	IOCFGO06	IOCFGO07
A110	IOCFGI00	IOCFGI01	IOCFGI02	IOCFGI03	IOCFGI04	IOCFGI05	IOCFGI06	IOCFGI07
A120	MFCFG00	MFCFG01	MFCFG02	MFCFG03	MFCFG04	MFCFG05	MFCFG06	MFCFG07
A130								
A140								
A150								
A160	-	-	-	-	-	-	-	-
A170	-	-	-	-	-	-	-	-
	8	9	A	B	C	D	E	F
A108	IOCFGO10	IOCFGO11	IOCFGO12	IOCFGO13	IOCFGO14	IOCFGO15	IOCFGO16	IOCFGO17
A118	IOCFGI10	IOCFGI11	IOCFGI12	IOCFGI13	IOCFGI14	IOCFGI15	IOCFGI16	IOCFGI17
A128	MFCFG10	MFCFG11	MFCFG12	MFCFG13	MFCFG14	MFCFG15	MFCFG16	MFCFG17
A138	-	-	-	-	-	-	-	-
A148	-	-	-	-	-	-	-	-
A158	-	-	-	-	-	-	-	-
A168	-	-	-	-	-	-	-	-
A178	-	-	-	-	-	-	-	-

1. 8051 CPU

1.1 CPU Register

ACC (0xE0) Accumulator R/W (0x00)

	7	6	5	4	3	2	1	0
RD	ACC[7-0]							
WR	ACC[7-0]							

ACC is the CPU accumulator register and is involved in direct operations of many instructions. ACC is bit addressable.

B (0xF0) B Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	B[7-0]							
WR	B[7-0]							

B register is used in standard 8051 multiply and divide instructions and also used as an auxiliary register for temporary storage. B is also bit addressable.

PSW (0xD0) Program Status Word R/W (0x00)

	7	6	5	4	3	2	1	0
RD	CY	AC	FO	RS1	RS0	OV	UD	P
WR	CY	AC	FO	RS1	RS0	OV	UD	P

CY	Carry Flag
AC	Auxiliary Carry Flag (BCD Operations)
FO	General Purpose
RS1, RS0	Register Bank Select
OV	Overflow Flag
UD	User Defined (reserved)
P	Parity Flag

SP (0x81) Stack Pointer R/W (0x00)

	7	6	5	4	3	2	1	0
RD	SP[7-0]							
WR	SP[7-0]							

PUSH will result ACC to be written to SP+1 address. POP will load ACC from IRAM with the address of SP.

ESP (0x9B) Extended Stack Pointer R/W (0x00)

	7	6	5	4	3	2	1	0
RD	ESP[7-0]							
WR	ESP[7-0]							

In FLAT address mode, ESP and SP together form a 16-bit address for stack pointer. ESP holds the higher byte of the 16-bit address.

STATUS (0xC5) Program Status Word RO(0x00)

	7	6	5	4	3	2	1	0
RD	-	HIP	LIP	-				
WR	-	-	-	-	-	-	-	-

HIP	High Priority (HP) Interrupt Status HIP=0 indicates no HP interrupt HIP=1 indicates HP interrupt progressing
LIP	Low Priority (LP) Interrupt Status LIP=0 indicates no LP interrupt LIP=1 indicates LP interrupt progressing

The program should check status conditions before entering SLEEP, STOP, IDLE, or PMM modes to prevent loss of intended functions from delayed entry until these events are finished.

1.2 Addressing Timing and Memory Modes

The clock speed of an MCU with embedded flash memory is usually limited by the access time of on-chip flash memory. While in modern process technology, the CPU can operate much faster and the access time of flash memory is usually around 40 nanoseconds, which becomes a bottleneck for CPU performance. To mitigate this problem, a programmable wait state function is incorporated to allow faster CPU clock rate to access slower embedded flash memory. The wait state is controlled by WTST register as shown in the following,

WTST (0x92) R/W (0x07) TA Protected

	7	6	5	4	3	2	1	0
RD	-	-	-	-	WTST3	WTST2	WTST1	WTST0
WR	-	-	-	-	WTST3	WTST2	WTST1	WTST0

WTST[3-0] Wait State Control register. WTST sets the wait state in CPU clock period

WTST3	WTST2	WTST1	WTST0	Wait State Cycle
0	0	0	0	0
0	0	0	1	1
0	0	1	0	2
0	0	1	1	3
0	1	0	0	4
0	1	0	1	5
0	1	1	0	6
0	1	1	1	7
1	0	0	0	8
1	0	0	1	9
1	0	1	0	10
1	0	1	1	11
1	1	0	0	12
1	1	0	1	13
1	1	1	0	14
1	1	1	1	15

The default setting of the program wait state register after reset is 0x07 and the software must initialize the setting to change the wait state setting. Using a SYSCLK of 4MHz, the WTST can be set to minimum because one clock period is 250ns, which is longer than the typical embedded flash access time. If SYSCLK is above 16MHz, then WTST should be set higher than 1 to allow enough read access time. And note that when IOSC is set to 32MHz range, WTST[3-0] = 0 is forced to be equivalent as WTST[3-0] = 1.

MCON (0xC6) XRAM Relocation Register R/W (0x00) TA Protected

	7	6	5	4	3	2	1	0
RD	MCON[7-0]							
WR	MCON[7-0]							

MCON holds the starting address of XRAM in 2KB steps. For example, if MCON[7-0]=0x01, the starting address is 0x001000h. MCON is not meaningful in IS32LT3183because it only contains on-chip XRAM and MCON should not be modified from 0x00.

The LARGE mode, addressing mode is compatible with standard 8051 in 16-bit address. FLAT mode extends the program address to 20-bit and expands the stack space to 16-bit data space. The data space is always 16-bit in either LARGE or FLAT mode.

ACON (0x9D) R/W (0x00) TA Protected

	7	6	5	4	3	2	1	0
RD	-	-	IVECSEL	-	DPXREN	SA	AM1	AM0
WR	-	-	IVECSEL	-	DPXREN	SA	AM1	AM0

ACON is addressing mode control register.

IVECSEL — Interrupt Vector Selection
INTVSEC=1 maps the interrupt vector to 0x3000 space.
INTVSEC=0 maps to normal 0x0000 space

DPXREN — DPXR Register Control Bit.
If DPXREN is 0, "MOVX, @Ri" instruction uses P2 (0xA0) register and XRAM Address [15-8].
If DPXREN is 1,DPXR (0xDA) register and XRAM Address [15-8] is used.

SA — Extended Stack Address Mode Indicator. This bit is read-only.
0 – 8051 standard stack mode where stack resides in internal 256-byte memory
1 – Extended stack mode. Stack pointer is ESP:SP in 16-bit addressing to data space.

AM1, AM0 — AM1 and AM0 Address Mode Control Bits
00 – LARGE address mode in 16-bit
1x – FLAT address mode with 20-bit program address

1.3 MOVX A, @Ri Instructions

DPXR (0xDA) R/W (0x00)

	7	6	5	4	3	2	1	0
RD	DPXR[7-0]							
WR	DPXR[7-0]							

DPXR is used to replace P2[7-0] for high byte of XRAM address bit[15-7] for "MOVX, @Ri" instructions only if DPXREN=1.

MXAX (0xEA) MOVX Extended Address Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	MXAX[7-0]							
WR	MXAX[7-0]							

MXAX is used to provide top 8-bit address for "MOVX @Ri" instructions only. MXAX does not affect other MOVX instructions.

When accessing XRAM using "MOVX, @DPTR" instruction, the address of XRAM access is formed by DPHi:DPLi depending on which data pointer is selected. Another form of MOVX instruction is "MOVX, @Ri". This instruction provides an efficient programming method to move content within a 256-byte data block. In "@RI" instruction, the XRAM address [15-7] can be derived from two sources. If ACON.DPXREN = 0, the high order address [15-8] is from P2 (0xA0), if ACON.DPXREN = 1, the high order address is from DPXR (0xDA) register.

The maximum addressing space of XRAM is up to 16MB thus requiring 24-bit address. For "MOVX, @DPTR", the XRAMADDR [23-16] is from either DPX (0x93) or DPX1 (0x95) depending on which data pointer is selected. For "MOVX, @Ri", the XRAMUADDR [23-16] is from MXAX (0xEA) register.

1.4 Dual Data Pointers and MOVX operations

In standard 8051, there is only one data pointers DPH:DPL to perform MOVX. The enhanced CPU provides 2nd data pointer DPH1:DPL1 to speed up the movement, or copying of data block. The active DPTR is selected by setting DPS (Data Pointer Select) register. Through the control DPS, efficient programming can be achieved.

DPS (0x86) Data Pointer Select R/W (0x00)

	7	6	5	4	3	2	1	0
RD	ID1	ID0	TSL	-	-	-	-	SEL
WR	ID1	ID0	TSL	-	-	-	-	SEL

ID[1:0] — Define the operation of Increment Instruction of DPTR, "INC DPTR". Standard 8051 only have increment DPTR instruction. ID[1-0] changes the definitions of "INC DPTR" instruction and allows flexible modifications of DPTR when "INC DPTR" instructions is executed.

ID1	ID0	SEL=0	SEL=1
0	0	INC DPTR	INC DPTR1
0	1	DEC DPTR	INC DPTR1
1	0	INC DPTR	DEC DPTR1
1	1	DEC DPTR	DEC DPTR1

TSL — Enable toggling selection of DPTR selection. When this bit is set, the selection of DPTR is toggled when DPTR is used in an instruction and executed.

SEL — DPTR selection bit. Set to select DPTR1, and clear to select DPTR. SEL is also affected by the state of ID[1:0] and TSL after DPTR is used in an instruction. When read, SEL reflects the current selection of command.

DPL (0x82) Data Pointer Low R/W (0x00)

	7	6	5	4	3	2	1	0
RD	DPL[7-0]							
WR	DPL[7-0]							

DPL register holds the low byte of data pointer, DPTR.

DPH (0x83) Data Pointer High R/W (0x00)

	7	6	5	4	3	2	1	0
RD	DPH[7-0]							
WR	DPH[7-0]							

DPH register holds the high byte of data pointer, DPTR.

DPL1 (0x84) Extended Data Pointer Low R/W (0x00)

	7	6	5	4	3	2	1	0
RD	DPL1[7-0]							
WR	DPL1[7-0]							

DPL1 register holds the low byte of extended data pointer 1, DPTR1.

DPH1 (0x85) Extended Data Pointer High R/W (0x00)

	7	6	5	4	3	2	1	0
RD	DPH1[7-0]							
WR	DPH1[7-0]							

DPH1 register holds the high byte of extended data pointer 1, DPTR1.

DPX (0x93) Data Pointer Top R/W (0x00)

	7	6	5	4	3	2	1	0
RD	DPX[7-0]							
WR	DPX[7-0]							

DPX is used to provide top 8-bit address of DPTR when address above 64KB. The lower 16-bit address is formed by DPH and DPL. DPX is not affected in LARGE mode, and will form full 24-bit address in FLAT mode, meaning auto increment and decrement when DPTR is changed. DPX value has no effect if on-chip data memory is less than 64KB.

DPX1 (0x95) Extended Data Pointer Top R/W (0x00)

	7	6	5	4	3	2	1	0
RD	DPX1[7-0]							
WR	DPX1[7-0]							

DPX1 is used to provide top 8-bit address of DPTR when address above 64KB. The lower 16-bit address is formed by DPH1 and DP1L. DPX1 is not affected in LARGE mode, and will form full 24-bit address in Flat mode, meaning auto increment and decrement when DPTR is changed. DPX value has no effect if on-chip data memory is less than 64KB.

1.5 Interrupt System

The CPU implements an enhanced Interrupt Control that allows total 15 interrupt sources and each with two programmable priority levels. The interrupts are sampled at rising edge of SYSCLK. If interrupts are present and enabled, the CPU enters interrupt service routine by vectoring to the highest priority interrupt. Of the 15 interrupt sources, 7 of them are from CPU internal integrated peripherals, 6 of them are for on-chip external peripherals, and 2 of them are used for external pin interrupt expansion. When an interrupt is shared, the interrupt service routine must determine which source is requesting the interrupt by examining the corresponding interrupt flags of sharing peripherals.

The following table shows the interrupt sources and corresponding interrupt vectors. The Flag Reset column shows whether the corresponding interrupt flag is cleared by hardware (self-cleared) or software. Please note the software can only clear the interrupt flag but not set the interrupt flag. The Natural Priority column shows the inherent priority if more than one interrupts are assigned to the same priority level. Please note that the interrupts assigned with higher priority levels always get serviced first compared with interrupts assigned with lower priority levels regardless of the natural priority sequence.

Interrupt	Peripheral Source Description	Vectors (*Note) IVECSEL=0/1	FLAG RESET	Natural Priority
PINT0	Expanded Pin INT0.x	0x0003/0xX003	Software	1
TF0	Timer 0	0x000B/0xX00B	Hardware	2
PINT1	Expanded Pin INT1.x	0x0013/0xX013	Software	3
TF1	Timer 1	0x001B/0xX01B	Hardware	4
TI0/RI0	EUART1	0x0023/0xX023	Software	5
TF2	Timer 2	0x002B/0xX02B	Software	6
TI2/RI2	EUART2/LIN/LIN_FAULT	0x0033/0xX033	Software	7
I2CM	I^{2}C Master	0x003B/0xX03B	Software	8
INT2	LVT	0x0043/0xX043	Software	9
INT3	Touch Key/ACMP	0x004B/0xX04B	Software	10
INT4	ADC	0x0053/0xX053	Software	11
WDIF	Watchdog WDT1	0x005B/0xX05B	Software	12
INT6	PWM/TCC/QE	0x0063/0xX063	Software	13
INT7	SPI/I2C Slave	0x006B/0xX06B	Software	14
INT8	T3/T4/T5/BZ	0x0073/0xX073	Software	15
ECC	PECC/DECC/WDT2	0x007B/0xX07B	Software	0
BKP	Break Point	0xX080	Software	0
DBG	I2CS Debug	0xX0C0	Software	0

* Note: When IVECSEL=1, the interrupt vector is relocated to the top available 4KB memory space for boot code usage. Therefore, X=F, for 64K, and X=B for 48K program memory size, and X=7 for 32K, and X=3 for 16K sizes.

In addition to the 15 peripheral interrupts, there are two highest priority interrupts associated with debugging and break point. DBG interrupt is generated when I^{2}C slave is configured as a debug port and a debug request from the host matches the debug ID. BKP interrupt is generated when break point match condition occurs. DBG has higher priority than BKP. The BKP and DBG interrupts are not affected by global interrupt enable, EA bit, IE register (0xA8).

The interrupt related registers are listed in the following. Each interrupt can be individually enabled or disabled by setting or clearing corresponding bits in IE, EXIE and integrated peripherals' control registers.

IE (0xA8) Interrupt Enable Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	EA	ES2	ET2	ES0	ET1	PINT1EN	ET0	PINT0EN

WR	EA	ES2	ET2	ES0	ET1	PINT1EN	ET0	PINT0EN

EA Global Interrupt Enable bit.
ES2 LIN-capable16550-likeUART2 Interrupt Enable bit.
ET2 Timer 2 Interrupt Enable bit.
ES0 eUART1 Interrupt Enable bit.
ET1 Timer 1 Interrupt Enable bit.
PINT1EN Pin PINT1.x Interrupt Enable bit.
ET0 Timer 0 Interrupt Enable bit.
PINT0EN Pin PINT0.x Interrupt Enable bit.

EXIE (0xE8) Extended Interrupt Enable Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	EINT8	EINT7	EINT6	EWDI	EINT4	EINT3	EINT2	EI2CM
WR	EINT8	EINT7	EINT6	EWDI	EINT4	EINT3	EINT2	EI2CM

EINT8 INT8 Interrupt Enable bit.
EINT7 INT7 Interrupt Enable bit.
EINT6 INT6 Enable bit.
EWD1 Watchdog Timer Interrupt Enable bit.
EINT4 INT4 Interrupt Enable bit.
EINT3 INT3 Interrupt Enable bit.
EINT2 INT2 Interrupt Enable bit.
EI2CM I^{2}C Master Interrupt Enable bit.

Each interrupt can be individually assigned to either high or low. When the corresponding bit is set to 1, it indicates it is of high priority.

IP (0xB8) Interrupt Priority Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	-	PS2	PT2	PS0	PT1	PX1	PT0	PX0
WR	-	PS2	PT2	PS0	PT1	PX1	PT0	PX0

PS2 LIN-capable 16550-like UART2 Priority bit.
PT2 Timer 2 Priority bit.
PS0 eUART1 Priority bit.
PT1 Timer 1 Priority bit.
PX1 Pin Interrupt INT1 Priority bit.
PT0 Timer 0 Priority bit.
PX0 Pin Interrupt INT0 Priority bit.

EXIP (0xF8) Extended Interrupt Priority Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	EINT8	EINT7	EINT6	EWDI	EINT4	EINT3	EINT2	EI2CM
WR	EINT8	EINT7	EINT6	EWDI	EINT4	EINT3	EINT2	EI2CM

EINT8 INT8 Priority bit.
EINT7 INT7 Priority bit.
EINT6 INT6 Priority bit.
EWDI Watchdog Priority bit.
EINT4 INT4 Priority bit.
EINT3 INT3 Priority bit.
EINT2 INT2 Priority bit.
EI2CM I^{2}C Master Priority bit.

EXIF (0x91) Extended Interrupt Flag R/W (0x00)

	7	6	5	4	3	2	1	0
RD	INT8F	INT7F	INT6F	-	INT4F	INT3F	INT2F	I2CMIF
WR	-	-	-	-	-	-	-	I2CMIF

INT8F	INT8 Flag bit
INT7F	INT7 Flag bit
INT6F	INT6 Flag bit
INT4F	INT4 Interrupt Flag bit
INT3F	INT3 Flag bit
INT2F	INT2 Flag bit
I2CMIF	I^2C Master Interrupt Flag bit. This bit must be cleared by software
Note:	Writing to INT2F to INT8F has no effect.

The interrupt flag of internal peripherals are stored in the corresponding flag registers in the peripheral and EXIF registers. These peripherals include T0, T1, T2, and WDT1. Software needs to clear the corresponding flags located in the peripherals (for T0, T1, and T2, and WDT1). For I2CM, the interrupt flag is located in the EXIF register bit I2CMIF. This needs to be cleared by software.

INT2 to INT8 are used to connect to the external peripherals. INT2F to INT8F are direct equivalents of the interrupt flags from the corresponding peripherals. These peripherals include I^2Cs, ADC, etc.

WKMASK (0x9F) R/W (0xFF) Wake Up Mask Register TB Protected

	7	6	5	4	3	2	1	0
RD	WEINT8	WEINT7	WEINT6	WEINT4	WEINT3	WEINT2	WEPINT1	WEPINT0
WR	WEINT8	WEINT7	WEINT6	WEINT4	WEINT3	WEINT2	WEPINT1	WEPINT0

WEINT8	Set this bit to allow INT8 to trigger the wake up of CPU from STOP modes.
WEINT7	Set this bit to allow INT7 to trigger the wake up of CPU from STOP modes.
WEINT6	Set this bit to allow INT6 to trigger the wake up of CPU from STOP modes.
WEINT4	Set this bit to allow INT4 to trigger the wake up of CPU from STOP modes.
WEINT3	Set this bit to allow INT3 to trigger the wake up of CPU from STOP modes.
WEINT2	Set this bit to allow INT2 to trigger the wake up of CPU from STOP modes.
WEPINT1	Set this bit to allow INT1 to trigger the wake up of CPU from STOP modes.
WEPINT0	Set this bit to allow INT0 to trigger the wake up of CPU from STOP modes.

WKMASK register defines the wakeup control of the interrupt signals from the STOP mode. The wake-up is performed by these interrupts and if enabled the internal oscillator is turned on and SYSCLK resumes. The interrupt can be set as a level trigger or an edge trigger and the wake-up always runs in accordance with the edge. Please note the wake-up control is wired separately from the interrupt logic, therefore, after waking up, the CPU does not necessarily enter the interrupt service routine if the corresponding interrupt is not enabled. In this case, the CPU continues onto the next instruction, which initiates the STOP mode. Extra attention should be exerted as designing the exit and re-entry of modes to ensure proper operation.

Please note that all clocks are stopped in STOP mode, therefore peripherals require clock such as I^2C slave, EUART1, EUART2, ADC, LVD, and T3 cannot perform wake-up function. Only external pins and peripherals that do not require a clock can be used for wakeup purposes. Such peripherals for examples are an analog comparator and GPIO.

PINT0 and PINT1 are used for external GPIO pin Interrupts. All GPIO pin can be enabled to generate the PINT0 or PINT1 depending on its MFCFG register setting. Each GPIO pin also contains the rising/falling edge detections and either or both edges can be used for interrupt triggering. The same signaling can be used for generating wake-up.

TCON (0x88) R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TF1	TR1	TF0	TR0	PINT1F	-	PINT0F	-
WR	-	TR1	-	TR0	PINT1F	-	PINT0F	-

TF1	Timer 1 Interrupt Flag bit. TF1 is cleared by hardware when entering the interrupt routine.
TR1	Timer 1 Run Control bit. Set to enable Timer 1.
TF0	Timer 0 Interrupt Flag. TF0 is cleared by hardware when entering the interrupt routine.
TR0	Timer 0 Run Control bit. Set to enable Timer 0.
PINT1F	Pin INT1 Interrupt Flag bit.
PINT0F	Pin INT0 Interrupt Flag bit.

1.6 Register Access Control

One important aspect of the embedded MCU is its reliable operations under a harsh environment. Many system failures result from the accidental loss of data or changes of critical registers that may lead to catastrophic effects. The CPU provides several protection mechanisms, which are described in this section.

TA (0xC7) Time Access A Control Register2 WO xxxxxxx0

	7	6	5	4	3	2	1	0
RD	-	-	-	-	-	-	-	TASTAT
WR	TA Register							

TA access control emulates a ticket that must be purchased before modifying a critical register. To modify or write into a TA protected register, TA must be accessed in a predefined sequence to obtain the ticket. The ticket is used when an intended modification operation is done to the TA protected register. To obtain the next access a new ticket must be obtained again by performing the same predefined sequence on TA. TA does not limit the read access of the TA protect registers. The TA protected register includes WDCON (0xD8), MCON (0xC6), and ACON (0x9D) registers. The following predefined sequence is required to modify the content of MCON.

```
MOV TA, #0xAA;
MOV TA, #0x55;
MOV MCON, #0x01;
```

Once the access is granted, there is no time limitation of the access. The access is voided if any operation is performed in TA address. When read, TASTAT indicates whether TA is locked or not (1 indicates “unlock” and 0 indicates “lock”).

TB (0xC9) Time Access B Control Register2 RW (0x00)

	7	6	5	4	3	2	1	0
RD	-	-	-	-	-	-	-	TBSTAT
WR	TB Register							

TB access control functions are similar to TA control, except the ticket is for multiple uses with a time limit. Once access is granted, the access is open for 256 clock periods and then expires. The software can also read TB address to obtain the current TB status. The TB protected registers are marked on the register names and descriptions. To modify registers with TB protection, the following procedure must be performed.

```
MOV TB, #0xAA
MOV TB, #0x55
```

This action creates a timed window of 256 SYSCLK periods to allow write access of these TB protected registers. If any above-mentioned sequences are repeated before the 128 cycles expires, a new 128 cycles is extended. The current 256 cycles can be terminated immediately by writing #0x00 to TB registers, such as

```
MOV TB, #0x00
```

It is recommended to terminate the TB access window once the user program finishes the modifications of TB protected registers.

Because TA and TB are critical reassurance of the reliable operation of the MCU that prevents accidental hazardous uncontrollable modifications of critical registers, the operation of these two registers should bear extreme cautions. It is strongly advised that these two registers should be turned on only when needed. Both registers use synchronous CPU clock, therefore it is imperative that any running tasks of TA and TB should be terminated before entering IDLE mode or STOP mode. Both modes turn off the CPU clock and if TA and TB are enabled, they stay enabled until the CPU clock resumes thus may create vulnerabilities for critical registers.

Another reliability concern of embedded Flash MCU is that the important content on the Flash can be accidentally erased. This concern is addressed by the content protection in the Flash controller.

1.7 Clock Control and Power Management Modes

This section describes the clock control and power saving modes of the CPU and its integrated peripherals. The settings are controlled by PCON (0x87) and PMR (0xC4) registers. The register description is defined as following.

PCON (0x87) R/W (0x00)

	7	6	5	4	3	2	1	0
RD	SMOD0	-	-	-	-	-	-	-

WR	SMOD0	-	-	-	-	SLEEP	STOP	IDLE

SMOD0 — UART 0 Baud Rate Control. This is used to select double baud rate in mode 1, 2 or 3 for UART0 using Timer 1 overflow. This definition is the same as standard 8051.
This implementation does not support UART 0

SLEEP — Sleep Mode Control Bit. When this bit and the Stop bit are set to 1, the clock of the CPU and all peripherals is disabled and enters SLEEP mode. The SLEEP mode exits when non-clocked interrupts or resets occur. Upon exiting SLEEP mode, Sleep bit and Stop bit in PCON is automatically cleared. In terms of power consumption, the following relationship applies: IDLE mode > STOP mode > SLEEP mode. SLEEP mode is the same as STOP mode, except it also turns off the band gap and the regulator. It uses a very low power back-up regulator (< 5uA). When waking up from SLEEP mode, it takes longer time (< 64 IOSC clock cycles, compared with STOP mode) because the regulator requires more time to stabilize.

STOP — Stop Mode Control Bit. The clock of the CPU and all peripherals is disabled and enters STOP mode if the Sleep bit is in the reset state. The STOP mode can only be terminated by non-clocked interrupts or resets. Upon exiting STOP mode, Stop bit in PCON is automatically cleared.

IDLE — Idle Bit. If the IDLE bit is set, the system goes into IDLE mode. In Idle mode, CPU clock becomes inactive and the CPU and its integrated peripherals such as WDT, T0/T1/T2, and UART0 are reset. But the clocks of external peripherals and CPU like ADC, LIN-capable16550-like EUART1, EUART2, SPI, T3, I^{2}C slave and the others are still active. This allows the interrupts generated by these peripherals and external interrupts to wake the CPU. The exit mechanism of IDLE mode is the same as STOP mode. Idle bit is automatically cleared at the exit of the IDLE mode.

PMR (0xC4) R/W (010xxxxx)

	7	6	5	4	3	2	1	0
RD	CD1=0	CD0	SWB	-	-	-	-	-
WR	-	CD0	SWB	-	-	-	-	-

CD1, CD0 — Clock Divider Control. These two bits control the entry of PMM mode. When CD0=1, and CD1=0, full speed operation is in effect. When CD0=1, and CD1=1, the CPU enters PMM mode where CPU and its integrated peripherals operate at a clock rate divided by 257. Note that in PMM mode, all integrated peripherals such as UART0, LIN-capable 16550-like UART2, WDT1, and T0/T1/T2 run at this reduced rate, thus may not function properly. All external peripherals to CPU still operate at full speed in PMM mode.

NOTE: CD1 is internally hardwired to 0. This implementation does not support PMM mode.

SWB — Switch Back Control bit. Setting this bit allows the actions to occur in integrated peripherals to automatically switch back to normal operation mode.

NOTE: PMM mode is not supported.

CKSEL (0x8F) System Clock Selection Register R/W (0x0C) TB Protected

	7	6	5	4	3	2	1	0
RD	IOSCDIV[3-0]				-	-	CLKSEL[1]	CLKSEL[0]
WR	IOSCDIV[3-0]				REGRDY[1]	REGRDY[0]	CLKSEL[1]	CLKSEL[0]

IOSCDIV[3-0] — IOSC Pre-Divider. Default is IOSC/32.

IOSCDIV[3-0]	SYSCLK
0	IOSC
1	IOSC/2
2	IOSC/4
3	IOSC/6
4	IOSC/8
5	IOSC/10
6	IOSC/12
7	IOSC/14

8	IOSC/16
9	IOSC/32
10	IOSC/64
11	IOSC/128
12	IOSC/256
13	IOSC/256
14	IOSC/256
15	IOSC/256

REGRDY[1-0] Wake up delay time for main regulator stable time from reset or from sleep mode wakeup. Default is longest delay at 256 SOSC (128KHz).

REGRDY[1]	REGRDY[0]	Delay time
0	0	8 SOSC cycle
0	1	16 SOSC cycle
1	0	64 SOSC cycle
1	1	256 SOSC cycle

CLKSEL[1-0] Clock Source Selection
These two bits define the clock source of the system clock SYSCLK. The selections are shown in the following table. The default setting after reset is IOSC.

CLKSEL[1]	CLKSEL[0]	SYSCLK
0	0	IOSC (through divider)
0	1	SOSC/4 (32KHz)
1	0	IOSC (through divider)
1	1	XCLKIN

WKMASK (0x9F) R/W (0xFF) Wake-Up Mask Register TB Protected

	7	6	5	4	3	2	1	0
RD	WEINT8	WEINT7	WEINT6	WEINT4	WEINT3	WEINT2	WEPINT1	WEPINT0
WR	WEINT8	WEINT7	WEINT6	WEINT4	WEINT3	WEINT2	WEPINT1	WEPINT0

WEINT8 Set this bit to allow INT8 to trigger the wake up of CPU from STOP modes.
WEINT7 Set this bit to allow INT7 to trigger the wake up of CPU from STOP modes.
WEINT6 Set this bit to allow INT6 to trigger the wake up of CPU from STOP modes.
WEINT4 Set this bit to allow INT4 to trigger the wake up of CPU from STOP modes.
WEINT3 Set this bit to allow INT3 to trigger the wake up of CPU from STOP modes.
WEINT2 Set this bit to allow INT2 to trigger the wake up of CPU from STOP modes.
WEPINT1 Set this bit to allow INT1 to trigger the wake up of CPU from STOP modes.
WEPINT0 Set this bit to allow INT0 to trigger the wake up of CPU from STOP modes.

WKMASK register defines the wake up control of the interrupt signals from the STOP/SLEEP mode. The wake-up is performed by these interrupts and if enabled the internal oscillator is turned on and SYSCLK resumes. The interrupt can be set as a level trigger or an edge trigger and the wake-up always runs in accordance with the edge. Please note the wake-up control is wired separately from the interrupt logic, therefore, after waking up, the CPU does not necessarily enter the interrupt service routine if the corresponding interrupt is not enabled. In this case, the CPU continues onto the next instruction, which initiates the STOP/SLEEP mode. Extra attention should be exercised as designing the exit and re-entry of modes to ensure proper operation.

Please note that all clocks are stopped in STOP/SLEEP mode, therefore peripherals require clock such as I^2C slave, EUART1, EUART2, ADC, LVD, and T3/T4 cannot perform wake-up function. Only external pins and peripherals that do not require a clock can be used for wakeup purposes. Such peripherals are LIN Wakeup and Timer5 with SOSC.

IDLE Mode

IDLE mode provides power saving by stopping SYSCLK to CPU and its integrated peripherals while other peripherals are still in operation with SYSCLK. Thus other peripherals still function normally and can generate interrupts that wake up the CPU from IDLE mode. The IDLE mode is enabled by setting IDLE bit to 1.

When the CPU is in idle mode, no processing is possible. All integrated internal peripherals such as T0/T1/T2, EUART1, LIN-capable 16550-like EUART2 and I^{2}C Master are inaccessible during idling. The IDLE mode can be excited by hardware reset through RSTN pin (no such pin) or by external interrupts as well as the interrupts from external peripherals that are OR-ed with the external interrupts. The triggering external interrupts need be enabled properly. Upon exiting from IDLE mode, the CPU resumes operation as the clock is being turned on. CPU immediately vectors to the interrupt service routine of the corresponding interrupt sources that wake up the CPU. When the interrupt service routine completes, RETI returns to the program and immediately follows the one that invokes the IDLE mode. Upon returning from IDLE mode to normal mode, idle bit in PCON is automatically cleared.

STOP Mode

STOP mode provides further power reduction by stopping SYSCLK to all circuits. In STOP mode, IOSC oscillator is disabled. STOP mode is entered by setting STOP=1. To achieve minimum power consumption, it is essential to turn off all peripherals with DC current consumption. It is also important that the software switches to the IOSC clock and disables all other clock generator before entering STOP mode. This is critical to ensure a smooth transition when resuming its normal operations. Upon entering STOP mode, the system uses the last edge of IOSC clock to shut down the IOSC clock generator.

Valid interrupt/wakeup event or reset will result the exit of STOP mode. Upon exit, STOP bit is cleared by hardware and IOSC is resumed. The triggering interrupt source must be enabled and its Wake-up bit is set in the WKMASK register. As CPU resumes the normal operation using previous clock settings. When an interrupt occurs, the CPU immediately vectors to the interrupting service routine of the corresponding interrupt source. When the interrupt service routine completes, RETI returns to the program immediately to execute the instruction that invokes the STOP mode.

The on-chip 1.5V regulator for core circuits is still enabled along with its reference voltage. As the result, the power consumption due to the regulator and its reference circuit is still around 100uA to 200uA. The advantage of STOP mode is its immediate resumption of the CPU.

SLEEP Mode

SLEEP mode achieves very low standby consumption by putting the on-chip 1.5V regulator in disabled state. An ultra-low power 1.3V backup regulator supplies the internal core circuit and maintains the logic state and SRAM data. The total current drain in SLEEP mode is less than 1uA for typical condition. Only the backup regulator and the SOSC circuit are still in operation in SLEEP mode.

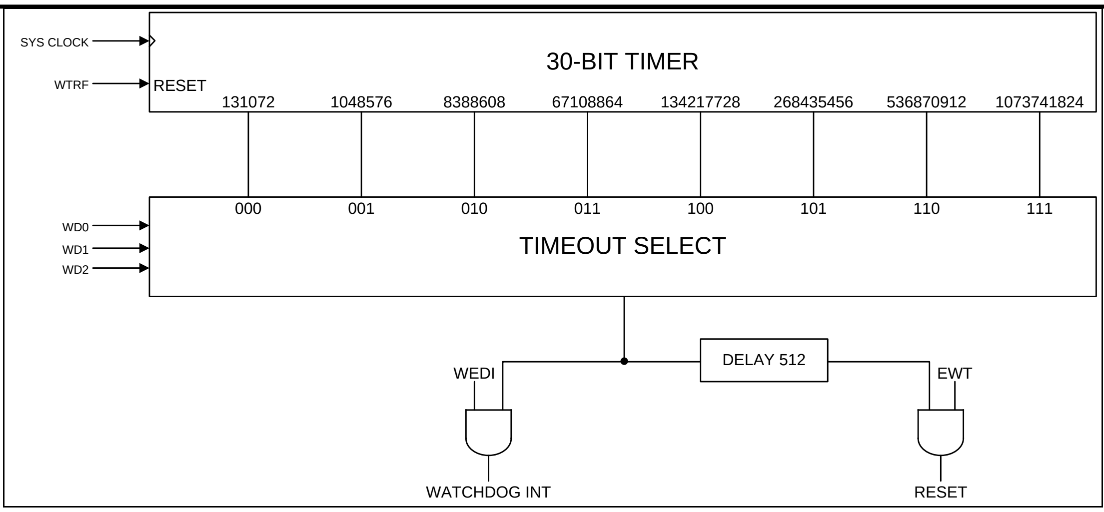
The exit of SLEEP mode is the same interrupt/wakeup event as in STOP node, and in addition the on-chip regulator is enabled, then after a delay set by REGRDY (clocked by SOSC), SYSCLK is resumed. REGRDY delay is necessary to ensure stable operation of the regulator. The larger the decoupling capacitance longer delay should be set.

Clock Control

The clock selection is defined by CKSEL register (0x8F). There are two selections either from divided IOSC or SOSC/4. The default selection is divided IOSC. Typical power consumption of CPU is 0.15mA/MHZ.

1.8 Watchdog Timer

The Watchdog Timer is a 30-bit timer that can be used by a system supervisor or as an event timer. The Watchdog timer can be used to generate an interrupt or to issue a system reset depending on the control settings. This section describes the register related to the operation of Watchdog Timer and its functions. The following diagram shows the structure of the Watchdog Timer. Note WDT1 shares the same clock with the CPU, thus WDT1 is disabled in IDLE mode or STOP mode however it runs at a reduced rate in PMM mode.



WDCON (0xD8) WDT1 Interrupt Flag Register R/W (0x02) TA Protected

	7	6	5	4	3	2	1	0
RD	-	-	-	-	WDT1IF	WDT1RF	WDT1REN	-
WR	-	-	-	-	WDT1IF	WDT2RF	WDT1REN	WDT1CLR

WDT1IF — WDT1 Interrupt Flag bit. This bit is set when the session expires regardless of a WDT1 interrupt is enabled or not. Note the WDT1 interrupt enable control is located in EXIE (0xE8).4 EWDI bit. It must be cleared by software

WDT1RF — WDT1 Reset Flag bit. WDT1RF is cleared by hardware reset including RSTN, POR etc. WDT1RF is set to 1 after a WDT1 reset occurs. It can be cleared by software. WDT1RF can be used by software to determine if a WDT1 reset has occurred.

WDT1REN — WDT1 Enable bit. Set this bit to enable the watchdog reset function. The default WDT1 reset is enabled and WDT1 timeout is set to maximum.

WDT1CLR — Reset the Watchdog timer 1. Writing 1 to WDT1CLR resets the WDT1 timer. WDT1CLR bit is not a register and does not hold any value. The clearing action of Watchdog timer is protected by TA access. In another word, to clear Watchdog timer 1, TA must be unlocked then and then followed by writing WDT1CLR bit to 1. If TA is still locked, the program can write 1 into WDT1CLR bit, but it does not reset the Watchdog timer.

CKCON (0x8E) Clock Control and WDT1 R/W (0xC7)

	7	6	5	4	3	2	1	0
RD	WD1	WD0	T2CKDCTL	T1CKDCTL	T0CKDCTL	WD2	-	-
WR	WD1	WD0	T2CKDCTL	T1CKDCTL	T0CKDCTL	WD2	-	-

T2CKDCTL — Timer 2 Clock Source Division Factor Control Flag. Setting this bit to 1 sets the Timer 2 division factor to 4, the Timer 2 clock frequency equals CPU clock frequency divided by 4. Setting this bit to 0 (the default power on value) sets the Timer 2 division factor to 12, the Timer 2 clock frequency equals CPU clock frequency divided by 12.

T1CKDCTL — Timer 1 Clock Source Division Factor Control Flag. Setting this bit to 1 sets the Timer 1 division factor to 4, the Timer 1 clock frequency equals CPU clock frequency divided by 4. Setting this bit to 0 (the default power on value) sets the Timer 1 division factor to 12, the Timer 1 clock frequency equals CPU clock frequency divided by 12.

T0CKDCTL — Timer 0 Clock Source Division Factor Control Flag. Setting this bit to 1 sets the Timer 0 division factor to 4, the Timer 0 clock frequency equals CPU clock frequency divided by 4. Setting this bit to 0 (the default power on value) sets the Timer 0 division factor equals 12, the Timer 0 clock frequency equals CPU clock frequency divided by 12.

WD[2-0] — This register controls the time out value of WDT1 as the following table. The time out value is shown as follows and the default is set to maximum:

WD2	WD1	WD0	Time Out Value
0	0	0	131072
0	0	1	1048576
0	1	0	8388608

0	1	1	67108864
1	0	0	134217728
1	0	1	268435456
1	1	0	536870912
1	1	1	1073741824

A second 16-bit Watchdog Timer (WDT2) clocked by the independent nonstop SOSC/4 (32KHz) is included. WDT2 can be used to generate interrupt/wakeup timing from STOP/SLEEP mode, or generate software reset.

WDT2CF (0xA0D8h) Watchdog Timer 2 Configure Registers R/W (0xA7) TB Protected

	7	6	5	4	3	2	1	0
RD	-	WDT2REN	WDT2RF	WDT2IEN	WDT2CS[2-0]			WDT2IF
WR	WDT2CLR	WDT2REN	WDT2RF	WDT2IEN	WDT2CS[2-0]			WDT2IF

WDT2CLR WDT2 Counter Clear
Writing “1” to WDT2CLR clears the WDT2 count to 0. It is self-cleared by hardware.

WDT2REN WDT2 Reset Enable
WDT2REN=1 configures WDT2 to perform software reset.

WDT2RF WDT2 Reset Flag
WDT2RF is set to “1” after a WDT2 reset occurs. This must be cleared by software by writing “0”.

WDT2IEN WDT2 Interrupt Enable
WDT2IEN=1 enables WDT2 interrupt.

WDT2CS[2-0] WDT2 Clock Scaling

WDT2CS[2-0]	Clock SOSC/4 Divider	WDT2Period (SOSC/4=32K)
000	2^8	8 msec
001	2^8	8 msec
010	2^8	8 msec
011	2^8	8 msec
100	2^12	128 msec
101	2^13	256 msec
110	2^14	512 msec
111	2^15	1024 msec

WDT2IF WDT2 Interrupt Flag
WDT2IF is set to “1” after a WDT2 interrupt. This must be cleared by software by writing “0”.

Please note the longest effective time WDT2 can be set is approximately 18 hours.

WDT2L (0xA0D9h) Watchdog Timer 2 Time Out Value Low Byte RW (0xFF) TB Protected

	7	6	5	4	3	2	1	0
RD	WDT2CNT[7-0]							
WR	WDT2[7-0]							

WDT2H (0xA0DAh) Watchdog Timer 2 Time Out Value High Byte RW (0x0F) TB Protected

	7	6	5	4	3	2	1	0
RD	WDT2CNT[15-8]							
WR	WDT2[15-8]							

WDT2L and WDT2H hold the time out value for watchdog timer 2. When the counter reaches WDT2 time out value, an interrupt or reset is generated. Reading this register returns the current count value.

A third Watchdog Timer (WDT3) is also included for further enhancement of fault recovery. WDT3 cannot be disabled in normal mode. It can be disabled only in SLEEP mode if SLEEPDIS[2-0] = 3’b101. WDT3 is clocked 4 times slower than WDT2, and is also set by WDT2CS[2-0].

WDT2CS[2-0]	Clock SOSC/4 Divider	WDT3 Period (SOSC/4=32K)
000	2^8	8 msec

001	2^8	8 msec
010	2^8	8 msec
011	2^8	8 msec
100	2^12	128 msec
101	2^13	256 msec
110	2^14	512 msec
111	2^15	1024 msec

Therefore the longest time of WDT3 is about 4 second time 2^16 approximately 72 hours.

WDT3CF (0xA0DBh) Watchdog Timer 3 Configure Registers R/W (0xD1) TB Protected

	7	6	5	4	3	2	1	0
RD	-	SLEPPDIS[2-0]			-			WDT3RF
WR	WDT3CLR	SLEPPDIS[2-0]			-			WDT3RF

WDT3CLR — WDT3 Counter Clear
Writing "1" to WDT3CLR clears the WDT3 count to 0. It is self-cleared by hardware.

SLEEPDIS[2-0] — Stop WDT3 increment in STOP/SLEEP mode
SLEEPDIS[2-0]=3b'101 stops WDT3 in STOP/SLEEP mode.

WDT3RF — WDT3 Reset Flag
WDT3RF is set to "1" after a WDT3 reset occurs. This must be cleared by software by writing "0".

WDT3L (0xA0DCh) Watchdog Timer 3 Time Out Value Low Byte RO R/W (0xFF) TB Protected

	7	6	5	4	3	2	1	0
RD	WDT3CNT[7-0]							
WR	WDT3[7-0]							

WDT3H (0xA0DDh) Watchdog Timer 3 Time Out Value High Byte RO R/W (0x0F) TB Protected

	7	6	5	4	3	2	1	0
RD	WDT3CNT[15-8]							
WR	WDT3[15-8]							

WDT3L and WDT3H hold the time out value for watchdog timer 3. When the counter reaches WDT3 time out value, a reset is generated. Reading this register returns the current count value.

1.9 System Timers – T0 and T1

The CPU contains three 16-bit timers/counters, Timer 0, Timer 1 and Timer 2. In timer mode, Timer 0, Timer 1 registers are incremented every 12 SYSCLK period when the appropriate timer is enabled. In the timer mode, Timer 2 registers are incremented every 12 or 2 SYSCLK period (depending on the operating mode). In the counter mode, the timer registers are incremented every falling edge on their corresponding inputs: T0, T1, and T2. These inputs are read every SYSCLK period.

Timer 0 and Timer 1 are fully compatible with the standard 8051. Timer 0 and 1 are controlled by TCON (0x88) and TMOD (0x89) registers while each timer consists of two 8-bit registers TH0 (0x8C), TL0 (0x8A), TH1 (0x8D), TL1 (0x8B).

TCON (0x88h) Timer 0 and 1 Configuration Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TF1	TR1	TF0	TR0	IE1	IT1	IE0	IT0
WR	TF1	TR1	TF0	TR0	IE1	IT1	IE0	IT0

TF1 — Timer 1 Overflow Interrupt Flag bit. TF1 is cleared by hardware when entering ISR.

TR1 — Timer 1 Run Control bit. Set to enable Timer 1, and clear to disable Timer 1.

TF0 — Timer 0 Overflow Interrupt Flag bit. TF0 is cleared by hardware when entering ISR.

TR0 — Timer 0 Run Control bit. Set to enable Timer 0, and clear to disable Timer 0.

IE1,IT1,IE0,IT0 — These bits are related to configurations of expanded interrupt INT1 and INT0. These are described in the Interrupt System section.

TMOD (0x89h) Timer 0 and 1 Mode Control Register R/W (0x00)

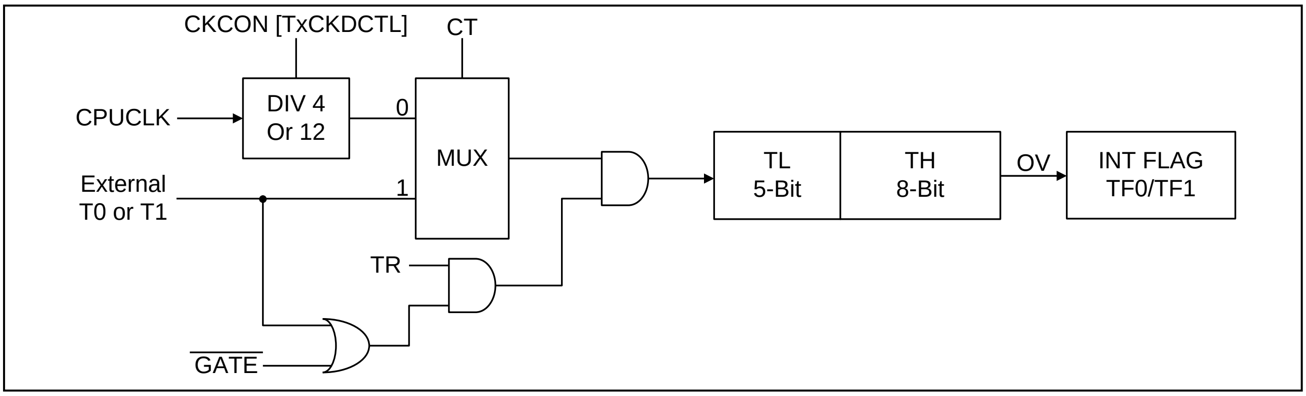
	7	6	5	4	3	2	1	0
RD	GATE1	CT1	T1M1	T1M0	GATE0	CT0	T0M1	T0M0
WR	GATE1	CT1	T1M1	T1M0	GATE0	CT0	T0M1	T0M0

GATE1	Timer 1 Gate Control bit. Set to enable external T1 to function as gating control of the counter.
CT1	Counter or Timer Mode Select bit. Set CT1 to access external T1 as the clock source. Clear CT1 to use internal clock.
T1M1	Timer 1 Mode Select bit.
T1M0	Timer 1 Mode Select bit.
GATE0	Timer 0 Gate Control bit. Set to enable external T0 to function as gating control of the counter.
CT0	Counter or Timer Mode Select bit. Set CT0 to use external T0 as the clock source. Clear CT0 to use internal clock.
T0M1	Timer 0 Mode Select bit.
T0M0	Timer 0 Mode Select bit.

M1	M0	Mode	Mode Descriptions
0	0	0	TL serves as a 5-bit pre-scaler and TH functions as an 8-bit counter/timer. They form a 13-bit operation.
0	1	1	TH and TL are cascaded to form a 16-bit counter/timer.
1	0	2	TL functions as an 8-bit counter/timer and auto-reloads from TH.
1	1	3	TL functions as an 8-bit counter/timer. TH functions as an 8-bit timer, which is controlled by GATE1. Only Timer 0 can be configured in Mode 3. When this happens, Timer 1 can only be used where its interrupt is not required.

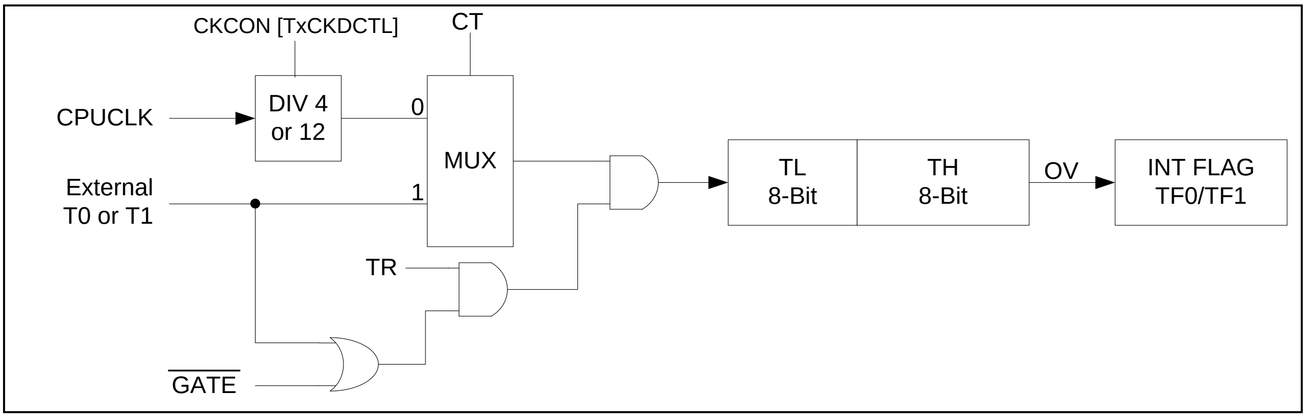
Mode 0

In this mode, TL serves as a 5-bit pre-scaler and TH functions as an 8-bit counter/timer, together working as a 13-bit counter/timer. The Mode 0 operation is shown in the following diagram.



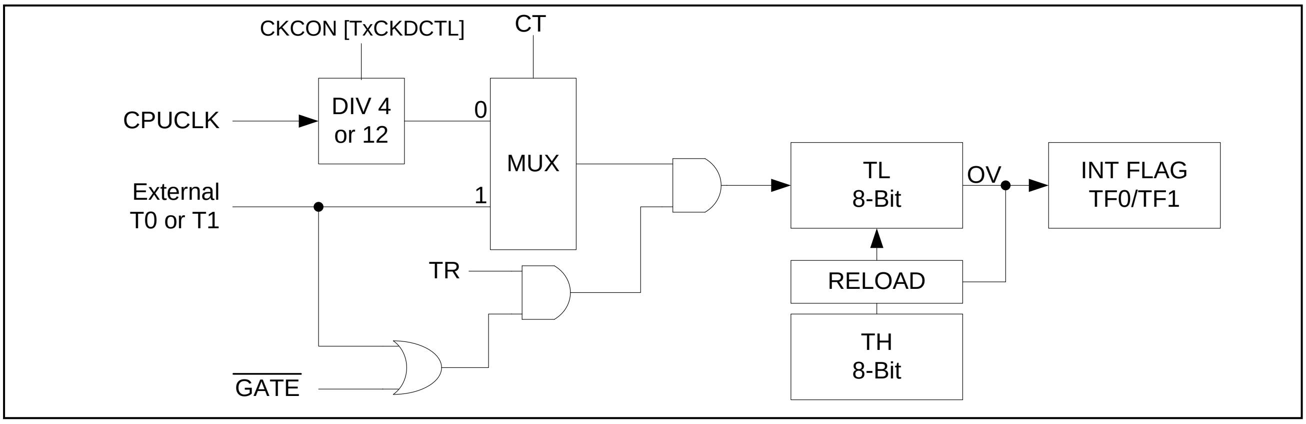
Mode 1

Mode 1 operates the same way Mode 0 does, except TL is configured as 8-bit and thus forming a 16-bit counter/timer. This is shown as the following diagram.



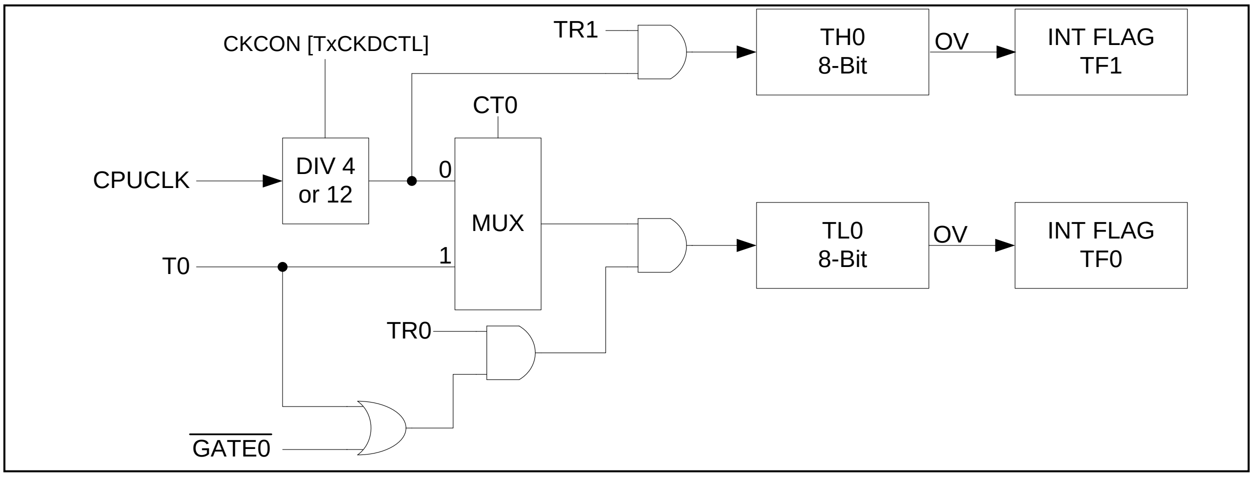
Mode 2

Mode 2 configures the timer as an 8-bit re-loadable counter. The counter is TL while TH stores the reload data. The reload occurs when TL overflows. The operation is shown in the following diagram:



Mode 3

Mode 3 is a special mode for Timer 0 only. In this mode, Timer 0 is configured as two separate 8-bit counters. TL uses control and interrupt flags of Timer 0 whereas TH uses control and interrupt flag of Timer 1. Since Timer 1's control and flag are occupied, Timer 2 can only be used for counting purposes such as Baud rate generating while Timer 0 is in Mode 3. The operation flow of Mode 3 is shown in the following diagram.



TL0 (0x8Ah) Timer 0 Low Byte Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TL0[7-0]							
WR	TL0[7-0]							

TH0 (0x8Ch) Timer 0 High Byte Register 0 R/W (x00)

	7	6	5	4	3	2	1	0
RD	TH0[7-0]							
WR	TH0[7-0]							

TL1 (0x8Bh) Timer 1 Low Byte Register 0 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TL1[7-0]							
WR	TL1[7-0]							

TH1 (0x8Dh) Timer 1 High Byte Register 0 R/W (0x00)

	7	6	5	4	3	2	1	0

RD	TH1[7-0]
WR	TH1[7-0]

1.10 System Timer – T2

Timer 2 is fully compatible with the standard 8052 timer 2. Timer 2 can be used as the re-loadable counter, capture timer, or baud rate generator. Timer 2 uses five SFR as counter registers, capture registers and a control register.

T2CON (0xC8h) Timer 2 Control and Configuration Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TF2	EXF2	RCLK	TCLK	EXEN2	TR2	CT2	CPRL2
WR	TF2	EXF2	RCLK	TCLK	EXEN2	TR2	CT2	CPRL2

TF2 — Timer 2 Interrupt Flag bit.
TF2 must be cleared by software. TF2 is not set when RCLK or TCLK is set (that means Timer 2 is used as an UART0 Baud rate generator).

EXF2 — T2EX Falling Edge Flag bit.
This bit is set when T2EX has a falling edge when EXEN2=1. EXF2 must be cleared by software.

RCLK — Receive Clock Enable bit
1 – UART0 receiver is clocked by Timer 2 overflow pulses
0 – UART0 receiver is clocked by Timer 1 overflow pulses

TCLK — Transmit Clock Enable bit
1 – UART0 transmitter is clocked by Timer 2 overflow pulses
0 – UART0 transmitter is clocked by Timer 1 overflow pulses

EXEN2 — T2EX Function Enable bit.
1 – Allows capture or reload as T2EX falling edge appears
0 – Ignore T2EX events

TR2 — Start/Stop Timer 2 Control bit
1 – Start
0 – Stop

CT2 — Timer 2 Timer/Counter Mode Select bit
1 – External event counter uses T2 pin as the clock source
0 – Internal clock timer mode

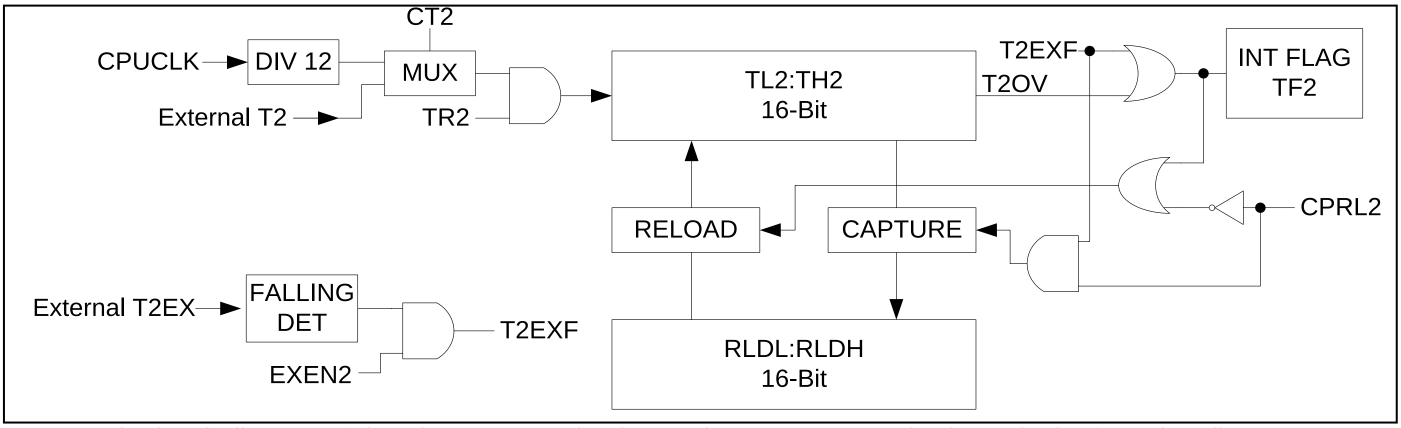
CPRL2 — Capture/Reload Select bit
1 – Use T2EX pin falling edge for capture
0 – Automatic reload on Timer 2 overflow or falling edge of T2EX (when EXEN2=1). If RCLK or TCLK is set (Timer 2 is used as a baud rate generator), this bit is ignored and an automatic reload is forced on Timer 2 overflows.

Note: This implementation does not support UART0

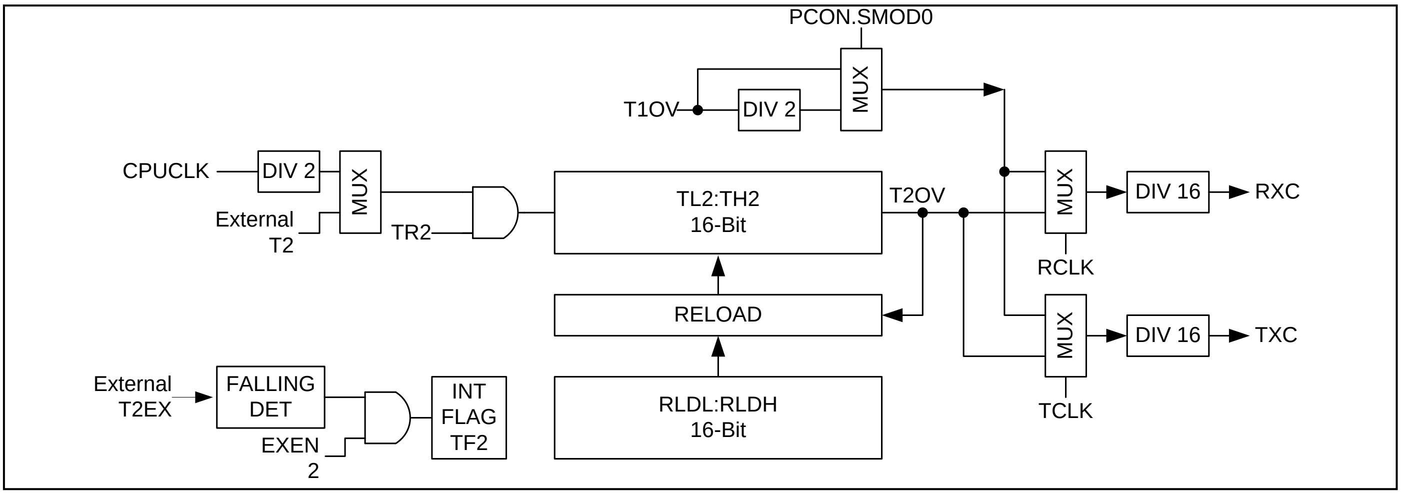
Timer 2 can be configured in three modes of operations –Auto-reload Counter, Capture Timer, or Baud Rate Generator. These modes are defined by RCLK, TCLK, CPRL2 and TR2 bits of T2CON registers. The definition is illustrated in the following table:

RCLK or TCLK	CPRL2	TR2	Mode Descriptions
0	0	1	16-bit Auto-reload Counter mode. Timer 2 overflow sets the TF2 interrupt flag and TH2/TL2 is reloaded with RLDH/RLHL register.
0	1	1	16-bit Capture Timer mode. Timer 2's overflow sets TF2 interrupt flag. When EXEN2=1, TH2/TL2 content is captured into RLDH/RLDL when T2EX falling edge occurs.
1	X	1	Baud Rate Generator mode. Timer 2's overflow is used for configuring UART0.
X	X	0	Timer 2 is stopped.

The block diagram of the Timer 2 operating in Auto-reload Counter and Capture Timer modes are shown in the following diagram. Please note External T2 and External T2EX are tied together in this product.



The block diagram of the Timer 2 operating in Baud Rate Generator is shown in the following diagram:



TL2 (0xCCh) Timer 2 Low Byte Register 0 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TL2[7-0]							
WR	TL2[7-0]							

TH2 (0xCDh) Timer 2 High Byte Register 0 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TH2[7-0]							
WR	TH2[7-0]							

RLDL (0xCAh) Timer 2 reload Low Byte Register 0 R/W (0x00)

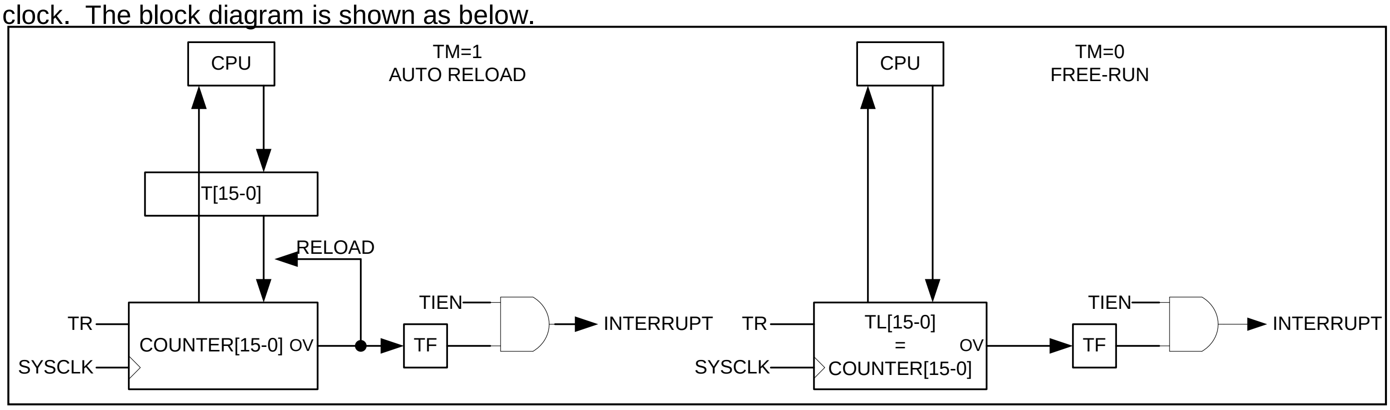
	7	6	5	4	3	2	1	0
RD	RLDL[7-0]							
WR	RLDL[7-0]							

RLDH (0xCBh) Timer 2 reload High Byte Register 0 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	RLDH[7-0]							
WR	RLDH[7-0]							

1.11 System Timer – T3 and T4

Both Timer 3 and Timer 4 are simple 16-Bit reload timers or free-run counters and are clocked by the system clock. The block diagram is shown as below.



T34CON (0xCFh) Timer 3 and Timer 4 Control and Status Register R/W (?????)

	7	6	5	4	3	2	1	0
RD	TF4	TM4	TR4	T4IEN	TF3	TM3	TR3	T3IEN
WR	TF4	TM4	TR4	T4IEN	TF3	TM3	TR3	T3IEN

TF4	Timer 4 Overflow Interrupt Flag bit. TF4 is set by hardware when overflow condition occurs. TF4 must be cleared by software.
TM4	Timer 4 Mode Control bit. TM4 = 1 set timer 4 as auto reload, and TM4=0 set timer 4 as free-run.
TR4	Timer 4 Run Control bit. Set to enable Timer 4, and clear to stop Timer 4.
T4IEN	Timer 4 Interrupt Enable bit. T4IEN=0 disable the Timer 4 overflow interrupt T4IEN=1 enable the Timer 4 overflow interrupt
TF3	Timer 3 Overflow Interrupt Flag bit. TF3 is set by hardware when overflow condition occurs. TF3 must be cleared by software.
TM3	Timer 3 Mode Control bit. TM3 = 1 set timer 3 as auto reload, and TM3=0 set timer 3 as free-run.
TR3	Timer 3 Run Control bit. Set to enable Timer 3, and clear to stop Timer 3.
T3IEN	Timer 3 Interrupt Enable bit. T3IEN=0 disable the Timer 3 overflow interrupt T3IEN=1 enable the Timer 3 overflow interrupt

TL3 (0xAEh) Timer 3 Low Byte Register 0 R/W 00000000

	7	6	5	4	3	2	1	0
RD	T3[7-0]							
WR	T3[7-0]							

TH3 (0xAFh) Timer 3 High Byte Register 0 R/W 00000000

	7	6	5	4	3	2	1	0
RD	T3[15-8]							
WR	T3[15-8]							

TL4 (0xACh) Timer 4 Low Byte Register 0 R/W 00000000

	7	6	5	4	3	2	1	0
RD	T4[7-0]							
WR	T4[7-0]							

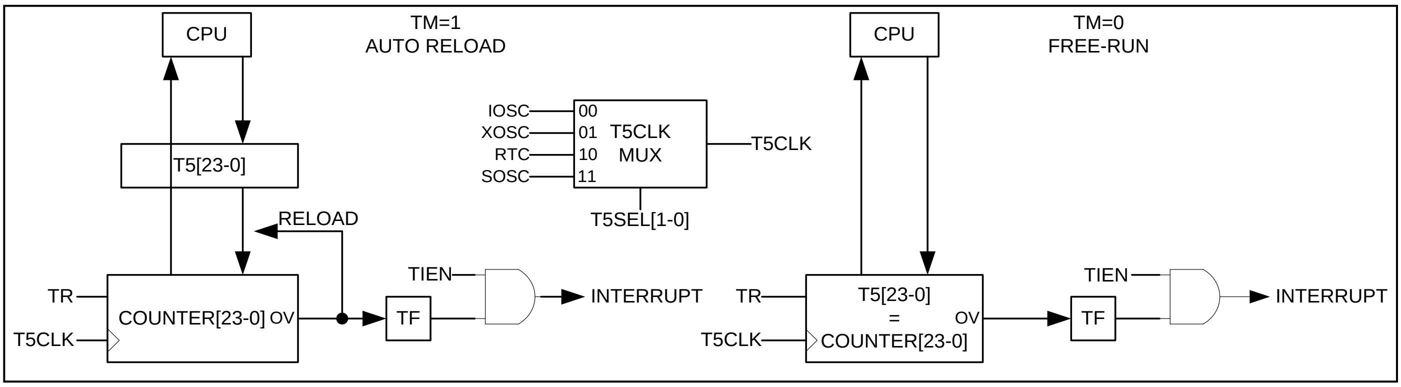
TH4 (0xADh) Timer 4 High Byte Register 0 R/W 00000000

	7	6	5	4	3	2	1	0
RD	T4[15-8]							
WR	T4[15-8]							

T3[15-0] and T4[15-0] function differently when been read or written. When written in auto-reload mode, its reload value register is written, and in free-run mode, the counter value is written immediately. When been read, the return value is always the present counter value. There is no snapshot buffer in the read operation, so software should always read the high byte then the low byte.

1.12 System Timer – T5

T5 is a 24-Bit simple timer. It can select four different clock sources and can be used for extended sleep mode wake up. The clock sources include IOSC, XOSC and SOSC/4. T5 can be configured either as free-run mode or auto-reload mode. Timer 5 does not depend on the SYSCLK, therefore it continues to count under STOP or SLEEP mode if the clock source is present. The following diagram shows the block diagram of Timer 5.



T5CON (0xA068h) Timer 5 Control and Status Register R/W (?????)

	7	6	5	4	3	2	1	0
RD	TF5	T5SEL[1]	T5SEL[0]	TM5	TR5	-	-	T5IEN
WR	TF5	T5SEL[1]	T5SEL[0]	TM5	TR5	-	-	T5IEN

TF5	Timer 5 Overflow Interrupt Flag bit. TF5 is set by hardware when overflow condition occurs. TF5 must be cleared by software.
T5SEL[1-0]	Timer 5 Clock Selection bits. T5SEL[1-0] = 00, IOSC T5SEL[1-0] = 01, IOSC T5SEL[1-0] = 10, SOSC/4 T5SEL[1-0] = 11, SOSC/4
TM5	Timer 5 Mode Control bit. TM5=1 set timer 5 as auto reload, and TM5=0 set timer 5 as free-run.
TR5	Timer 5 Run Control bit. Set to enable Timer 5, and clear to stop Timer 5.
T5IEN	Timer 5 Interrupt Enable bit. T5IEN=0 disable the Timer 5 overflow interrupt T5IEN=1 enable the Timer 5 overflow interrupt

TL5 (0xA069) Timer5 Low Byte Register 0 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	T5[7-0]							
WR	T5[7-0]							

TH5 (0xA06A) Timer5 Medium Byte Register 0 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	T5[15-8]							
WR	T5[15-8]]							

TT5 (0xA06B) Timer5 High Byte Register 0 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	T5[23-16]							
WR	T5[23-16]							

T5[23-0] functions differently when been read or written. When written in auto-reload mode, its reload value register is written, and in free-run mode, the counter value is written immediately. When been read, the return value is always the present counter value. There is no snapshot buffer in the read operation, so software should always read the high byte then the low byte.

1.13 Multiplication and Division Unit (MDU)

MDU provides acceleration on unsigned integer operations of 16-bit multiplications, 32-bit division, and shifting and normalizing operations. The following table shows the execution characteristics of these operations. The MDU does not contain the operation completion status flag. Therefore the most efficient utilization of MDU uses NOP delay for the required clock time of the MDU operation types. The number of the clock cycles required for each operation is shown in the following table and it is counted from the last write of the writing sequence.

Operations	Result	Reminder	# of Clock Cycle
32-bit division by 16-bit	32-bit	16-bit	17
16-bit division by 16-bit	16-bit	16-bit	9
16-bit multiplication by 16-bit	32-bit	-	10
32-bit normalization	-	-	3 – 20
32-bit shift left/right	-	-	3 – 18

The MDU is accessed through MD0 to MD5 that contains the operands and the results, and the operation is controlled by ARCON register.

ARCON (0xFF) MDU Control R/W (0x00)

	7	6	5	4	3	2	1	0
RD	MDEF	MDOV	SLR	SC4	SC3	SC2	SC1	SC0
WR	MDEF	MDOV	SLR	SC4	SC3	SC2	SC1	SC0

MDEF	MDU Error Flag bit. Set by hardware to indicate MDx being written before the previous operation completes. MDEF is automatically cleared after reading ARCON.
MDOV	MDU Overflow Flag bit. MDOV is set by hardware if dividend is zero or the result of multiplication is greater than 0x0000FFFFh
SLR	Shift Direction Control bit. SLR = 1 indicates a shift to the right and SLR =0 indicates a shift to the left.
SC4-0	Shift Count Control and Result bit. If SC0-4 is written with 00000, the normalization operation performed by MDU. When the normalization is completed, SC4-0 contains the number of shift performed in the normalization. If SC4-0 is written with a non-zero value, then the shift operation is performed by MDU with the number of shift specified by SC4-0 value.

MD0 (0xF9) MDU Data Register 0 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	MD0[7-0]							
WR	MD0[7-0]							

MD1 (0xFA) MDU Data Register 1 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	MD1[7-0]							
WR	MD1[7-0]							

MD2 (0xFB) MDU Data Register 2 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	MD2[7-0]							
WR	MD2[7-0]							

MD3 (0xFC) MDU Data Register 3 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	MD3[7-0]							
WR	MD3[7-0]							

MD4 (0xFD) MDU Data Register 4 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	MD4[7-0]							
WR	MD4[7-0]							

MD5 (0xFE) MDU Data Register 5 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	MD5[7-0]							
WR	MD5[7-0]							

MDU operation consists of three phases.

1. Loading MD0 to MD5 data registers in an appropriate order depending on the operation.
2. Execution of the operations.
3. Reading result from MD0 to MD5 registers.

The following list shows the MDU read and write sequences. Each operation has its unique writing sequence and reading sequence of MD0 to MD5 registers therefore a precise access sequence is required.

Division – 32-bit divide by 16-bit or 16-bit divide by 16-bit

Follow the following write-sequence. The first write of MD0 resets the MDU and initiates the MDU error flag mechanism. The last write incites calculation of MDU.

Write MD0 with Dividend LSB byte

Write MD1 with Dividend LSB+1 byte

Write MD2 with Dividend LSB+2 byte (ignore this step for 16-bit divide by 16-bit)

Write MD3 with Dividend MSB byte (ignore this step for 16-bit divide by 16-bit)

Write MD4 with Divisor LSB byte

Write MD5 with Divisor MSB byte

Then follow the following read-sequence. The last read prompts MDU for the next operations.

Read MD0 with Quotient LSB byte

Read MD1 with Quotient LSB+1 byte

Read MD2 with Quotient LSB+2 byte (ignore this step for 16-bit divide by 16-bit)

Read MD3 with Quotient MSB byte (ignore this step for 16-bit divide by 16-bit)

Read MD4 with Remainder LSB byte

Read MD5 with Remainder MSB byte

Read ARCON to determine error or overflow condition

Please note if the sequence is violated, the calculation may be interrupted and result in errors.

Multiplication – 16-bit multiply by 16-bit

Follow the following write sequence.

Write MD0 with Multiplicand LSB byte

Write MD4 with Multiplier LSB byte

Write MD1 with Multiplicand MSB byte

Write MD5 with Multiplier MSB byte

Then follow the following read sequence.

Read MD0 with Product LSB byte

Read MD1 with Product LSB+1 byte

Read MD2 with Product LSB+2 byte

Read MD3 with Product MSB byte

Read ARCON to determine error or overflow condition

Normalization – 32-bit

Normalization is obtained with integer variables stored in MD0 to MD3. After normalization, all leading zeroes are removed by shift left operations. To start the normalization operation, SC4-0 in ARCON is first written with 00000. After completion of the normalization, SC4-0 is updated with the number of leading zeroes and the normalized result is restored on MD0 to MD3. The number of the shift of the normalization can be used as exponents. The following write sequence should be followed. The last write to ARCON initiates the normalization operations by MDU.

Write MD0 with Operand LSB byte

Write MD1 with Operand LSB+1 byte

Write MD2 with Operand LSB+2 byte

Write MD3 with Operand MSB byte

Write ARCON with SC4-0 = 00000

Then follow the following read sequence.

Read MD0 with Result LSB byte

Read MD1 with Result LSB+1 byte

Read MD2 with Result LSB+2 byte

Read MD3 with Result MSB byte

Read SC[4-0] from ARCON for normalization count or error flag

Shift – 32-bit

Shift is done with integer variables stored in MD0 to MD3. To start the shift operation, SC4-0 in ARCON is first written with shift count and SLR with shift direction. After completion of the Shift, the result is stored back to MD0 to MD3.The following write sequence should be followed. The last write to ARCON initiates the normalization operations by MDU.

Write MD0 with Operand LSB byte

Write MD1 with Operand LSB+1 byte

Write MD2 with Operand LSB+2 byte

Write MD3 with Operand MSB byte

Write ARCON with SC4-0 = Shift count and SLR with shift direction

Then follow the following read sequence.

Read MD0 with Result LSB byte

Read MD1 with Result LSB+1 byte

Read MD2 with Result LSB+2 byte

Read MD3 with Result MSB byte

Read ARCON’s for error flag

MDU Flag

The error flag (MDEF) of MDU indicates improperly performed operations. The error mechanism starts at the first MD0 write and finishes with the last read of MD result register. MDEF is set if current operation is interrupted or restarted by improper write of MD register before the operation completes. MDEF is cleared if the operations and proper write/read sequences successfully complete. The overflow flag (MDOV) of MDU indicates an error of operations. MDOV is set if

The divisor is zero

Multiplication overflows

Normalization operation is performed on already normalized variables (MD3.7 =1)

1.14 I²C Master

The I²C master controller provides the interface to I²C slave devices. It can be programmed to operate with arbitration and clock synchronization to allow it to operate in multi-master configurations. The master uses SCL and

SDA pins. The controller contains a built-in 8-bit timer to allow various I²C bus speed. The maximum I²C bus speed is limited to SYSCLK/12.

I2CMTP (0xF7h) I²C Master Time Period R/W (x00)

	7	6	5	4	3	2	1	0
RD	I2CMTP[7-0]							
WR	I2CMTP[7-0]							

This register set the frequency of I²C bus clock. If I2CMTP[7-0] is equal to or larger than 0x01, then SCL_FREQ = SYSCLK_FREQ/8/(1 + I2CMTP). If I2CMTP[7-0] = 0x00, SCL_FREQ = SYSCLK_FREQ /12.

I2CMSA (0xF4) I²C Master Slave Address R/W (0x00)

	7	6	5	4	3	2	1	0
RD	SA[6-0]							RS
WR	SA[6-0]							RS

SA[6-0]	Slave Address. SA[6-0] defines the slave address the I²C master uses to communicate.
RS	Receive/Send Bit. RS determines if the following operation is to RECEIVE (RS=1) or SEND (RS=0).

I2CMBUF (0xF6) I²C Master Data Buffer Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	RD[7-0]							
WR	TD[7-0]							

I2CMBUF functions as a transmit-data register when written and as a receive-data register when read. When written, TD is sent to the bus by the next SEND or BURST SEND operations. TD[7] is sent first. When read, RD contains the 8-bit data received from the bus upon the last RECEIVE or BURST RECEIVE operation.

I2CMCR (0xF5) I²C Master Control and Status Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	-	BUSBUSY	IDLE	ARBLOST	DATANACK	ADDRNACK	ERROR	BUSY
WR	CLEAR	INFILEN	-	HS	ACK	STOP	START	RUN

The I2CMCR register is used for setting control when it is written, and as a status signal when read.

CLEAR	Reset I2C Master State Machine Set CLEAR=1 will reset the state machine. CLEAR is self-cleared when reset is completed.
INFILEN	Input Noise Filter Enable. When IFILEN is set, pulses shorter than 50 nsec on inputs of SDA and SCL are filtered out.
IDLE	This bit indicates that I²C master is in the IDLE mode.
BUSY	This bit indicates that I²C master is receiving or transmitting data, and other status bits are not valid.
BUSBUSY	This bit indicates that the external I²C bus is busy and access to the bus is not possible. This bit is set/reset by START and STOP conditions.
ERROR	This bit indicates that an error occurs in the last operation. The errors include slave address was not acknowledged, or transmitted data is not acknowledged, or the master controller loses arbitration.
ADDRNACK	This bit is automatically set when the last operation slave address transmitted is not acknowledged.
DATANACK	This bit is automatically set when the last operation transmitted data is not acknowledged.
ARBLOST	This bit is automatically set when the last operation I²C master controller loses the bus arbitration.

START, STOP, RUN and HS, RS, ACK bits are used to driveI²C Master to initiate and terminate a transaction. The Start bit generates START, or REPEAT START protocol. The Stop bit determines if the cycle stops at the end of the data cycle or continues to a burst. To generate a single read cycle, the designated address is written in SA, RS is set to 1, ACK=0, STOP=1, START=1, RUN=1 are set in I2CMCR to perform the operation and then STOP. When the operation is completed (or aborted due to errors), I²C master generates an interrupt. The ACK bit must be set to 1. This causes the controller to send an ACK automatically after each byte transaction. The ACK bit must be reset when set to 0 when the master operates in receive mode and not to receive further data from the slave devices.

The following table lists the permitted control bits combinations in master IDLE mode.

HS	RS	ACK	STOP	START	RUN	OPERATIONS
0	0	-	0	1	1	START condition followed by SEND. Master remains in TRANSMITTER mode
0	0	-	1	1	1	START condition followed by SEND and STOP
0	1	0	0	1	1	START condition followed by RECEIVE operation with negative ACK. Master remains in RECEIVER mode
0	1	0	1	1	1	START condition followed by RECEIVE and STOP
0	1	1	0	1	1	START condition followed by RECEIVE. Master remains in RECEIVER mode
0	1	1	1	1	1	Illegal command
1	0	0	0	0	1	Master Code sending and switching to HS mode

The following table lists the permitted control bits combinations in master TRANSMITTER mode.

HS	RS	ACK	STOP	START	RUN	OPERATIONS
0	-	-	0	0	1	SEND operation. Master remains in TRANSMITTER mode
0	-	-	1	0	0	STOP condition
0	-	-	1	0	1	SEND followed by STOP condition
0	0	-	0	1	1	REPEAT START condition followed by SEND. Master remains in TRANSMITTER mode
0	1	-	1	1	1	REPEAT START condition followed by SEND and STOP condition
0	1	0	0	1	1	REPEAT START condition followed by RECEIVE operation with negative ACK. Master remains in TRANSMITTER mode
0	1	0	1	1	1	REPEAT START condition followed by SEND and STOP condition.
0	1	1	0	1	1	REPEAT START condition followed by RECEIVE. Master remains in RECEIVER mode.
0	1	1	1	1	1	Illegal command

The following table lists the permitted control bits combinations in master RECEIVER mode.

HS	RS	ACK	STOP	START	RUN	OPERATIONS
0	-	0	0	0	1	RECEIVE operation with negative ACK. Master remains in RECEIVE mode
0	-	-	1	0	0	STOP condition
0	-	0	1	0	1	RECEIVE followed by STOP condition
0	-	1	0	0	1	RECEIVE operation. Master remains in RECEIVER mode
0	-	1	1	0	1	Illegal command
0	1	0	0	1	1	REPEAT START condition followed by RECEIVE operation with negative ACK. Master remains in RECEIVER mode
0	1	0	1	1	1	REPEAT START condition followed by RECEIVE and STOP conditions
0	1	0	1	1	1	REPEAT START condition followed by RECEIVE. Master remains in RECEIVER mode
0	0	-	0	1	1	REPEAT START condition followed by SEND. Master remains in TRANSMITTER mode.
0	0	-	1	1	1	REPEAT START condition followed by SEND and STOP conditions.

All other control-bit combinations not included in three tables above are NOP. In Master RECEIVER mode, STOP should be generated only after data negative ACK executed by Master or address negative ACK executed by slave. Negative ACK means SDA is pulled low when the acknowledge clock pulse is generated.

I2CMTO (0xC3) I²CTime Out Control Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	I2CMTOF	I2CMTO[6-0]						
WR	I2CMTOEN	I2CMTO[6-0]						

I2CMTOEN I2CM Time Out Enable

I2CMTOF I2CM Time Out Flag
This bit is set when a time out occurs. It is cleared when I2CM CLEAR command is issued.

I2CMTO[6-0] I2CM Time Out Setting
The TO time is set to (I2CMTO[6-0]+1)*2*BT. When time out occurs, an I2CM interrupt will be generated.

1.15 Checksum/CRC Accelerator

To enhance the performance, a hardware Checksum/CRC Accelerator is included and closely coupled with CPU. This provides most commonly used checksum and CRC operation for 8/16/24/32-bit data width. For 8-bit data, one SYSCLK cycle is used, and for 16-bit data two cycles is used, and 32-bit takes four cycles.

CCCFG (0xA078h) Checksum/CRC Accelerator Configuration Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	DWIDTH[1-0]		REVERSE	NOCARRY	SEED	-	-	BUSY
WR	DWIDTH[1-0]		REVERSE	NOCARRY	SEED	CRCMODE[2-0]		

DWIDTH[1-0] Data Input Width
00 – set input as 8-bit wide
01 – set input as 16-bit wide
10 – set the input as 24-bit wide
11 – set the input as 32-bit wide

REVERSE Reverse input MSB/LSB Sequence
REVERSE=0 is for LSB first operations.
REVERSE=1 is for MSB first operation.
The reverse order is based on the data width. For example, if the data width is 32-bit, and REVERSE=1, then CCDATA[0] holds MSB, and CCDATA[31] holds LSB.
REVERSE dose not affect output result and SEED ordering i.e. CCDATA[31] always holds MSB, CCDATA[0] always holds MSB.
The following table shows the MSB/LSB relationship

DWIDTH	REVERSE=0	REVERSE=1
0	CRCIN[7-0] = CCDATA[7-0]	CRCIN[7-0] = CCDATA[0-7]
1	CRCIN[15-0] = CCDATA[15-0]	CRCIN[15-0] = CCDATA[0-15]
2	CRCIN[23-0] = CCDATA[23-0]	CRCIN[23-0] = CCDATA[0-23]
3	CRCIN[31-0] = CCDATA[31-0]	CRCIN[31-0] = CCDATA[0-31]

NOCARRY Carry Setting for Checksum
NOCARRY=0 uses previous carry result for new result
NOCARRY=1 discard previous carry result.

SEED Seed Entry
SEED=1 results writing into CCDATA to become SEED value
SEED=0 for normal data inputs.
Please note, the MSB/LSB ordering of SEED entry from CCDATA is not affected by REVERSE.

CRCMODE[2-0] Defines CRC/Checksum Mode
000 – Accelerator is disabled and clock gated off
001 – 8-bit Checksum
010 – 32-bit Checksum
011 – CRC-16 (IBM 0x8005)
X16+X15+X2+1
100 – CRC-16 (CCITT 0x1021)
X16+X12+X5+1
101 – CRC-32 (ANSI 802.3 0x104C11DB7)

X32+X26+C23+X22+X16+X12+X11+X10+X8+X7+X5+X4+X2+X1+1
110 – Reserved
111 – CRC and Checksum Clear
Writing “111” to CRCMODE[1-0] resets the CS/CRC states and restore default seed value (for checksum, seed value=0x00 or 0x00000000, for CRC seed value = 0xFFFF or 0xFFFFFFFF). Writing “111” does not affect the previously set mode selection.

BUSY — CRC Status
BUSY=1 indicates the results is not yet completed. Since only up to four cycles are used to calculate the Checksum or CRC, there is no need to check BUSY status before next data entry and reading the results.

CCDATA registers are the data I/O port for Checksum/CRC Accelerator. For 8-bit data width only CCDATA[7-0] should be used. For data width wider than 8-bit, high byte should always be written first, writing the low byte (CCDATA0) completes the data entry and starts the calculations. When SEED=1, the data been written goes to CRC seed value. The SEED value entry bit ordering is not affected by REVERSE setting. The result of accelerator can be directly read out from CCDATA registers also not affected by REVERSE setting.

CCDATA0 (0xA07Ch) Chceksum/CRC Data Register 0 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	CCDATA[7-0]							
WR	CCDATA[7-0]							

CCDATA1 (0xA07Dh) Chceksum/CRC Data Register 1 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	CCDATA[15-0]							
WR	CCDATA[15-0]							

CCDATA2 (0xA07Eh) Chceksum/CRC Data Register 2 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	CCDATA[23-16]							
WR	CCDATA[23-16]							

CCDATA3 (0xA07Fh) Chceksum/CRC Data Register 2 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	CCDATA[31-24]							
WR	CCDATA[31-24]							

1.16 Break Point and Debug Controller

The CPU core also includes a Break Point Controller for software debugging purposes and handling exceptions. Program Counter break point triggers at PC address matching, and there are seven PC matching settings available. Single Step break point triggers at interaction return from an interrupt routine.

Upon the matching of break point conditions, the Break Point Controller issues BKP Interrupt for handling the break points. The BKP Interrupt vector is located at 0x7B. Upon entering the BKP ISR (Break Point Interrupt Service Routine), all interrupts and counters (WDT1, T0, T1, and T2) are disabled. To allow further interrupts and continuing counting, the BKP ISR must be enabled. At exiting, the BKP ISR setting must be restored to resume normal operations.

BPINTF (A0E0h) Break Point Interrupt Flag Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	STEP_IF	-	-	-	-	-	PC2IF	PC1IF
WR	STEP_IF	-	-	-	-	-	PC2IF	PC1IF

This register is for reading the Break Points interrupt flags.

STEP_IF — This bit is set when the Break Point conditions are met by a new instruction fetching from an interrupt routine. This bit must be cleared by software.

PC2IF – PC1IF — These bits are set when Break Point conditions are met by PC2 – PC1 address. These bits must be cleared by software.

BPINTE (A0E1h) Break Point Interrupt Enable Register R/W (0x00) TB Protected

	7	6	5	4	3	2	1	0
RD	STEP_IE	-	-	-	-	-	PC2IE	PC1IE
WR	STEP_IE	-	-	-	-	-	PC2IE	PC1IE

This register controls the enabling of individual Break Points interrupt.

STEP_IE Set this bit to enable Single Step event break point interrupt.

PC2IE – PC1IE Set these bits to enable PC2 to PC1 address match break point interrupts.

BPINTC (A0E2h) Break Point Interrupt Control Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	-	-	-	-	-	-	-	-
WR	-	-	-	-	-	-	-	-

This register is reserved for other applications.

BPCTRL (A0E3h) DBG and BKP ISR Control and Status Register R/W (0xFC)

	7	6	5	4	3	2	1	0
RD	DBGINTEN	DBGWDT1EN	DBGT2EN	DBGT1EN	DBGT0EN	-	-	DBGGST
WR	DBGINTEN	DBGWDT1EN	DBGT2EN	DBGT1EN	DBGT0EN	-	-	DBGGST

When entering the DBG or BKP ISR (Interrupt Service Routine), all interrupts and timers are disabled. The enabled bits are cleared by hardware reset in this register. As the interrupts and timers are disabled, the ISR can process debugging requirement in a suspended state. If a specific timer should be kept active, it must be enabled by ISR after ISR entry. Before exit of DBG and BKP ISR, the control bits should be enabled to allow the timers to resume operating. This register should be modified only in Debug ISR.

DBGINTEN Set this bit to enable all interrupts (except WDT1 interrupt). This bit is cleared automatically at the entry of DBG and BKP ISR. Set this bit to allow ISR to be further interrupted by other interrupts. This is sometimes necessary if DBG or BKP ISR needs to use UART or I^{2}C, for example.

DBGWDT1EN Set this bit to allow WDT1 counting during the DBG and BKP ISR. This bit should always be set before exiting the ISR.

DBGT2EN Set this bit to allow T2 counting during the DBG and BKP ISR. This bit should always be set before exiting the ISR. This bit only controls the counting but not T2 interrupt.

DBGT1EN Set this bit to allow T1 counting during the DBG and BKP ISR. This bit should always be set before exiting the ISR. This bit only controls the counting but not T1 interrupt.

DBGT0EN Set this bit to allow T0 counting during the DBG and BKP ISR. This bit should always be set before exiting the ISR. This bit only controls the counting but not T0 interrupt.

DBGST This bit indicates the DBG and BKP ISR status. It is set to 1 when entering DBG and BKP ISR. It should be cleared when exiting the DBG and BKP ISR. Checking this bit allows other interrupt routine to determine whether it is a sub-service of the DBG and BKP ISR.

PC1AL (A0F0h) Program Counter Break Point 1 Low Address Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	PC1AL[7-0]							
WR	PC1AL[7-0]							

This register defines the PC low address for PC match break point 1.

PC1AH (A0F1h) Program Counter Break Point 1 High Address Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	PC1AH[7-0]							
WR	PC1AH[7-0]							

This register defines the PC high address for PC match break point 1.

PC1AT (A0F2h) Program Counter Break Point 1 Top Address Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	PC1AT[7-0]							
WR	PC1AT[7-0]							

This register defines the PC top address for PC match break point 1. PC1AT:PC1HT:PC1LT together form a 24 bit compare value of break point 1 for Program Counter.

PC2AL (A0F4h) Program Counter Break Point 2 Low Address Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	PC2AL[7-0]							
WR	PC2AL[7-0]							

This register defines the PC low address for PC match break point 2.

PC2AH (A0F5h) Program Counter Break Point 2 High Address Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	PC2AH[7-0]							
WR	PC2AH[7-0]							

This register defines the PC high address for PC match break point 2.

PC2AT (A0F6h) Program Counter Break Point 2 Top Address Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	PC2AT[7-0]							
WR	PC2AT[7-0]							

This register defines the PC top address for PC match break point 2. PC2AT:PC2HT:PC2LT together form a 24-bit compare value of PC break point 2 for Program Counter.

Host or program can obtain the status of the break point controller through the current break point address and next PC address register. DBPCID[23-0] contains the PC address of just executed instruction when the break point occurs. DBNXPC[23-0] contains the next PC address to be executed when the break point occurs, therefore, it is usually exactly the same value of the break pointer setting.

DBPCIDL (A098h) Debug Program Counter Address Low Register RO (0x00)

	7	6	5	4	3	2	1	0
RD	DBPCID[7-0]							
WR	-							

DBPCIDH (A099h) Debug Program Counter Address High Register RO (0x00)

	7	6	5	4	3	2	1	0
RD	DBPCID[15-8]							
WR	-							

DBPCIDT (A09Ah) Debug Program Counter Address Top Register RO (0x00)

	7	6	5	4	3	2	1	0
RD	DBPCID[23-16]							
WR	-							

DBPCNXL (A09Bh) Debug Program Counter Next Address Low Register RO (0x00)

	7	6	5	4	3	2	1	0
RD	DBPCNX[7-0]							
WR	-							

DBPCNXH (A09Ch) Debug Program Counter Next Address High Register RO (0x00)

	7	6	5	4	3	2	1	0
RD	DBPCNX[15-8]							
WR	-							

DBPCNXT (A09Dh) Debug Program Counter Next Address Top Register RO (0x00)

	7	6	5	4	3	2	1	0
RD	DBPCNX[23-16]							
WR	-							

STEPCTRL (A09Eh) Single Step Control Enable Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	STEPCTRL[7-0]							
WR	STEPCTRL[7-0]							

To enable single-step debugging, STEPCTRL must be written with value 0x96.

1.17 Debug I²C Port

The I²C Slave 2 (I2CS2) can be configured as the debug and ISP port. This is achieved by assigning a predefined debug ID for the I²CSlave address. When a host issues an I²C access to this special address, a DBG interrupt is generated. DBG Interrupt has the highest priority. The DBG interrupt vector is located at 0x83. DBG ISR is used to communicate with the host and is usually closely associated with BKP ISR.

SI2CDBGID (A09Fh) Slave I²C Debug ID Register R/W (0x36) TB Protected

	7	6	5	4	3	2	1	0
RD	DBGSI2C2EN	SI2CDBGID[6:0]						
WR	DBGSI2C2EN	SI2CDBGID[6:0]						

DBGSI2C2EN DBGSI2C2EN=1 enables I2CS2 as debug port. When I2CS2 receives an access of I²C address matching SI2CDBGID[6:0], a debug interrupt is generated.

SI2CDBGID[6:0] Slave I²C ID address for debug function.

1.18 Data SRAM ECC Handling

The data SRAM (IRAM and XRAM) is configured as 1024 x 16-bit. In default, the low byte is at even address and the high byte is at odd address. For higher system integrity, ECC can be enabled, then the high byte is used for ECC code, and low byte is for data. The ECC is based on 4-bit nibble bases, therefore it can correct 1-bit error in each nibble, and detect 2-bit error in each nibble. All generation and checking are done in hardware. It is strongly recommended all SRAM data should be initialized if ECC is enabled to avoid initial ECC error. If ECC encounters either an uncorrectable error, hardware will latch the address and triggers an interrupt. Software needs to examine the severity of data corruption and determine appropriate actions. Please also note, switching between ECC and non-ECC mode, all the data in SRAM will be corrupted thus require re-initialization. It is strongly suggested keeping ECC enabled for best reliability as well as noise immunity.

DECCCFG (0xA02Dh) Data ECC Configuration Register R/W (0x80) TB Protected

	7	6	5	4	3	2	1	0
RD	DECCEN	-	DECCIEN2	DECCIEN1	-	-	DECCIF2	DECCIF1
WR	DECCEN	-	DECCIEN2	DECCIEN1	-	-	DECCIF2	DECCIF1

DECCEN Data ECC Enable

DECCIEN2 Data ECC Uncorrectable Error Interrupt Enable

DECCIEN1 Data ECC Correctable Error Interrupt Enable

DECCIF2 Data ECC Uncorrectable Error Interrupt Flag
DECCIF2 is set to 1 by hardware when reading SRAM encounters uncorrectable error. DECCIF2 is set independent of DECCIEN2. DECCIF2 needs to be cleared by software.

DECCIF1 Data ECC Correctable Error Interrupt Flag
DECCIF1 is set to 1 by hardware when reading SRAM encounters correctable error. DECCIF1 is set independent of DECCIEN1. DECCIF1 needs to be cleared by software.

Please note if a correctable error is encountered, the data will be automatically corrected. To prevent further corruption, software upon DECIF1 interrupt should read and rewrite the data into the SRAM.

DECCADL (0xA02Eh) Data ECC Configuration and Address Register Low RO (0x00)

	7	6	5	4	3	2	1	0
RD	DECCAD[7-0]							
WR	-							

DECCADH (0xA02Fh) Data ECC Configuration and Address Register High R/W (0x80)

	7	6	5	4	3	2	1	0
RD	DECCAD[15-8]							
WR	-							

DECCAD[15-0] records the address of ECC fault when data SRAM ECC error occurs. It is read-only and reflects the error address that causes DECCIF to be set. If DECCIF is set and not cleared, DECCAD will not be updated if further error is detected.

1.19 Program ECC Handling

The program code stored in e-Flash has built-in ECC checking. The e-Flash is in 16-bit width, and when read by CPU program space accesses, the lower LSB 8-bit is read for instruction and the upper MSB 8-bit contains the ECC value of the LSB 8-bit. The ECC is nibble based, [15-12] is ECC for [7-4], and [11-8] is ECC for [3-0]. Four bits ECC for four bits data allows one bit error correction and two bits error detection. This means for an 8-bit code stored, 2-bit error corrects is possible, and this greatly increases the reliability of the overall program robustness.

During program fetch and execution, ECC is performed simultaneously by hardware. If any ECC correctable error is detected, the value fetched is corrected, and optionally a PECCIEN1 interrupt can be generated. If any ECC non-correctable error is detected, two options can be configured, either a PECCIEN2 interrupt can be generated or software reset can be generated. In both PECCIEN interrupt, the address of the error encountered is latched in PECCADL[15-0].

PECCCFG (0xA00Dh) Program ECC Configuration Register R/W (0x80) TB Protected

	7	6	5	4	3	2	1	0
RD	FCECCEN	-	PECCIEN2	PECCIEN1		-	PECCIF2	PECCIF1
WR	FCECCEN	-	PECCIEN2	PECCIEN1		-	PECCIF2	PECCIF1

FCECCEN　Flash Controller Read ECC Control
This bit controls the Flash Controller Read command. If FCECCEN=1, then the Flash Controller read low byte contains ECC corrected data. If FCECCEN=0, then the read operation returns the raw data from e-Flash.

PECCIEN2　Program ECC Uncorrectable Error Interrupt Enable

PECCIEN1　Program ECC Correctable Error Interrupt Enable

PECCIF2　Program ECC Uncorrectable Error Interrupt Flag
PECCIF2 is set to 1 by hardware when program fetching from e-Flash encounters uncorrectable error. PECCIF2 is set independent of PECCIEN2. PECCIF2 needs to be cleared by software.

PECCIF1　Program ECC Correctable Error Interrupt Flag
PECCIF1 is set to 1 by hardware when program fetching from e-Flash encounters correctable error. PECCIF1 is set independent of PECCIEN1. PECCIF1 needs to be cleared by software.

PECCADL (0xA00Eh) Program ECC Fault Address Register Low RO (0x00)

	7	6	5	4	3	2	1	0
RD	PECCAD[7-0]							
WR	-							

PECCADH (0xA00Fh) Program ECC Fault Address Register High R/W (0x80)

	7	6	5	4	3	2	1	0
RD	PECCAD[15-8]							
WR	-							

PECCAD[15-0] records the address of ECC fault when Flash ECC error occurs. It is read-only and reflects the last error address.

1.20 Memory and Logic BIST Test

BSTCMD (0xA016h) SRAM Built-In and Logic Self Test R/W (0x00) TB Protected

	7	6	5	4	3	2	1	0
RD	MODE[3-0]				BST	-	FAIL	FINISH
WR	MODE[3-0]				BSTCMD[3-0]			

MODE[3-0] BIST Mode Selection
0000 – Normal Mode
0001 – SRAM MBIST
0010 – Reserved
0011 – Reserved
0100 – Register LBIST
0101 – Reserved
0110 – Reserved
0111 – Reserved
1000 – Normal Mode
1001 – SRAM MBIST and monitor on pins
1010 – Reserved
1011 – Reserved
1100 – Register LBIST and monitor on pins
1101 – Reserved
1110 – Reserved
1111 – Reserved
Please note MODE[3-0] is cleared only by POR and RSTN. Software can read this setting along with the Pass/Fail status to determine which BIST was performed and its result even after a software reset.

BST BIST Status
BST is set to 1 by hardware when BIST in ongoing.

FAIL BIST Test Fail Flag
FAIL is set to 1 by hardware when BIST error has occurred. FAIL is cleared to 0 by hardware when a new BIST command is issued.

FINISH BIST Completion Flag
FINISH is set to 1 by hardware when BIST controller finishes the test. FINISH is cleared to 0 by hardware when a new BIST command is issued.

BSTCMD[3-0] Memory BIST Command
Writing BSTCMD[3-0] with value 4b'0101 causes the BIST controller to perform BIST.
Writing BSTCMD[3-0] with value 4b'1010 causes the BIST controller to perform BIST, and after BIST is completed, it automatically generates a software reset.
Writing BSTCMD[3-0] with value 4b'0000 causes FAIL and FINISH bits to be cleared to 0.
Any other value will either have no effect or abort any ongoing BIST.

Please note after the BSTCMD is issued, CPU is paused until BIST is completed. And any BIST operations will results the state of CPU in undefined states, and the content of the SRAM undefined. Therefore it is highly recommended that a software reset or initiation should be performed after any BIST operation. Please also note MODE[3-0], FINISH, FAIL bits are not cleared by software resets.

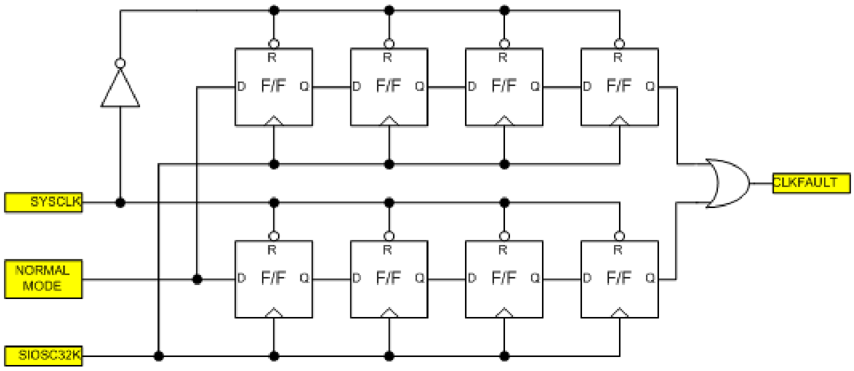
TSTMON (0xA014h) Test Monitor Flag R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TSTMON[7-0]							
WR	TSTMON[7-0]							

TSTMON register stores temporary status and is initialized by power-on reset only.

1.21 System Clock Monitoring

SYSCLK in normal running mode is monitored by SOSC/4 (32KHz). If SYSCLK is not present in normal mode for four SOSC/4 cycles, a hardware reset is triggered.

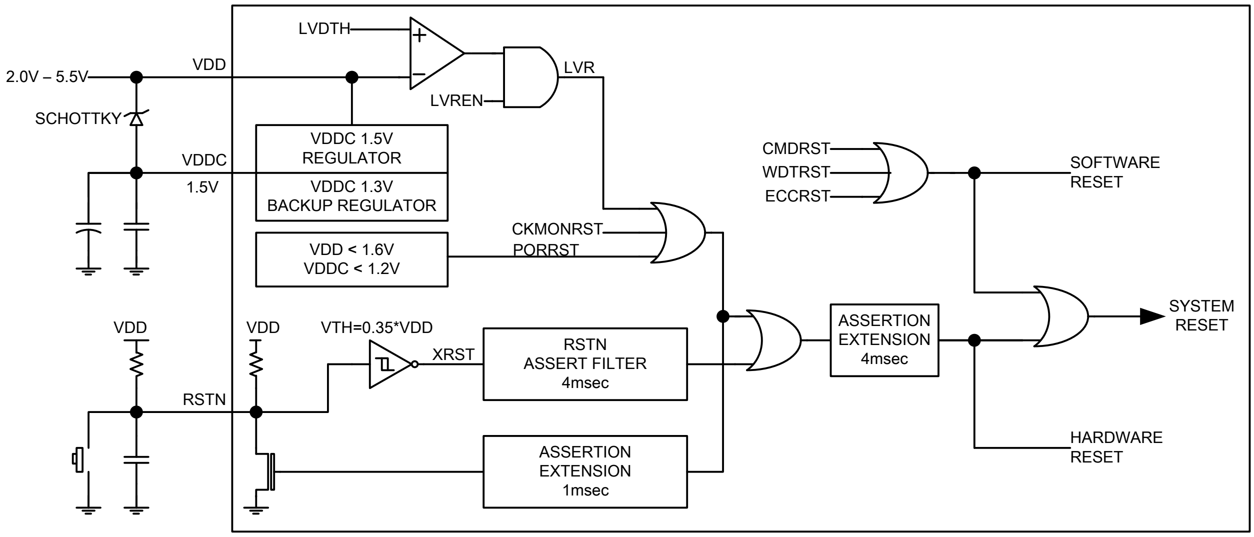


The clock monitoring is default turned off after reset.

1.22 Reset

There are several reset sources and includes both software resets and hardware resets. Software resets include command reset, WDT reset and ECC error reset. Hardware resets include power-on reset (low voltage detect on VDDC), LVD reset (low voltage detect on VDD), SYSCLK monitor reset, and external RSTN reset. Software reset only restores some registers to default values, and hardware reset restore all registers to its default values.

RSTN reset is filtered that ignores any low going glitch on RSTN with less than 4msec. All hardware reset condition once being met will be extended by 4 msec when exiting reset. Internal hardware resets also has feedback to RSTN pin and extend the reset duration by external RSTN R/C time. The reset scheme is shown in the following diagram.



RSTCMD (0xA017h) Reset Command Register R/W (0x00) TB Protected

	7	6	5	4	3	2	1	0
RD	RSTCKM	RSTECC	-	-	CKMRF	ECCRF	WDTRF	CMDRF
WR	RSTCKM	RSTECC	-	CLRF	RSTCMD[3-0]			

RSTCKM Reset Enable for Clock Monitor Fault
RENCKM=1 enables reset after clock fault detection. RSTCKM is cleared to 0 after any reset. Default RSTCKM is 0.

RSTECC	Reset Enable for Uncorrectable Code Fetch ECC Error RSTECC=1 enables reset at e-Flash code fetch ECC error. Default RSTECC is 0.
CKMRF	Clock Monitor Fault Reset Flag CKMRF is set to 1 by hardware when a clock fault reset has occurred. CKMRF is not cleared by reset except power-on reset.
ECCRF	ECC Error Reset Flag ECCRF is set to 1 by hardware when an ECC error reset has occurred. ECCRF is cleared to 0 when writing CLRF=0. ECCRF is not cleared by reset except power-on reset.
WDTRF	WDT Reset Flag WDTRF is set to 1 by hardware when WTRF, WT1RF or WT2RF is set.
CLRF	Clear Reset Flag Writing 1 to CLRF will clear CKMRF, ECCRF, WDTRF, and CMDRF. It is self-cleared.
RSTCMD[3-0]	Software Reset Command Writing RSTCMD[3-0] with consecutive 4b’0101, 4b’1010 sequences will cause a software reset. Any other value will clear the sequence state. These bits are write-only and self-cleared.

2. Flash Controller

The flash controller connects the CPU to the on-chip embedded FLASH memory. The FLASH memory functions as the program storage as well as non-volatile data storage. The program access of the FLASH does not require any special attention. When an ECC error during program fetch occurs, this cause ECC interrupt or reset.

When the FLASH is used as data storage, the software issues commands to the FLASH controller through the XFR registers. And when the FLASH controller processes these commands, CPU is held idle until the command is completed. There is a time-out mechanism for holding CPU in idle to prevent hanged operations.

From FLASH controller point of view, the embedded Flash is always in 16-bit width with no distinction between ECC and data information. For code storage through FLASH controller, ECC byte (upper MSB 8-bit) must be calculated by software. During read command, ECC is detected but not corrected, the raw content is loaded into FLSHDAT[15-0]. If ECC error is detected, FAIL status is set after the read command execution.

The e-Flash contains 32 pages (also referred as Sector), and each page is 512x16. It also contains two IFB (Information Blocks) pages. In Flash operation, the erase command only operates on unit of page.

FLSHCMD (0xA025h) Flash Controller Command Register R/W (0x80) TB Protected

	7	6	5	4	3	2	1	0
RD	WRVFY	BUSY	FAIL	CMD4	CMD3	CMD2	CMD1	CMD0
WR	CYC[2-0]			CMD4	CMD3	CMD2	CMD1	CMD0

WRVFY — Write Result Verify. At the end of a write cycle, hardware reads back the data and compares it with which should be written to the flash. If there is a mismatch, this bit represents 0. It is reset to 1 by hardware when another ISP command is executed.

BUSY — Flash command is in processing. This bit indicates that Flash Controller is executing the Flash Read, Write, or Sector Erase and other commands are not valid.

FAIL — Command Execution Result. It is set if the previous command execution fails due to any reasons. It is recommended that the program should verify the command execution after issuing a command to the Flash controller. It is not cleared by reading but when a new command is issued. Possible causes of FAIL include address over range, or address falls into protected region, and also include ECC error for read, and command time out.

CYC[2-0] — Flash Command Time Out

CYC[2-0] defines command time out cycle count. Cycle period is defined by ISPCLK, which is SYSCLK/256/(ISPCLKF[7-0]+1). The number of cycles is tabulated as following.

CYC[2-0]			WRITE	ERASE
0	0	0	55	5435
0	0	1	60	5953
0	1	0	65	6452
0	1	1	69	6897
1	0	0	75	7408
1	0	1	80	7906
1	1	0	85	8404
1	1	1	89	8889

For normal operations, CYC[2-0] should be set to 111.

CMD4 – CMD0 — Flash Command

These bits define commands for the Flash controller. The valid commands are listed in the following table. Any invalid commands do not get executed but return with a Fail bit.

CMD4	CMD3	CMD2	CMD1	CMD0	COMMAND
1	0	0	0	0	Main Memory Read
0	1	0	0	0	Main Memory Sector Erase
0	0	1	0	0	Main Memory Write
0	0	0	1	0	IFB Read
0	0	0	0	1	IFB Write
0	0	0	1	1	IFB Sector Erase
1	0	0	1	0	-

IFB1 contains manufacture data and user OTP, therefore IFB write command are limited to IFB1 (0x0040-0x01FF) and IFB2. IFB Sector Erase is limited to IFB2.

For any Read command, the result high byte contains the ECC code, and low byte contains the data that is ECC corrected. If there is ECC error, then FAIL bit is set. To find out what ECC error occurs, software can inspect PECCIF1 and PEECIF2 bits in PECCCFG register. To read the e-Flash raw data, the FCECCEN in PECCFG register can bit set to 0.

FLSHDATL (0xA020h) Flash Controller Data Register R/W (0x00) TB Protected

	7	6	5	4	3	2	1	0
RD	Flash Read Data Register DATA[7-0]							
WR	Flash Write Data Register DATA[7-0]							

Please note DATA[7-0] in READ operation will returns either ECC corrected data or e-Flash raw data depends on FCECEEN bit setting in PECCCFG register.

FLSHDATH (0xA021h) Flash Controller Data Register R/W (0x00) TB Protected

	7	6	5	4	3	2	1	0
RD	Flash Read Data Register DATA[15-8]							
WR	Flash Write Data Register DATA[15-8]							

FLSHADL (0xA022h) Flash Controller Low Address Data Register R/W (0x00) TB Protected

	7	6	5	4	3	2	1	0
RD	Flash Address Low Byte Register ADDR[7-0]							
WR	Flash Address Low Byte Register ADDR[7-0]							

FLSHADH (0xA023h) Flash Controller High Address Data Register R/W (0x00) TB Protected

	7	6	5	4	3	2	1	0
RD	Flash Address High Byte Register ADDR[15-8]							
WR	Flash Address High Byte Register ADDR[15-8]							

FLSHECC (0xA024h) Flash ECC Accelerator Register R/W (????)

	7	6	5	4	3	2	1	0
RD	ECC[7-0]							
WR	DATA[7-0]							

FLSHECC aids the calculation of ECC value of an arbitrary 8-bit data. The data is written to FLSHECC, and its corresponding ECC value can be read out from ECC.

ISPCLKF (0xA026h) Flash Command Clock Scaler R/W (0x25) TB Protected

	7	6	5	4	3	2	1	0
RD	ISPCLKF[7-0]							
WR	ISPCLKF[7-0]							

ISPCLKF[7-0] configures the clock time base for generation of Flash erase and write timing. ISPCLK = SYSCLK * (ISPCLKF[7-0]+1)/256. For correct timing, ISPCLK should be set to approximately at 2MHz.

FLSHPRT0 (0xA030h) Flash Controller Zone Protection Register 0 R/W (0xFF) TB Protected

	7	6	5	4	3	2	1	0
RD	FLSHPRT[7-0]							
WR	FLSHPRT[7-0]							

FLSHPRT1 (0xA031h) Flash Controller Zone Protection Register 1 R/W (0xFF) TB Protected

	7	6	5	4	3	2	1	0
RD	FLSHPRT[15-8]							
WR	FLSHPRT[15-8]							

FLSHPRT2 (0xA032h) Flash Controller Zone Protection Register 2 R/W (0xFF) TB Protected

	7	6	5	4	3	2	1	0
RD	FLSHPRT[23-16]							
WR	FLSHPRT[23-16]							

FLSHPRT3 (0xA033h) Flash Controller Zone Protection Register 3 R/W (0xFF) TB Protected

	7	6	5	4	3	2	1	0
RD	FLSHPRT[31-24]							
WR	FLSHPRT[31-24]							

FLSHPRT4 (0xA034h) Flash Controller Zone Protection Register 4 R/W 0xFF) TB Protected

	7	6	5	4	3	2	1	0
RD	FLSHPRT[39-32]							
WR	FLSHPRT[39-32]							

FLSHPRT5 (0xA035h) Flash Controller Zone Protection Register 5 R/W (0xFF) TB Protected

	7	6	5	4	3	2	1	0
RD	FLSHPRT[47-40]							
WR	FLSHPRT[47-40]							

FLSHPRT6 (0xA036h) Flash Controller Zone Protection Register 6 R/W (0xFF) TB Protected

	7	6	5	4	3	2	1	0
RD	FLSHPRT[55-48]							
WR	FLSHPRT[55-48]							

FLSHPRT7 (0xA037h) Flash Controller Zone Protection Register 7 R/W (0xFF) TB Protected

	7	6	5	4	3	2	1	0
RD	FLSHPRT[63-56]							
WR	FLSHPRT[63-56]							

NOTE: FLSHPRT3~7 are not supported.

FLSHPRT partitions the total code space of 64K into 64 uniform 1K zones for protection. If the corresponding bit in the FLSHPRT is 0, the zone protection is on. All bits in FLSHPRT are set to 1 by any reset. A “1” state corresponds to unprotected state. A bit can only be written to “0” by software and cannot be set to “1”. When a bit is “0”, the protection is on and disallowed erasure or modifications. For contents reliability, the user program should turn off the corresponding access after initialization as soon as possible.

FLSHPRT[63]	Flash Zone Protect 63 This bit protect area 0xFC00 – 0xFFFF
FLSHPRT[30]	Flash Zone Protect 62 This bit protect area 0xF800 – 0xFBFF
…	…
FLSHPRT[4]	Flash Protect 4 This bit protect area 0x1000 – 0x13FF
FLSHPRT[3]	Flash Protect 3 This bit protect area 0x0C00 – 0x0FFF
FLSHPRT[2]	Flash Protect 2 This bit protect area 0x0800 – 0x0BFF
FLSHPRT[1]	Flash Protect 1 This bit protect area 0x0400 – 0x07FF
FLSHPRT[0]	Flash Protect 0 This bit protect area 0x0000 – 0x03FF

FLSHPRTC (0xA027h) Flash Controller Code Protection Register R/W (0x00) TB Protected

	7	6	5	4	3	2	1	0
RD	-							STAT
WR	FLSHPRTC[7-0]							

This register further protects the code space (0x0000 – 0xFFFF). The protection is on after any reset. Software write "55" into this register turns off protection. However, protection is maintained on until a wait time (approximately 300msec) has expired. The 300msec delay prevents any false action due to power or interface transient. Any write other than "55" will turn on the protection immediately. STAT indicates the protection, STAT=1 indicates the protection is off, and STAT=0 indicates the protection is on.

Please note, in order to modify or erase the flash (not including IFB) both FLSHPRT and FLSHPRTC conditions needs to be satisfied at the same time. IFB1's manufacturing data is always protected while user data can only be written "0". IFB2 are user application data and thus not protected.

FLSHVDD (0xA015h) Flash VDD Switch Control Register R/W (0x00) TB Protected

	7	6	5	4	3	2	1	0
RD	-							SLEEPSW
WR	FLSHVDD[7-0]							

FLSHVDD is used to control the supply voltage to the e-Flash during sleep mode. Writing FLSHVDD with 0x55 will set configure the SLEEPSW to 1. If SLEEPSW=1, the power supply to the e-Flash is turned off during sleep mode. Default SLEEPSW is 0 and the e-Flash supply is always on.

3. I²C Slave Controller 2 (I2CS2)

The I²C Slave Controller 2 has dual functions – as a debug port for communication with host or as a regular I²C slave port. Please note both functions can coexist. I²C Slave 2 controller also supports the clock stretching functions.

The debug accessed by the host is through I²C slave address defined by SI2CSDBGID register and enabled by DBGSI2C2EN=1. When I2CS2 received this address match, a DBG interrupt is generated. This is described in the Debug and ISP sections. If DBGSI2C2EN=0, then I2CS2 functions as a regular I²C slave. The address of the slave is set by I2CSADR2 register. The MSB in I2CSADDR2 is the enable bit for the I²C slave controller and I2CSADR2[6-0] specifies the actual slave address.

In receive mode, the controller detects a valid matching address and issues an ADDRMI interrupt. At the same time, the data bit on SDA line is shifted into receive buffer. The RCBI interrupt is generated whenever a complete byte is received and is ready to be read from I2CSDAT. If for any reason, the software does not respond to RCBI interrupt in time (i.e. RCBI is not cleared), and a new byte is received, the controller either forces an NACK response on I²C (if CLKSTREN bit is not set) or by pulling and holding SDA low (if CLKSTREN bit is set) to stretch the SCL low duration to force the master into a wait state. In clock stretching mode, SCL is released when the software responds to RCBI interrupt and cleared RCBI flag.

In transmit mode, the controller detects a valid matching address and issue an ADDRMI interrupt. At the same time, the data preloaded in the transmit data register through I2CSDAT is transferred to the transmit shift register and is serially shifted out onto SDA line. When this occurs, the controller generates a TXBI interrupt to inform the software that a new byte can be written into I2CSDAT. When the shift register is empty and ready for the next transmit, the slave controller checks if the new byte is written to the I2CSDAT. If TXBI is not cleared, it indicates lack of new data and the slave controller holds SCL line low to stretch the current clock cycle if CLKSTREN is set. If the clock stretching is not enabled, the slave controller takes the old byte into the shift register and replies with NACK, thus causing data corruption. On the other hand, if the master returns the NACK after the byte transfer, this indicates the end of data to the I²C slave. In this case, the I²C slave releases the data line to allow the master to generate a STOP or REPEAT START.

The I²C slave controller also implements the input noise spike filter, and this is enabled by INFILEN bit in the I2CSCON register. The filter is implemented using digital circuit. When INFILEN is set, the spikes less than 1/2 SYSCLK period on the input of SDA and SCL lines are filtered out. If INFILEN is low, no input filtering is done. The following registers are related to I²C Slave Controller. Also please note the I²C slave controller uses SYSCLK to sample the SCL and SDA signals, therefore, the maximum allowable I²C bus speed is limited to SYSCLK/8 with conforming data setup and hold times. If setup and hold time cannot be guaranteed, then it is recommended the bus speed is limited to 1/40 SYSCLK.

I2CSCON2 (0xDB) I2CS2 Configuration Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	-	-	-	START	-	-	-	XMT
WR	I2CSRST	EADDRMI	ESTOPI	ERPSTARTI	ETXBI	ERCBI	CLKSTREN	INFILEN

I2CSRST — I²C Slave Reset bit.
Set this bit causes the Slave Controller to reset all internal state machine. Clear this bit for normal operations. Setting this bit clears the I2CSADR2 (I²C slave address x).

EADDRMI — ADDRMI Interrupt Enable bit.
Set this bit to set ADDRMI interrupt as the I²C slave interrupt. This interrupt is generated when I²C slave received a matching address.

ESTOPI — STOPI Interrupt Enable bit.
Set this bit to set STOPI interrupt as the I²C slave interrupt.

ERPSTARTI — RPTSTARTI Interrupt Enable Bit.
Set this bit to set RPTSTARTI interrupt as the I²C slave interrupt.

ETXBI — TXBI Interrupt Enable bit. Set this bit to allow TXBI interrupt as the I²C slave interrupt.

ERCBI — RCBI Interrupt Enable bit. Set this bit to allow RCBI interrupt as the I²C slave interrupt.

CLKSTREN — Clock Stretching Enable bit. Set to enable the clock stretching function of the slave controller. Clock stretching is an optional feature defined in I²C specification.
If the clock stretching option is enabled (for slave I²C), the data written into transmit buffer is shifted out only after the occurrence of clock stretching, and the data cannot be loaded to transmit shift register. The programmer must write the same data again to the transmit buffer.

INFILEN — Input Noise Filter Enable bit.

	Set this bit to enable the input noise filter of SDA and SCL lines. When the filter is enabled, it filters out the spike of less than 50nsec.
XMT	This bit is set by the controller when the I^{2}C slave is in transmit operation; is clear when the I^{2}C slave controller is in receive operation.

I2CSST2 (0xDC) I2CS2 Status Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	FIRSTBT	ADDRMI	STOPI	RPSTARTI	TXBI	RCBI	START	NACK
WR	DADDR	ADDRMI	STOPI	RPSTARTI	HOLDT[3]	HOLDT[2]	HOLDT[1]	HOLDT[0]

FIRSTBT	This bit is set to indicate the data in the data register as the first byte received after address match. This bit is cleared after the first byte of the transaction is read. The bit is read only and generated by the slave controller.
DADDR	Double Address Enable If DADDR=1, the LSB bit of the address register is ignored. This allows receiving two consecutive slave addresses, for example, 0x1010000 and 0x1010001.
ADDRMI	Slave Address Match Interrupt Flag bit. This bit is set when the received address matches the address defined in I2CSADR2. If EADDMI is set, this generates an interrupt. This bit must be cleared by software.
STOPI	Stop Condition Interrupt Flag bit. This bit is set when the slave controller detects a STOP condition on the SCL and SDA lines. This bit must be cleared by software.
RPTSARTI	Repeat Start Condition Interrupt Flag bit. This bit is set when the slave controller detects a REPEAT START condition on the SCL and SDA lines. This bit must be cleared by software.
TXBI	Transmit Buffer Interrupt Flag. This bit is set when the slave controller is ready to accept a new byte for transmission. This bit is cleared when new data is written into I2CSDAT register.
RCBI	Receiver Buffer Interrupt Flag bit. This bit is set when the slave controller puts new data in the I2CSDAT and ready for software reading. This bit is cleared after the software reads I2CSDAT.
START	Start Condition. This bit is set when the slave controller detects a START condition on the SCL and SDA lines. This bit is not very useful as the start of transaction can be indicated by address match interrupt. This read-only bit is cleared when STOP condition is detected.
NACK	NACK Condition. This bit is set when the host responds with NACK in the byte transaction. This bit is only meaningful for slave-transmit operation. Please note if the master returns with NACK on the byte transaction, the slave does not upload new data into the shift register. And the slave transmits the old data again as the next transfer, and this re-transmission continues if NACK is repeated until the transmission is successful and returned with ACK. This bit is cleared when a new ACK is detected or it can be cleared by software.
HOLDT[3-0]	These four bits define the hold time in SYSCLK cycles between SDA to SCL. The I^{2}C specification requires for minimum of 300nsec hold time, so the condition of SYSCLK*(HOLDT[3:0]+3) ≧300nsec hold time" equation must be met. For example, SYSCLK is 20MHz, then HOLD[3-0] should be set to ≧3.

I2CSADR2 (0xDD) I2CS2 Slave Address Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	I2CSEN	ADDR[6-0]						
WR	I2CSEN	ADDR[6-0]						

I2CSEN	Set this bit to enable the I^{2}C slave controller.
ADDR[6-0]	7-bit Slave Address When written, ADDR[6-0] stores the slave address of the slave. When read, ADDR[6-0] holds the slave address of the received slave address. Software can use this to determine the address if double address is enabled.

I2CSDAT2 (0xDE) I2CS2 Data Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	I²C Slave Receive Data Register							
WR	I²C Slave Transmit Data Register							

4. EUART1 Enhanced Function UART1

LIN-capable 16550-like EUART1 is an enhanced UART controller (EUART) with separate transmit and receive FIFO. Both transmit and receive FIFO are 15-bytes deep and can be parameterized for interrupt triggering. The addition of FIFO significantly reduces the CPU load to handle high-speed serial interface. Transmit FIFO and receive FIFO have respective interrupt trigger levels that can be set based on optimal CPU performance adjustment. The EUART1 also has dedicated 16-bit Baud Rate generator and thus provides accurate baud rate under wide range of system clock frequency.

SCON1 (0xB1) EUART1 Configuration Register, R/W (0x00)

	7	6	5	4	3	2	1	0
RD	EUARTEN	SB	WLS[1]	WLS[0]	BREAK	OP	PERR	SP
WR	EUARTEN	SB	WLS[1]	WLS[0]	BREAK	OP	PE	SP

EUARTEN — Transmit and Receive Enable bit
Set to enable EUART1 transmit and receive functions: To transmit messages in the TX FIFO and to store received messages in the RX FIFO.

SB — Stop Bit Control
Set to enable 2 Stop bits, and clear to enable 1 Stop bit.

WLS[1-0] — The number of bits of a data byte. This does not include the parity bit when parity is enabled.
00 - 5 bits
01 - 6 bits
10 - 7 bits
11 - 8 bits

BREAK — Break Condition Control Bit.
Set to initiate a break condition on the UART interface by holding UART output at low until BREAK bit is cleared.

OP — Odd/Even Parity Control Bit

PE/PERR — Parity Enable / Parity Error status
Set to enable parity and clear to disable parity checking functions. If read, PERR=1 indicates a parity error in the current data of RX FIFO.

SP — Parity Set Control Bit
When SP is set, the parity bit is always transmitted as 1.

SCON1X (0xB2) EUART1 Configuration Register, R/W (0x00)

	7	6	5	4	3	2	1	0
RD	RXST	BITERR	BECLRX	BECLRR	LBKEN	BERIE	-	TXPOL
WR	-	BITERR	BECLRX	BECLRR	LBKEN	BERIE	CLRFIFO	TXPOL

RXST — Receive Status
RXST controlled by hardware. RXST is set by hardware when a START bit is detected. It is cleared when STOP condition is detected.

BITERR — Bit Error Flag
BITERR is set by hardware when received bit does not match with transmit bit, if BERIE=1, then this error generates an interrupt. BITERR must be cleared by software.

BECLRX — Bit Error Force Clear Transmit Enable
If BECLRX=1, when BITERR is set by hardware, hardware also immediately disables current transmission and clears TX state machines and FIFO.

BECLRR — Bit Error Force Clear RECEIVE Enable
If BECLRX=1, when BITERR is set by hardware, hardware also immediately disables current reception and clears RX state machines and FIFO.

LBKEN — Enable EUART Loopback Test,
When LBKEN=1, EUART1 enters into loopback mode, with its TX output connected to RX input. When in loopback mode, to prevent the TX to pin output, corresponding MFCFG bit must be cleared.

BERIE — Bit Error Interrupt Enable (1:Enable / 0:Disable)

CLRFIFO — Set to clear transmit/received FIFO pointer and state machine. CLRFIFO bit is auto clear by hardware

TXPOL — EUART output polarity

SFIFO1 (0xB3) EUART1 FIFO Status/Control Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	RFL[3-0]				TFL[3-0]			
WR	RFLT[3-0]				TFLT[3-0]			

RFL[3-0] Current Receive FIFO level. This is read only and indicate the current receive FIFO byte count.

RFLT[3-0] Receive FIFO trigger threshold. This is write-only. RDA interrupt will be generated when RFL[3-0] is greater than RFLT[3-0].

RFLT[3-0]	Description
0000	RX FIFO trigger level = 0
0001	RX FIFO trigger level = 1
0010	RX FIFO trigger level = 2
0011	RX FIFO trigger level = 3
0100	RX FIFO trigger level = 4
0101	RX FIFO trigger level = 5
0110	RX FIFO trigger level = 6
0111	RX FIFO trigger level = 7
1000	RX FIFO trigger level = 8
1001	RX FIFO trigger level = 9
1010	RX FIFO trigger level = 10
1011	RX FIFO trigger level = 11
1100	RX FIFO trigger level = 12
1101	RX FIFO trigger level = 13
1110	RX FIFO trigger level = 14
1111	Reset Receive State Machine and Clear RX FIFO

TFL[3-0] Current Transmit FIFO level. This is read only and indicate the current transmit FIFO byte count.

TFLT[3-0] Transmit FIFO trigger threshold. This is write-only. TRA interrupt will be generated when TFL[3-0] is less than TFLT[3-0].

TFLT[3-0]	Description
0000	Reset Transmit State Machine and Clear TX FIFO
0001	TX FIFO trigger level = 1
0010	TX FIFO trigger level = 2
0011	TX FIFO trigger level = 3
0100	TX FIFO trigger level = 4
0101	TX FIFO trigger level = 5
0110	TX FIFO trigger level = 6
0111	TX FIFO trigger level = 7
1000	TX FIFO trigger level = 8
1001	TX FIFO trigger level = 9
1010	TX FIFO trigger level = 10
1011	TX FIFO trigger level = 11
1100	TX FIFO trigger level = 12
1101	TX FIFO trigger level = 13
1110	TX FIFO trigger level = 14
1111	TX FIFO trigger level = 15

SINT1 (0xB5) EUART1 Interrupt Status/Enable Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	INTEN	TRA	RDA	RFO	RFU	TFO	FERR	TI
WR	INTEN	TRAEN	RDAEN	RFOEN	RFUEN	TFOEN	FERREN	TIEN

INTEN	Interrupt Enable bit. Write only Set to enable EUART1 interrupt. Clear to disable interrupt. Default is 0.
TRA/TRAEN	Transmit FIFO is ready to be filled. This bit is set when transmit FIFO has been emptied below FIFO threshold. Write “1” to enable interrupt. The flag is automatically cleared when the condition is absent.
RDA/RDAEN	Receive FIFO is ready to be read. This bit is set by hardware when receive FIFO exceeds the FIFO threshold. Write “1” to enable interrupt. RDA will also be set when RFL < RFLT for bus idle duration longer than RFLT * 16 * Baud Rate. This is to inform software that there are still remaining unread received bytes in the FIFO. The flag is cleared when RFL < RFLT and writing “0” on the bit (the interrupts is disabled simultaneously)
RFO/RFOEN	Receive FIFO Overflow Enable bit This bit is set when overflow condition of receive FIFO occurs. Write “1” to enable interrupt. The flag can be cleared by software by writing “0” on the bit (the interrupt is disabled simultaneously), or by FIFO reset action.
RFU/RFUEN	Receive FIFO Underflow Enable bit This bit is set when underflow condition of receive FIFO occurs. Write “1” to enable interrupt. The flag can be cleared by software by writing “0” on the bit (the interrupt is disabled simultaneously), or by FIFO reset action.
TFO/TFOEN	Transmit FIFO Overflow Interrupt Enable bit This bit is set when overflow condition of transmit FIFO occurs. Write “1” to enable interrupt. The flag can be cleared by software by writing “0” on the bit (the interrupt is disabled simultaneously), or by FIFO reset action.
FERR/FERREN	Framing Error Enable bit This bit is set when framing error occurs as the byte is received. Write “1” to enable interrupt. The flag must be cleared by software, writing “0” on the bit (the interrupt is disabled simultaneously).
TI/TIEN	Transmit Message Completion Interrupt Enable bit This bit is set when all messages in the TX FIFO are transmitted and thus the TX FIFO becomes empty. Write “1” to enable interrupt. The flag must be cleared by software, writing “0” on the bit (the interrupt is disabled simultaneously).

SBUF1 (0xB4) EUART1 Data Buffer Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	EUART1 Receive Data Register							
WR	EUART1 Transmit Data Register							

This register is the virtual data buffer register for both receive and transmit FIFO. When being read, it reads out the top byte of the RX FIFO; when being written, it writes into the top byte of the TX FIFO.

SBR1L (0xB6) EUART1 Baud Rate Register Low byte RO (0x00)

	7	6	5	4	3	2	1	0
RD	SBR1[7:0]							
WR	SBR1[7-0]							

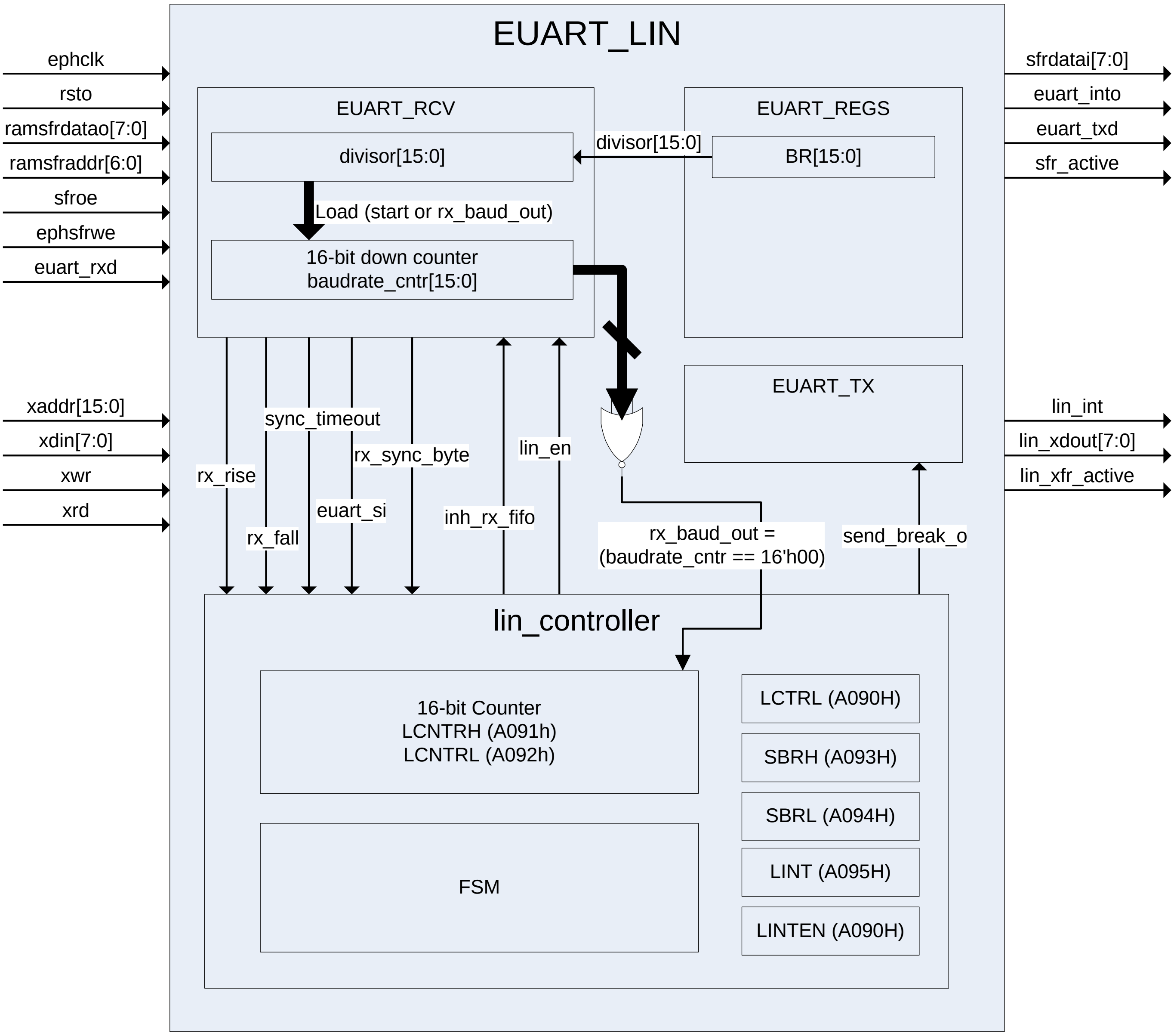
SBR1H (0xB7) EUART1 Baud Rate Register High byte RO (0x00)

	7	6	5	4	3	2	1	0
RD	SBR1[15-8]							
WR	SBR1[15-8]							

SBR1[15-0]	The Baud Rate Setting of EUART. SBR`[15-0] cannot be 0. BUAD RATE = SYSCLK/SBR1[15-0].

5. EUART2 with LIN Controller

LIN-capable 16550-like EUART2 is an enhanced UART controller (EUART) with separate transmit and receive FIFO. Both transmit and receive FIFO are 15-bytes deep and can be parameterized for interrupt triggering. The addition of FIFO significantly reduces the CPU load to handle high-speed serial interface. Transmit FIFO and receive FIFO have respective interrupt trigger levels that can be set based on optimal CPU performance adjustment. The EUART2 also has dedicated 16-bit Baud Rate generator and thus provides accurate baud rate under wide range of system clock frequency. The EUART2 also provides LIN extensions that incorporate message handling and baud-rate synchronization. The block diagram of EUART2 is shown in the following.



The following registers are used for configurations of and interface with EUART2.

SCON2 (0xC2) UART2 Configuration Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	EUARTEN	SB	WLS[1]	WLS[0]	BREAK	OP	PERR	SP
WR	EUARTEN	SB	WLS[1]	WLS[0]	BREAK	OP	PE	SP

EUARTEN Transmit and Receive Enable bit
Set to enable EUART2 transmit and receive functions: To transmit messages in the TX FIFO and to store received messages in the RX FIFO.

SB Stop Bit Control
Set to enable 2 Stop bits, and clear to enable 1 Stop bit.

WLS[1-0]	The number of bits of a data byte. This does not include the parity bit when parity is enabled. 00 - 5 bits 01 - 6 bits 10 - 7 bits 11 - 8 bits
BREAK	Break Condition Control Bit. Set to initiate a break condition on the UART interface by holding UART output at low until BREAK bit is cleared.
OP	Odd/Even Parity Control Bit
PE/PERR	Parity Enable / Parity Error status Set to enable parity and clear to disable parity checking functions. If read, PERR=1 indicates a parity error in the current data of RX FIFO.
SP	Parity Set Control Bit When SP is set, the parity bit is always transmitted as 1.

SFIFO2 (0xA5) UART2 FIFO Status/Control Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	RFL[3-0]				TFL[3-0]			
WR	RFLT[3-0]				TFLT[3-0]			

RFL[3-0] Current Receive FIFO level. This is read only and indicate the current receive FIFO byte count.

RFLT[3-0] Receive FIFO trigger threshold. This is write-only. RDA interrupt will be generated when RFL[3-0] is greater than RFLT[3-0].

RFLT[3-0]	Description
0000	RX FIFO trigger level = 0
0001	RX FIFO trigger level = 1
0010	RX FIFO trigger level = 2
0011	RX FIFO trigger level = 3
0100	RX FIFO trigger level = 4
0101	RX FIFO trigger level = 5
0110	RX FIFO trigger level = 6
0111	RX FIFO trigger level = 7
1000	RX FIFO trigger level = 8
1001	RX FIFO trigger level = 9
1010	RX FIFO trigger level = 10
1011	RX FIFO trigger level = 11
1100	RX FIFO trigger level = 12
1101	RX FIFO trigger level = 13
1110	RX FIFO trigger level = 14
1111	Reset Receive State Machine and Clear RX FIFO

TFL[3-0] Current Transmit FIFO level. This is read only and indicate the current transmit FIFO byte count.

TFLT[3-0] Transmit FIFO trigger threshold. This is write-only. TRA interrupt will be generated when TFL[3-0] is less than TFLT[3-0].

TFLT[3-0]	Description
0000	Reset Transmit State Machine and Clear TX FIFO
0001	TX FIFO trigger level = 1
0010	TX FIFO trigger level = 2
0011	TX FIFO trigger level = 3
0100	TX FIFO trigger level = 4
0101	TX FIFO trigger level = 5
0110	TX FIFO trigger level = 6

0111	TX FIFO trigger level = 7
1000	TX FIFO trigger level = 8
1001	TX FIFO trigger level = 9
1010	TX FIFO trigger level = 10
1011	TX FIFO trigger level = 11
1100	TX FIFO trigger level = 12
1101	TX FIFO trigger level = 13
1110	TX FIFO trigger level = 14
1111	TX FIFO trigger level = 15

Receive and transmit FIFO can be reset by clear FIFO operation. This is done by setting BR[15-0]=0 and EUARTEN=0. This also clears RFO, RFU and TFO interrupt flags without writing the interrupt register. The LIN counter LCNTR is also cleared.

SINT2 (0xA7) UART2 Interrupt Status/Enable Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	INTEN	TRA	RDA	RFO	RFU	TFO	FERR	TI
WR	INTEN	TRAEN	RDAEN	RFOEN	RFUEN	TFOEN	FERREN	TIEN

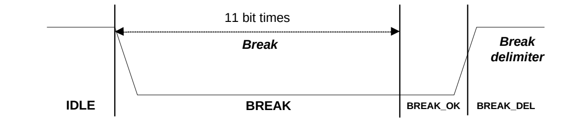
INTEN	Interrupt Enable bit. Write only Set to enable UART2 interrupt. Clear to disable interrupt. Default is 0.
TRA/TRAEN	Transmit FIFO is ready to be filled. This bit is set when transmit FIFO has been emptied below FIFO threshold. Write “1” to enable interrupt. The flag is automatically cleared when the condition is absent.
RDA/RDAEN	Receive FIFO is ready to be read. This bit is set by hardware when receive FIFO exceeds the FIFO threshold. Write “1” to enable interrupt. RDA will also be set when RFL < RFLT for bus idle duration longer than RFLT * 16 * Baud Rate. This is to inform software that there are still remaining unread received bytes in the FIFO. The flag is cleared when RFL < RFLT and writing “0” on the bit (the interrupts is disabled simultaneously)
RFO/RFOEN	Receive FIFO Overflow Enable bit This bit is set when overflow condition of receive FIFO occurs. Write “1” to enable interrupt. The flag can be cleared by software by writing “0” on the bit (the interrupt is disabled simultaneously), or by FIFO reset action.
RFU/RFUEN	Receive FIFO Underflow Enable bit This bit is set when underflow condition of receive FIFO occurs. Write “1” to enable interrupt. The flag can be cleared by software by writing “0” on the bit (the interrupt is disabled simultaneously), or by FIFO reset action.
TFO/TFOEN	Transmit FIFO Overflow Interrupt Enable bit This bit is set when overflow condition of transmit FIFO occurs. Write “1” to enable interrupt. The flag can be cleared by software by writing “0” on the bit (the interrupt is disabled simultaneously), or by FIFO reset action.
FERR/FERREN	Framing Error Enable bit This bit is set when framing error occurs as the byte is received. Write “1” to enable interrupt. The flag must be cleared by software, writing “0” on the bit (the interrupt is disabled simultaneously).
TI/TIEN	Transmit Message Completion Interrupt Enable bit This bit is set when all messages in the TX FIFO are transmitted and thus the TX FIFO becomes empty. Write “1” to enable interrupt. The flag must be cleared by software, writing “0” on the bit (the interrupt is disabled simultaneously).

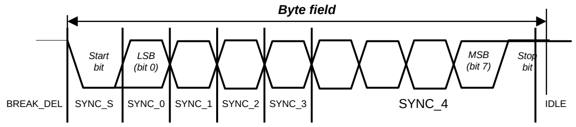
SBUF2 (0xA6) UART2 Data Buffer Register R/W (0x00)

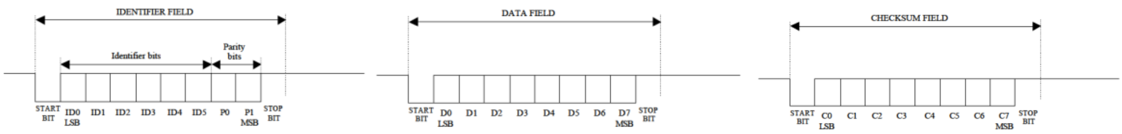
	7	6	5	4	3	2	1	0
RD	EUART2 Receive Data Register							
WR	EUART2 Transmit Data Register							

This register is the virtual data buffer register for both receive and transmit FIFO. When being read, it reads out the top byte of the RX FIFO; when being written, it writes into the top byte of the TX FIFO.

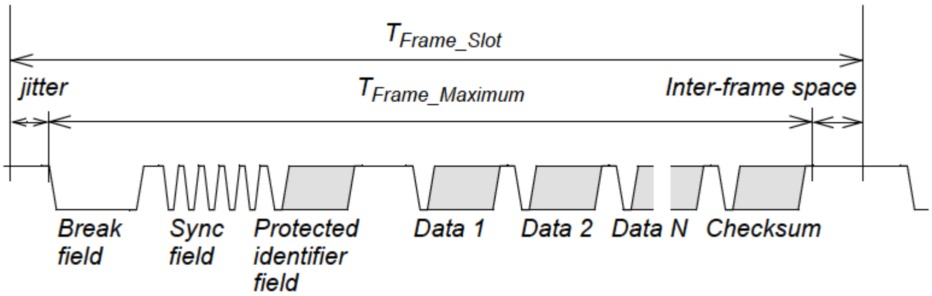
EUART2 can be configured to add LIN capability. The major enhancement of LIN includes master/slave configurations, auto baud-rate synchronization, and frame based protocol with header. Under LIN extension mode, all EUART2 registers and functions are still effective and operational. LIN is a single-wire bus and it requires external components to combine RX and TX signals externally. LIN is frame based and consists of message protocols with master/slave configurations. The following diagram shows the basic composition of a header message sent by the master. It starts with BREAK, the SYNC byte, ID bytes, DATA bytes, and CRC bytes.







A LIN frame structure is shown and the frame time matches the number of bits sent and has a fixed timing.



LIN bus protocol is based on frame. Each frame is partitioned into several parts as shown above. For master to initiate a frame, the software follows the following procedure.

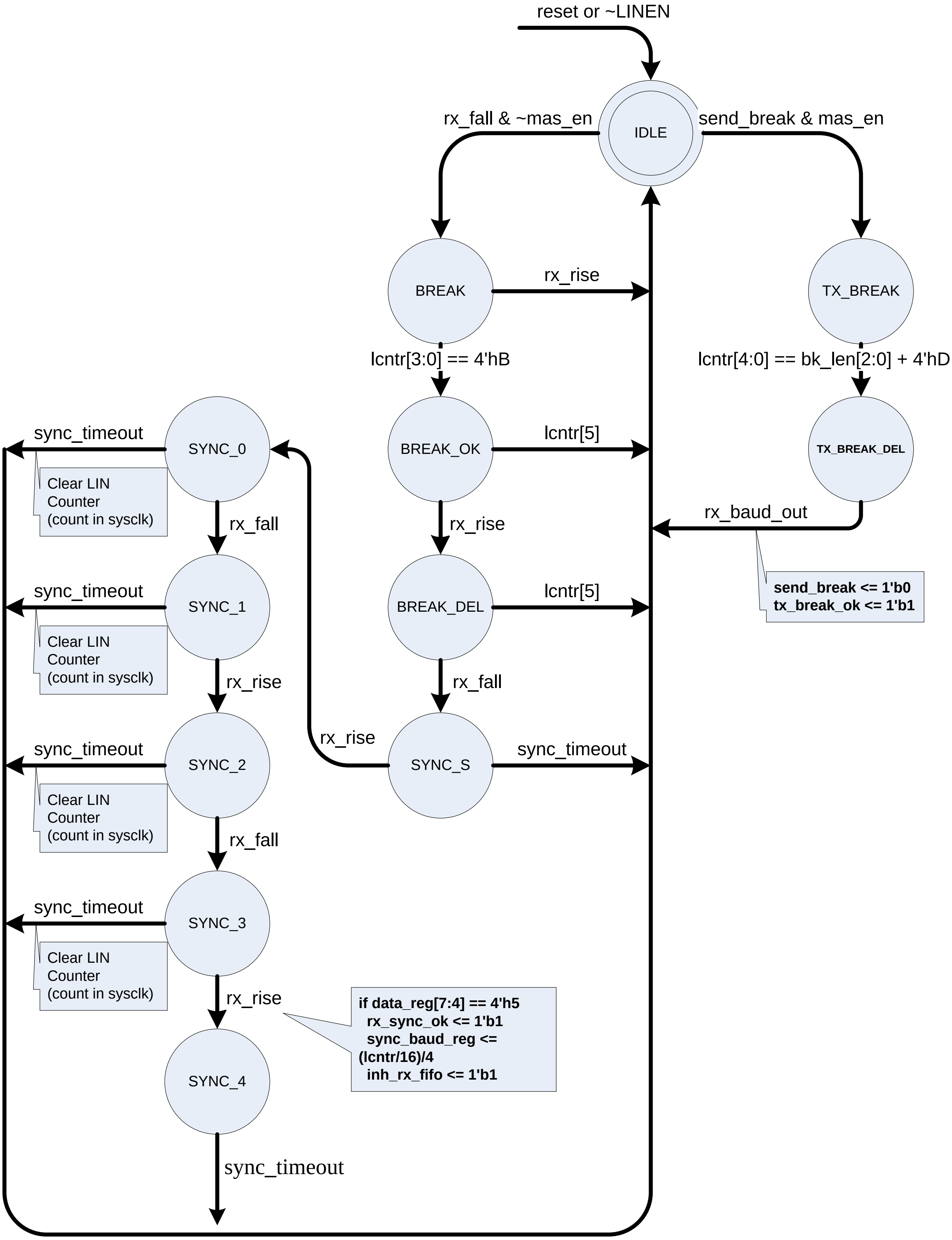
Initiate a SBK command. (SW needs to check if the bus is in idle state, and there is no pending transmit data).

Write “55” into TFIFO.

Write “PID” into TFIFO.

Wait for SBK to complete interrupts and then write the following transmit data if applicable. (This is optional).

The following diagram shows Finite State Machine (FSM) of the LIN extension and is followed by registers within EUART2.


reset or ~LINEN
IDLE
rx_fall & ~mas_en
send_break & mas_en
BREAK
rx_rise
TX_BREAK
lcntr[3:0] == 4'hB
lcntr[4:0] == bk_len[2:0] + 4'hD
sync_timeout
SYNC_0
BREAK_OK
lcntr[5]
TX_BREAK_DEL
Clear LIN
Counter
(count in sysclk)
rx_fall
rx_rise
rx_baud_out
sync_timeout
SYNC_1
BREAK_DEL
lcntr[5]
send_break <= 1'b0
tx_break_ok <= 1'b1
Clear LIN
Counter
(count in sysclk)
rx_rise
rx_fall
rx_rise
sync_timeout
SYNC_2
SYNC_S
sync_timeout
Clear LIN
Counter
(count in sysclk)
rx_fall
sync_timeout
SYNC_3
Clear LIN
Counter
(count in sysclk)
rx_rise
if data_reg[7:4] == 4'h5
rx_sync_ok <= 1'b1
sync_baud_reg <=
(lcntr/16)/4
inh_rx_fifo <= 1'b1
SYNC_4
sync_timeout

LINCTRL (0xA090) LIN Status/Control RegisterR/W (0x00)

	7	6	5	4	3	2	1	0
RD	LINEN	MASEN	ASU	MASU	SBK	BL[2:0]		
WR	LINEN	MASEN	ASU	MASU	SBK	BL[2:0]		

LINEN — LIN Enable (1: Enable / 0: Disable)
LIN header detection / transmission is functional when LINEN = 1.
※ Before enabling LIN functions, the EUART2 registers must be set correctly：0xB0 is recommended for SCON2.

MASEN — Master Enable bit (1: Master / 0: Slave) LIN operating mode selection. This bit is changeable only when LINEN = 0 (must clear LINEN before changing MASEN).

ASU — Auto-Sync Update Enable (1: Enable / 0: Disable), Write Only
If ASU is 1, the LIN controller will automatically overwrite BR[15-0] with SBR[15-0] and issue an ASUI interrupt when received a valid SYNC field.
If ASU is 0, the LIN controller will only notice the synchronized baud rate in SBR[15-0] by issuing an RSI interrupt.
Please note, ASU should not be set under UART mode. ASU capability is based on the message containing BREAK and SYNC field in the beginning.
When ASU=1, the auto sync update is performed on every receiving frame, and is updated frame by frame.
Please note when ASU is set to 1, LININTEN[SYNCMD] should also be set to 1.

MASU — Message Auto Sync Update Enable.
MASU is meaningful only if ASU=0. MASU=1 will enable the auto sync update on the next received frame only. It is self-cleared when the sync update is completed. The software must set MASU again if another auto sync operation is desired.
Please note when MASU is set to 1, LININTEN[SYNCMD] should also be set to 1.

SBK — Send Break (1: Send / 0: No send request)
LINEN and MASEN should be set before setting SBK. When LINEN and MASEN are both 1, set SBK to send a bit sequence of 13+BL[2:0] consecutive dominant bits and 1 recessive bit (Break Delimiter). Once SBK is set, this bit represents the “Send Break” status and CANNOT be cleared by writing to “0”; instead, clearing LINEN cancels the “Send Break” action. In normal cases, SBK is cleared automatically when the transmission of Break Delimiter is completed.

BL[2:0] — Break Length Setting
Break Length = 13 + BL[2:0]. Default BL[2:0] is 3’b000.

LINCNTRH (0xA091) LIN Timer Register High R/W (0xFF)

	7	6	5	4	3	2	1	0
RD	LCNTR15-8]							
WR	LINTMR[15-8]							

LINCNTRL (0xA092) LIN Time Register Low R/W (0xFF)

	7	6	5	4	3	2	1	0
RD	LCNTR[7-0]							
WR	LINTMR[7-0]							

LCNTR[15-0] is read only and is an internal 16-bit counter clocked by the baud rate clock. LINTMR[15-0] is write only and is the timer limit for LCNTR[15-0]. If MASEN=1 as LIN master mode, this timer is used to generate Frame time base. The internal counter LCNTR[15-0] is cleared whenever a “SEND BREAK” command is executed, and when the counter reaches LINTMR [15-0] (LCNTR[15-0] >= LINTMR[15-0]), a LCNTRO interrupt is generated. Thus the software can write a Frame Time value into LINTMR and use interrupts to initiate frames. If MASEN=0 as LIN slave mode, this timer is used for determining the accumulated bus idle time. The internal counter is cleared whenever a RX transition occurs. When the internal counter reaches LINTMR[15-0], an LCNTRO interrupt is generated. The software can use this interrupt to enter sleep mode by writing the required bus idling time into LINTMR[15-0].

LINSBRH (0xA093) EUART/LIN Baud Rate Register High byte RO (0x00)

	7	6	5	4	3	2	1	0
RD	SBR[15-8]							
WR	BR[15-8]							

LINSBRL (0xA094) EUART/LIN Baud Rate Register Low byte (0x00) RO

	7	6	5	4	3	2	1	0
RD	SBR[7:0]							
WR	BR[7-0]							

SBR[15-0] The acquired Baud Rate under LIN protocol. This is read-only.
SBR[15-0] is the acquired baud rate from last received valid sync byte. SBR is meaningful only in LIN-Slave mode.

BR[15-0] The Baud Rate Setting of EUART/LIN. This is write-only. BR[15-0] can not be 0.
BUAD RATE = SYSCLK/BR[15-0].

When a slave receives a BREAK followed by a valid SYNC field, an RSI interrupt is generated and the acquired baud rate from SYNC field is stored in SBR[15-0]. The acquired baud rate is BAUD RATE = SYSCLK/SBR[15-0]. The software can just update this acquired value into BR[15-0] to achieve synchronization with the master. If Auto-Sync Update (ASU) register bit is enabled under LIN slave mode, LIN controller will automatically perform the update of BR[15-0] with SBR[15-0] and issue another ASUI interrupt when received a valid SYNC field.

LININT (0xA095) LIN Interrupt Flag Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	RXST	BITERR	LSTAT	LIDLE	ASUI	SBKI	RSI	LCNTRO
WR	LBKEN	BITERR	BECLRX	BECLRR	ASUI	SBKI	RSI	LCNTRO

RXST Receive Status
RXST is set by hardware when a START bit is detected. It is cleared when STOP condition is detected.

LBKEN Enable EUART Loopback Test,
When LBKEN=1, EUART2 enters into loopback mode, with its TX output connected to RX input. When in loopback mode, to prevent the TX output to pin, corresponding MFCFG bit must be cleared.

LBKEN Loopback Enable

BITERR Bit Error Flag
BITERR is set by hardware when received bit does not match with transmit bit, if BERIE=1, then this error generates an interrupt. BITERR must be cleared by software.

BECLRX Bit Error Force Clear Transmit Enable
If BECLRX=1, when BITERR is set by hardware, hardware also immediately disables current transmission and clears TX state machines and FIFO.

BECLRR Bit Error Force Clear RECEIVE Enable
If BECLRX=1, when BITERR is set by hardware, hardware also immediately disables current reception and clears RX state machines and FIFO.

LSTAT LIN Bus Status bit (1: Recessive / 0: Dominant), Read only.
LSTAT = 1 indicates that the LIN bus (RX pin) is in recessive state.

LIDLE LIDLE is 1 when LIN bus is idle and not transmitting/receiving LIN header or data bytes. This bit read only. It is 1 when LINEN = 0.

ASUI Auto-Sync Updated completion Interrupt (1: Set / 0: Clear)
This flag is set when auto baud rate synchronization has been completed and BR[15-0] has been updated with SBR[15-0] by hardware. It must be cleared by writing “1” on the bit.

SBKI Send Break Completion Interrupt bit (1: Set / 0: Clear)
This flag is set when Send Break completes. It must be cleared by writing “1” in the bit.

RSI Receive Sync Completion Interrupt bit (1: Set / 0: Clear)
This flag is set when a valid Sync byte is received following a Break. It must be cleared by writing “1” in the bit.

LCNTRO LIN Counter Overflow Interrupt bit (1: Set / 0: Clear).
This flag is set when the LIN counter reaches 0xFFFF. It must be cleared by writing “1” in the bit.

LININTEN (0xA096) LIN Interrupt Enable Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	LINTEN	BERIE	SYNCMD	SYNCVD	ASUIE	SBKIE	RSIE	LCNTRIE
WR	LINTEN	BERIE	SYNCMD	EUARTOPL	ASUIE	SBKIE	RSIE	LCNTRIE

LINTEN	LIN Interrupt Enable (1: Enable / 0: Disable) Set to enable all LIN interrupts. LINT flags should be checked before setting or modifying.
BERIE	Bit Error Interrupt Enable (1:Enable/ 0:Disable)
SYNCMD	Synchronization Mode Selection SYNCMD=1 will automatic re-synchronize with newly received message frame and update the baud rate register with newly acquired baud rate. SYNCMD should be set to 1 when either ASU or MASU is 1.
SYNCVD	Synchronization Valid Status SYNCVD is updated by the hardware when SYNCMD=1. SYNCVD is set to 1 if the auto synchronization is successful.
EUARTOPL	EUART/LIN output polarity EUARTOPL=1 will reverse the transmit output polarity
ASUIE	Auto-Sync Update Interrupt Enable (1: Enable / 0: Disable)
SBKIE	Send Break Completion Interrupt Enable (1: Enable / 0: Disable)
RSIE	Receive Sync Completion Interrupt Enable (1: Enable / 0: Disable)
LCNTRIE	LIN Counter Overflow Interrupt Enable (1: Enable / 0: Disable)

LINTCON (0xA0B0h) LIN Time Out configuration R/W (0x00)

	7	6	5	4	3	2	1	0
RD	RXDTO[0]	LINRXFEN	RXTOWKE	TXTOWKE	RXDD_F	TXDD_F	RXDDEN	TXDDEN
WR	RXDTO[0]	LINRXFEN	RXTOWKE	TXTOWKE	RXDD_F	TXDD_F	RXDDEN	TXDDEN

RXDTO[0]	RXD Dominant Time Out Timer [0] This is combined with RXDTOH and RXDTOL to form RXDTO[16-0]
LINRXFEN	LIN Break State Exit when RXD dominant fault occurs. LINRXFEN=1 configures the automatic BREAK state exit under RXD dominant fault conditions. LINRXFEN=0 disable this automatic exit (does not affect other break exit conditions). Software must take care of the LIN state machine.
RXDDEN	RXD Dominant Fault Interrupt Enable
RXDD_F	RXD Dominant Fault Interrupt Flag RXDD_F is set to 1 by hardware and must be cleared by software
TXDDEN	TXD Dominant Fault Interrupt Enable
TXDD_F	TXD Dominant Fault Interrupt Flag TXDD_F is set to 1 by hardware and must be cleared by software
TXTOWKE	TXD Dominant Timeout Wakeup Enable
RXTOWKE	RXD Dominant Timeout Wakeup Enable

TXDTOL (0xA0B1h) LIN TXD Dominant Time Out LOW Registers R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TXDTO[7:0]							
WR	TXDTO[7:0]							

TXDTOH (0xA0B2h) LIN TXD Dominant Time Out HIGH Registers R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TXDTO[15:8]							
WR	TXDTO[15:8]							

TXDTO	TXD Dominant Time Out (TXDTO +1) * IOSCCLK

RXDTOL (0xA0B3h) LIN RXD Dominant Time Out LOW Registers R/W (0x00)

	7	6	5	4	3	2	1	0
RD	RXDTO[8-1]							
WR	RXDTO[8:1]							

RXDTOH (0xA0B4h) LIN RXD Dominant Time Out HIGH Registers R/W (0x00)

	7	6	5	4	3	2	1	0
RD	RXDTO[16-9]							
WR	RXDTO[16-9]							

RXDTO RXD Dominant Time Out (RXDTO[16-0] +1) * IOSCCLK

BSDCLRL (0xA0B5h) Bus Stuck Dominant Clear Width Low Registers R/W (0x00)

	7	6	5	4	3	2	1	0
RD	BSDCLR[7-0]							
WR	BSDCLR[7-0]							

BSDCLRH (0xA0B6h) Bus Stuck Dominant Clear Width High Registers R/W (0x00)

	7	6	5	4	3	2	1	0
RD	BSDCLR[15-8]							
WR	BSDCLR[15-8]							

BSDCLR Bus Stuck Dominant Clear Time (BSDCLR[15-0] +1) * SOSC/4

BSDACT (0xA0B8h) Bus Stuck Dominant Active Width Registers R/W (0x00)

	7	6	5	4	3	2	1	0
RD	BSDACT[7-0]							
WR	BSDACT[7:0]							

BSDACT Bus Stuck Dominant Active Time (BSDACT[7-0] +1) * SOSC/4

BSDWKC (0xA0B7h) Bus Stuck Dominant Fault Wakeup configuration R/W (0x00)

	7	6	5	4	3	2	1	0
RD	BSDWF	BFWF	BSDWEN	BFWEN	WKFLT[3-0]			
WR	BSDWF	BFWF	BSDWEN	BFWEN	WKFLT[3-0]			

WKFLT[3-0]	LIN Wakeup time (WKFLT[3-0]+1) * SOSC/4
BFWEN	LIN Wakeup/Interrupt Enable
BFWF	LIN Wakeup Interrupt Flag BFWF is set to 1 by hardware and must be cleared by software
BSDWEN	LIN Bus Stuck Wakeup Interrupt Enable
BSDWF	LIN Bus Stuck Wakeup Interrupt Flag

6. Serial Peripheral Interface (SPI)

The Serial Peripheral Interface (SPI) is an enhanced synchronous serial hardware, which is compatible with Motorola's SPI specifications. The SPI Controller includes 4-bytes FIFO for both transmit and receive. SPI Interface uses Master-Out-Slave-In (MOSI), Master-In-Slave-Out (MISO), Serial Clock (SCK) and Slave Select (SSN) for interface. SSN is low active and only meaningful in slave mode.

SPICR (0xA1) SPI Configuration Register R/W (0b001000xx)

	7	6	5	4	3	2	1	0
RD	SPIE	SPEN	MSTR	CPOL	CPHA	SCKE	SICKFLT	SSNFLT
WR	SPIE	SPEN	MSTR	CPOL	CPHA	SCKE	SICKFLT	SSNFLT

SPIE SPI interface Interrupt Enable bit.

SPEN SPI interface Enable bit.

MSTR SPI Master/Slave Switch. Set as a master; clear as a slave.

CPOL SPI interface Polarity bit: Set to configure the SCK to stay HIGH while the SPI interface is idling and clear to keep it LOW.

CPHA Clock Phase Control bit: If CPOL=0, set to shift output data at rising edge of SCK, and clear to shift output data at falling edge of SCK. If CPOL=1, set to shift output data at falling edge of SCK and clear to shift output data at rising edge of SCK.

SCKE Clock Edge Selection bit for Master Mode.
SCKE = 0 SDI and SDO uses opposite SCK edges.
SCKE = 1 SDI and SDO uses the same SCK edges.
CPOL, CPHA and SCKE together define the edge relationship between SCK edges used for sampling SDO/SDI as shown in the following table. Here R means rising edge and F means falling edge.

SCKE	CPOL	CPHA	MASTER		SLAVE	
			SDI	SDO	SDI	SDO
0	0	0	R	F	R	F
0	0	1	F	R	F	R
0	1	0	F	R	F	R
0	1	1	R	F	R	F
1	0	0	F	F	R	F
1	0	1	R	R	F	R
1	1	0	R	R	F	R
1	1	1	F	F	R	F

SSNFLT Enable noise filter function on signal SSN

SICKFLT Enable noise filter function on signals SDI and SCK

SPIMR (0xA2) SPI Mode Control Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	ICNT1	ICNT0	FCLR	-	SPR[2]	SPR[1]	SPR[0]	DIR
WR	ICNT1	ICNT0	FCLR	-	SPR[2]	SPR[1]	SPR[0]	DIR

ICNT1, ICNT0 FIFO Byte Count Threshold.
This sets the FIFO threshold for generating SPI interrupts.
00 –the interrupt is generated after 1 byte is sent or received;
01 –the interrupt is generated after 2 bytes are sent or received;
10 –the interrupt is generated after 3 bytes are sent or received;
11 –the interrupt is generated after 4 bytes are sent or received.

FCLR FIFO Clear/Reset
Set to clear and reset transmit and receive FIFO

SPR[2-0] SPI Clock Rate Setting. This is used to control the SCK clock rate of SPI interface.
000 –SCK = SYSCLK/4;
001 – SCK = SYSCLK/6;
010 – SCK = SYSCLK/8;
011 – SCK = SYSCLK/16;

	100 – SCK = SYSCLK/32;
	101 – SCK = SYSCLK/64;
	110 – SCK = SYSCLK/128;
	111 – SCK = SYSCLK/256.
DIR	Transfer Format DIR=1 uses MSB-first format. DIR=0 uses LSB-first format.

SPIST (0xA3) SPI Status Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	SSPIF	ROVR	TOVR	TUDR	RFULL	REMPT	TFULL	TEMPT
WR	SSPIF	ROVR	TOVR	TUDR	-	-	-	-

SSPIF	SPI Interrupt Flag bit. Set by hardware to indicate the completion of data transfer. Clear by assigning this bit to 0 or disabling SPI.
ROVR	Receive FIFO-overrun Error Flag bit. When Receiver FIFO Full Status occurs and SPI receives new data, ROVR is set and generates an interrupt. Clear by assigning this bit to 0 or disabling SPI.
TOVR	Transmit FIFO-overrun Error Flag bit. When Transfers FIFO Full Status occurs and new data is written, TOVR is set and generates an interrupt. Clear by assigning this bit to 0 or disabling SPI.
TUDR	Transmit Under-run Error Flag bit. When Transfers FIFO Empty Status and new data transmission occur, TOVR is set and generates an interrupt. Clear by written 0 to this bit or disable SPI.
RFULL	Receive FIFO Full Status bit. Set when receiver FIFO is full. Read only.
REMPT	Receive FIFO Empty Status bit. Set when receiver FIFO is empty. Read only.
TFULL	Transmitter FIFO Full Status bit. Set when transfer FIFO is full. Read only.
TEMPT	Transmitter FIF0 Empty Status bit. Set when transfer FIFO is empty. Read only.

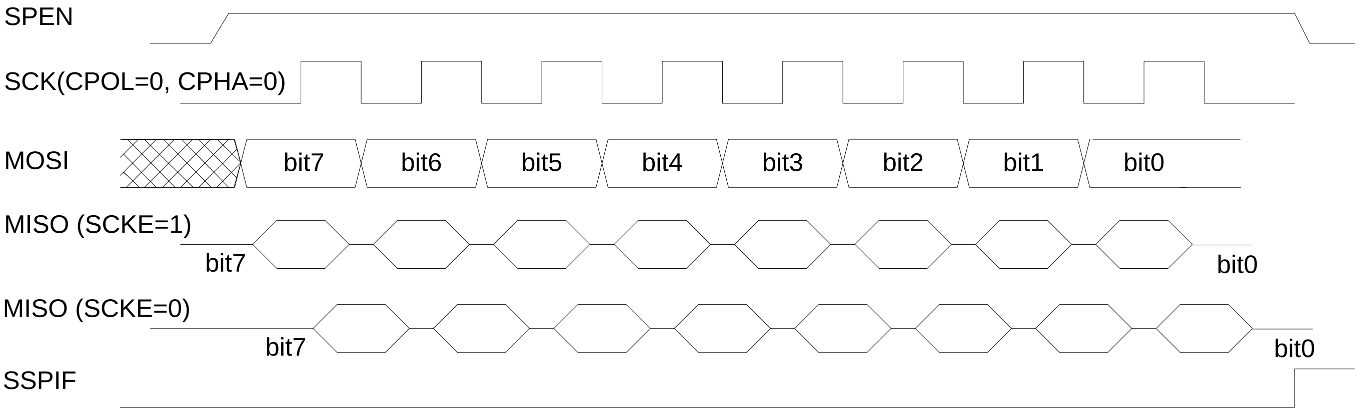
SPIDATA (0xA4) SPI Data Register R/W (0xXX)

	7	6	5	4	3	2	1	0
RD	SPI Receive Data Register							
WR	SPI Transmit Data Register							

6.1 SPI Master Timing Illustration

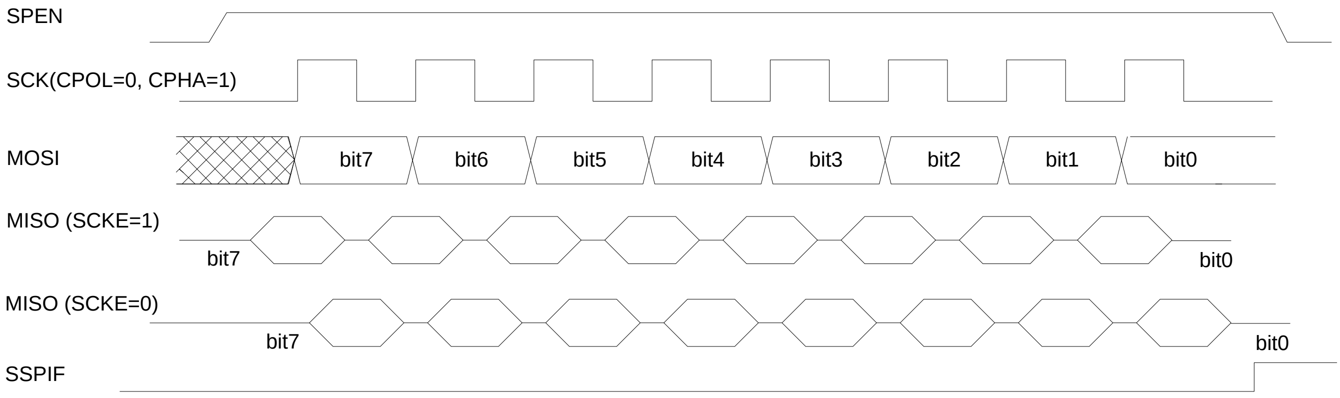
6.1.1 CPOL=0 CPHA=0

SPI MODE TIMING, MASTER MODE



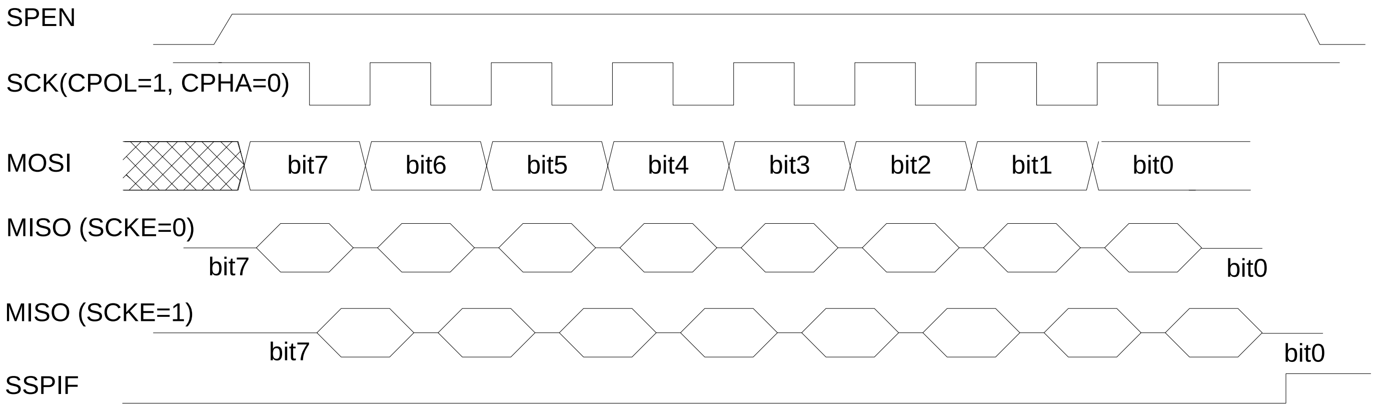
6.1.2 CPOL=0 CPHA=1

SPI MODE TIMING, MASTER MODE



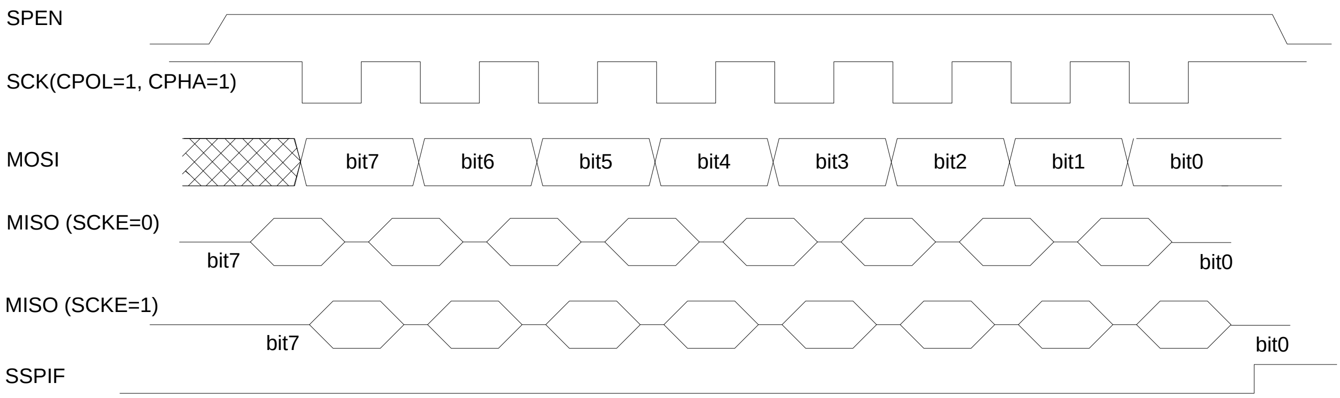
6.1.3 CPOL=1 CPHA=0

SPI MODE TIMING, MASTER MODE



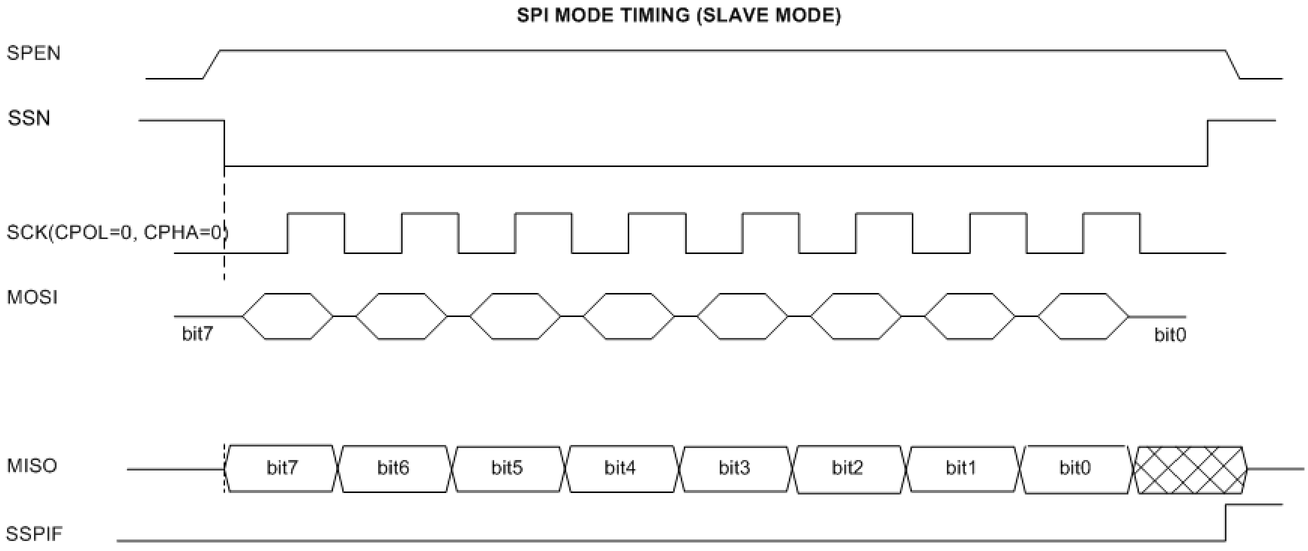
6.1.4 CPOL=1 CPHA=1

SPI MODE TIMING, MASTER MODE

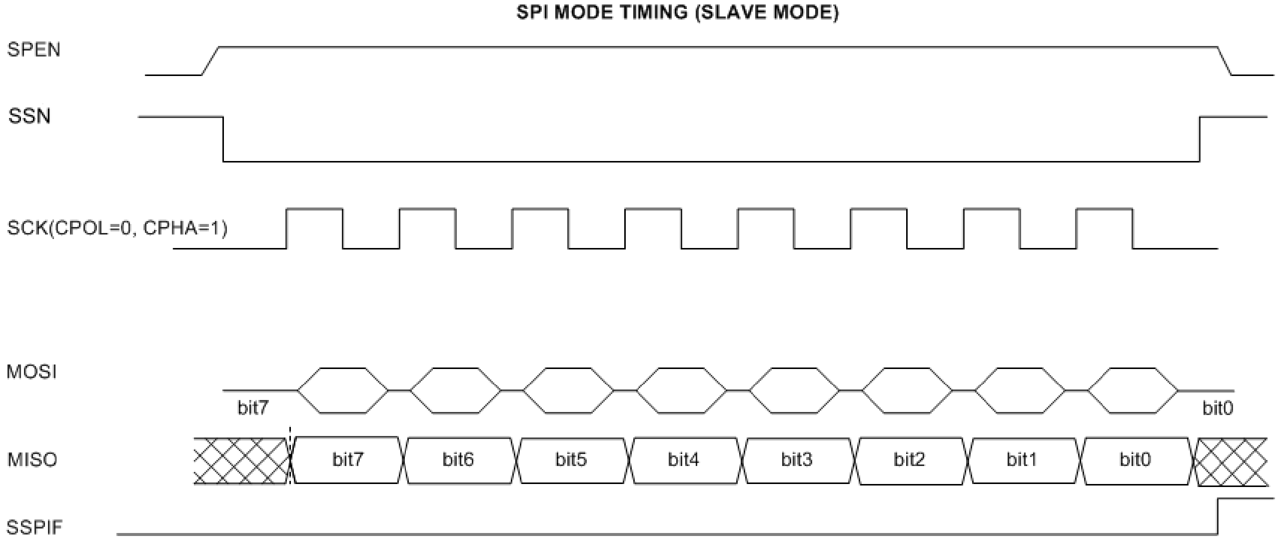


6.2 SPI Slave Timing Illustration

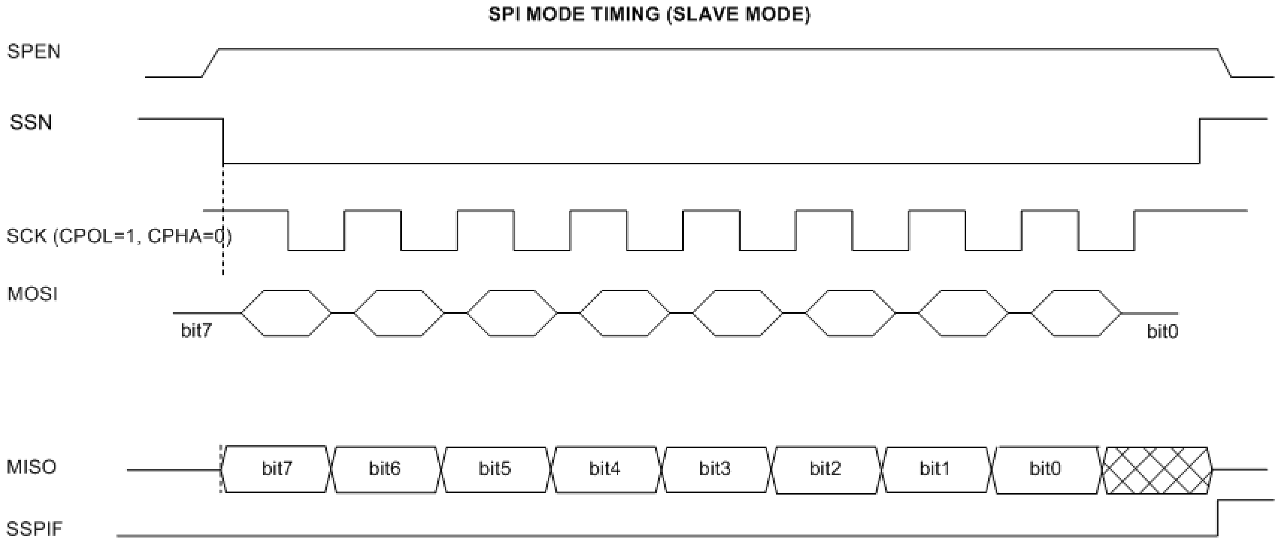
6.2.1 CPOL=0 CPHA=0



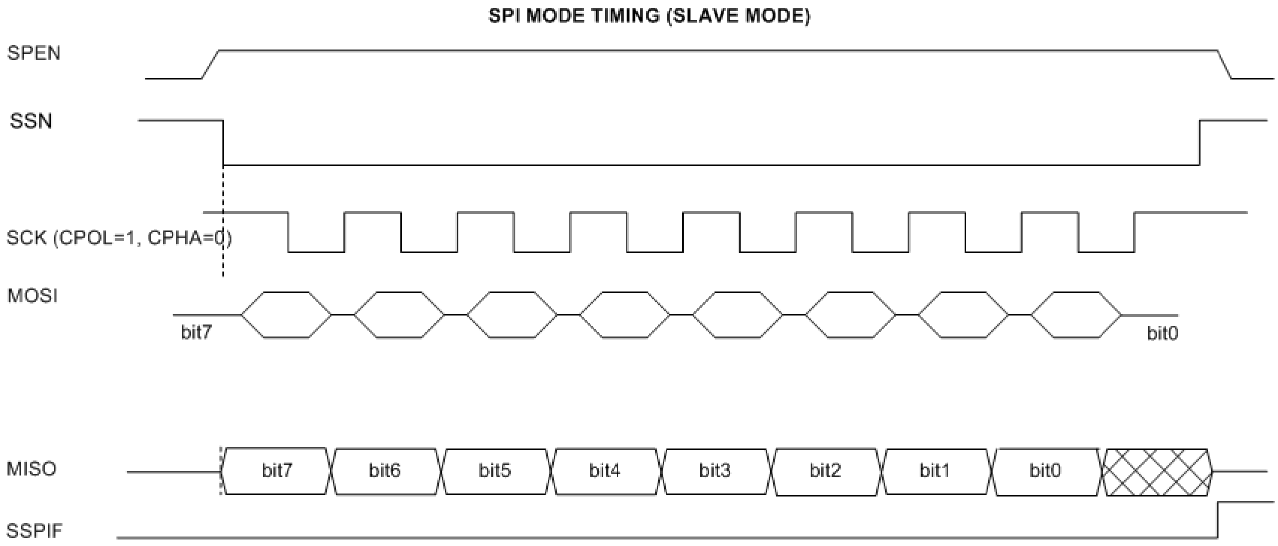
6.2.2 CPOL=0 CPHA=1



6.2.3 CPOL=1 CPHA=0

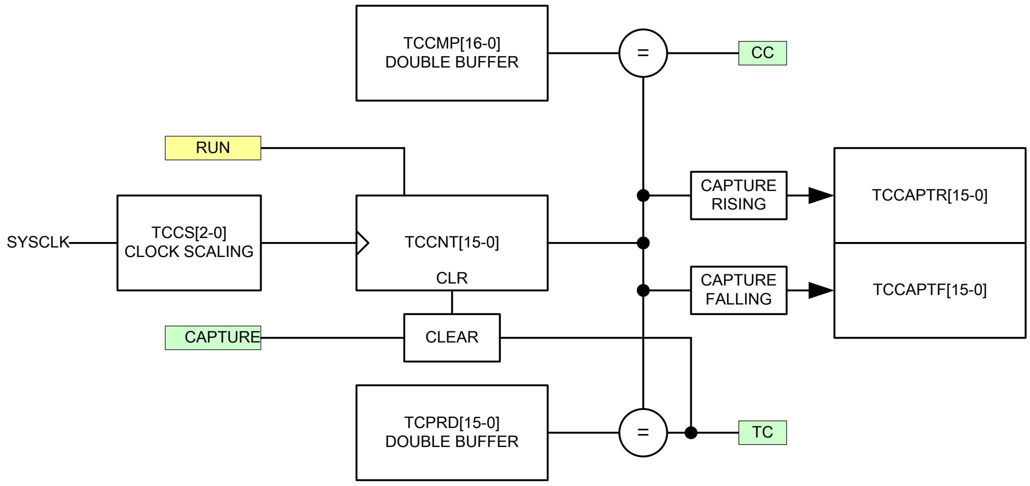


6.2.4 CPOL=1 CPHA=1



7. Timer with Compare/Capture and Quadrature Encoder

The Timer/Capture unit is based on a 16-bit counter with pre-scalable SYSCLK as counting clock. The count starts from 0 and reload when reach TC (terminal count). TC is met when the count equals period value. Along the counting, the count value is compared with COMP and when it matches, a CC condition is met. Note that both PERIOD and COMP register are double buffered, therefore any new value is updated after the current period ends. TC and CC can be used for triggering interrupt, and also routed to GPIO. The output pulse width of TC and CC is programmable. For CC, it can also be configured as a PWM output. There are two data registers for capture events. The capture event can be from external signals from GPIO (XCAPT) with edge selection option, or from QE block, or triggered by software. The software can also select if to reset the counter or not, this option give simpler calculation of consecutive capture evens without and offset. The following block diagram shows the TCC implementations.



TCCFG1 (0xA050h) TCC Configuration Register 1 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TCEN	TCCS[2-0]			CCSEL[1-0]		TCSEL	RUNST
WR	TCEN	TCCS[2-0]			CCSEL[1-0]		TCSEL	RUN

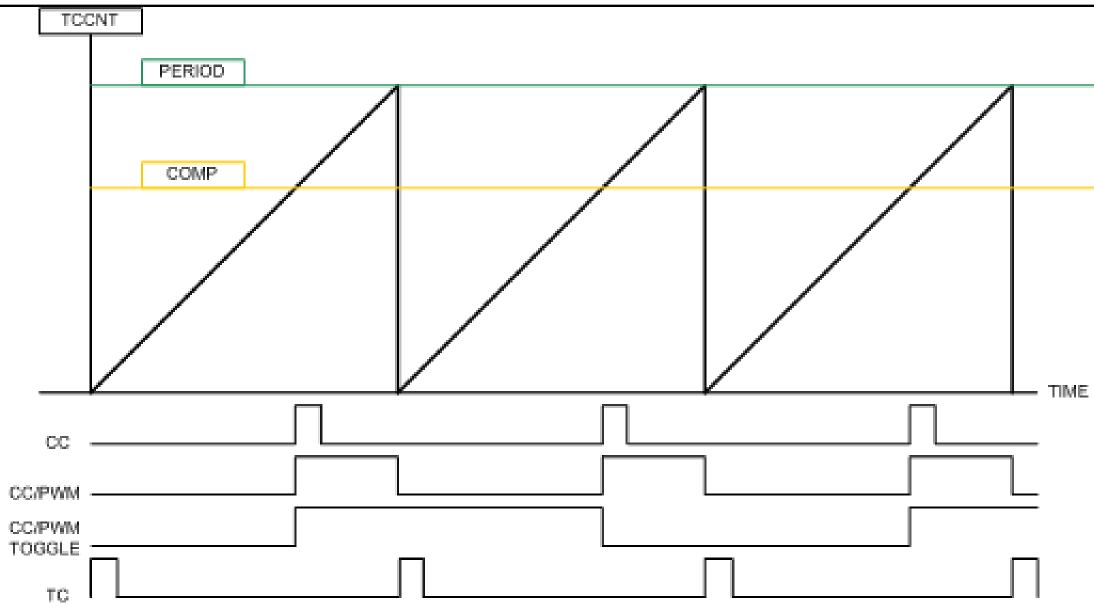
TCEN — TC Enable
TC = 0 disables TC. In disabled state, TCCNT, and TCCPTR/TCCPTF are cleared to 0. TC and CC are also set to low.
TC = 1 enable TC. RUN bit also needs to set to 1 to start the counter, otherwise if RUN=0 then counter is in pause mode.

TCCS[2-0] — TC Clock Scaling
000 SYSCLK
001 SYSCLK/2
010 SYSCLK/4
011 SYSCLK/8
100 SYSCLK/16
101 SYSCLK/32
110 SYSCLK/64
111 SYSCLK/128

CCSEL[1-0] — CC Output Pulse Select
00 PW = 16 TCCLK
01 PW = 64 TCCLK
10 PWM Waveform (CC = low when TCCNT < CMP, CC = high when TCCNT >= CMP).
11 PWM Toggle waveform (CC toggles when TCCNT = CMP).

TCSEL — TC Output Pulse Select
0 PW = 16 TCCLK

1 PW = 64 TCCLK



RUNST	Run Status
Set by hardware to indicate running TC counter. RUNST=1 indicates running.

RUN	Run or Pause TC Counter
Writing “0” to RUN will pause the TC counting.
Writing “1” to RUN will resume the TC counting.

TCCFG2 (0xA051h) TC Configuration Register 2 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	-	IDXST	PHAST	PHBST	TCPOL	CCPOL	TCF	CCF
WR	RSTTC	-	-	-	TCPOL	CCPOL	TCF	CCF

RSTTC	Reset TC
Writing RSTTC “1” will reset the TC counter and capture registers. Once counter is cleared, TC counter is put in STOP mode. To resume counting, RUN bit must be set by software.

IDXST	Index Input real-time status

PHAST	PHA input real-time status

PHBST	PHB input real-time status

TCPOL	TC output polarity

CCPOL	CC output polarity

TCF	Terminal Count Interrupt Flag
TCF is set to “1” by hardware when terminal count occurs. TCF must be cleared by software by writing “0”.

CCF	Compare Match Interrupt Flag
CCF is set to “1” by hardware when compare match occurs. CCF must be cleared by software by writing “0”.

TCCFG3 (0xA052h) TC Configuration Register 3 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	IENTC	IENCC	QECEN	CPTCLR	XCREN	XCFEN	-	-
WR	IENTC	IENCC	QECEN	CPTCLR	XCREN	XCFEN	SWCPTR	SWCPTF

IENTC	TC Interrupt Enable

IENCC	CC Interrupt Enable

QECEN	QE Capture Enable
QECEN=1 use QE output event as capture event.

CPTCLR	Enable Clear Counter after Capture
If CPTCLR=1, the TCCNT is cleared to 0 after each capture event. This allows continuous capture value with identical initial value.
If CPTCLR=0, the capture event does not affect the TCCNT counting.

XCREN	External Rising Edge Capture Enable XCREN=1 use external input rising edge as capture event.
XCFEN	External Falling Edge Capture Enable XCFEN=1 use external input falling edge as capture event.
SWCPTR	Software Capture R Writing “1” to SWCPTR will generate a capture event and capture the count value into TCCPTR register. This bit is cleared by hardware.
SWCPTF	Software Capture F Writing “1” to SWCPTF will generate a capture event and capture the count value into TCCPTF register. This bit is cleared by hardware.

Please note all capture sources are not mutually exclusive, i.e. allow several capture sources can coexist.

TCPRDL (0xA054h) TC Period Register Low Double Buffer R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TCCNT[7-0]							
WR	TCPRD[7-0]							

TCPRDH (0xA055h) TC Period Register High Double Buffer R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TCCNT15-8]							
WR	TCPRD[15-8]							

Note: Writing of PERIOD register must be done high byte first, then low byte. The writing takes effect at low byte writing. When reading the TCPRD register, it returns the current count value TCCNT[15-0].

TCCMPL (0xA056h) TC Compare Register Low Double Buffer R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TCCMP[7-0]							
WR	TCCMP[7-0]							

TCCMPH (0xA057h) TC Compare Register High Double Buffer R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TCCMP15-8]							
WR	TCCMP[15-8]							

Note: Writing of COMPARE register must be done high byte first, then low byte. The writing takes effect at low byte writing.

TCCPTRL (0xA060h) TC Capture Register R Low R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TCCPTR[7-0]							
WR	-							

TCCPTRH (0xA061h) TC Capture Register R High R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TCCPTR15-8]							
WR	-							

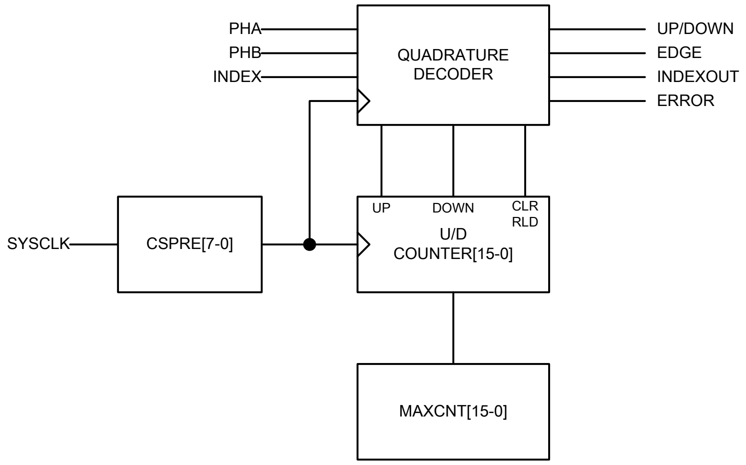
TCCPTFL (0xA062h) TC Capture Register F Low R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TCCPTF[7-0]							
WR	-							

TCCPTFH (0xA063h) TC Capture Register F High R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TCCPTF[15-8]							
WR	-							

The quadrature encoder is clocked by a scaled SYSCLK, and has three external inputs through GPIO multi-functions. The three inputs include two signals of 90 degrees phase difference, PHA and PHB, and an index indicating the terminal of the encoder. QE can function as an independent function block and also can be configured to couple with TCC and use TCC to calculate the speed information of the encoder. Using TCC to capture TCC count value using the Index input of QE or terminal count of QE, the speed of QE input can be calculated. The QE unit implementation is shown in the following block diagram.

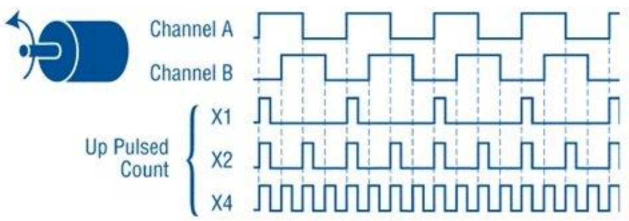


Please QE Counter is in signed integer format, the MSB (Bit 15) indicates the sign, and reload action cause the counter loads a default value of 0x8000. The corresponding maximum count register thus only have 15 valid bits, MSB bit 15 is not used. The reload action is triggered either by external INDEX event or terminal count condition when counter absolute value reaches (equal) to MAXCNT value.

QECFG1 (0xA070h) TCC Configuration Register 1 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	QEMODE[1-0]		QECS[1-0]		SWAP	DBCS[2-0]		
WR	QEMODE[1-0]		QECS[1-0]		SWAP	DBCS[2-0]		

MODE[1-0] QE Mode
00 – Disable QE
01 – 1X mode
10 – 2X mode
11 – 4X mode



QECS[1-0] QE Clock Scaling
00 SYSCLK/4
01 SYSCLK/16
10 SYSCLK/64
11 SYSCLK/256

SWAP Swap PHA and PHB

DBCS[2-0]	De-Bounce Clock Scaling 000 Disable de-bounce 001 SYSCLK/2 010 SYSCLK/4 011 SYSCLK/8 100 SYSCLK/16 1/32 SYSCLK/32 1/64 SYSCLK/64 1/128 SYSCLK/128 1/256 SYSCLK/256 De-bounce time is three DBCS period.

QECFG2 (0xA071h) QE Configuration Register 2 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	DIR	ERRF	RLDM[1-0]		TCF	IDXF	DIRF	CNTF
WR	-	ERRF	RLDM[1-0]		TCF	IDXF	DIRF	CNTF

DIR	Direction Status Indicate UP/DOWN direction
ERRF	Phase Error Flab ERRF is set to 1 by hardware if PHA and PHB change value at the same time. ERRF must be cleared by software.
RLDM[1-0]	QE Counter Reload Mode RLDM[1-0] = 00 No Reload, QECNT will count up/down cycling through 0x0000 or 0xFFFF RLDM[1-0] = 01 Reload using Index event. Reload QECNT=0, when Index==1 && UP Reload QECNT=QEMAX, when Index==1 && DOWN RLDM[1-0] = 10 Reload using TC event. Reload QECNT=0, when QECNT==QEMAX && UP Reload QECNT=QEMAX, when QECNT==0 && DOWN RLDM[1-0] = 11 Reload using both Index and TC events Combine Index and TC events and reload whichever occurs earlier
TCF	TC Event Interrupt Flag TCF is set by hardware when a TC event interrupt has occurred. TCF needs to be cleared by software by writing “0”.
IDXF	Index Event Interrupt Flag IDXF is set by hardware when an Index event interrupt has occurred. IDXF needs to be cleared by software by writing “0”.
DIRF	Direction Change Event Interrupt Flag DIRF is set by hardware when a Direction change event interrupt has occurred. DIRF needs to be cleared by software by writing “0”.
CNTF	Count Change Event Interrupt Flag CNTF is set by hardware when a QE count change event interrupt has occurred. CNTF needs to be cleared by software by writing “0”.

QECFG3 (0xA072h) QE Configuration Register 3 R/W (0x00)

	7	6	5	4	3	2	1	0
RD	IENTC	IENIDX	IENDIR	IENCNT	IENERR	IDXEN	IDXM[1-0]	
WR	IENTC	IENIDX	IENDIR	IENCNT	IENERR	IDXEN	IDXM[1-0]	

IENTC	Interrupt Enable for TC TC condition for QE is defined as the following conditions 1. QECNT=QEMAX when UP 2. QECNT=0 when down
IENIDX	Interrupt Enable for Index event
IENDIR	Interrupt Enable for Direction Change
IENCNT	Interrupt Enable for any QECNT change
IDXEN	Index Input Enable

IDXEN=0 gates out the external INDEX input is gated to 0.
IDXEN=1 allows external INDEX.

IDXM[1-0] Index Match Selection, this is applicable only for X2 and X4 modes.
00 = up phase 00 → 10 down phase 10 → 00
01 = up phase 10 → 11 down phase 11 → 10
10 = up phase 01 → 00 down phase 00 → 01
11 = up phase 11 → 01 down phase 01 → 11

QECNTL (0xA074h) QE Counter Low R/W (0x00)

	7	6	5	4	3	2	1	0
RD	QECNT[7-0]							
WR	QECNTINI[7-0]							

QECNTH (0xA075h) QE Counter High R/W (0x00)

	7	6	5	4	3	2	1	0
RD	QECNT[15-8]							
WR	QECNTINI[15-8]							

Reading QECNT will return the current QE counter value. Writing QECNT will set the current count value. Writing QECNT is allowed only when QE is in disabled state.

QEMAXL (0xA076h) QE Counter Low R/W (0x00)

	7	6	5	4	3	2	1	0
RD	QEMAX[7-0]							
WR	QEMAX[7-0]							

QEMAXH (0xA077h) QE Counter High R/W (0x00)

	7	6	5	4	3	2	1	0
RD	QEMAX[15-8]							
WR	QEMAX[15-8]							

QEMAX hold the maximum count of the QE counter. When QEMAX is reached a TC event is triggered and QE counter is reloaded.

8. PWM Controller

PWM controller provides programmable 6 channels 12/10/8 bit PWM center-aligned duty cycle outputs. The counting clock of PWM is programmable and the base frequency of the PWM is just the counting clock divided by 8192/2048/512 for 12/10/8 bit configurations due to center-alignment counting. PWM outputs are multiplexed with GPIO ports.

PWMCFG1 (0xA080h) PWM Clock Scaling Setting Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	PWMEN	MODE[1-0]		CS[4-0]				
WR	PWMEN	MODE[1-0]		CS[4-0]				

PWMEN PWM Controller Enable
PWMEN=0 clears the counter, reset the PWM state and all channel outputs are forced to 0.
PWMEN=1 allows normal running operation of PWM controller.

MODE[1-0] PWM Resolution Select
00 = 8-bit
01 = 10-bit
10 = 12-bit
11 = Reserved

CS[4-0] PWM Counting Clock Scaling
The counting clock is SYSCLK/(CS[4-0]+1)

PWMCFG2 (0xA081h) PWM Interrupt Enable and Flag Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	ZTRGEN	CTRGEN	ZINTEN	CINTEN	-	-	ZINTF	CINTF
WR	ZTRGEN	CTRGEN	ZINTEN	CINTEN	-	-	ZINTF	CINTF

ZTRGEN Zero ADC Trigger Enable
CTRGEN Center ADC Trigger Enable
ZINTEN Zero Interrupt Enable
ZINTEN=1 allows PWM Controller to generate interrupt when counter is 0.

CNTEN Center Interrupt Enable
CINTEN=1 allows PWM Controller to generate interrupt when counter is at the mid value.

ZINTF Zero Interrupt Flag
ZINTF is set to 1 by hardware to indicate a Zero interrupt has occurred. ZINTF must be cleared by software.

CINTF Center Interrupt Flag
CINTF is set to 1 by hardware to indicate a Center interrupt has occurred. CINTF must be cleared by software.

PWMCFG3 (0xA082h) PWM Configuration 3 Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	PRSEN	SYNC	POL[5-0]					
WR	PRSEN	SYNC	POL[5-0]					

PRSEN Pseudo-Random Sequence Enable
PRSEN=1 will enable a pseudo random sequence to the PWM output width. This can be an effective way to reduce EMI for output. When PRSEN=1, the instantaneous duty cycle will be affected cycle by cycle, but the average duty cycle remains the same.

SYNC Channel Synchronize
Writing SYNC=1 will cause the loading of duty register on the nextcount=0 event. The purpose of this is to synchronize the timing of all the PWM channels. SYNC is cleared by hardware after reloading is completed.
Reading SYNC by software can tell whether reload has been in effect or not.

POL[5-0] Channel Polarity Control
POL[J] = 0 for normal polarity and POL[J]=1 for reverse polarity.

There are 6 PWMDTY registers to define the duty cycle of each PWM channel. If PWMDTY = 0, the output is 0. If PWMDTY = full, the output duty cycle is maximum to (period – 1)/period. PWMDTY is always double buffered and is loaded to duty cycle comparator when the SYNC bit is set and current counting cycle is completed. For 8-bit, only the PWMDTY[7-0] is used, and for 10-bit, PWMDTY[9-0] is used, and for 12-bit PWMDTY[11-0] is used. Please note if PWMEN=0 (PWM is disabled), then writing to PWMDTY register is immediate.

PWM0DTYL (0xA084h) PWM0 Duty Register L R/W (0x00)

	7	6	5	4	3	2	1	0
RD	PWM0DTY[7-0]							
WR	PWM0DTY[7-0]							

PWM0DTYH (0xA085h) PWM0 Duty Register H R/W (0x00)

	7	6	5	4	3	2	1	0
RD	-	-	-	-	PWM0DTY[11-8]			
WR	-	-	-	-	PWM0DTY[11-8]			

PWM1DTYL (0xA086h) PWM1 Duty Register L R/W (0x00)

	7	6	5	4	3	2	1	0
RD	PWM1DTY[7-0]							
WR	PWM1DTY[7-0]							

PWM1DTYH (0xA087h) PWM1 Duty Register H R/W (0x00)

	7	6	5	4	3	2	1	0
RD	-	-	-	-	PWM1DTY[11-8]			
WR	-	-	-	-	PWM1DTY[11-8]			

PWM2DTYL (0xA088h) PWM2 Duty Register L R/W (0x00)

	7	6	5	4	3	2	1	0
RD	PWM2DTY[7-0]							
WR	PWM2DTY[7-0]							

PWM2DTYH (0xA089h) PWM2 Duty Register H R/W (0x00)

	7	6	5	4	3	2	1	0
RD	-	-	-	-	PWM2DTY[11-8]			
WR	-	-	-	-	PWM2DTY[11-8]			

PWM3DTYL (0xA08Ah) PWM3 Duty Register L R/W (0x00)

	7	6	5	4	3	2	1	0
RD	PWM3DTY[7-0]							
WR	PWM3DTY[7-0]							

PWM3DTYH (0xA08Bh) PWM3 Duty Register H R/W (0x00)

	7	6	5	4	3	2	1	0
RD	-	-	-	-	PWM3DTY[11-8]			
WR	-	-	-	-	PWM3DTY[11-8]			

PWM4DTYL (0xA08Ch) PWM3 Duty Register L R/W (0x00)

	7	6	5	4	3	2	1	0
RD	PWM4DTY[7-0]							
WR	PWM4DTY[7-0]							

PWM4DTYH (0xA08Dh) PWM3 Duty Register H R/W (0x00)

	7	6	5	4	3	2	1	0
RD	-	-	-	-	PWM4DTY[11-8]			
WR	-	-	-	-	PWM4DTY[11-8]			

PWM5DTYL (0xA08Eh) PWM5 Duty Register LR/W (0x00)

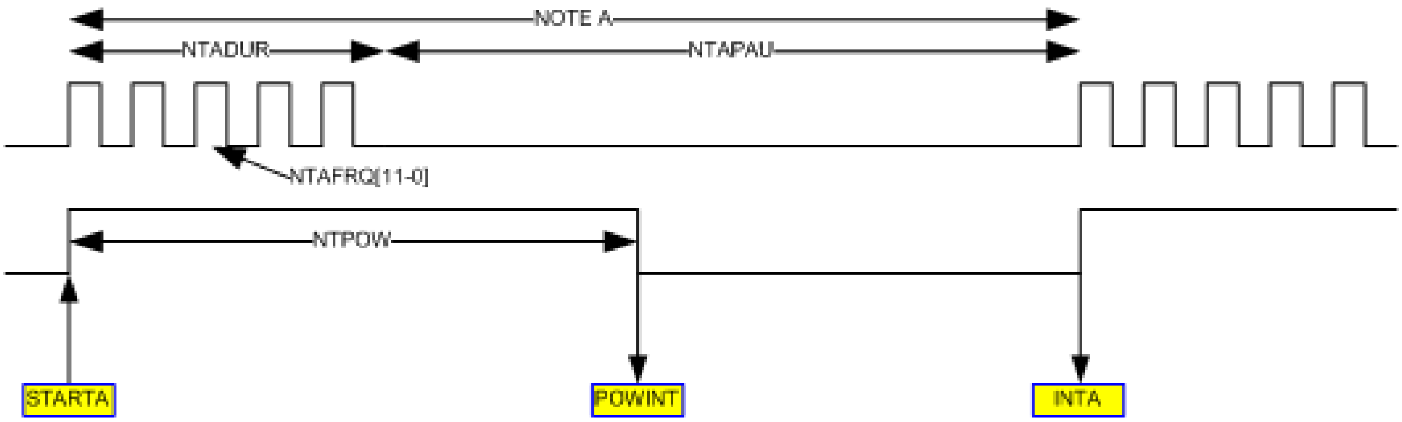
	7	6	5	4	3	2	1	0
RD	PWM5DTY[7-0]							
WR	PWM5DTY[7-0]							

PWM5DTYH (0xA08Fh) PWM5 Duty Register H R/W (0x00)

	7	6	5	4	3	2	1	0
RD	-	-	-	-	PWM5DTY[11-8]			
WR	-	-	-	-	PWM5DTY[11-8]			

9. Buzzer and Melody Controller

The buzzer and melody controller can be used to generate simple buzzer sound or single tone melody. It contains a two note Ping-Pong buffers, each with programmable tone frequency, and duration/pause timer. The tone frequency is derived from SYSCLK divided by either 32 or 64, and the tone frequency is generated with resolution of 12-bit to support precision tone generation with wide octave span. The duration/pause timers can be programmed in 1ms/2ms/4ms/8ms steps. The two notes can be played sequentially once, or can be played as Ping-Pong styles for melody. A POW (Power On Width) timer is also included with same time steps, POW timer can be used to generate external power control of the buzzer element. POW timer is started when either note A or B is started.



NTAFRQL (0xA040h) Note A Frequency Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	NTAFRQ[7-0]							
WR	NTAFRQ[7-0]							

NTAFRQH (0xA041h) Note A Frequency Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	-		-		NTAFRQ[11-8]			
WR	-		-		NTAFRQ[11-8]			

Tone frequency is SYSCLK/(32 or 64)/(NTAFRQ[11-0]+1).

NTADUR (0xA042h) Note A Duration Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	NTADUR[7-0]							
WR	NTADUR[7-0]							

Tone duration is TU * NTADUR[7-0]

NTAPAU (0xA043h) Note A Pause Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	NTAPAU[7-0]							
WR	NTAPAU[7-0]							

Tone pause is TU * NTAPAU[7-0]

NTBFRQL (0xA044h) Note B Frequency Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	NTBFRQ[7-0]							
WR	NTBFRQ[7-0]							

NTBFRQH (0xA045h) Note B Frequency Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	-		-		NTBFRQ[11-8]			
WR	-		-		NTBFRQ[11-8]			

NTBDUR (0xA046h) Note B Duration Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	NTBDUR[7-0]							
WR	NTBDUR[7-0]							

NTBPAU (0xA047h) Note B Pause Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	NTBPAU[7-0]							
WR	NTBPAU[7-0]							

NTPOW (0xA049h) Note Power On Window Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	NTPOW [7-0]							
WR	NTPOW [7-0]							

NTPOW defines a timer after either STARTA or STARTB. It uses the same time unit as duration and pause. When the timer expires, it generates an interrupt by setting INTFP bit.

NTTU (0xA04Ah) Note Time Unit Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TU[1-0]		-	TBASE	-	-	INTEPOW	INTFP
WR	TU[1-0]		-	TBASE	-	-	INTEPOW	INTFP

TU[1-0]	Time Unit TU[1-0] defines the time unit for duration and pause, and POW timer. This is derived from SOSC 128KHz and not dependent on tone frequency setting. 00 = 1msec 01 = 2msec 10 = 4msec 11 = 8msec
TBASE	Tone Base Frequency Select TBASE=0 uses SYSCLK/32 as base TBASE=1 uses SYSCLK/64 as base
INTEPOW	POW Timer Interrupt Enable
INTFP	POW Interrupt Flag INTFP is set by hardware when POW timer expires. It must be cleared by software.

BZCFG (0xA048h) Buzzer Configure Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	BZEN	BZPOL	INTENB	INTENA	INTFB	INTFA	BUSYB	BUSYA
WR	BZEN	BZPOL	INTENB	INTENA	INTFB	INTFA	STARTB	STARTA

BZEN	Buzzer Control Enable BZEN=1 enables the buzzer controller BZEN=0 disables the buzzer controller
BZPOL	BZOUT Polarity Setting BZPOL=1, BZOUT is inverted BZPOL=0, normal polarity
INTENB	Note B End Interrupt Enable

	INTENB=1 enables the note B end interrupt. The interrupt is triggered when note B playing completed.
INTENA	Note A End Interrupt Enable INTENA =1 enables the note A end interrupt. The interrupt is triggered when note A playing completed.
INTFB	Note B End Interrupt Flag INTFB is set to 1 by hardware if INTENB=1 and Note B playing end. INTFB needs to be cleared by software writing 0.
INTFA	Note A End Interrupt Flag INTFA is set to 1 by hardware if INTENA=1 and Note A playing end. INTFA needs to be cleared by software writing 0.
STARTB	Note B Start Command Writing STARTB=1 initiate a session output on the buzzer. Writing 0 to STARTB has no effect. STARTB is self-cleared when the note is completed.
STARTA	Note A Start Command Writing STARTA=1 initiate a session output on the buzzer. Writing 0 to STARTA has no effect. STARTA is self-cleared when the note is completed.

*** Note if STARTA and STARTB are set to 1 at the same time, then Note A is played first followed by Note B. Software can do this for simple two notes melody.

BUSYB	Note B is playing busy Status BUSYB is set to 1 by hardware when the output is active playing note B.
BUSYA	Note A is playing busy Status BUSYA is set to 1 by hardware when the output is active playing note A.

10. Core Regulator and Low Voltage Detection

An on-chip serial regulator converts VDD into VDDC for internal circuit supply voltage. Typical value for VDDC is 1.5V at normal mode. In sleep mode, a backup regulator with typical value of 1.3V supplies VDDC. The VDDC can be trimmed and calibrated trim value for 1.5V is stored in IFB by the manufacture test.

REGTRM (0xA000h) Regulator Trim Register R/W (0x80) TB protected

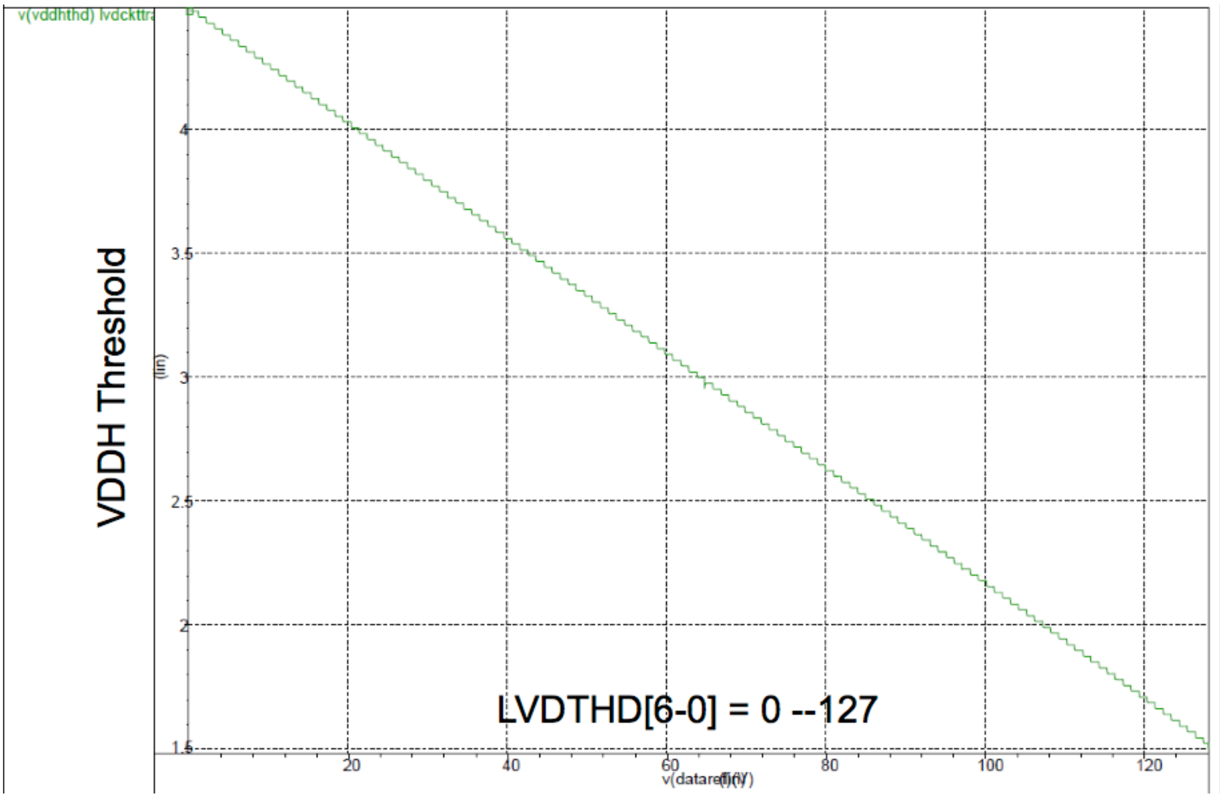
	7	6	5	4	3	2	1	0
RD	REGTRM[7-0]							
WR	REGTRM[7-0]							

10.1 Supply Low Voltage Detection (LVD)

The supply Low Voltage Detection (LVD) circuit detects VDD < VTH condition and can be used to generates an interrupt or reset condition. LVD defaults to disabled state to save power. An enabled LVD circuit consumes about 100uA to 200uA. The LVDTHD[6-0] sets the compare threshold according to the following equation when LVDTHV is the detection voltage.

LVDTHV = VDDC * (1 + 2 * (1 – LVDTHD[6-0]/128)

= 1.5 + 3 * (1 – LVDTHD[6-0]/128), if VDDC is calibrated to 1.5V.



LVDCFG (0xA010h) Supply Low Voltage Detection Configuration Register R/W (0x08) TB Protected

	7	6	5	4	3	2	1	0
RD	LVDEN	LVREN	LVTEN	LVDFLTEN	-	-	-	LVTIF
WR	LVDEN	LVREN	LVTEN	LVDFLTEN	-	-	-	LVTIF

LVDEN	LVD Enable bit. Set to turn on supply voltage detection circuits.
LVREN	LVR Enable bit. LVREN = 1 allows low voltage detect condition to cause a system reset.
LVTEN	LVT Enable bit. LVTEN = 1 allows low voltage detect condition to generate an interrupt.
LVDFLTEN	LVD Filter Enable LVDFLTEN = 1 enables a noise filter on the supply detection circuits. The filter is set at around 30usec.
LVTIF	Low Voltage Detect Interrupt Flag LVTIF is set by hardware when LVD detection occurs and must be cleared by software.

LVDTHD (0xA011h) Supply Low Voltage Detection Threshold Register R/W (0bx1111111) TB Protected

	7	6	5	4	3	2	1	0
RD	-	LVDTHD6	LVDTHD5	LVDTHD4	LVDTHD3	LVDTHD2	LVDTHD1	LVDTHD0
WR	-	LVDTHD6	LVDTHD5	LVDTHD4	LVDTHD3	LVDTHD2	LVDTHD1	LVDTHD0

LVDTHD = 0x00 will set the detection threshold at its maximum, and LVDTHD = 0x7F will set the detection threshold at its minimum.

LVDHYS (0xA012h) Supply Low Voltage Detection Threshold Hysteresis Register R/W (0x00) TB Protected

	7	6	5	4	3	2	1	0
RD	LVDHYEN	LVDHYS6	LVDHYS5	LVDHYS4	LVDHYS3	LVDHYS2	LVDHYS1	LVDHYS0
WR	LVDHYEN	LVDHYS6	LVDHYS5	LVDHYS4	LVDHYS3	LVDHYS2	LVDHYS1	LVDHYS0

To ensure a solid Low Voltage detection, a digital controlled hysteresis is used. If LVDHYEN=1, when LVD is asserted a new threshold defined by LVDHYS[6-0] replaces LVDTHD[6-0]. In typical applications, LVDHYS[6-0] should be set to be smaller than LVDTHD[6-0] such that recovery voltage is higher than detection voltage.

11. IOSC and SIOC

11.1 IOSC 16MHz/32MHz

An on-chip 16MHz/32MHz Oscillator with low temperature coefficient provides the system clock to the CPU and other logic. IOSC uses VDD15 as supply and can be calibrated and trimmed. The accuracy of the frequency is +/- 2% within the operating conditions. This oscillator is stopped and enters into stand-by mode when CPU is in STOP/SLEEP mode and resumes oscillation when CPU wakes up.

IOSCITRM (0xA001h) IOSC Coarse Trim Register R/W (0x01) TB Protected

	7	6	5	4	3	2	1	0
RD	SSC[3-0]				SSA[1-0]		ITRM[1-0]	
WR	SSC[3-0]				SSA[1-0]		ITRM[1-0]	

SSC[3-0] SSC[3-0] defines the spread spectrum sweep rate. If SSC[3-0] = 0000, then the spread spectrum is disabled.

SSA[1-0] SSA[1-0] defines the amplitude of spread spectrum frequency change. The frequency is changed by adding SSA[1-0] range to actual IOSCVTRM[7-0].
SSA[1-0] = 11, +/- 32
SSA[1-0] = 10, +/- 16
SSA[1-0] = 01, +/- 8
SSA[1-0] = 00, +/- 4

ITRM[1-0] ITRM[1-0] is the coarse trimming of the IOSC.

IOSCVTRM (0xA002h) IOSC Fine Trim Register R/W (0x80) TB Protected

	7	6	5	4	3	2	1	0
RD	IOSCVTRM[7-0]							
WR	IOSCVTRM[7-0]							

This register provides fine trimming of the IOSC frequency. The higher the value of IOSCVTRM, the lower the frequency is.

The manufacturer trim value is stored in IFB and is trimmed to 16MHz. The user program provides the freedom to set the IOSC at a preferred frequency as long as the program is able to calibrate the frequency. Once set, the IOSC frequency has accuracy deviation within +/- 2% over the operation conditions. The following lists the range of the typical IOSC frequency for each trimming setting.

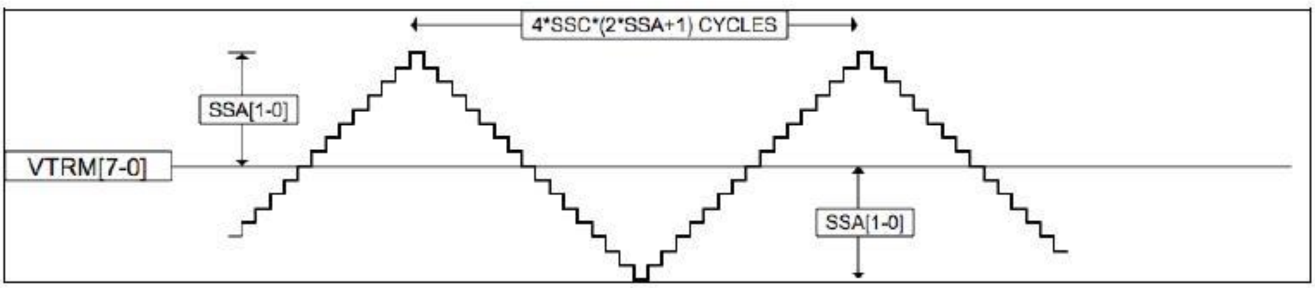
ITRM[1:0]=2’b11, IOSC=27.4—36.8MHz

ITRM[1:0]=2’b10, IOSC=25.5—34.3MHz

ITRM[1:0]=2’b01, IOSC=14.1—19.2MHz

ITRM[1:0]=2’b00, IOSC=12.2—16.5MHz

A hardware Spread Spectrum can be enabled for the IOSC. This is controlled by SSC[3-0]. When SSC[3-0] = 0, the spread spectrum is disabled, and IOSC functions normally as a fixed frequency oscillator. If SSC[3-0] is not 0, then Spread Spectrum is enabled and IOSC frequency is swept according to the setting of SSC[3-0] and SSA[1-0]. The spread is achieved by varying the actual VTRM output to the oscillator circuit thus effectively changes the oscillation frequency. The effect of SSC[3-0] and SSA[1-0] is shown in the following graph.



When Spread Spectrum is enabled, the actual controlling output to IOSC is VTRM[7-0] +/- SSA. This is shown in the graph above as the bold curve. The above example shows SSA[1:0] = 01, and the deviation is +/- 8. SSC[3-0] defines the update time in IOSC cycles. Then we can calculate the period of a complete sweep is 4*SSC*(2SSA+1) IOSC cycles, and we can obtain the sweep frequency from this period. When SS is enabled, the frequency of IOSC varies according to time and setting, therefore, the accuracy of IOSC frequency cannot be guaranteed. Please also note that VTRMOUT is VTRM[7-0] +/- SSA but is bounded by 0 and 255. Therefore for a linear non-clipped sweep, VTRM[7-0] needs to be within the range of SSA – 256-SSA, for example, SSA[10] = 01, then SSA is 8. VTRM[7-0] should be in the range from 8 to 248 to prevent the sweep from being clipped. As Spread Spectrum suggests, the total EMI energy is not reduced, but the energy is spread over wider frequency. It is recommended that SS usage should be carefully evaluated and the setting of spread amplitude and the sweep frequency should be chosen carefully for reducing EMI effect.

11.2 SOSC 128KHz

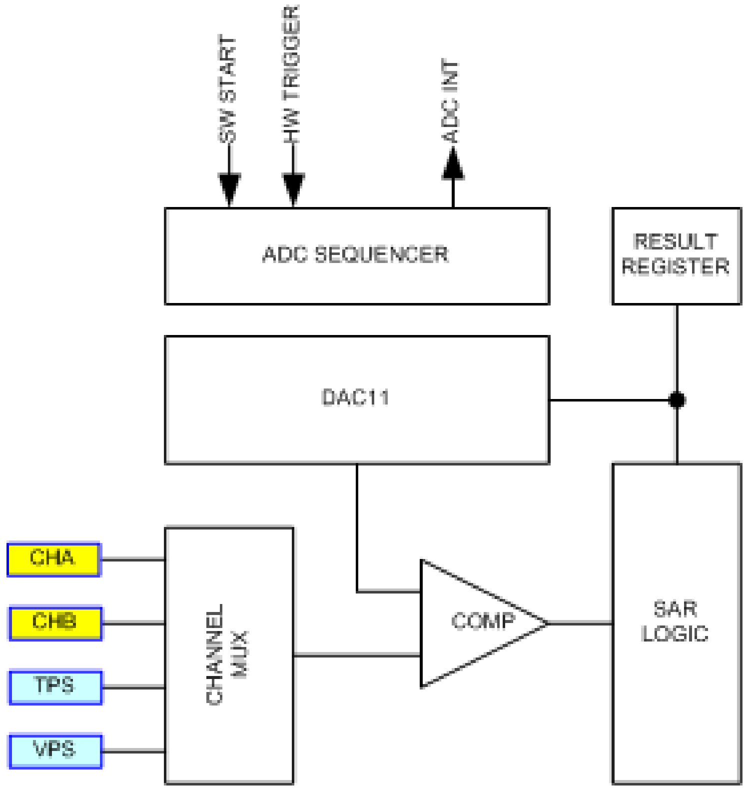
An ultralow power slow oscillator of 128KHz is also included. SOSC consume less than 0.5uA from VDDC and is always enabled. The system uses SOSC/4 = 32KHz for system clock, and for wake-up timer T5, and WDT2/WDT3. SOSC is not very accurate and varies chip to chip, but it is relatively supply and temperature stable. Therefore software can use IOSC to calibrate SOSC through SOCTRM[4-0]. Default design characteristics shows when SOICTRM=5b’1_1111/SOSC = 158KHz, 5b’1_0000/SOSC=126KHz, 5b’0_0000/SOSC=105KHz.

SOSCTRM (0xA007h) SOSC Trim Register R/W (0x10) TB Protected

	7	6	5	4	3	2	1	0
RD	-			SOSCTRM[4-0]				
WR	-	-		SOSCTRM[4-0]				

12. 11-Bit SAR ADC (ADC)

The on-chip ADC is an 11-bit SAR based ADC with maximum ADC clock rate of 4MHz (2.5V – 5V) or 500KHz (1.8V – 2.4V). The ADC uses VDDC (1.5V typical) as full-scale reference. Typical ADC accuracy is about 9.5 bit to 10 Bit to at 1.5V reference with input range between 0.2V to 1.5. The ADC has four intrinsic channels. CHA and CHB are further connected to GPIO's analog I/O switches to expand multiplexed inputs. TPS is connected to internal temperature sensor (a diode-connected NPN) with negative temperature coefficient. VPS is 1/5th of VDDH. When enabled, the ADC consumes about 1mA of current. The ADC also includes hardware to perform result average. Average can be set to 1 to 8 times. The block diagram of ADC is shown in the following.



ADCCFG (0xA9h) ADC Configuration Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	ADCEN	ADCINTE	ADCFM	-	-	PRE[2-0]		
WR	ADCEN	ADCINTE	ADCFM	-	-	PRE[2-0]		

ADCEN — ADC Enable bit
ADCEN=1 enables ADC.
ADCEN=0 puts ADC into power down mode.
When ADCEN is set from 0 to 1, the program needs to wait at least 20us to allow analog bias to stabilize to ensure ADC's proper functionality.

ADCINTE — ADC Interrupt Enable bit
ADCINTE=1 enables the ADC interrupt when conversion completes.
ADCINTE=0 disables the ADC interrupt

ADCFM — ADC Result Format Control bit
ADCFM = 1 sets ADC result as MSB justified. ADCAH contains the MSB bits of the result. ADCAL[7-5] contains LSB results and ADCAL[4-0] is filled with 0000.
ADCFM = 0 sets ADC result as LSB justified. ADCAH[7-3] is filled with 0000. ADCAH[2-0] contains MSB result. ADCAL contains the LSB results.

PRE[2-0] — ADC Clock Divider

PRE[2-0]	ADC CLOCK
0	SYSCLK/2
1	SYSCLK/4

2	SYSCLK/8
3	SYSCLK/16
4	SYSCLK/32
5	SYSCLK/64
6	SYSCLK/128
7	SYSCLK/256

ADCCTL (0xCEh) ADC Control Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	AVG[1-0]		CHSEL[1-0]		-		ADCIF	CSTART
WR	AVG[1-0]		CHSEL[1-0]		-		-	CSTART

AVG[1-0] AVG[2-0] controls the hardware averaging logic of ADC readout. It is recommended the setting is changed only when ADC is stopped. If multiple channels are enabled, then each channel is averaged in sequence. The default is 00.

AVG1	AVG0	ADC Result
0	0	1 Times Average
0	1	2 Times Average
1	0	4 Times Average
1	1	8 Times Average

CHSEL[1-0] ADC Channel Select

CHSEL[1]	CHSEL[0]	ADC Channel
0	0	CHA
0	1	CHB
1	0	Temperature
1	1	1/5 VDD

ADCIF ADC Conversion Completion Interrupt Flag bit
ADCIF is set by hardware when the conversion is completed and new result is written to ADCL and ADCH result registers. If ADC interrupt is enabled, this also generates an interrupt. This bit is cleared when ADCL is read. When this flag is set, no new conversion result is updated.

CSTART Software Start Conversion bit
Set this CSTART=1 to trigger an ADC conversion on selected channels. This bit is self-cleared when the conversion is done.

ADCH and ADCL are the high and low byte result registers respectively, and are read-only. Reading low byte result also clears its corresponding interrupt flag. If the flag is not cleared, no new result is updated. The software should always read the low byte last. The format of the high byte and low byte depends on ADCFM setting.

If ADCFM = 1, the valid ADC Result is located on ADCH[7-0] and ADCL[3-0]. If ADCFM = 0, the valid ADC Result is located on ADCH[3-0] and ADCL[7-0].

ADCL (0xBAh) ADC Result Register Low Byte RO (0xXX)

	7	6	5	4	3	2	1	0
RD	ADCL[7-0]							
WR	-							

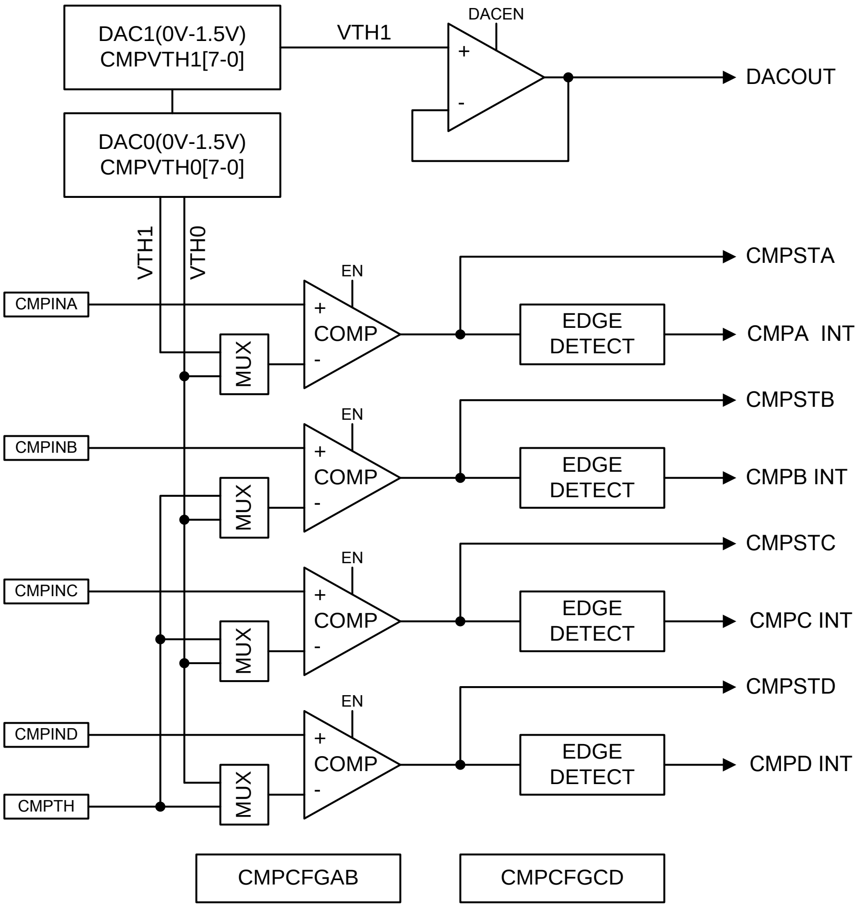
ADCH (0xBBh) ADC Result Register High Byte RO (0xXX)

	7	6	5	4	3	2	1	0
RD	ADCH[7-0]							
WR	-							

13. Analog Comparators (ACMP) and 8-bit DAC

There are four analog comparators as its on-chip external peripherals. When enabled, each comparator consumes about 250uA. The input signal range is from 0 to VDD. There are two 8-bit R-2R DAC associated with the comparators to generate the compare threshold. The R-2R DAC uses the internal 1.5V supply as the full-scale range thus limiting the comparator threshold from 0V to 1.5V in 256 steps. Comparator A can select either VTH0 or VTH1 as the threshold. Comparator B/C/D can also select between VTH0 and external threshold. VTH1 is also sent to a unity gain buffer for use an DAC output. The buffer can supply or sink up to 150uA. Individual comparator when enabled consumes about 80uA/each, and the unity gain buffer consumes about 400uA/800uA under 3V/5V supply conditions.

The CPU can read the real-time outputs of the comparator directly through register access. The output is also sent to an edge-detector and any edge transition can be used to trigger an interrupt. The stabilization time from off state to enabled state of the comparator block is about 20usec. The block diagram of the analog comparator is shown in the following diagram.



CMPCFGAB (0xA038h) Analog Comparator A/B Configuration Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	CMPENA	THSELA	INTENA	POLA	CMPENB	THSELB	INTENB	POLB
WR	CMPENA	THSELA	INTENA	POLA	CMPENB	THSELB	INTENB	POLB

CMPENA	Comparator A Enable bit. Set to enable the comparator. When CMPENA is set from 0 to 1, the program needs to wait at least 20us allowing analog bias to stabilize to ensure comparator A’s proper functionality.
THSELA	Comparator A Threshold Select bit. THSELA = 0, the comparator A uses VTH0 as the threshold. THSELA = 1, the comparator A uses VTH1 as the threshold.
INTENA	Set to enable the comparator A’s interrupt.
POLA	Channel A Output polarity control bit POLA=0 set default polarity POLA=1 reverse the output polarity of the comparator
CMPENB	Comparator B Enable bit. Set to enable the comparator.

	When CMPENB is set from 0 to 1, the program needs to wait at least 20us allowing analog bias to stabilize to ensure comparator B's proper functionality.
THSELB	Comparator B Threshold Select Bit. THSELB = 0, the comparator B uses VTH0 as the threshold. THSELB = 1, the comparator B uses external threshold.
INTENB	Set to enable the comparator B's interrupt.
POLB	Channel B Output polarity control bit POLB=0 set default polarity POLB=1 reverse the output polarity of the comparator

CMPCFGCD (0xA039h) Analog Comparator C/D Configuration Register R/W (0X00)

	7	6	5	4	3	2	1	0
RD	CMPENC	THSELC	INTENC	POLC	CMPEND	THSELD	INTEND	POLD
WR	CMPENC	THSELC	INTENC	POLC	CMPEND	THSELD	INTEND	POLD

CMPENC	Comparator C Enable Bit. Set to enable the comparator. When CMPENC is set from 0 to 1, the program needs to wait at least 20us to allow analog bias to stabilize to ensure comparator C's proper functionality.
THSELC	Comparator C Threshold Select Bit. THSELC = 0, the comparator C uses VTH0 as the threshold. THSELC = 1, the comparator C uses external threshold.
INTENC	Set to enable the comparator C interrupt.
POLC	Channel C Output polarity control bit POLC=0 set default polarity POLC=1 reverse the output polarity of the comparator
CMPEND	Comparator D Enable Bit. Set to enable the comparator. When CMPEND is set from 0 to 1, the program needs to wait at least 20us to allow analog bias to stabilize to ensure comparator D's proper functionality.
THSELD	Comparator D Threshold Select Bit. THSELD = 0, the comparator D uses VTH0 as the threshold. THSELD = 1, the comparator D uses external threshold.
INTEND	Set to enable the comparator D interrupt.
POLD	Channel D Output polarity control bit POLD=0 set default polarity POLD=1 reverse the output polarity of the comparator

CMPVTH0 (0xA03Ah) Analog Comparator Threshold Control Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	VTH0 Register							
WR	VTH0 Register							

CMPVTH0 register controls the comparator threshold VTH0 through an 8-bit DAC. When set to 0x00h, the threshold is 0V. When set to 0xFFh, the threshold is at 1.5V. When not used, it should be set to 0x00 to save power consumption.

CMPVTH1 (0xA03Bh) Analog Comparator Threshold Control Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	VTH1 Register							
WR	VTH1 Register							

CMPVTH1 register controls the comparator threshold VTH1 through 8-bit DAC. When set to 0x00h, the threshold is 0V. When set to 0xFFh, the threshold is at 1.5V. When not used, it should be set to 0x00 to save power consumption. VTH1's DAC level is also used for DAC voltage output.

CMPST (0xA03Dh) Analog Comparator Status Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	CMPIFD	CMPIFC	CMPIFB	CMPIFA	CMPSTD	CMPSTC	CMPSTB	CMPSTA
WR	CMPIFD	CMPIFC	CMPIFB	CMPIFA	FILEND	FILENC	FILENB	FILENA

CMPIFD	Comparator D Interrupt Flag bit. This bit is set when CMPSTD is toggled and the comparator D setting is enabled. This bit must be cleared by software.
CMPIFC	Comparator C Interrupt Flag bit. This bit is set when CMPSTC is toggled and the comparator C setting is enabled. This bit must be cleared by software.
CMPIFB	Comparator B Interrupt Flag bit. This bit is set when CMPSTB is toggled and the comparator B setting is enabled. This bit must be cleared by software.
CMPIFA	Comparator A Interrupt Flag bit. This bit is set when CMPSTA is toggled and the comparator A setting is enabled. This bit must be cleared by software.
CMPSTD	Comparator D Real-time Output. If the comparator is disabled, this bit is forced low.
CMPSTC	Comparator C Real-time Output. If the comparator is disabled, this bit is forced low.
CMPSTB	Comparator B Real-time Output. If the comparator is disabled, this bit is forced low.
CMPSTA	Comparator A Real-time Output. If the comparator is disabled, this bit is forced low.
FILEND	Comparator D Digital Filter Enable. Filter is 16 SYSCLK.
FILENC	Comparator C Digital Filter Enable. Filter is 16 SYSCLK.
FILENB	Comparator B Digital Filter Enable. Filter is 16 SYSCLK.
FILENA	Comparator A Digital Filter Enable. Filter is 16 SYSCLK.

DACCFG (0xA03Ch) Analog Comparator Status Register R/W (0x00)

	7	6	5	4	3	2	1	0
RD	DACEN	VDDCCMPA	DACTEST	-	CMPHYSD	CMPHYSC	CMPHYSB	CMPHYSA
WR	DACEN	VDDCCMPA	DACTEST	-	CMPHYSD	CMPHYSC	CMPHYSB	CMPHYSA

DACEN	DAC Enable DACEN=1 turns on the DAC output buffer. DACEN=0 turns off the output buffer
VDDCCMPA	Force CMPINA as VDDC. VDDCCMPA = 1, connect CMPINA to VDDC. This is for testing purpose only. By connecting VDDC to CMPINA and GPIO ANIO switch, VDDC is exposed on GPIO pin so testing and trimming of VDDC can be done.
DACTEST	DAC/ADC Test Mode DACTEST=1 connect DACOUT to ADC's CHB input internally. This needs software to perform DAC output and ADC conversion.
CMPHYSD	Comparator D Hysteresis Disable CMPHYSD = 1 disables the hysteresis of Comparator D CMPHYSD = 0 enables the hysteresis (typical 10mV) of Comparator D.
CMPHYSC	Comparator C Hysteresis Disable CMPHYSC = 1 disables the hysteresis of Comparator C CMPHYSC = 0 enables the hysteresis (typical 10mV) of Comparator C.
CMPHYSB	Comparator B Hysteresis Disable CMPHYSB = 1 disables the hysteresis of Comparator B CMPHYSB = 0 enables the hysteresis (typical 10mV) of Comparator B.
CMPHYSA	Comparator A Hysteresis Disable CMPHYSA = 1 disables the hysteresis of Comparator A CMPHYSA = 0 enables the hysteresis (typical 10mV) of Comparator A.

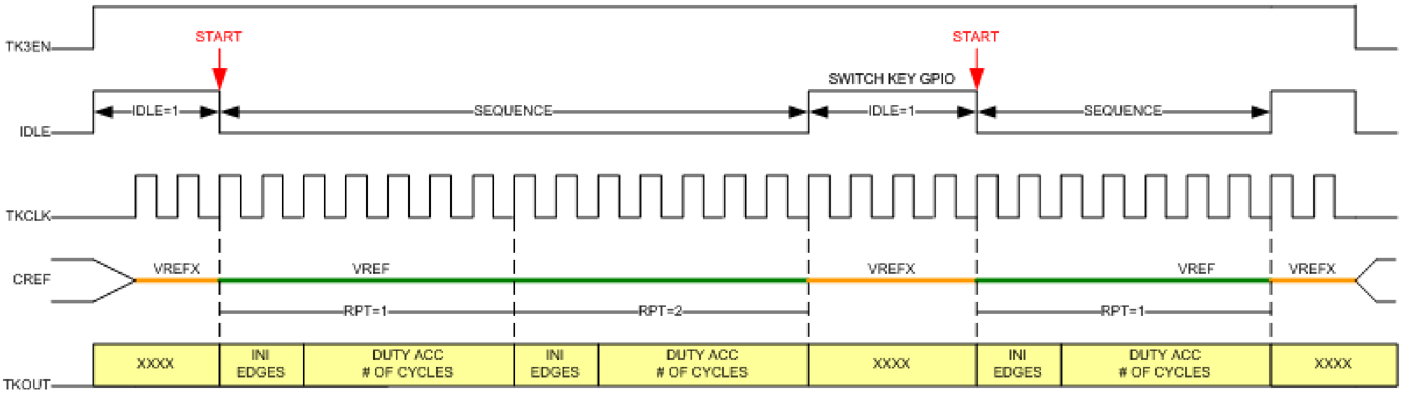
14. Touch Key Control III

TK3 is an enhanced TK2 implementation with differential dual slope operations. The capacitance to time conversion goes through two phase of charge transfer, one is charging up and one is discharging down using two thresholds equally spaced from ½ VDDC. Each charge transfer is obtained by subtraction of charge on internal reference capacitance and key capacitance. The difference of charge/discharge counting behavior is used to determine the key capacitance change in ratio of internal capacitance. Better noise immunity from power and ground noise and common-mode noise is achieved by dual slope operation. Better S/N can also be achieved because only differential charge is used for transfer, and the internal capacitance exhibits better temperature and environmental stability making the conversion result less sensitive to these changes.

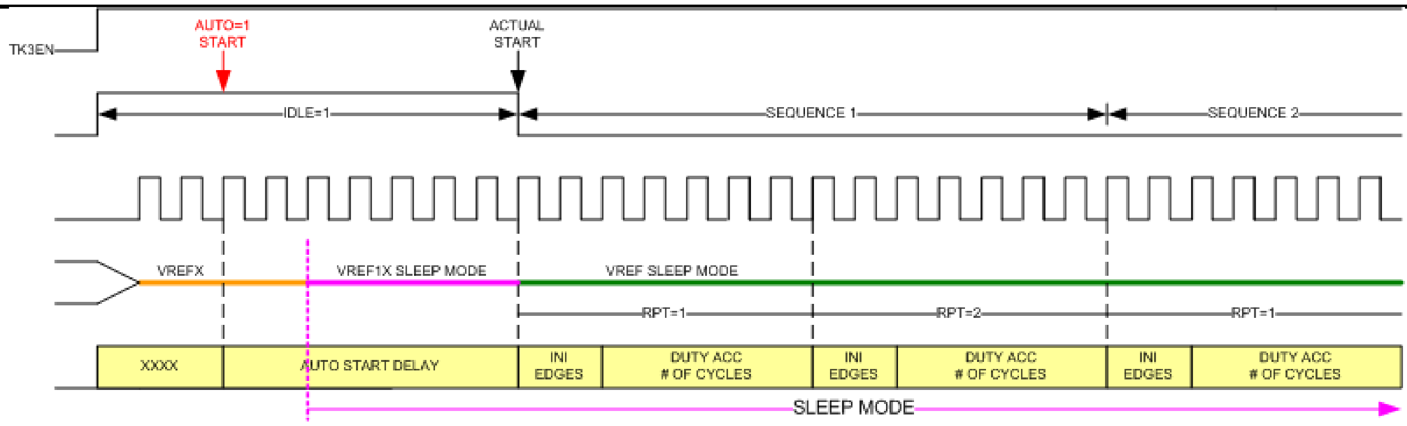
CREF, the integration capacitor of the charge transfer, is connected to P00 through ANIO multiplexer and CKEY is connected to other GPIO through multiplexer. A replica signal of CKEY is provided through a buffer and routed out as SHIELD through GPIO. The shield signal can be used to cancel mutual capacitance effect from neighboring signal trace of the detected key and provides better noise immunity against moisture or water.

To detect a key press, the duty count value TKLDT[15-0] or TKHDT[15-0] can be processed by software and compare with an average non-press duty count. The hardware can also be configured to auto repeat accumulations of the duty cycle count to filter the sporadic noise effect. Since the comparator output should be a random duty with average equals to the capacitance ratio, for low frequency noise rejection, the hardware can be set to reject a continuous high or low comparator output that exceed long durations. For high frequency noise rejection, the hardware includes a pseudo-random sequence that randomizes the charge and discharge timing sequences. A slow moving average of the duty count value is stored in TKBASE[15-0] and software can use this for baseline calculation to auto compensate environment change.

Issuing a START command in the TK3CFGD register starts a conversion sequence that accumulates the comparator output into count value. The count value and the total number of the cycle of the sequence can then be calculated to obtain the capacitance of the key. The timing diagram of the TK3 in normal operation is shown in the following diagram. CREF is first equalized to VREFX that is in close range of VREF. When a START command is issued, first few edges of the comparator output is ignored to avoid any noise caused by the VREFX switching. And then the compactor output is accumulated into DTYL and DTYH registers. A sequence can consist of several conversion cycles depending on the RPT setting, and DTYL and DTYH maintains accumulation to obtain higher resolutions. After the sequence completed, CREF is also connected to VREFX to stay ready for next sequence to start.



TK3 can be set into low power auto detect mode by setting AUTO bit in TK3CFGA. In this mode, an ultra-low power comparator is used and the clock for TK3 should be set to SOSC/2 (64KHz). This mode can be used specifically for touch key wakeup during the MCU sleep mode. The total power consumption of TK3 in this mode is less than 5uA. A threshold register can be set to determine the auto detect threshold either in absolute value or relative value versus the slow-moving baseline value. When the duty count value exceeds the threshold value, a wakeup and interrupt is generated to CPU. The timing diagram for auto mode detection and entering into SLEEP mode is shown in the following diagram. Note the actual start of the sequence is delayed by AUTO START DELAY setting. This allows the internal VDDC to stabilize from switching normal mode to sleep mode supply regulators.



TK3CFGA (0xA018h) TK3 Configuration Register A R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TK3EN	TKCS[2-0]			SHIELDEN	TKIEN	TKLPM	AUTO
WR	TK3EN	TKCS[2-0]			SHIELDEN	TKIEN	TKLPM	AUTO

TK3EN — TK3 Enable
TK3EN=0 Disables the TK3 circuits and clear all states
TK3EN=1 for TK3 normal operations.

TKCS[2-0] — TK3 Clock Select

TKCS[2-0]=000	SYSCLK/2
TKCS[2-0]=001	SYSCLK/4
TKCS[2-0]=010	SYSCLK/6
TKCS[2-0]=011	SYSCLK/8
TKCS[2-0]=100	SYSCLK/10
TKCS[2-0]=101	SYSCLK/16
TKCS[2-0]=110	SYSCLK/32
TKCS[2-0]=111	SOSC/2

SOSC/2 should be used for sleep mode auto wakeup. Typical SOSC/2 is 64KHz.

SHIELDEN — Shield Output Buffer Enable
SHIELDEN=1 enables the shield signal buffer. The buffer consumes about 200uA when enabled.

TKIEN — TK3 Interrupt Enable
TKIEN=1 enables the TK3 interrupt. TK3 interrupt is generated when a counting sequence is completed (including the repeat count if RPT[1-0] is not 00). Interrupt and wakeup is also generated when TKIEN=1 and AUTO=1 after auto detection threshold is met.
When TK3 interrupt is generated, TKIF is also set to 1 by hardware.

TKLPM — TK3 Low Power Mode
TKLPM=0 for normal mode operations.
TKLPM=1 put the comparator into ultra low power mode and should be used in auto wakeup power saving mode. In this mode, TKCLK should use SOSC/2 (64KHz) slow clock.

AUTO — Auto Wake Up Mode
AUTO=1 enables auto detect mode. In auto mode, the current duty count register value is compared with baseline plus threshold (either absolute or relative). If duty count value is higher then an interrupt and wakeup is generated.
AUTO=0 enable normal detect mode. In normal mode, writing START with “1” initiates a conversion sequence, and when the duty count is obtained, an interrupt is generated.

TK3CFGB (0xA019h) TK3 Configuration Register B R/W (0x00)

	7	6	5	4	3	2	1	0
RD	RPT[1-0]		INI[1-0]		ASTDLY[1-0]		LFNF[1-0]	
WR	RPT[1-0]		INI[1-0]		ASTDLY[1-0]		LFNF[1-0]	

RPT[1-0] — Repeat Sequence Count
00 = No Repeat

	01 = 4 times 10 = 8 times 11 = 16 times
INI[1-0]	Initial Settling Delay INI[1-0] defines the number of TKCLK period for initial settling of CREF. The delay is set to (INI[1-0] + 1) *4*TKCLK.
ASTDLY[1-0]	Auto Mode Start Delay STDLY[1-0] inserts an inter-sequence idle time of (ASTDLY[1-0]+1) * 256 TKCLK at each sequence start. Tis delay allows the stabilization time of VREFX from normal mode to sleep mode.
LFNF[1-0]	Low Frequency Noise Filter Setting 00 = disables LFNF Noise injection longer than LFNF[1-0]*8 time is ignored. **Please note in the presence of such noise, the cycle count still continues. The end result is that the sum of DUTYL and DUTYH will not be equal to cycle count.**

TK3CFGC (0xA01Ah) TK3 Configuration Registers C R/W (0x00)

	7	6	5	4	3	2	1	0
RD	SLOW[1-0]		CYCLE[2-0]			BASEINI	THDSEL	AUTOLFEN
WR	SLOW[1-0]		CYCLE[2-0]			BASEINI	THDSEL	AUTOLFEN

SLOW[1-0]	Baseline Slow Moving Average setting 00 = 32 average 01 = 64 average 10 = 128 average 11 = 256 average The duty value is averaged by SLOW[1-0] conversion and updated to BASELINE register through moving average.
CYCLE[2-0]	Cycle Count of each conversion sequence 000 = 1024 001 = 2048 010 = 4096 011 = 8192 100 = 12288 101 = 16384 110 = 32768 111 = 65536 The cycle count is each sequence cycle count. And it is repeated if RPT is not 0. **Please note the conversion always ends with the defined cycle count.**
BASEINI	Baseline Initial Value If BASEINI=1, then the first DTYL count after entering auto mode is loaded to BASELINE register as its initial value to start moving average. If BASEINI=0, then the value written in BASELINE before entering auto mode is used as the initial value to start moving average.
THDSEL	Threshold Value Setting THDSEL=0 uses TKTHD[15-0] as the threshold to compare with DTYL to generate the interrupt and wakeup THDSEL=1 uses TKTHD[15-0] + TKBASE[15-0] as the threshold.
AUTOLFEN	Low Frequency Noise Filtering in Auto mode If AUTOLFEN=0, then low frequency noise filtering in Auto mode is disabled. If AUTOLFEN=1, then low frequency noise filtering in auto mode is enabled. The low noise filtering status flag is still valid regardless of AUTOLFEN setting. Software can determine if to discard the current conversion result by checking LFNF flag.

TK3CFGD (0xA01Bh) TK3 Configuration Registers D R/W (0x00)

	7	6	5	4	3	2	1	0
RD	CCHG[2-0]			ASTDLYEN	PSRDEN	LFNF	TKIF	BUSY
WR	CCHG[2-0]			ASTDLYEN	PSRDEN	LFNF	TKIF	START

CCHG[2-0] Charge Capacitance Select
000 = 10pF
001 = 20pF
010 = 30pF
011 = 40pF
100 = 50pF
101 = 60pF
110 = 70pF
111 = 80pF

ASTDLYEN Auto Start Delay Enable
ASTDLYEN=1 enables ASTDLY[1-0] delay start for auto mode.
ASTDLYEN=0 disables ASTDLY[1-0] delay.

PSRDEN Pseudo Random Sequence Enable
PSRDEN=1 enables the random sequence in conversion
PSRDEN=0 disables

LFNF Low Frequency Noise Detection Flag
LFNF is set by hardware if in the present conversion a Low Frequency Noise is detected. LFNF needs to be cleared to “0” by software

TKIF TK3 Interrupt Flag
TKIF is set by hardware when a TK3 interrupt occurred by either conversion sequence completed or a valid detection in auto mode. TKIF needs to be cleared to “0” by software.

START Start Conversion
Writing “1” into START initiates the conversion sequence. It is cleared by hardware when conversion is complete. Please not writing AUTO “1” also starts the conversion in auto mode.

BUSY Conversion Status
BUSY is set to 1 by hardware indicating the conversion sequences are still running.

TK3HDTYL (0xA01Ch) TK3 High Duty Count Register L RO (0x00)

	7	6	5	4	3	2	1	0
RD	TK3HDTY[7-0]							
WR	-							

TK3HDTYH(0xA01Dh) TK3 High Duty Count Register H RO (0x00)

	7	6	5	4	3	2	1	0
RD	TK3HDTY[15-8]							
WR	-							

TK3LDTYL (0xA01Eh) TK3 Low Duty Count Register L RO (0x00)

	7	6	5	4	3	2	1	0
RD	TK3LDTY[7-0]							
WR	-							

TK3LDTYH(0xA01Fh) TK3 Low Duty Count Register H RO (0x00)

	7	6	5	4	3	2	1	0
RD	TK3LDTY[15-8]							
WR	-							

TK3BASEL (0xA028h) TK3 Baseline Register L R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TK3BASE[7-0]							
WR	TK3BASE[7-0]							

TK3BASEH (0xA029h) TK3 Baseline Register H R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TK3BASE[15-8]							
WR	TK3BASE[15-8]							

TK3THDL (0xA02Ah) TK3 Threshold Register L R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TK3THD[7-0]							
WR	TK3THD[7-0]							

TK3THDH (0xA02Bh) TK3 Threshold Register H R/W (0x00)

	7	6	5	4	3	2	1	0
RD	TK3THD[15-8]							
WR	TK3THD[15-8]							

TK3PUD (0xA02Ch) TK3 DC Pull-Up/Pull-Down Control Register H R/W (0x00)

	7	6	5	4	3	2	1	0
RD	PUDIEN	PUDREN	-	-	PUD[3-0]			
WR	PUIDEN	PUDREN	-	-	PUD[3-0]			

TK3PUD is to configure a constant DC pull-up/pull-down on CREF to allow high capacitance touch-key detection. A DC pull-up/pull-down can compensate the equivalent resistance caused a high capacitance key. Connecting a switching current source or resistor can thus maintaining touch key detection sensitivity.

PUDIEN	Pull-up/Pull-down DC Current Enable
PUDREN	Pull-up/Pull-down DC Resistor Enable
PUD[3-0]	Pull-up/Pull-down Selection For DC current, PUD[3-0] enables 8uA/4uA/2uA/1uA current source. For Resistor, PUD[3-0] enables 5K/10K/20K/40K resistor.

15. GPIO Multi-Function Select and Pin Interrupt

Each IO pin has configurable IO buffer that can meet various interface requirement. The GPIO pins can be configured as external pin interrupt input or for wakeup purpose. Each port has edge detection logic and latch for rising and falling edge detections. During hardware reset and after, the IO buffer is put in high impedance state with all drive disabled.

IOCFGOxx(0xA100h – 0xA10Fh) IO Buffer Output Configuration Registers R/W (0x00) (xx = 00~07, 10~17)

	7	6	5	4	3	2	1	0
RD	-	PDRVEN	NDRVEN	OPOL	ANEN2	ANEN1	PUEN	PDEN
WR	-	PDRVEN	NDRVEN	OPOL	ANEN2	ANEN1	PUEN	PDEN

PDRVEN Output PMOS driver enable. Set this bit to enable the PMOS of the output driver. DISABLE is the default value.

NDRVEN Output NMOS driver enable. Set this bit to enable the NMOS of the output driver. DISABLE is the default value.

OPOL Output Polarity Control
Output buffer data polarity control.

ANEN1 Analog MUX 1 enables control. Set this bit to connect the pin to the internal analog peripheral. DISABLE is the default value.

ANEN2 Analog MUX 2 enables control. Set this bit to connect the pin to the internal analog peripheral. DISABLE is the default value.

PUEN Pull up resistor control. Set this bit to enable pull-up resistor connection to the pin. The pull-up resistor is approximately 6K Ohm. DISABLE is the default value.

PDEN Pull down resistor control. Set this bit to enable pull-down resistor connection to the pin. The pull-down resistor is approximately 6K Ohm. DISABLE is the default value.

IOCFGI xx(0xA110h – 0xA11Fh) IO Buffer Input Configuration Registers R/W (0x00) (xx = 00~07, 10~17)

	7	6	5	4	3	2	1	0
RD	PI1EN	PI0EN	RIF	FIF	INEN	IPOL	DSTAT	INSTAT
WR	PI1EN	PI0EN	RIEN	FIEN	INEN	IPOL	DBN[1-0]	

PI1EN Pin Interrupt 1 Enable

PI0EN Pin Interrupt 0 Enable

RIEN Rising Edge Pin Interrupt Enable

RIF Rising Edge Pin Interrupt Flag
RIF is set to 1 by hardware after either a PI1 or PI0 rising edge interrupt has occurred. RIF must be cleared by software writing RIEN with "0". RIEN needs to be enabled if next rising edge interrupt is required.

FIEN Falling Edge Pin Interrupt Enable

FIF Falling Edge Pin Interrupt Flag
FIF is set to 1 by hardware after either a PI1 or PI0 falling edge interrupt has occurred. FIF must be cleared by software writing FIEN with "0". FIEN needs to be enabled if next falling edge interrupt is required.

INEN Input Buffer Enable
INEN=1 enables the input buffer.
INEN=0 disables the input buffer. In the disabled state, the output of input buffer is logic 0. If input is floating or not solid 0 and 1 voltage level, DC current may flow in the input buffer. Disabling input buffer can remove DC leakage of input buffer due to this reason.

IPOL Input Polarity
IPOL=1 reverse the input logic. IPOL=0 for normal logic polarity.

DBNST Real Time Status after De-bounce. DBNST is read only.
Please note the de-bounced input is used for generating interrupt, as well as all other multi-function inputs including PORT registers. The non-debounced input can only be read through INSTAT bit.

INSTAT Real Time Status of Input Buffer. INSTAT is read only.

DBN[1-0] De-Bounce Time Setting
00 – OFF
01 – 4 SOSC/4 (130usec)

10 – 16 SOSC/4 (530usec)
11 – 64 SOSC/4 (2msec)

MFCFGxx (0xA120 – 0x A12Fh) Port Multi-Function Configuration Registers R/W (0x00) (xx = 00~07, 10~17)

	7	6	5	4	3	2	1	0
RD	MFCFG[7-0]							
WR	MFCFG[7-0]							

Please see PIN OUT section for description of each port multi-function selection.

16. Information Block IFB

There are two IFB block each contains 512 x 16 bit information. The address 0x000h to 0x03Fh in first IFB is used to store manufacturer information. Address 0x040 is for boot code wait time, and 0x041 to 0x043 are used for boot code. The first IFB can be erased only in Writer Mode and can be written using Flash Controller for address beyond 0x40. This is to protect any alteration of the manufacturing and calibration data. The 2nd IFB is open for erase/write for user access. The following table shows the contents of the first IFB for the manufacturing data. Please note, these are in lower LSB bytes. The upper MSB byte contains its corresponding ECC code.

ADDRESS	TYPE	DESCRIPTION
00 – 01	M	IFB Version
02 – 07	M	Product Name
08 - 09	M	Package and Product Code
0A – 0B	M	Product Version and Revision
0C	M	Flash Memory Size
0D	M	SRAM Size
0E – 0F	M	Customer Specific Code
10	M	CP1 Information
11	M	CP2 Information
12	M	CP3 Version
13	M	CP3 BIN
14	M	FT Version
15	M	FT BIN
16 - 1B	M	Last Test Date
1C – 1D	M	Boot Code Version
1E	M	Boot Code Segment
1F	M	Checksum for 0x00 – 0x1E
20	M	REGTRM value for 1.5V
21	M	IOSC ITRM value for 16MHz
22	M	IOSC VTRM value for 16MHz
23	M	LVDTHD value for detection of 4.0V
24	M	LVDTHD value for detection of 3.0V
25	M	IOSC ITRM value for 32MHz
26	M	IOSC VTRM value for 32MHz
27	M	Reserved
28	M	Reserved
29	M	Reserved
2A	M	Reserved
2B – 2C	M	Temperature Offset LSB/MSB
2D	M	Temperature Coefficient
2E – 2F	M	Internal Reference LSB/MSB
30		SOSC 128KHz Trim
31 – 38	M	Reserved
39	M	Checksum for 0x20 – 0x39
3A – 3F	M	Retention Value
40	M/U	Boot Code Wait Time. Boot code uses this byte to determine the ISP wait-time. This wait-time is necessary for stable ISP. After user program download, the wait time can be reduced to minimize power-on time. Each “1” in bit [1-0] constitutes 1 second and bits [3-2] constitutes 2 second and bits [7-6] are I2CSCL2 and I2CSCL1 check. For example, 0b10000111 is 4 second wait time and also checks I2CSCL2 pad status. If I2CSCL2 is low, then wait time of 6 second is used regardless of bit [3-0] setting. The maximum wait time is 6 second, and minimum wait time is 0 second.

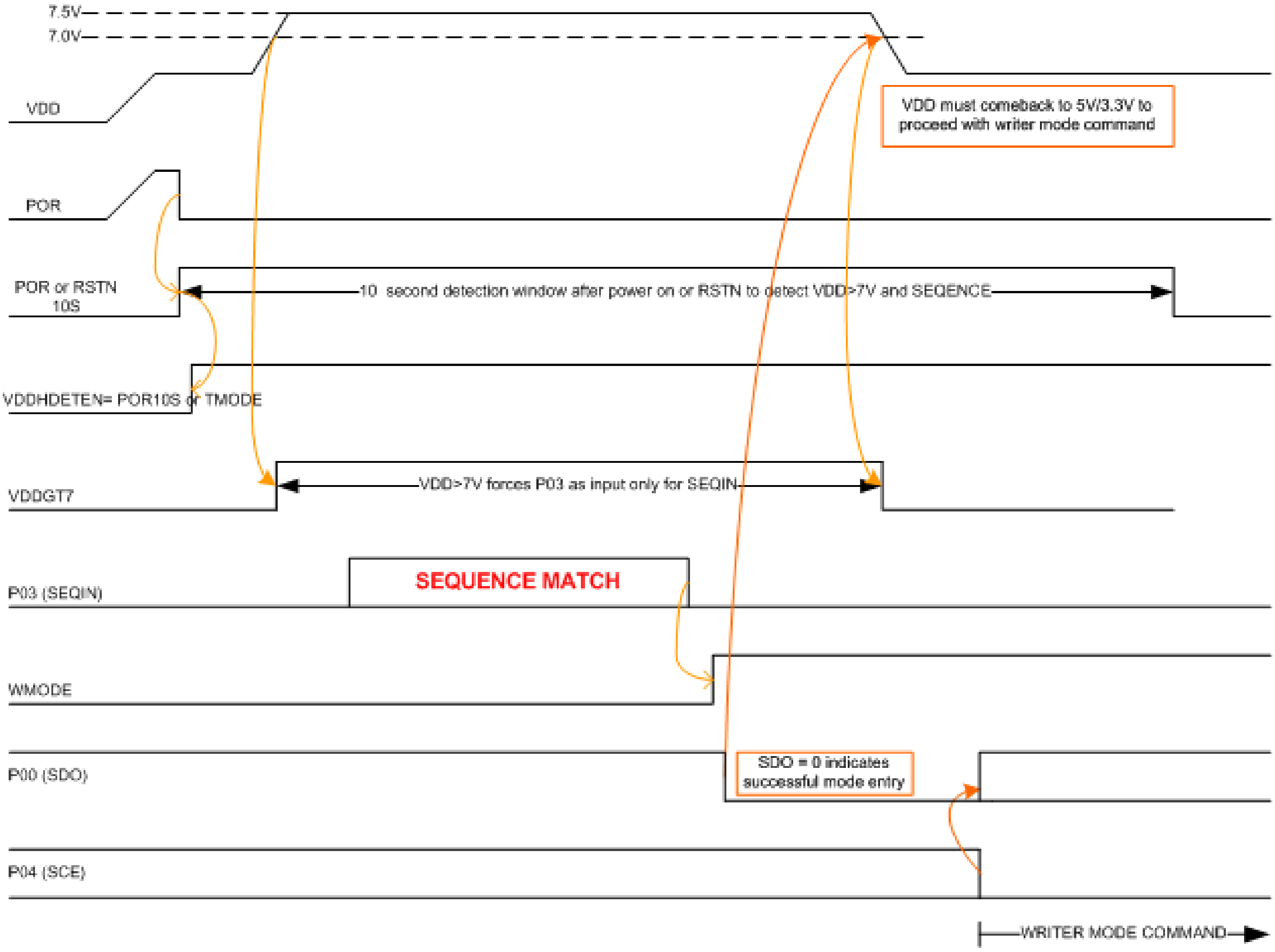
41	M/U	Boot Code LVR
42	M/U	User Code Protect L
43	M/U	User Code Protect H
44 - 1FF	U	User One-Time Programmable Space

17. Writer Mode

Writer Mode (WM) is used by the manufacturer or by users to program the flash (including IFB) through a dedicated hardware (Writer or Gang Writer). There are several pins involved for WM as shown in the following table. Please note these pins are also used for test mode such as scan test, MBIST, and trim test.

PIN	IO	Description	Function
P00	O	Serial data out	SDO
P01	I	Serial clock input	SCK
P02	O	Flash TBIT signal output	TBIT
P03	I	Serial data in and sequence in	SEQIN
P04	I	Serial port enable, low active	SCE
VDD	I	Power supply for DUT and Disable P03 Output when VDD > 7.0V	VDD
VSS	I	Ground supply for DUT	VSS

To enter into WM, a predefined sequence must be present at SDI (SEQIN) pin within 10 second of power on or RSTN reset. The following timing diagram shows the waveform relationship.



1. After power-on reset or RSTN reset, a 10-second window is open for SEQIN buffer and detection comparator for VDD>7V.
2. If VDD>7V is detected, it forces P03 to tri-state output and allows SEQIN buffer to detect entry sequence. **If P03 is not configured by user program as output, then VDD>7V is not necessary (but always recommended).**
3. If a correct sequence is detected, the WMODE internal signal is asserted and this also enables SDO pull-down to low to acknowledge Writer hardware for successful entry.

4. Writer hardware upon receiving acknowledgement should bring down VDD to normal value (either 5V or 3.3V) to proceed with writer mode commands.
5. Writer hardware should have all writer mode related pins 10K pull-up resistor to its supply voltage (either 5V or 3.3V).

Once successful mode entry is completed, since there are code protection mechanism against code piracy, the protection must first unlocked to fully utilize the writer mode commands. Before unlocking, only full memory erase command is supported. Unlocking is accomplished by READ AND VERIFY Main Memory command with correct lock key (8-byte) of the key addresses. The following lists the writer mode commands. The red indicates the command available in locked state.

ERASEMM - ERASE Main Memory

ERASEMMIFB - ERASE Main Memory and IFB

READVERIFYMM - READ AND VERIFY Main Memory (8-Byte)

WRTEBYTEMM - WRITE BYTE Main Memory

READBYTEMM – READ BYTE Main Memory

WRITEBYTEIFB – WRITE BYTE IFB

READBYTEIFB - READ BYTE IFB

FCWRITE - Fast Continuous WRITE

FCREAD - Fast Continuous READ

The default state of the device is locked writer mode. Only ERASEMM and ERASEMMIFB, and READVERIFYMM commands can be executed. It can be unlocked by READVERIFYMM the range of 0x2FF8 to 0x2FFF. These locations contain an 8-byte security key that user can place to secure the e-Flash contents. The probability of guessing the key is 1 in 2^64 = 1.8E19. Since each trial of READVERIFY takes 10usec, it takes about 6E6 years to exhaust the combinations. If the key is unknown, a user can choose to issue the ERASEMM command then fully erase the entire contents (including the key). Once fully erased, all data in the flash is 0xFF, and it can be successfully unlocked by READVERIFYMM with 8-bytes of 0xFF. The users must not erase the information in IFB. And the user should not modify the manufacturer data. Any violation of this results in the void of manufacturer warranty.

18. Boot Code and In-System Programming

After production testing of the packaged devices, the manufacture writes the manufacturer information and calibration data in the IFB. At the last stage, it writes a fixed boot-code in the main memory residing from 0x3000 to 0x3FFF. The boot code is executed after any resets. The boot code first reads IFB's wait time setting and scan the I^2C slave for any In-System-Programming request during the wait time duration. If any valid request occurs during the scan, the boot-code proceeds to follow the request and performs the programming from the host. Otherwise, the boot code jumps to 0x0000 at wait time expiration. The default ISP commands available are

UNLOCK

DEVICE NAME

BOOTC VERSION

READ AND VERIFY Main Memory (8-Byte)

ERASE Main Memory excluding Boot Code

ERASE SECTOR Main Memory

WRITE BYTE Main Memory

SET ADDRESS

CONTINUOUSE WRITE

CONTINUOUS READ

READ BYTE IFB

WRITE BYTE IFB

Similar to writer mode, ISP is in default locked state. No command is accepted under locked state. To unlock the ISP, an 8-byte READVERIFY of 0x2FF8 to 0x2FFF must be successfully executed. Thus default ISP boot program provides similar code security as the Writer mode.

19. Electrical Specifications

19.1 Absolute Maximum Ratings

SYMBOL	PARAMETER	RATING	UNIT	NOTE
VDD	Supply Voltage	5.5	V	
TA	Ambient Operating Temperature	-40 –125	°C	
TSTG	Storage Temperature	-65 – 150	°C	

19.2 Recommended Operating Condition

SYMBOL	PARAMETER	RATING	UNIT	NOTE
VDD	Supply Voltage for IO and 1.5V regulator	2.35 – 5.5	V	
TA	Ambient Operating Temperature	-40 – 85	°C	

19.3 DC Electrical Characteristics (VDDH = 2.35V to 5.5V TA=-40°C to 85°C)

SYMBOL	PARAMETER	MIN	TYP	MAX	UNIT	NOTE
Power Supply Current						
IDD Normal	Total IDD through VDD at 16MHz Peripherals off	-	5	-	mA	
IDD Normal	Total IDD through VDD at 1MHz Peripherals off	-	1.0	-	mA	
IDD versus Frequency	IDD Core Current versus Frequency	-	150	-	uA/ MHz	
IDD, Stop	IDD, stop mode	-	150	-	µA	Main regulator on
IDD, Sleep	IDD, sleep mode, 25°C	-	1.5	5	µA	Main regulator off
	IDD, sleep mode, 85°C	-	4	10	µA	Main regulator off
	IDD, sleep mode, 125°C	-	15	40	µA	Main regulator off
RSTN Reset						
VIHRS	Input High Voltage, reference to VDD	-0.8	-	-	V	
VILRS	Input Low Voltage	-	-	0.8	V	
VRSHYS	RSTN Hysteresis	-	1.2	-	V	
GPIO DC Characteristics						
VOH,4.5V	Output High Voltage 1 mA	-	-0.2	-0.5	V	Reference to VDD
VOH,4.5V	Output High Voltage 2 mA	-	-0.3	-0.7	V	Reference to VDD
VOL,4.5V	Output Low Voltage 4 mA	-	0.2	0.4	V	Reference to VSS
VOL,4.5V	Output Low Voltage 8 mA	-	0.3	0.5	V	Reference to VSS
VOH,3.0V	Output High Voltage 1 mA	-	-0.3	-0.6	V	Reference to VDD
VOH,3.0V	Output High Voltage 2 mA	-	-0.4	-0.8	V	Reference to VDD
VOL,3.0V	Output Low Voltage 4 mA	-	0.2	0.4	V	Reference to VSS
VOL,3.0V	Output Low Voltage 8 mA	-	0.3	0.6	V	Reference to VSS
IIOT	Total IO Sink and Source Current	-80	-	80	mA	
VIH	Input High Voltage	¾VDD	-	-	V	
VIL	Input Low Voltage	-	-	¼ VDD	V	
VIHYS	Input Hysteresis	100	300	600	mV	
RPU	Equivalent Pull-Up resistance	-	25K	-	Ohm	
RPU,RSTN	RSTN Pull-Up resistance	-	5K	-	Ohm	
RPD	Equivalent Pull-Down Resistance	-	25K	-	Ohm	
REQAN1	Equivalent ANIO Switch Resistance, 3.3V	-	800	-	Ohm	ANIO1 Switch
	Equivalent ANIO Switch Resistance, 5V	-	500	-	Ohm	ANIO1 Switch
REQAN2	Equivalent ANIO Switch Resistance, 3.3V	-	4K	-	Ohm	ANIO2 Switch

SYMBOL	PARAMETER	MIN	TYP	MAX	UNIT	NOTE
	Equivalent ANIO Switch Resistance, 5V	-	2.5K	-	Ohm	ANIO2 Switch
VDDC Characteristics						
VDDCN	Normal Core Voltage 1.5V (Calibrated)	1.4	1.5	1.6	V	Normal Mode
VDDCS	Sleep Core Voltage 1.5V	-	1.42	-	V	Sleep Mode
Low Supply (VDD) Voltage Detection						
VDET	Detection Range	2.0	-	4.8	V	
VDETHYS	Detection Hysteresis	-	100	-	mV	
ADC11 Characteristics						
ADCLIN	ADC Linearity, Center range	-2	0	+2	LSB	
	ADC Linearity, 0.2V to FS-0.2V	-4	0	+4	LSB	
ADCFQ	ADC Frequency	-	2	4	MHz	

19.4 AC Electrical Characteristics (VDD =2.3V to 5.5V TA=-40°C to 85/125°C)

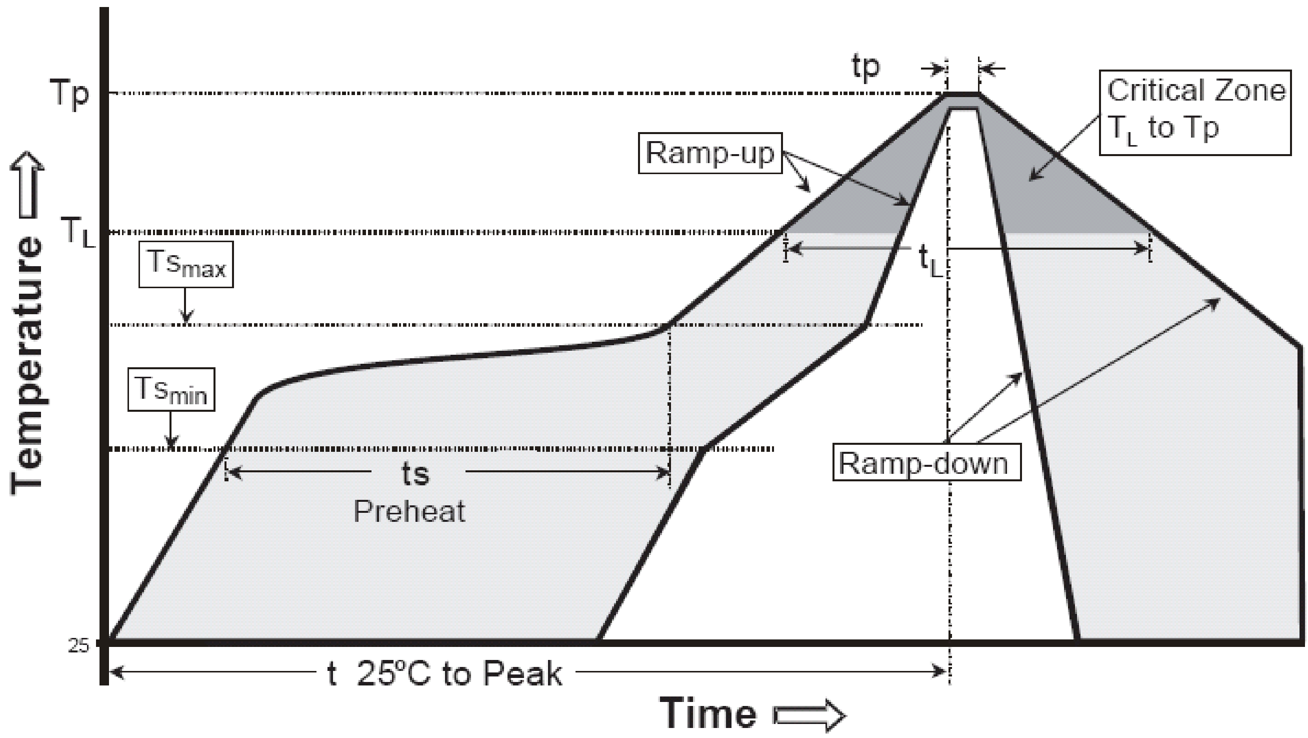
SYMBOL	PARAMETER	MIN	TYP	MAX	UNIT	NOTE
System Clock and Reset						
FSYS	System Clock Frequency	-	16	33	MHz	
FIOSC	Crystal Oscillator Frequency	5	16	25	MHz	
TSIOSC	Stable Time for IOSC after power up	2	-	-	msec	After VDD > 2.0V
Supply Timing						
TSUPRU	VDD Ramp Up time	1	-	50	msec	WST = 0 for 16MHz
TSUPRD	VDD Ramp Down Time	-	-	50	msec	
TPOR	Power On Reset Delay	-	5	-	msec	
IOSC						
FIOSC	IOSC Calibrated 16MHz/32MHz	-1	0	+1	%	
	IOSC Startup Time	-	-	1	µsec	
	Temperature and VDD variation 85°C	-2	0	+2	%	
	Temperature and VDD variation 125°C	-3	0	+3	%	
SOSC						
FSOSC	Slow Oscillator frequency	-	128	-	KHz	
IO Timing						
TPD3 ++	Propagation Delay 3.3V No load	-	6	-	nsec	
TPD3 ++	Propagation Delay 3.3V 25pF load	-	15	-	nsec	
TPD3 ++	Propagation Delay 3.3V 50pF load	-	20	-	nsec	
TPD3 --	Propagation Delay 3.3V No load	-	5	-	nsec	
TPD3 --	Propagation Delay 3.3V 25pF load	-	12	-	nsec	
TPD3 --	Propagation Delay 3.3V 50pF load	-	15	-	nsec	
TPD5 ++	Propagation Delay 3.3V No load	-	5	-	nsec	
TPD5 ++	Propagation Delay 3.3V 25pF load	-	12	-	nsec	
TPD5 ++	Propagation Delay 3.3V 50pF load	-	16	-	nsec	
TPD5 --	Propagation Delay 3.3V No load	-	4	-	nsec	
TPD5 --	Propagation Delay 3.3V 25pF load	-	9	-	nsec	
TPD5 --	Propagation Delay 3.3V 50pF load	-	12	-	nsec	
Flash Memory Timing						
TEMAC	Embedded Flash Access Time	-	40	45	nsec	TWAIT must > TEMAC
TEMWR	Embedded Flash Write Time	-	20	25	µsec	
TEMSER	Embedded Flash Sector Erase Time	-	2	2.5	msec	
TEMMER	Embedded Flash Mass Erase Time	-	10	12	msec	

CLASSIFICATION REFLOW PROFILES

Pb-Free Process-Package Classification Temperatures

Package Thickness	Volume mm3<350	Volume mm3: 350-2000	Volume mm3>2000
<1.6 mm	260ºC	260ºC	260ºC
1.6 mm-2.5 mm	260ºC	250ºC	245ºC
>=2.5 mm	250ºC	245ºC	245ºC

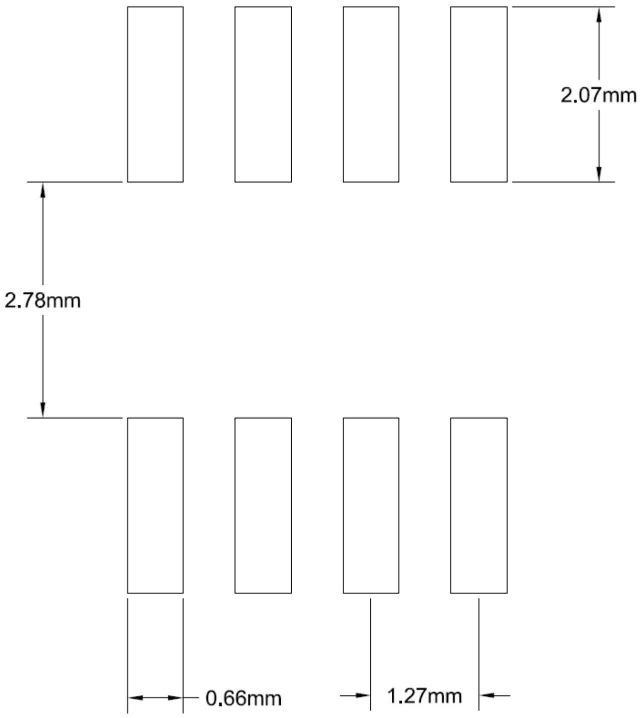
Profile Feature	Pb-Free Assembly
Ramp-Up Rate (TL to Tp)	3 ºC / second max.
Preheat – Temoperature Min (Tsmin) to Max (Tsmax)	150~200 ºC
–To,e (tsmin to tsmax)	60-120 seconds
Time maintained above – Temperature (TL)	217 ºC
– Time (tL)	60-150 seconds
Peak package body temperature (Tp)(Note 2)	See package classification
Time within 5ºC of specified classification Temperature (tp)	30 second min. (Note 3)
Ramp-Down Rate (Tp to TL)	6 ºC / second max.
Time 25 ºC to Peak Temperature	8 minutes max.
Number of applicable Temperature cycles	3 cycles max.



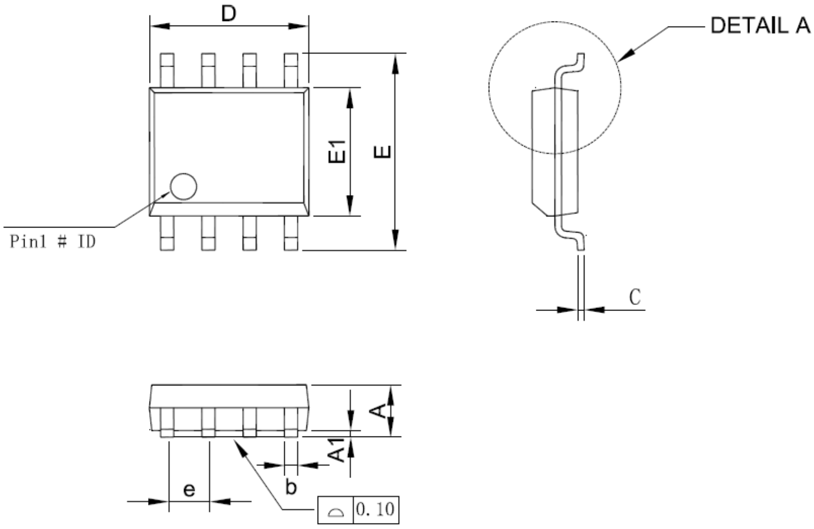
20. Packaging Outline

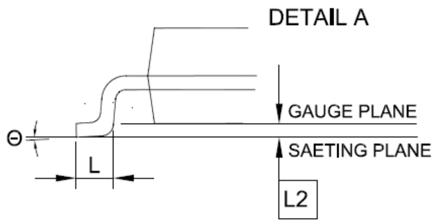
20.1 8-pin SOP

RECOMMENDED LAND PATTERN



POD





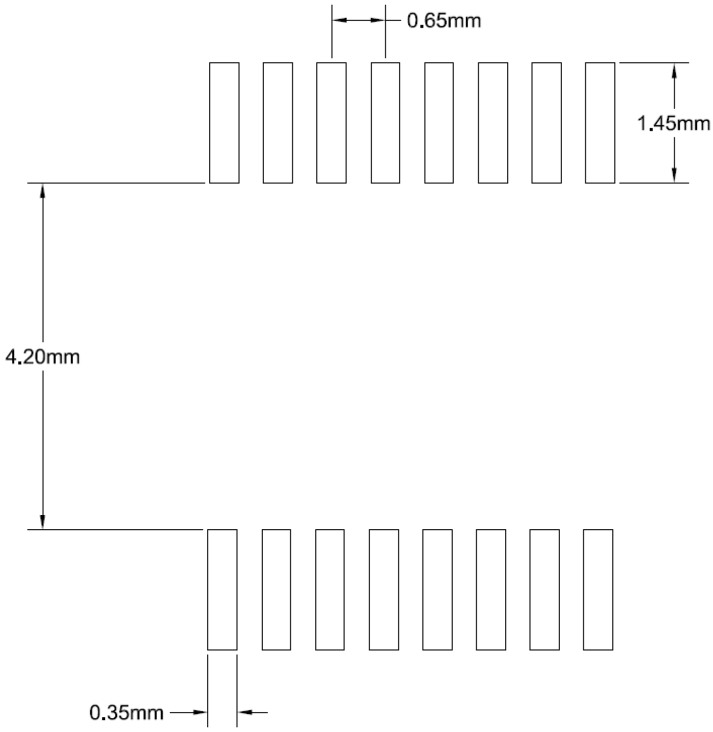
SYMBOL	MILLIMETER		
	MIN	NOM	MAX
A	–	–	1. 75
A1	0. 10	–	0. 25
E1	3. 80	3.90	4. 00
E	5. 80	6.00	6. 20
D	4. 80	4.90	5. 00
b	0. 31	–	0. 51
e	1. 27BSC		
L	0. 40	–	1. 27
L2	0. 25BSC		
θ	0°	–	8°
C	0. 10	–	0. 25

NOTE :

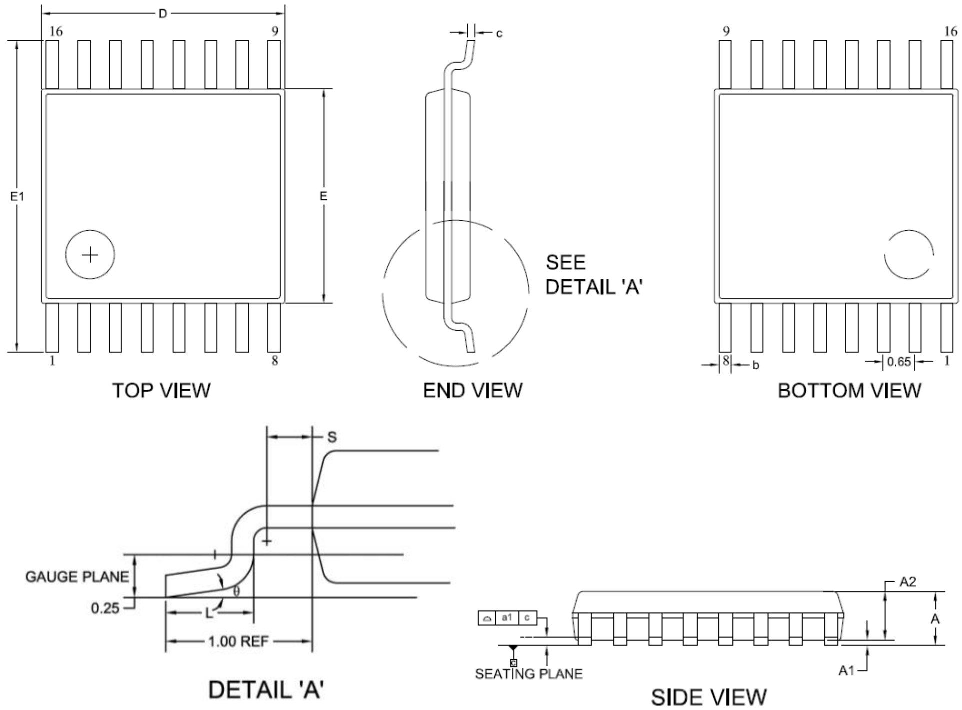
1. CONTROLLING DIMENSION : MM
2. DIMENSION D DOES NOT INCLUDE MOLD FLASH, PROTRUSIONS OR GATE BURRS.
3. DIMENSION b DOES NOT INCLUDE DAMBAR PROTRUSION.
4. REFERENCE DOCUMENT : JEDEC MS-012
5. THE SHAPE OF BODY SHOWE DIFFERENT SHAPE AMONG DIFFERENT FACTORIES.

20.2 16-pin TSSOP

RECOMMENDED LAND PATTERN



POD



SYMBOL	MILLIMETER		
	MIN	NOM	MAX
A	—	—	1. 20
A1	0.05	—	0. 15
A2	0. 80	1.00	1. 05
D	4. 90	5.00	5. 10
E	4. 30	4. 40	4. 50
E1	6. 40BSC		
L	0. 45	0. 60	0. 75
b	0. 19	—	0. 30
S	0. 20		
c	0. 09	—	0. 20
θ	0°		8°
a1	0. 10		

NOTES:

1. CONTROLLING DIMENSION: MM
2. REFERENCE DOCUMENT: JEDEC MO-153

21. Ordering Information

Temperature Range: -40°C to 85°C

Order Part No.	Package	QTY/Reel	Remark
IS31CS8975-GRLS2-TR	SOP-8, Lead-free	2500/Reel	
IS31CS8975-ZNLS2-TR	TSSOP-16, Lead-free	2500/Reel	

22. Revisions

22.1 V.020A

Modify Flash Protection zones into 2K sizes

Add Clock Monitoring and its reset, and ECC interrupt and ECC reset, in RSTCMD register

Modify SYSCLK divider max to 256. CKSEL register.

22.2 V.020B

Update Flash Controller Read ECC flag in Fail

Update TK3 CCHG[2-0]. REFSEL not used.

22.3 V.020C

Update register-map and register addresses

Add IFB, Writer mode, ISP.

Need further modifications if we change to 32Kx16.

22.4 V.021

Correct some XFR addresses and default value.

TBIT on P23.

Modify QE registers definition

Add external clock input and clock selections for compatibility on pin 5 and pin 13.

22.5 V.022

SOSC Trim 5-bit default 5'b10000

TK2 should always use VDDC as VREF.

TK3CFGD AUTODLY. Add Auto mode entry delay.

22.6 V.025

Refine TK3 operation description, timing diagram and register definition

22.7 V.026

Correct LVDTH formula and descriptions.

Add de-bounce input for all function descriptions.

Change WDT2/WDT3 default value

Change LVDCFG default value.

Change IOSCITRM IOSCVTRM default value.

Modify LIN controller's descriptions and add BER interrupt and automatically clear RX/TX state machine option.

22.8 V.027

Change PWM to 8/10/12 bit option.

Add external clock in option.

Add ADC.

22.9 V.030

SRAM ECC (1K)

Writer Mode descriptions

DAC/ADC Internal test

Add Flash ECC address registers

Modify DECC PECC register locations and description

Modify buzzer to melody generation

22.10 V.031

Add PWM SYNC control.

Remove RSTNFLTEN. Add MBISTCMD register.

22.11 V.035

Merge SDI and SEQIN into P03 for writer mode.
Clarify DECCAD address is updated when DECCIF is set.
MBIST will put CPU on hold and resume automatically.
Add time unit in buzzer and POW timer/interrupt
P04 change CC to MSDA function

22.12 V.040

Merge LBIST command into BISTCMD register using mode.
Add FLSHVDD register to control e-Flash power during sleep mode.
Modify REGRDY definition.
I2CS add double address feature.

22.13 V.045

Remove duplicate CKSEL register paragraph.
Add TK3PU register.
Modify DECCFG/DECCADL/DECCADH address, PECCCFG address.
TSTMON meaning?

22.14 V.045

TSTMON
CCDATA2, CCDATA3

22.15 V.046

Update CRC/CC description
RSTCMD default 0x00
TSSOP-8 → SOP-8

22.16 V.047

Modify some inconsistency in descriptions
Add B0 option
Add EUART1 and remove UART0.
IOSC 32M/16M options

22.17 V.048

Add ECC control for Flash Controller Read in PECCCFG bit 7.
Add sleep mode current spec

22.18 V.049

Modify SPI
Modify TK3
Modify PIN multifunction

22.19 V.050

Corrected miscellaneous errors.
Add package outline and ordering information

22.20 0A

Prepare for release.
WDT2/WDT3 pre-scale and WDT3 default SLEEP/STOP setting for B1
Wait State switch and 16M/32M for B1.

22.21 A

The first version datasheet for formal product release