

TDA38827 OptiMOS™ IPOL

25 A single-voltage synchronous Buck regulator

Features

- Single 4.3 V to 17 V application or Wide Input Voltage Range from 2.0 V to 17 V with an External VCC
- Precision Reference Voltage (0.6 V +/- 0.5%)
- Enhanced Fast COT engine stable with Ceramic Output Capacitors and No External Compensation
- Optional Forced Continuous Conduction Mode and Diode Emulation for Enhanced Light Load Efficiency
- Programmable Switching Frequency from 600 kHz to 2 MHz
- Monotonic Start-Up with Four Selectable Soft-Start Time & Enhanced Pre-Bias Start-Up
- Thermally Compensated Internal Over Current Protection with Four Selectable Settings
- Enable input with Voltage Monitoring Capability & Power Good Output
- Thermal Shut Down
- Operating Temp: $-40\text{ }^{\circ}\text{C} < T_j < 125\text{ }^{\circ}\text{C}$
- Small Size: 6 mm x 5 mm PQFN
- Halogen-free and RoHS2 Compliant with Exemption 7a

Potential applications

- Server Applications
- Storage Applications
- Telecom & Datacom Applications
- Distributed Point of Load Power Architectures

Product validation

Qualified for industrial applications according to the relevant tests of JEDEC47/20/22

Description

The TDA38827 is an easy-to-use, fully integrated dc - dc Buck regulator. The onboard PWM controller and OptiMOS™ FETs with integrated bootstrap diode make TDA38827 a small footprint solution, providing high-efficient power delivery. Furthermore, it uses a fast Constant On-Time (COT) control scheme, which simplifies the design efforts and achieves fast control response.

The TDA38827 has an internal low dropout voltage regulator, allowing operations with a single supply. It can also operate with an external bias supply, extending the operating input voltage (PVin) range.

The TDA38827 is a versatile regulator, offering programmable switching frequency from 600 kHz to 2 MHz, four selectable current limits, four selectable soft-start time, Forced Continuous Conduction Mode (FCCM) and Diode Emulation Mode (DEM) operation.

It also features important protection functions, such as pre-bias start-up, thermally compensated current limits, over voltage and under voltage protection, and thermal shutdown to give required system level security in the event of fault conditions.

Table of contents

Features	1
Potential applications	1
Product validation	1
Description	1
Table of contents	2
1 Ordering information	4
2 Functional block diagram	5
3 Typical application diagram	6
4 Pin descriptions	7
5 Absolute maximum ratings	8
6 Thermal characteristics	9
6.1 Thermal characteristics	9
7 Electrical specifications	10
7.1 Recommended operating conditions	10
7.2 Electrical characteristics	11
8 Typical efficiency and power loss curves	14
8.1 $P_{V_{in}} = V_{in} = 12\text{ V}, F_{sw} = 600\text{ kHz}$	14
8.2 $P_{V_{in}} = V_{in} = 12\text{ V}, F_{sw} = 800\text{ kHz}$	15
8.3 $P_{V_{in}} = V_{in} = 12\text{ V}, F_{sw} = 1000\text{ kHz}$	16
8.4 $P_{V_{in}} = V_{in} = V_{CC} = 5\text{ V}, F_{sw} = 600\text{ kHz}$	17
9 Thermal de-rating curves	18
10 $R_{DS(ON)}$ of MOSFET over temperature	19
11 Typical operating characteristics ($-40\text{ °C} \leq T_j \leq +125\text{ °C}$)	20
12 Theory of operation	23
12.1 Fast Constant On-Time control	23
12.2 Enable	23
12.3 FCCM and DEM operation	24
12.4 Pseudo constant switching frequency	24
12.5 Soft-start	25
12.6 Pre-bias start-up	26
12.7 Internal Low – Dropout (LDO) regulator	26
12.8 Over Current Protection (OCP)	27
12.9 Under Voltage Protection (UVP)	28
12.10 Over Voltage Protection (OVP)	28
12.11 Over Temperature Protection (OTP)	29
12.12 Power Good (Pgood) output	29
12.13 Minimum on – time and minimum off – time	30
12.14 Selection of feedforward capacitor and feedback resistors	30
12.15 Resistors for configuration pins	31
13 Design example	32
13.1 Enabling the TDA38827	32
13.2 Programming the switching frequency and operation mode	32
13.3 Selecting input capacitors	32
13.4 Inductor selection	33

Table of contents

13.5	Output capacitor selection	33
13.6	Output voltage programming.....	34
13.7	Feedforward capacitor	34
13.8	Bootstrap capacitor	34
13.9	VIN and VCC/LDO bypass capacitor.....	34
14	Application information	35
14.1	Application diagram.....	35
14.2	Typical operating waveforms	35
15	Layout recommendations	38
15.1	Solder mask.....	42
15.2	Stencil design	43
16	Package	44
16.1	Marking information	44
16.2	Dimensions	44
16.3	Tape and reel information	45
17	Environmental qualifications	46
18	Evaluation boards and support documentation	47
	Revision history.....	48

TDA38827 OptiMOS™ IPOL

25 A single-voltage synchronous Buck regulator

Ordering information

1 Ordering information

1. Ordering Information

Sales Product Name	Package Type	Standard Pack Form and Qty		Orderable Part Number
TDA38827	QFN 6 mm x 5 mm	Tape and Reel	5000	TDA38827AUMA1

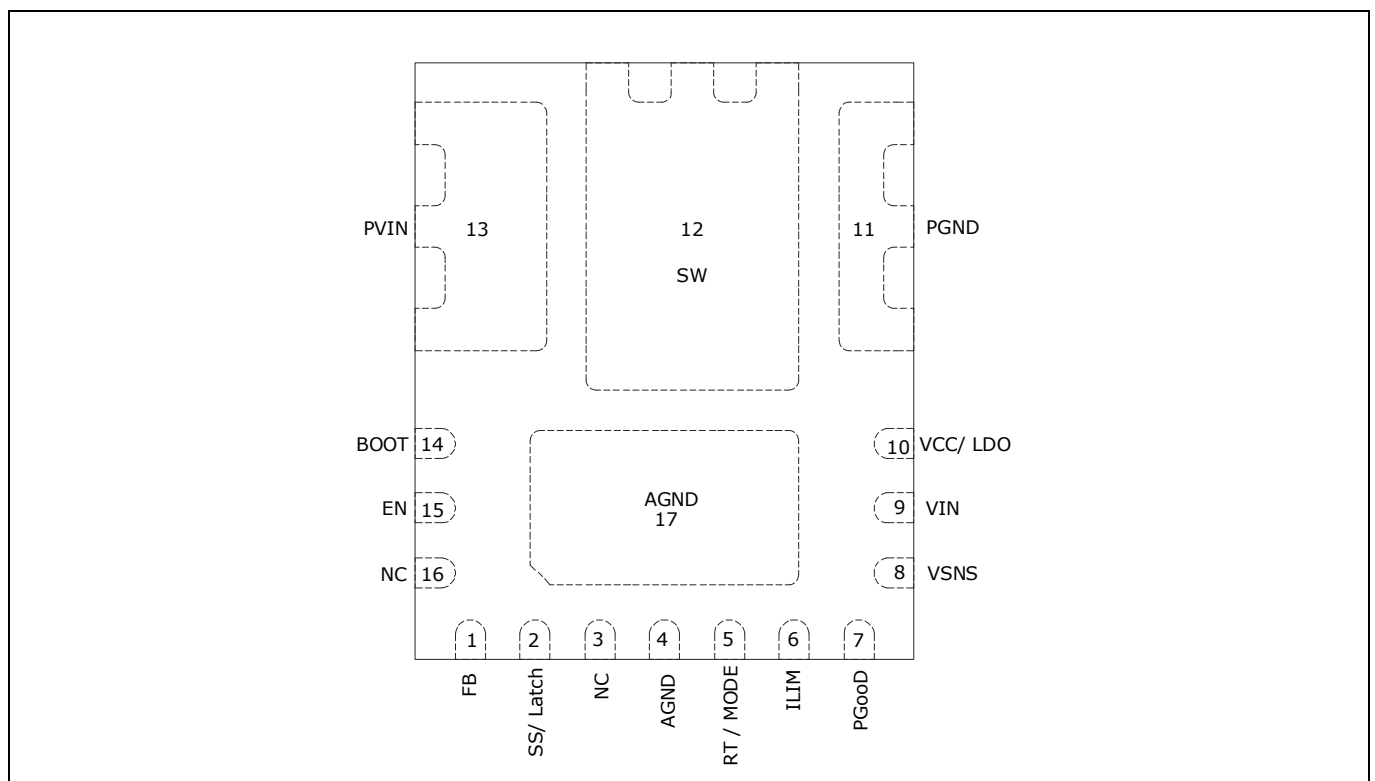
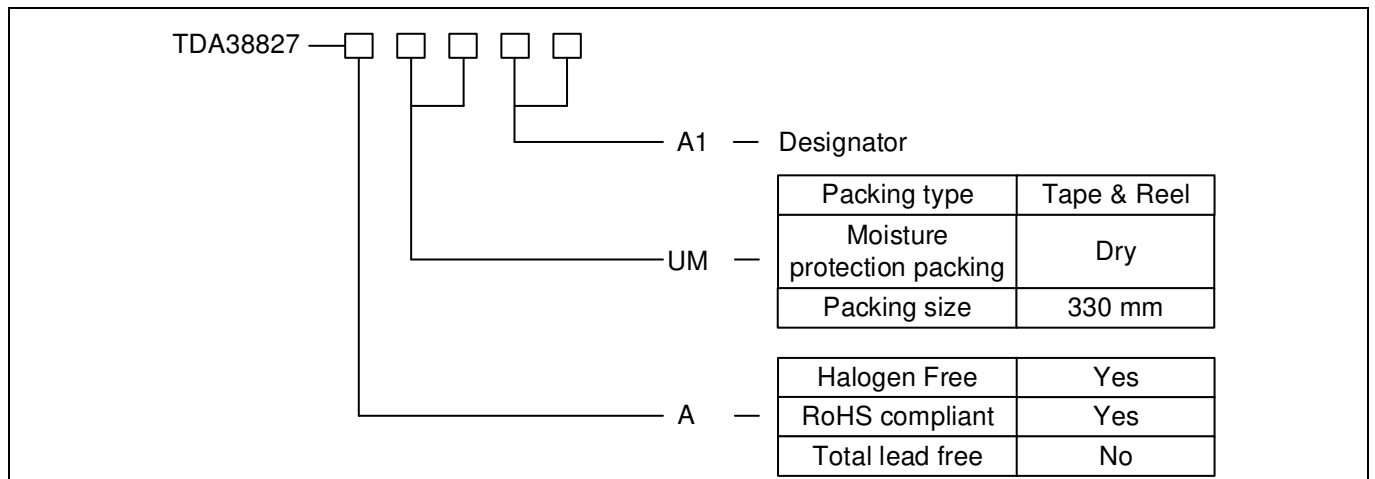


Figure 1 Package Top View

2 Functional block diagram

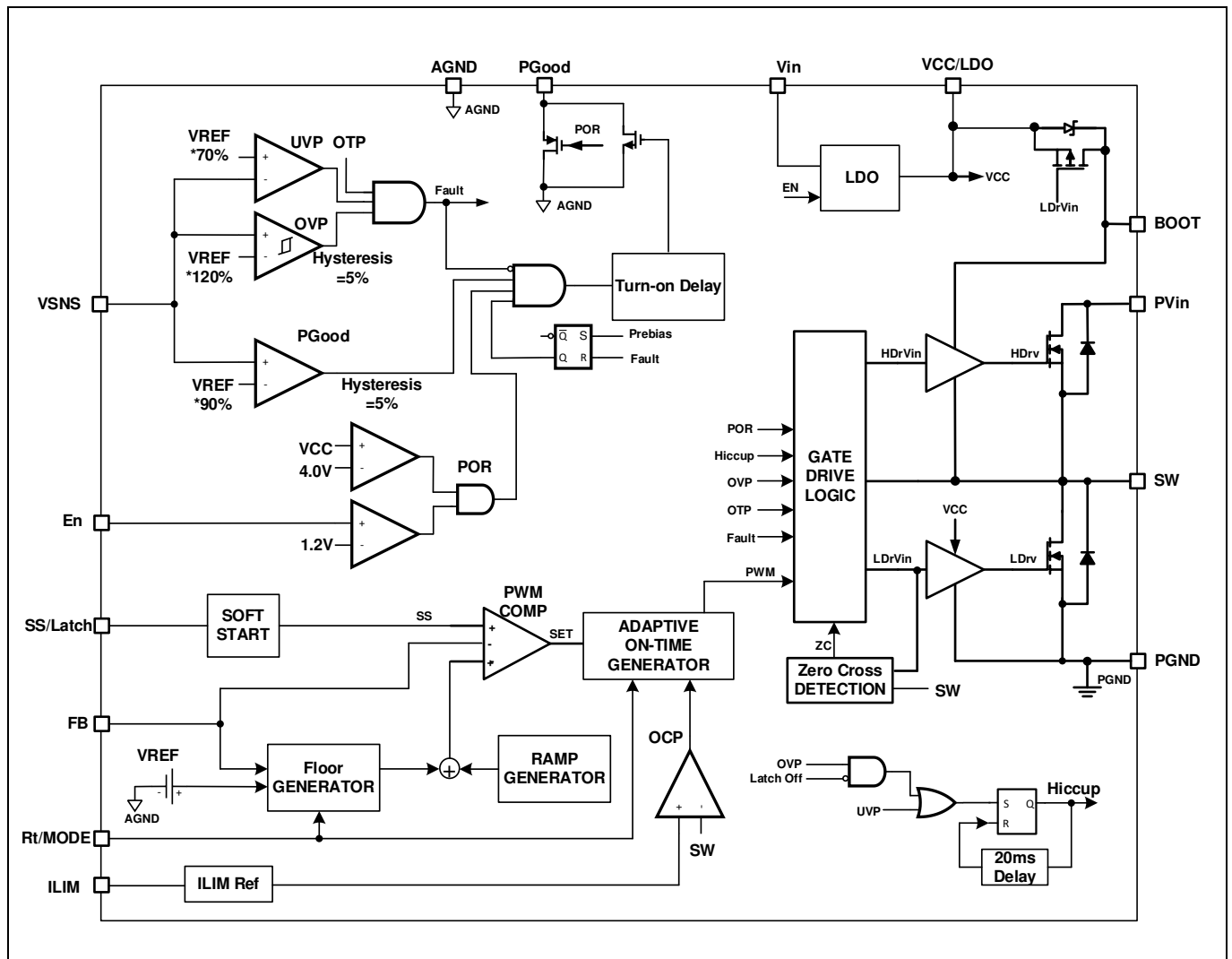


Figure 2 Block diagram

3 Typical application diagram

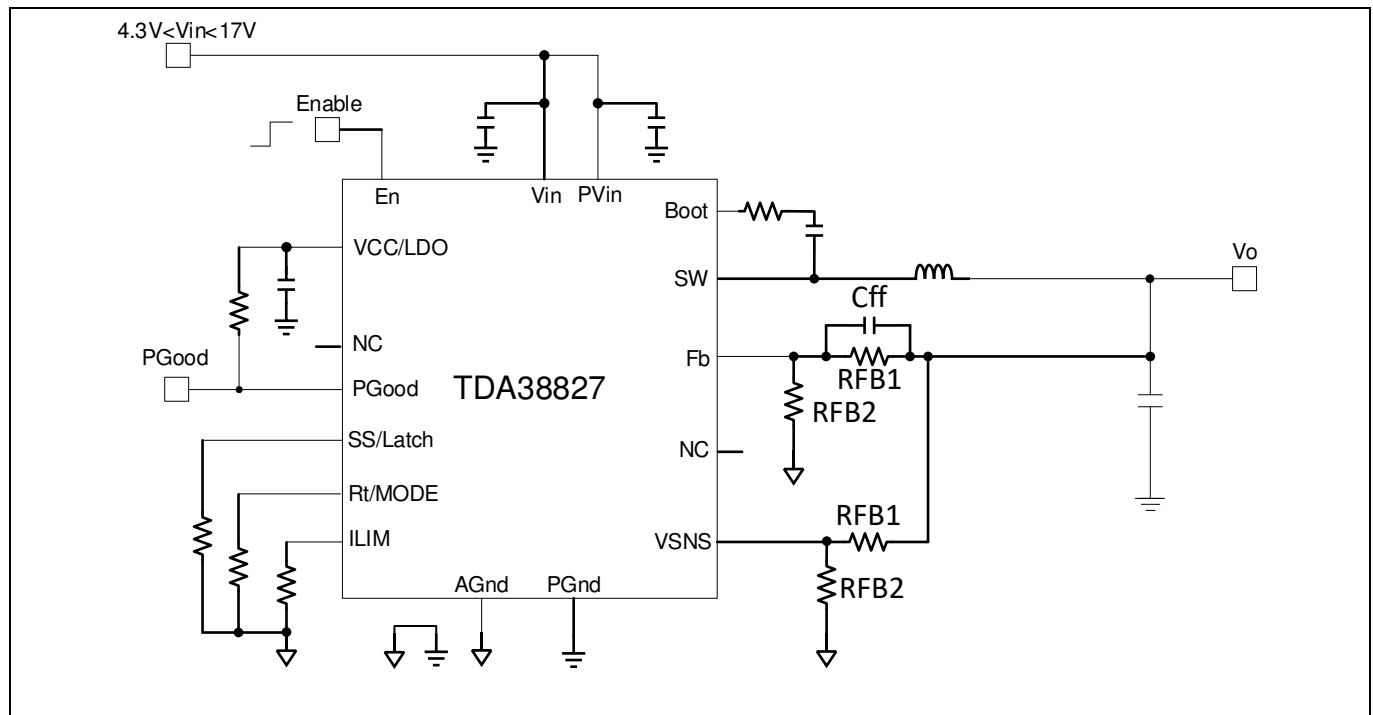


Figure 3 TDA38827 basic application circuit

Pin descriptions

4 Pin descriptions

Note: I = Input, O = Output

Pin#	Pin Name	I/O	Type	Pin Description
1	Fb	I	Analog	Output voltage feedback pin. Connect this pin to the output of the regulator via a resistor divider to set the output voltage.
2	SS/Latch	I	Analog	Multi-function pin. This pin sets the Soft-Start time to 1 of 4 options. This pin also selects latched-off Over Voltage Protection (OVP) or non-latched OVP. Refer to Table 6.
3, 16	NC	-	Not connected	Not connected internally. They can be left floating on PCB or connected to other signals as needed.
4, 17	AGND	-	Ground	Signal ground for the internal circuitry except the internal reference voltage. AGND and PGND are not internally connected. AGND and PGND must be connected on PCB with a single ground connection.
5	Rt/MODE	I	Analog	Multi-function pin. This pin sets the switching frequency to 1 of 8 settings and sets the mode of operation to FCCM or DEM. Refer to Table 5.
6	ILIM	I	Analog	Connecting a resistor to ground sets the Over Current Protection (OCP) limit. Four user selectable OCP limits are available.
7	PGood	O	Analog	Power Good status output pin is open drain. Connect a pull up resistor from this pin to VCC or to an external bias voltage, e.g. 3.3 V.
8	VSNS	I	Analog	Sense pin for over voltage protection and Pgood. Tie this pin to Vout using a resistor divider. Alternatively, tie this pin to FB pin directly.
9	Vin	I	Power	Input voltage for an Internal LDO. A 4.7 μ F capacitor should be connected between this pin and PGnd. If an external supply is connected to VCC/LDO pin, this pin should be shorted to VCC/LDO pin and a 10 μ F ceramic capacitor can be shared with Vin and VCC/LDO pin.
10	VCC/LDO	I/O	Power	Input bias for an external VCC voltage or output of the internal LDO. A 2.2 μ F – 10 μ F ceramic capacitor is recommended to use between VCC, and the Power ground (PGND).
11	PGND	-	Ground	Power Ground. Should be connected to the system's power ground plane.
12	SW	O	Power	Switch Node. Connect these pins to an output inductor.
13	Pvin	I	Power	Input supply for the power stage.
14	Boot	I	Analog	Supply voltage for the high side driver. Connect this pin to the SW pin through a bootstrap capacitor.
15	En	I	Analog	Enable pin to turn the IC on and off.

Absolute maximum ratings

5 Absolute maximum ratings

Absolute maximum ratings

Description	Min	Max	Unit	Conditions
Pvin, Vin, En to PGND	-0.3	25	V	Note 1
Pvin to SW	-0.3 V(dc) , below -5 V for 5 ns	25 V(dc), above 32 V for 2 ns	V	
VCC to PGND	-0.3	6	V	Note 1
Boot to PGND	-0.3 V(dc), below -0.3 V for 5 ns	29	V	Note 1
SW to PGND	-0.3 (dc), below -5 V for 5 ns	25 V(dc), above 32 V for 2 ns	V	Note 1
Boot to SW	-0.3	6 V(dc), 7 V for 5 ns	V	
ILIM, Fb, Pgood, Rt/MODE, VSNS and SS/Latch to GND	-0.3	6	V	Note 1
PGnd to AGND	-0.3	0.3	V	
Storage Temperature Range	-55	150	°C	
Junction Temperature Range	-40	150	°C	

Note:

1. PGND, and AGND pin are connected together

Attention: Stresses beyond these listed under “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications are not implied. wing2865

6 Thermal characteristics

6.1 Thermal characteristics

Description	Symbol	Values	Test Conditions
Junction to Ambient Thermal Resistance	θ_{JA}	17 °C/W	Note 2
Junction to PCB Thermal Resistance	θ_{JC-PCB}	3.5 °C/W	Note 3
Junction to Case Top Thermal Resistance	θ_{JC}	34 °C/W	

Note:

2. Thermal resistance is measured with components mounted on a standard EVAL_38827_1Vout demo board in free air.
3. Thermal resistance is based on the board temperature near the Pvin pin.

7 Electrical specifications

7.1 Recommended operating conditions

Description	Min	Max	Unit	Note
PV _{in} Voltage Range with External VCC	2	17	V	Note 4, Note 5
PV _{in} Voltage Range with Internal LDO	4.5	17	V	Note 5, Note 6 & 10
VCC Supply Voltage Range	4.3	5.5	V	Note 4, Note 7
Typical Output Voltage Range	0.6	6	V	Note 8, Note 9
Continuous Output Current Range		25	A	Note 9
Typical Switching Frequency	600	2000	kHz	Note 10
Operating Junction Temperature	-40	125	°C	

Note:

4. V_{in} is shorted to VCC and use an external bias voltage.
5. A common practice is to have 20% margin on the maximum SW node voltage in the design. For applications requiring PV_{in} equal to or above 14 V, a small resistor in series with the Boot pin might be needed to ensure the maximum SW node spike voltage does not exceed 20 V. Alternatively, a snubber can be used at the SW node to reduce the SW node spike.
6. V_{in} is connected to PV_{in} and the internal LDO is used. For single-rail applications with the internal LDO, and PV_{in} = V_{in} = 4.3 V-5.4 V, the internal LDO may enter dropout mode. OCP limits can be reduced due to the lower VCC voltage. Please refer to [Section 12.7](#) for more detailed design guidelines.
7. The TDA38827 is designed to function with VCC down to 4.2 V, however, electrical specifications such as OCP limits may be degraded.
8. The maximum output voltage is also limited by the minimum off-time. Please refer to [Section 12.13](#) for details. Also note that OCP limit may be degraded when off-time is close to the minimum off-time.
9. Refer to [Section 9](#) for maximum output current rating at different ambient temperatures.
10. The maximum LDO output current must be limited within 50 mA for operations requiring full operating temperature range of -40 °C ≤ T_J ≤ 125 °C. [Figure 6](#) shows the maximum LDO output current capability over junction temperature. Thermal de-rating may be needed at an elevated ambient temperature to ensure the junction temperature within the recommended operating range.

TDA38827 OptiMOS™ IPOL

25 A single-voltage synchronous Buck regulator



Electrical specifications

7.2 Electrical characteristics

Note: Unless otherwise specified, the specifications apply over, $4.5\text{ V} \leq V_{in} = P_{vin} \leq 17\text{ V}$, in $0\text{ }^{\circ}\text{C} < T_j < 125\text{ }^{\circ}\text{C}$. Typical values are specified at $T_a = 25\text{ }^{\circ}\text{C}$.

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Power Stage						
Top Switch	R _{ds(on)_Top}	V _{Boot} – V _{sw} = 5.0 V, I _o = 25 A, T _j =25 °C		3.3		mΩ
Bottom Switch	R _{ds(on)_Bot}	VCC = 5.0 V, I _o = 25 A, T _j =25 °C		2.1		
Bootstrap Forward Voltage		I(Boot) = 25 mA		370	600	mV
SW float voltage	V _{SW}	En = 0 V			300	mV
		En = high, No Switching			300	
Dead Band Time	T _{db}	SW node falling edge, I _o = 25 A, Internal LDO, T _j = 25 °C, Note 11		7		ns
		SW node rising edge, I _o = 25 A, Internal LDO, T _j = 25 °C, Note 11		5		ns
Supply Current						
Vin Supply Current (standby)	I _{in(Standby)}	En = Low, No Switching		4	10	μA
Vin Supply Current (static)	I _{in(Static)}	En=2 V, No Switching		2.3	4	mA
Soft Start						
Soft Start Ramp Rate	SS rate	SS/Latch = 0 kΩ, 4.53 kΩ, 10.5 kΩ, 18.7 kΩ;	0.4	0.6	0.84	mV/μs
		SS/Latch = 1.5 kΩ, 5.76 kΩ, 12.1 kΩ, 21.5 kΩ;	0.2	0.3	0.42	
		SS/Latch = 2.49 kΩ, 7.32 kΩ, 14 kΩ, 24.9 kΩ;	0.1	0.15	0.21	
		SS/Latch = 3.48 kΩ, 8.87 kΩ, 16.2 kΩ, 28.7 kΩ;	0.05	0.075	0.105	
		SS/Latch = Floating, or VCC	0.1	0.15	0.21	
Feedback Voltage						
Feedback Voltage	V _{FB}			0.6		V
Accuracy		0°C < T _j < 85 °C	-0.5		+0.5	%
		-40 °C < T _j < 125 °C, Note 12	-1		1	
V _{FB} Input Current	I _{V_{FB}}	V _{FB} =0.6 V, T _j =25 °C	-0.15	0	+0.15	μA
On-Time Timer Control						
On Time	T _{on}	Vin=12 V, Vo=1 V, Rt= 0 kΩ, 10.5 kΩ, Note 13		152		ns
		Vin=12 V, Vo=1 V, Rt= 1.5 kΩ, 12.1 kΩ, Note 13		114		
		Vin=12 V, Vo=1 V, Rt= 2.49 kΩ, 14 kΩ, Note 13;		91.5		
		Vin=12 V, Vo=1 V, Rt= 3.48 kΩ, 16.2 kΩ, Note 13		77		

Electrical specifications

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
		Vin=12 V, Vo=1 V, Rt= 4.53 kΩ, 18.7 kΩ, Note 13		66.5		
		Vin=12 V, Vo=1 V, Rt= 5.76 kΩ, 21.5 kΩ, Note 13		58.5		
		Vin=12 V, Vo=1 V, Rt= 7.32 kΩ, 24.9 kΩ, Note 13		52		
		Vin=12V , Vo=1 V, Rt= 8.87 kΩ, 28.7 kΩ, Note 13		47		
		Vin=12V, Vo=1 V, Rt = Floating, Note 13		114		
Minimum On-Time	T _{on} (Min)	Vin=12 V, Vo=0 V		23	32	ns
Minimum Off-Time	T _{off} (Min)	T _j =25 °C, V _{FB} =0 V		270	360	ns
VCC LDO Output						
Output Voltage	VCC	5.5 V ≤ Vin ≤ 17 V, when I _{cc} =50 mA, C _{load} = 2.2 μF	4.7	5.0	5.3	V
VCC Dropout	VCC_drop	Vin = 4.3 V, I _{cc} =50 mA, C _{load} =2.2 μF			300	mV
Short Circuit Current	I _{short}	5.5 V ≤ Vin ≤ 17 V		90		mA
Under Voltage Lockout						
VCC-Start Threshold	V _{cc_UVLO_Start}	VCC Rising Trip Level	3.8	4.0	4.2	V
VCC-Stop Threshold	V _{cc_UVLO_Stop}	VCC Falling Trip Level	3.6	3.8	4.0	
Enable-Start-Threshold	En_UVLO_Start	ramping up	1.14	1.2	1.36	V
Enable-Stop-Threshold	En_UVLO_Stop	ramping down	0.9	1	1.06	
Input Impedance	R _{EN}		500	1000	1500	kΩ
Over Current Limit						
Current Limit Threshold (Valley current)	I _{oc}	T _j = 25 °C, Int LDO, RILIM=24.9 kΩ Or RILIM = VCC, Floating	28.4	32.8	35.3	A
		T _j = 25 °C, Int LDO, RILIM=21.5 kΩ	23.6	27.3	29.4	
		T _j = 25 °C, Int LDO, RILIM=16.2 kΩ	18.9	21.8	23.5	
		T _j = 25 °C, Int LDO, RILIM=12.1 kΩ Or RILIM = GND	13.9	16.4	17.6	
Over Voltage Protection						
OVP Trip Threshold	OVP_Vth	VSNS Rising	115	121	125	% V _{ref}
		VSNS Falling, OVP hysteresis	110	115	120	
OVP Protection Delay	OVP_Tdly			7		μs
Hiccup Blanking Time	T _{blk_Hiccup}	Unlatched OVP		20		ms
Under Voltage Protection						
UVP Trip Threshold	UVP_Vth	VSNS Falling	65	70	75	% V _{ref}
UVP Protection Delay	UVP_Tdly			5		μs
Hiccup Blanking Time	T _{blk_Hiccup}			20		ms

Electrical specifications

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Power Good						
Pgood Turn on Threshold	VPG(upper)	VSNS Rising	85	91	95	% Vref
Pgood Turn off Threshold	VPG(lower)	VSNS Falling	80	84	90	% Vref
Pgood Sink Current	I _{PG}	PG = 0.5 V, En = 2 V	2.5	5		mA
Pgood Voltage Low	V _{PG(low)}	Vin = VCC = 0 V, Rpull-up = 50 kΩ to 3.3 V		0.3	0.5	V
Pgood Turn on Delay	V _{PG(on)_Dly}	VSNS Rising, see VPG(upper)		2.5		ms
Pgood Comparator Delay	V _{PG(comp)_Dly}	VSNS < VPG(lower) or VSNS > VPG(upper)	1	2	3.5	μs
Pgood Open Drain Leakage Current		PG = 3.3 V			1	μA
Thermal Shutdown						
Thermal Shutdown		Note 11		140		°C
Hysteresis		Note 11		20		

Note:

11. Guaranteed by construction and not tested in production
12. Cold temperature performance is guaranteed via correlation using statistical quality control. Not tested in production.
13. The Ton is trimmed so that the target switching frequency is achieved at around 10A load current using EVAL_38827_1Vout demo board.

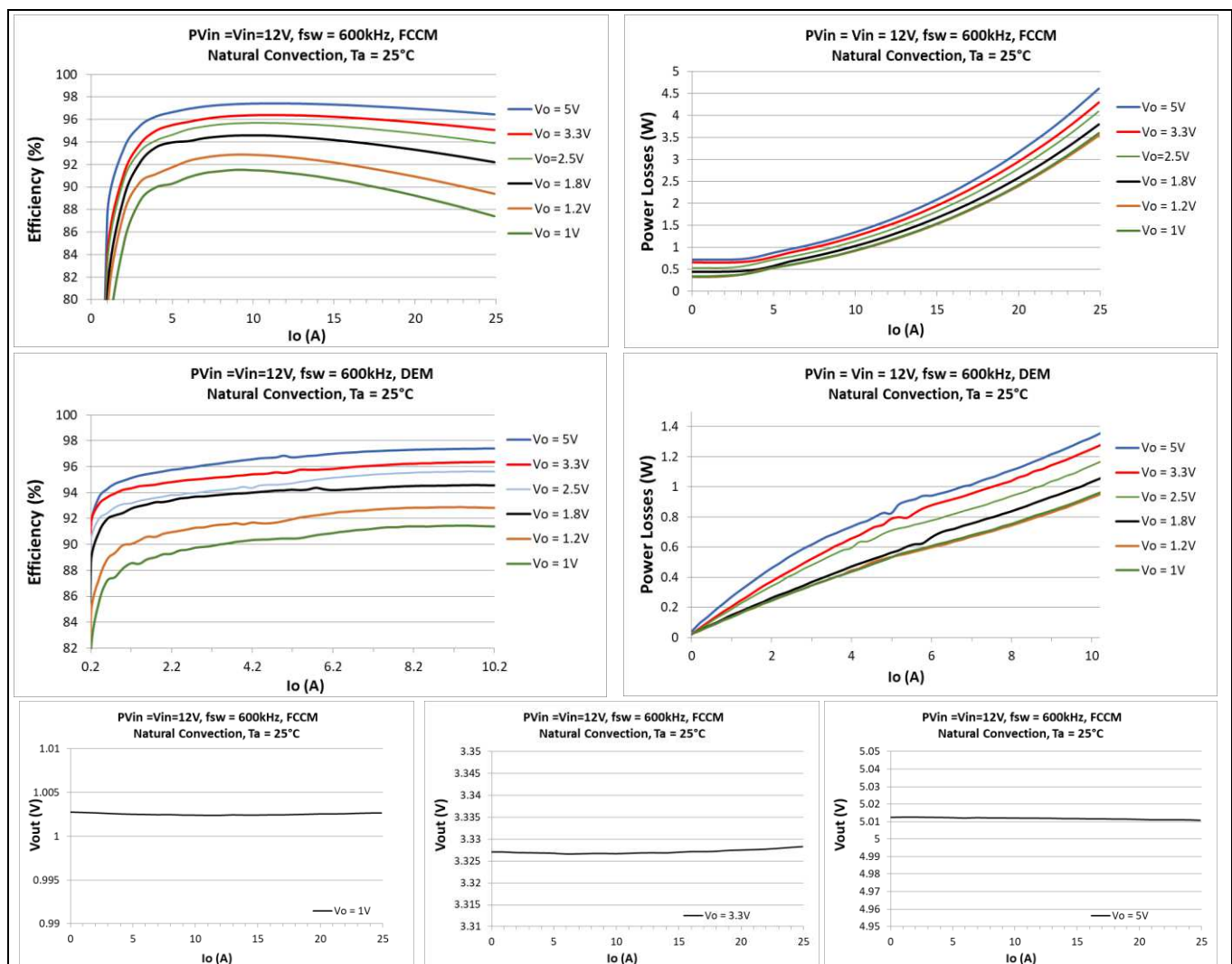
8 Typical efficiency and power loss curves

8.1 $P_{Vin} = V_{in} = 12\text{ V}$, $F_{sw} = 600\text{ kHz}$

$P_{Vin} = V_{in} = 12\text{ V}$, $V_{CC} = \text{Internal LDO}$, $I_o = 0\text{ A}-25\text{ A}$, $F_{sw} = 600\text{ kHz}$, Room Temperature, No Air Flow. Note that the efficiency and power loss curves include the losses of TDA38827, the inductor losses, the losses of the input and output capacitors, and PCB trace losses. The table below shows the inductors used for each of the output voltages in the efficiency measurement.

Table 1 Inductors for $P_{Vin}=V_{in}=12\text{ V}$, $F_s = 600\text{ kHz}$

Vout (V)	Lout (nH)	P/N	DCR (mΩ)	Size (mm)
1.0	150	HCB138380D-151 (Delta)	0.15	12.4 x 8.3 x 8
1.2	220	FP1008R5-R220-R (Cooper)	0.17	10.8 x 8 x 8
1.8	220	FP1008R5-R220-R (Cooper)	0.17	10.8 x 8 x 8
2.5	350	HCBD101195-351(Delta)	0.35	10.1 x 11.4 x 9.5
3.3	350	HCBD101195-351(Delta)	0.35	10.1 x 11.4 x 9.5
5	450	HCBD101195-451(Delta)	0.35	10.1 x 11.4 x 9.5

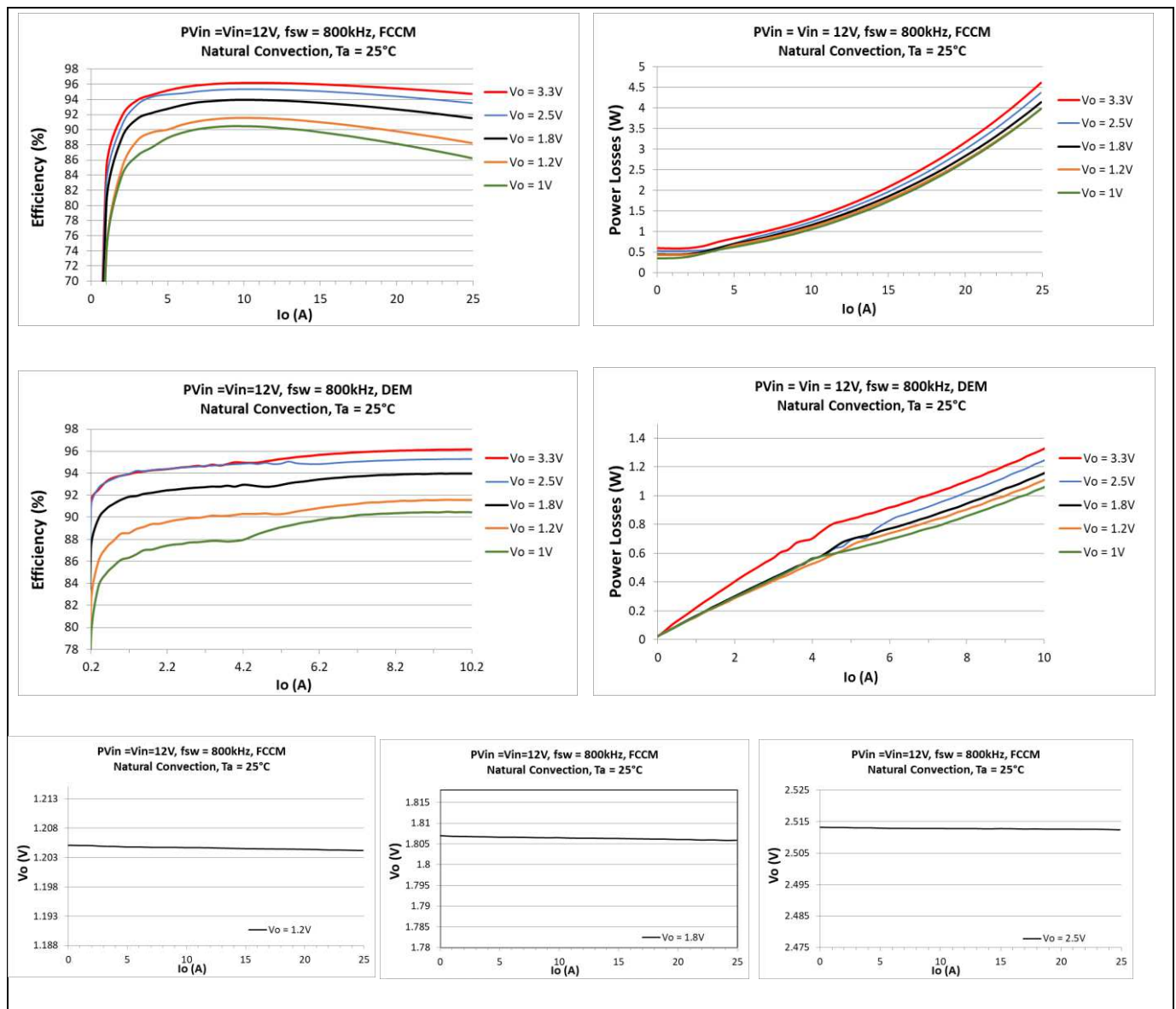


8.2 $P_{Vin} = V_{in} = 12\text{ V}$, $F_{sw} = 800\text{ kHz}$

$P_{Vin} = V_{in} = 12\text{ V}$, $V_{CC} = \text{Internal LDO}$, $I_o = 0\text{ A}-25\text{ A}$, $F_{sw} = 800\text{ kHz}$, Room Temperature, No Air Flow. Note that the efficiency and power loss curves include the losses of TDA38827, the inductor losses, the losses of the input and output capacitors, and PCB trace losses. The table below shows the inductors used for each of the output voltages in the efficiency measurement.

Table 2 Inductors for $P_{Vin}=V_{in}=12\text{ V}$, $F_{sw} = 800\text{ kHz}$

Vout (V)	Lout (nH)	P/N	DCR (mΩ)	Size (mm)
1.0	150	HCB138380D-151 (Delta)	0.15	12.4 x 8.3 x 8
1.2	150	HCB138380D-151 (Delta)	0.15	12.4 x 8.3 x 8
1.8	220	FP1008R5-R220-R (Cooper)	0.17	10.8 x 8 x 8
2.5	220	FP1008R5-R220-R (Cooper)	0.17	10.8 x 8 x 8
3.3	350	HCBD101195-351(Delta)	0.35	10.1 x 11.4 x 9.5

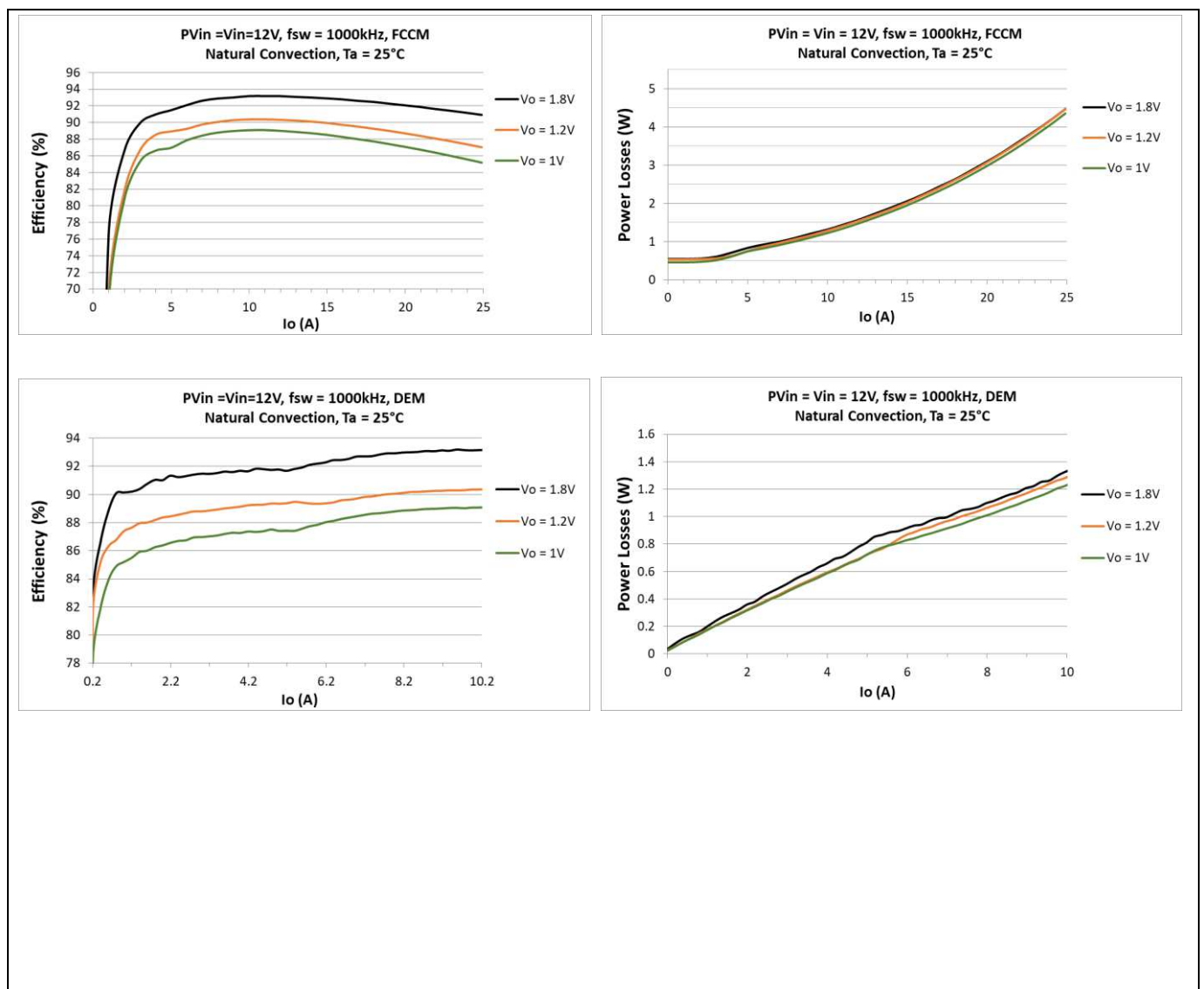


8.3 $P_{Vin} = V_{in} = 12\text{ V}$, $F_{sw} = 1000\text{ kHz}$

$P_{Vin} = V_{in} = 12\text{ V}$, $V_{CC} = \text{Internal LDO}$, $I_o = 0\text{ A}-25\text{ A}$, $F_{sw} = 1000\text{ kHz}$, Room Temperature, No Air Flow. Note that the efficiency and power loss curves include the losses of TDA38827, the inductor losses, the losses of the input and output capacitors, and PCB trace losses. The table below shows the inductors used for each of the output voltages in the efficiency measurement.

Table 3 Inductors for $P_{Vin}=V_{in}=12\text{ V}$, $F_{sw} = 1000\text{ kHz}$

Vout (V)	Lout (nH)	P/N	DCR (mΩ)	Size (mm)
1.0	100	AH3740A-100K (ITG)	0.145	6.4 x 9.5 x 10
1.2	100	AH3740A-100K (ITG)	0.145	6.4 x 9.5 x 10
1.8	150	AH3740A-150K (ITG)	0.145	6.4 x 9.5 x 10

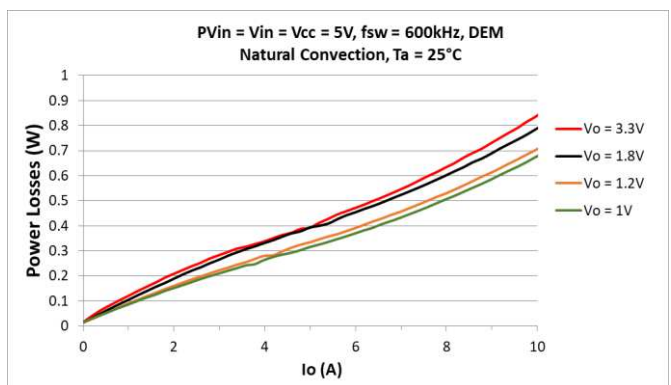
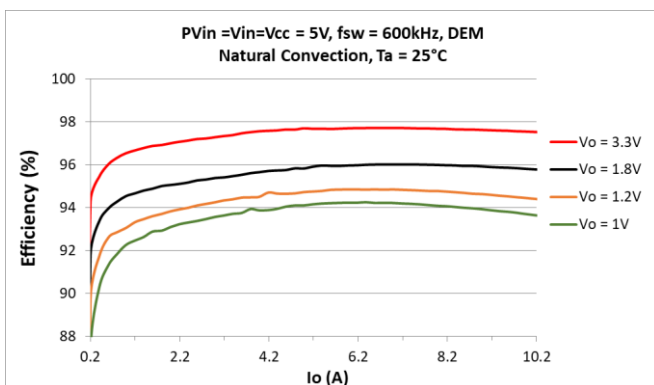
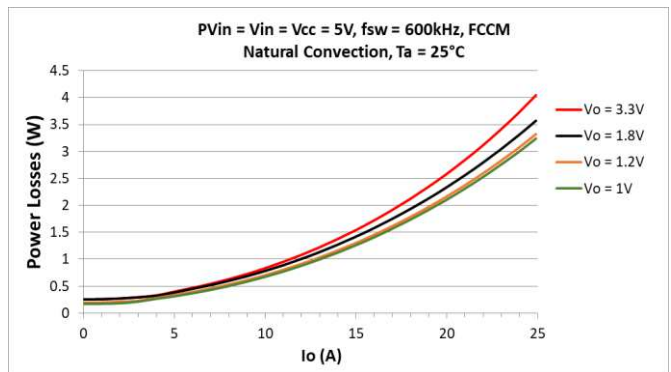
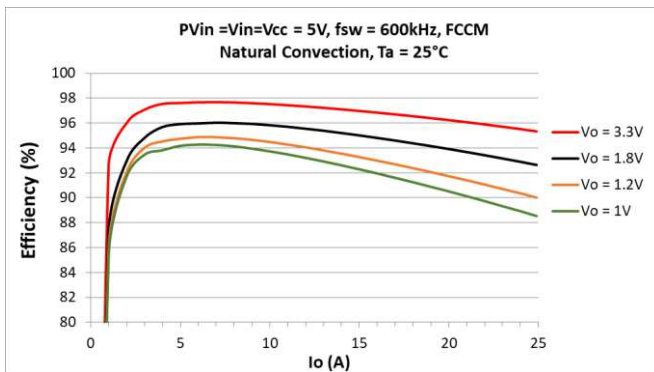


8.4 $P_{Vin} = V_{in} = V_{CC} = 5\text{ V}$, $F_{sw} = 600\text{ kHz}$

$P_{Vin} = V_{in} = V_{CC} = 5.0\text{ V}$, $I_o = 0\text{ A} - 25\text{ A}$, $F_{sw} = 600\text{ kHz}$, Room Temperature, No Air Flow. Note that the efficiency and power loss curves include the losses of TDA38827, the inductor losses, the losses of the input and output capacitors and PCB trace losses. The table below shows the inductors used for each of the output voltages in the efficiency measurement.

Table 4 Inductors for $P_{Vin} = V_{in} = V_{CC} = 5\text{ V}$, $F_{sw} = 600\text{ kHz}$

Vout (V)	Lout (nH)	P/N	DCR (mΩ)	Size (mm)
1.0	150	AH3740A-150K (ITG)	0.145	6.4 x 9.5 x 10
1.2	150	AH3740A-150K (ITG)	0.145	6.4 x 9.5 x 10
1.8	150	AH3740A-150K (ITG)	0.145	6.4 x 9.5 x 10
3.3	150	AH3740A-150K (ITG)	0.145	6.4 x 9.5 x 10



9 Thermal de-rating curves

Measurement is done on Evaluation board of EVAL_38827. PCB is a 6-layer board with 1.5 ounce Copper for top and bottom layer and 2 ounce Copper for the inner layers, FR4 material, size 3.0"x3.75".

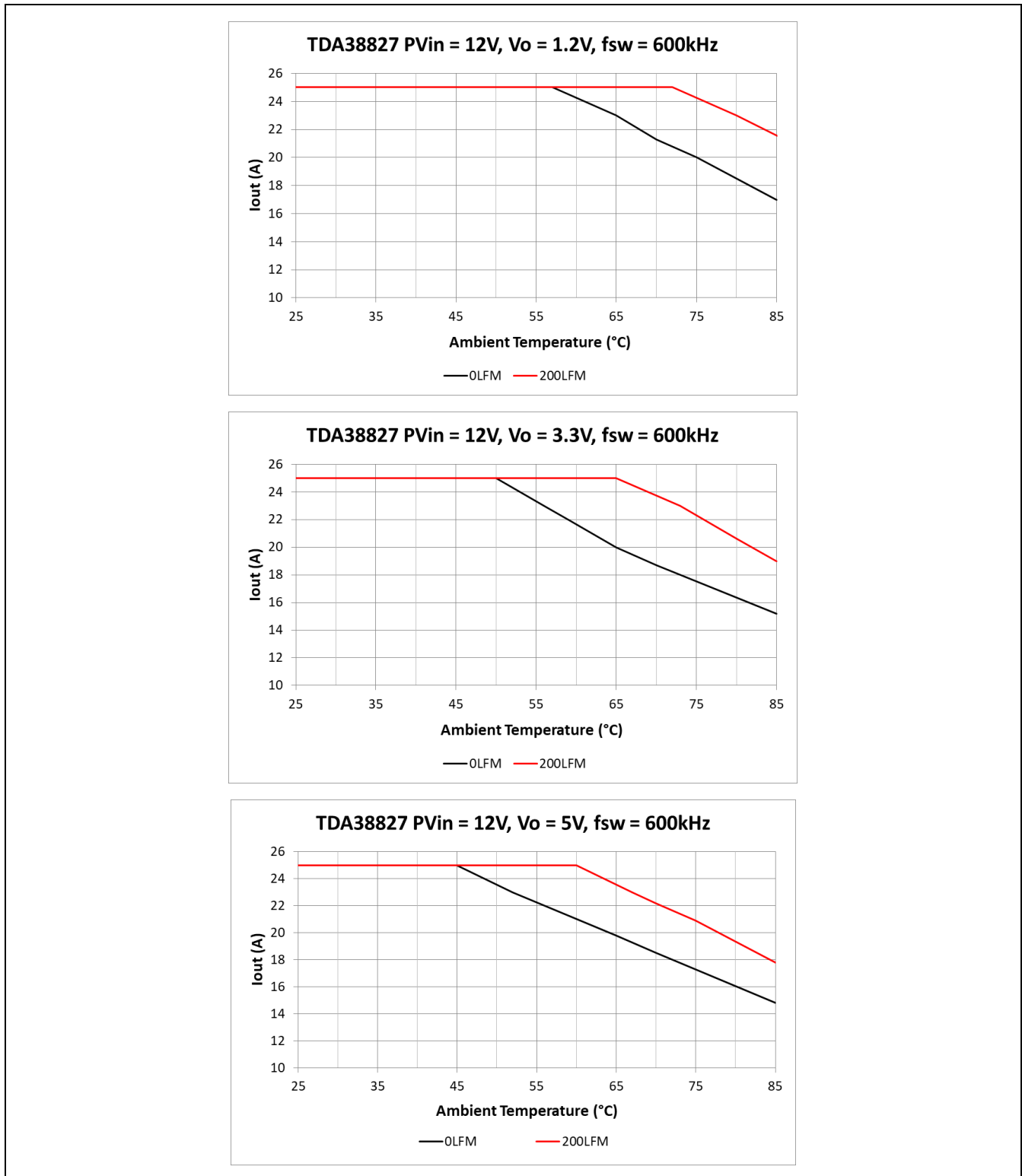


Figure 4 Thermal de-rating curves, $P_{Vin} = 12V$, $V_{out} = 1.2V/3.3V/5V$, $f_{sw} = 600kHz$, $V_{CC} = \text{Internal LDO}$

10 $R_{DS(on)}$ of MOSFET over temperature

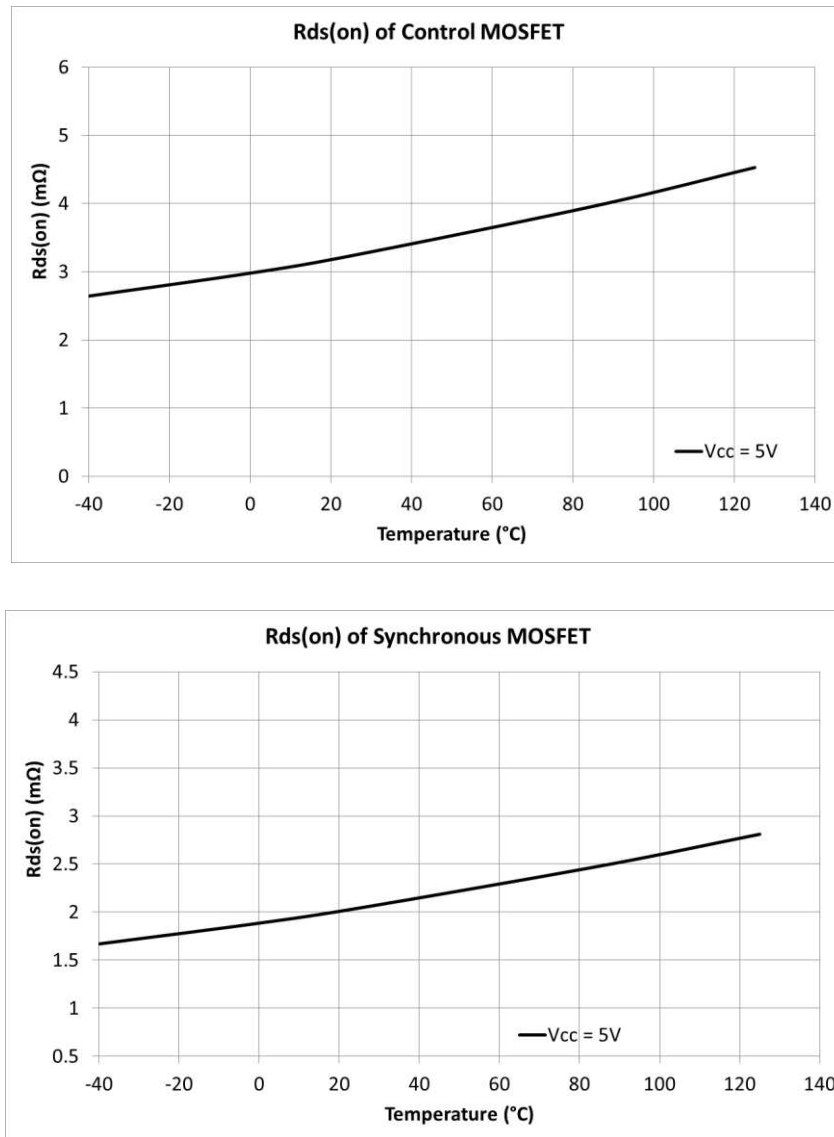


Figure 5 $R_{DS(on)}$ of MOSFETs over Junction Temperature

11 Typical operating characteristics ($-40\text{ }^{\circ}\text{C} \leq T_j \leq +125\text{ }^{\circ}\text{C}$)

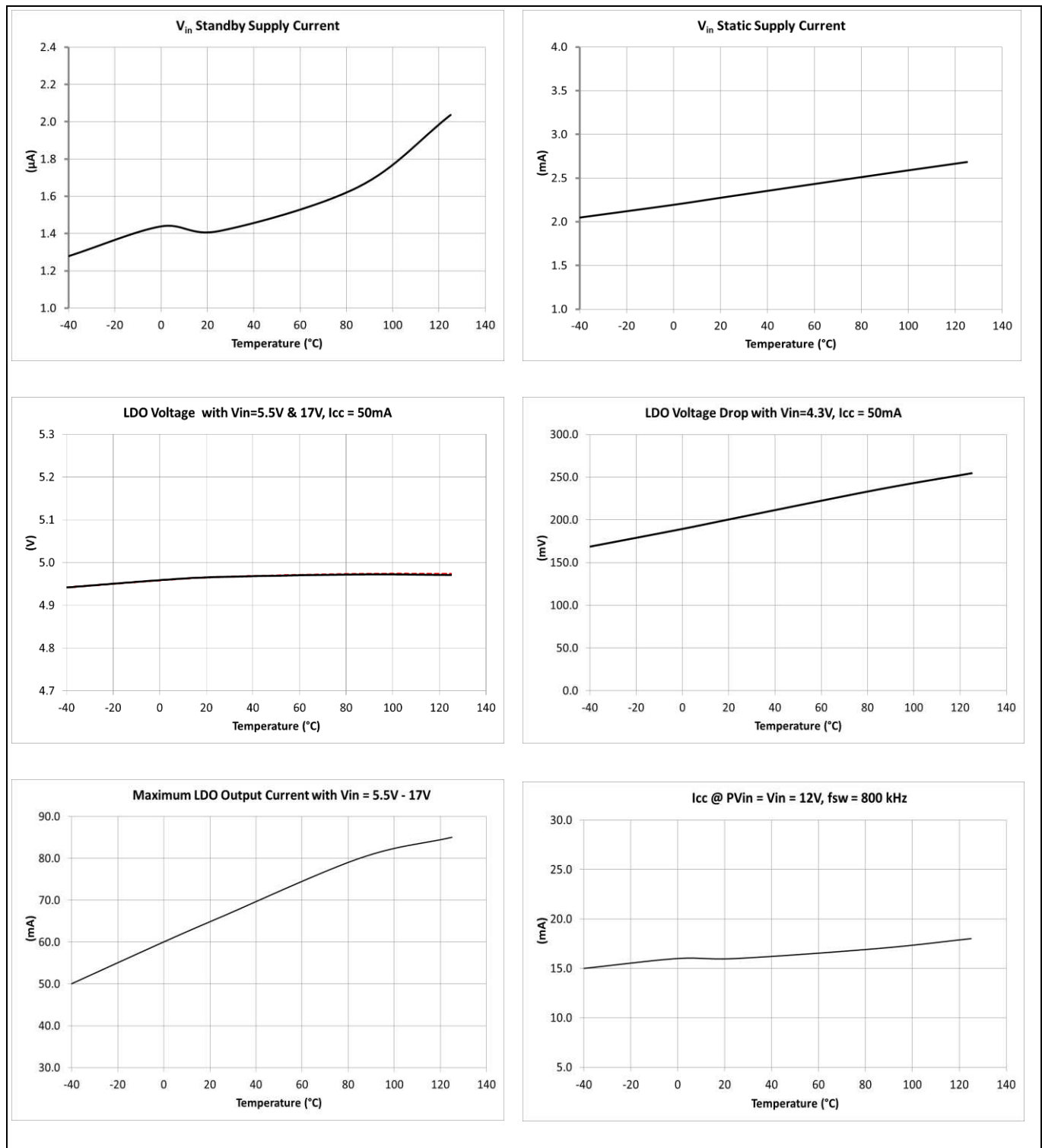


Figure 6 Typical operating characteristics (set 1 of 3)

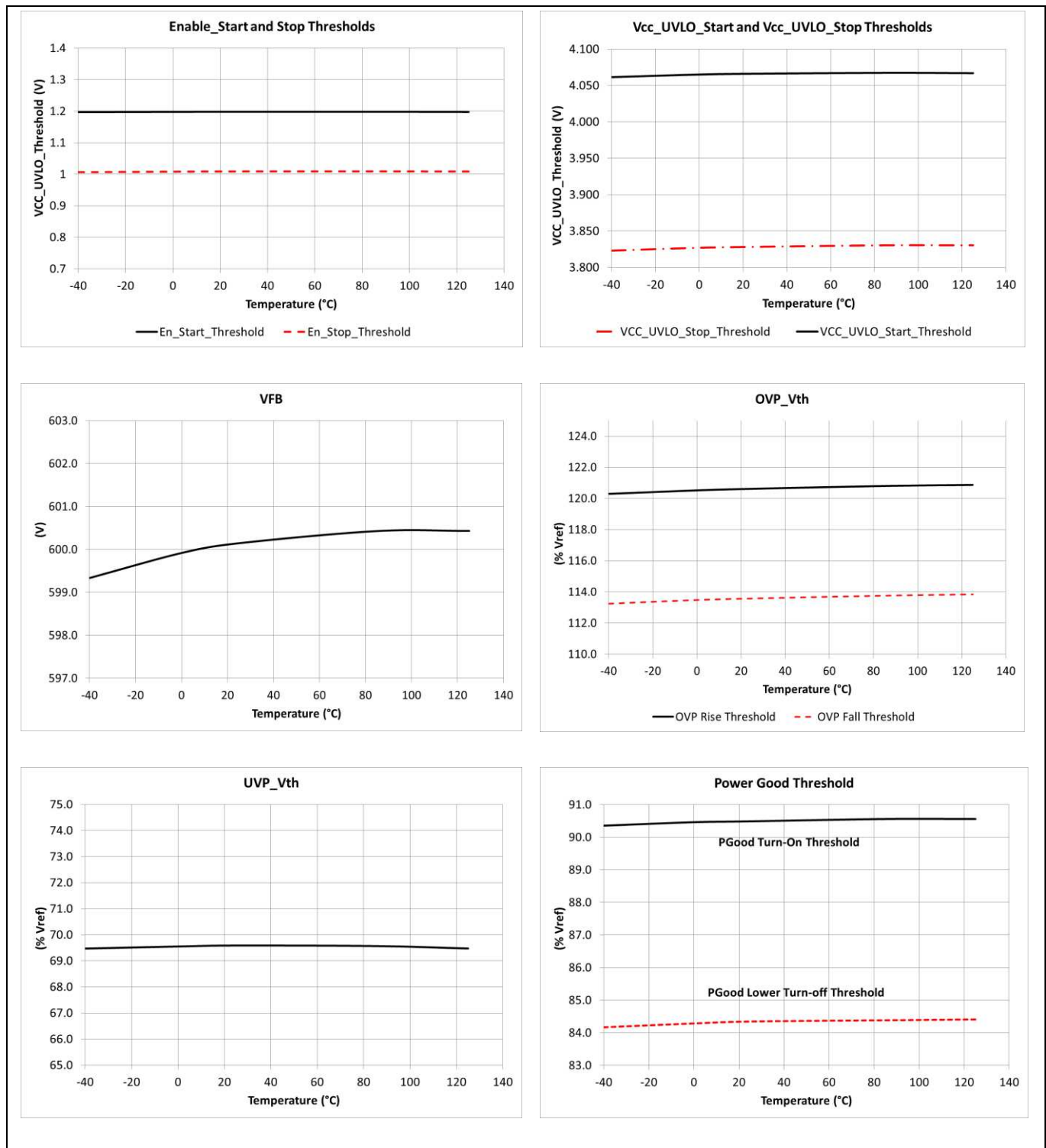


Figure 7 Typical operating characteristics (set 2 of 3)

TDA38827 OptiMOS™ IPOL

25 A single-voltage synchronous Buck regulator

Typical operating characteristics ($-40\text{ }^{\circ}\text{C} \leq T_j \leq +125\text{ }^{\circ}\text{C}$)

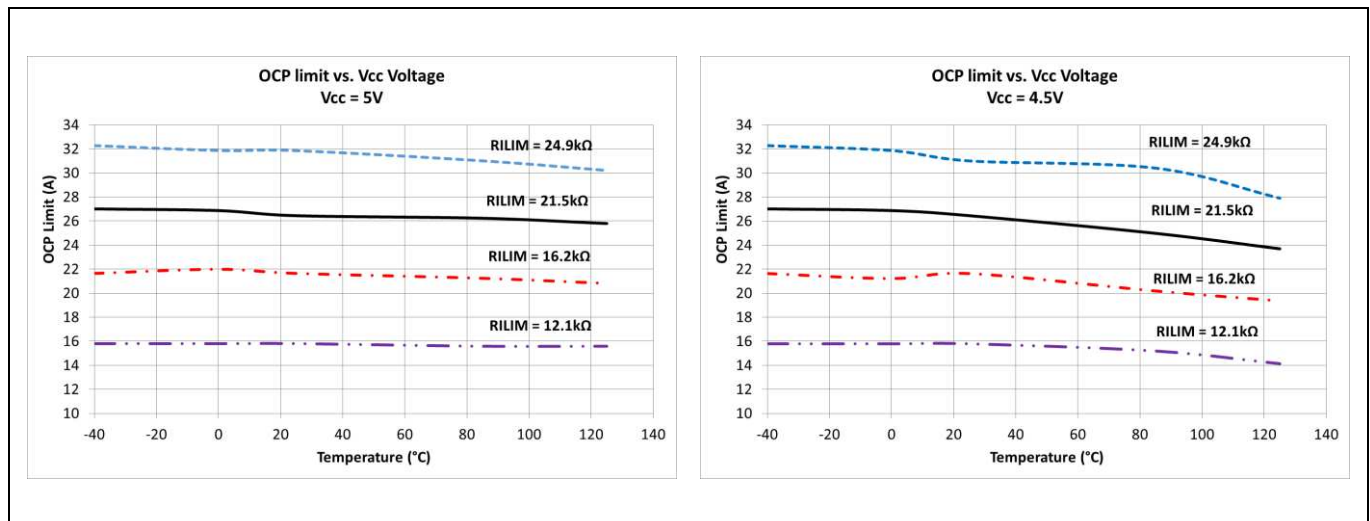


Figure 8 Typical operating characteristics (set 3 of 3)

12 Theory of operation

12.1 Fast Constant On-Time control

The TDA38827 features a proprietary Fast Constant On-Time (COT) Control, which can provide fast load transient response, good output regulation and minimize the design effort. Fast COT control compares the output voltage, V_o , to a floor voltage combined with an internal ramp signal. When V_{out} drops below that signal, a PWM signal is initiated to turn on the high-side FET for a fixed on-time. The floor voltage is generated from an internal compensated error amplifier, which compares the V_{out} with a reference voltage. Compared to the traditional COT control, Fast COT control significantly improves the V_{out} regulation.

12.2 Enable

En pin controls the on/off of the TDA38827. An internal Under Voltage Lock-Out (UVLO) circuit monitors the En voltage. When the En voltage is above an internal threshold, the internal LDO starts to ramp up. When the VCC/LDO voltage rises above the VCC_UVLO_Start threshold, the soft-start sequence starts. The En pin can be configured in three ways, as shown in [Figure 9](#). With configuration 2, the Enable signal is derived from the Pvin voltage by a set of resistive divider, REN1 and REN2. By selecting different divider ratios, users can program a UVLO threshold voltage for the bus voltage. This is a very desirable feature because it prevents the TDA38827 from operating until Pvin is higher than a desired voltage level. For some space constrained designs, En pin can be directly connected to Pvin without using the external resistor dividers, as shown in Configuration 3. En pin should not be left floating. A pull down resistor in the range of tens of kilohms is recommended. [Figure 10](#) illustrates the corresponding start-up sequences with three En configurations.

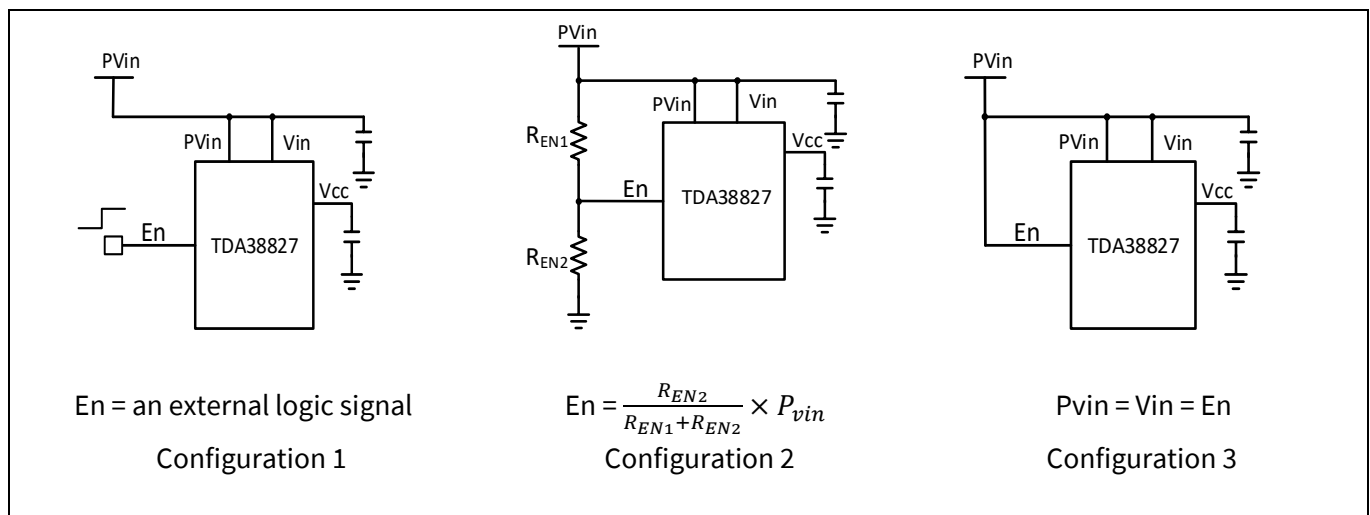


Figure 9 Enable Configurations

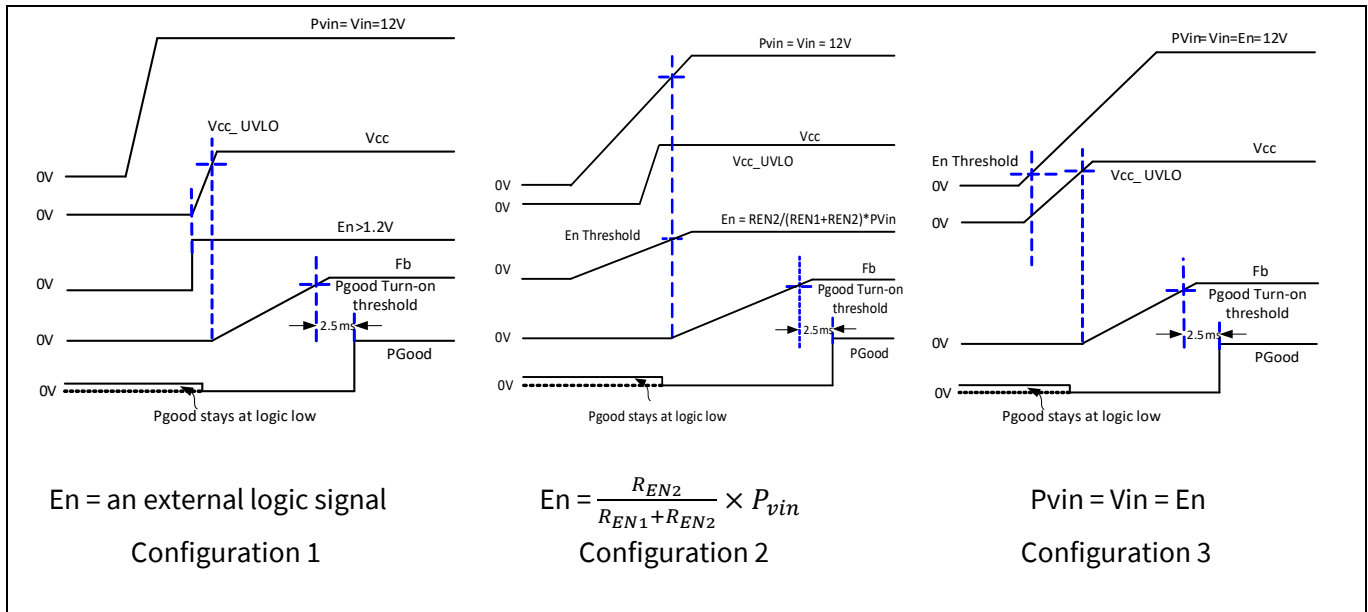


Figure 10 Start-up sequence

12.3 FCCM and DEM operation

The TDA38827 offers two operation modes: Forced Continuous Conduction (FCCM) and Diode Emulation Mode (DEM). With FCCM, the TDA38827 always operates as a synchronous buck converter with a pseudo constant switching frequency and therefore achieves small output voltage ripples. In DEM, the synchronous FET is turned off when the inductor current is close to zero, which reduces the switching frequency and improves the efficiency at light load. At heavy load, both FCCM and DEM operate in the same way. The operation mode can be selected with TON/MODE pin, as shown in [Table 5](#). It should be noted that the selection of the operation mode cannot be changed on the fly. To load a new TON/MODE configuration, En or VCC voltage needs to be cycled.

12.4 Pseudo constant switching frequency

The TDA38827 offers eight programmable switching frequencies, f_{sw} , from 600 kHz to 2 MHz, by connecting an external resistor from TON/MODE pin to the ground. Based on the selected f_{sw} , the TDA38827 generates the corresponding on-time of the Control FET for a given PV_{in} and V_o , as shown by the formula below.

$$T_{on} = \frac{V_o}{PV_{in}} \times \frac{1}{f_{sw}}$$

Where f_{sw} is the desired switching frequency. During the operation, the TDA38827 monitors PV_{in} and V_o , and can automatically adjust the on-time to maintain the pre-selected f_{sw} . With the increase of the load, the switching frequency can increase to compensate for the power losses. Therefore, the TDA38827 has a pseudo constant switching frequency.

Table 5 lists the resistors for TON/MODE pin. In this table, E96 resistors with $\pm 1\%$ tolerance are used. If E12 resistor values are preferred, please refer to the [Section 12.15](#). To load a new TON/MODE configuration, En or VCC voltage needs to be cycled.

Table 5 Configuration Resistors for Rt/MODE Pin

Rt/MODE Resistor (kΩ) ±1% Tolerance	Freq (kHz)	Mode
0	600	FCCM
1.5	800	
2.49	1000	
3.48	1200	
4.53	1400	
5.76	1600	
7.32	1800	
8.87	2000	
10.5	600	DEM
12.1	800	
14	1000	
16.2	1200	
18.7	1400	
21.5	1600	
24.9	1800	
28.7	2000	
Rt/MODE = Floating	800	FCCM

12.5 Soft-start

The TDA38827 has an internal digital soft-start to control the output voltage rise and to limit the current surge at the start-up. To ensure a correct start-up, the soft-start sequence initiates when the EN and VCC voltages rise above their respective thresholds. The internal soft-start signal linearly rises from 0 V to 0.8 V in a defined time duration. The soft-start time does not change with the output voltage. During the soft-start, the TDA38827 operates in DEM until 1ms after the output voltage ramps above the Pgood turn-on threshold. The TDA38827 has four soft-start time options selected by placing a resistor from SS/Latch pin to the ground. [Table 6](#) lists the resistor values and its corresponding soft-start time. In this table, E96 resistors with ±1% tolerance are used. If E12 resistor values are preferred, please refer to the Section [12.15](#). For each soft-start time, there are two resistor options available. Please note that SS/Latch pin is a multi-function pin, which is also used to select different responses for Over Voltage Protection (OVP). To load a new SS/Latch selection, En or VCC voltage needs to be cycled.

Table 6 Configuration Resistor for SS/Latch Pin

SS/Latch Resistor (kΩ) ±1% Tolerance	Soft-start Time (ms)	OVP
0	1	Latch
4.53		
1.5		
5.76	2	
2.49		
7.32		
3.48	4	
8.87		
10.5		
18.7	1	
12.1	2	
21.5		
14		4
24.9		
16.2	8	
28.7		
SS/Latch = Floating, VCC	4	Latch

12.6 Pre-bias start-up

The TDA38827 is able to start up into a pre-charged output without causing oscillations and disturbances of the output voltage. When TDA38827 starts up with a pre-biased output voltage, both control FET and Synch FET are kept off till the internal soft-start signal exceeds the FB voltage.

12.7 Internal Low – Dropout (LDO) regulator

The TDA38827 has an integrated low-dropout LDO regulator, providing the bias voltage for the internal circuitry. To minimize the standby current, the internal LDO is disabled when the En voltage is pulled low. VIN pin is the input of the LDO. When using the internal LDO for a single rail operation, VIN pin should be connected to PVIN pin. To save the power losses on the LDO, an external bias voltage can be used by connecting VIN pin to the VCC/LDO pin. **Figure 11** illustrates the configuration of VCC/LDO, and VIN pin.

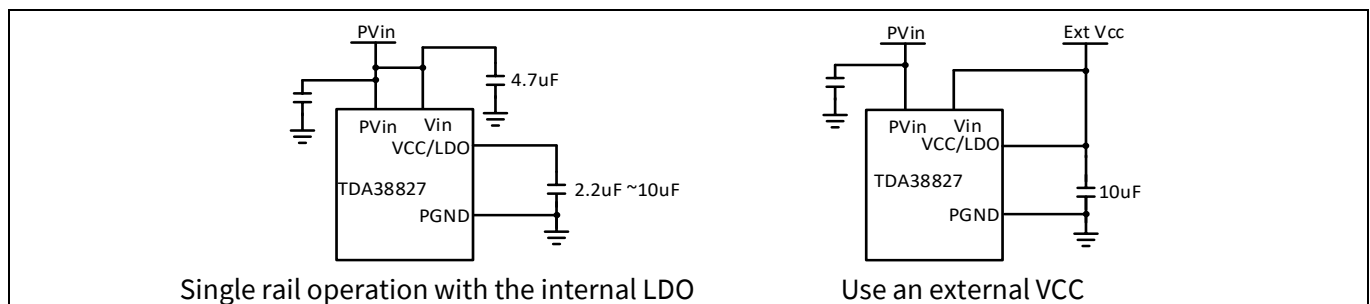


Figure 11 Configuration of Using the internal LDO or an external VCC.

Section 7.1 specified the recommended operating voltage range of V_{in} and VCC under different configurations. Following design guidelines are recommended when configuring the VCC/LDO.

- Place a bypass capacitor to minimize the disturbance on the VCC pin. For a single rail operation using the internal LDO, a 4.7 μF low ESR ceramic capacitor must be used between VIN pin and PGND and a 2.2 μF ~10 μF low ESR ceramic capacitor is required to be placed close to the VCC/LDO with reference to PGND. 10 μF MLCC is recommended for VCC bypass capacitor when VIN is below 5.5 V. When using an external VCC bias voltage, a 10 μF ceramic capacitor can be shared with VIN, and VCC/LDO pin.
- For applications using the internal LDO with $4.3\text{ V} \leq V_{in} \leq 5.4\text{ V}$, the LDO can be in the dropout mode. It is important to ensure that the LDO voltage does not fall below the VCC UVLO threshold voltage. At $V_{in} = 4.3\text{ V}$, I_{CC} must not exceed 50 mA under all operating conditions such as during a step-up load transient, in which the control loop may require the increase of f_{sw} . OCP limits can be reduced due to the lower VCC voltage.

12.8 Over Current Protection (OCP)

The TDA38827 offers cycle-by-cycle OCP response with four selectable current limits, which is set by the resistance between ILIM pin and GND. The selected OCP limit bank is loaded to the IC during the power up and cannot be changed on the fly. To change the OCP limit, users must cycle EN signal or VCC voltage. Cycle-by-cycle OCP response allows the TDA38827 to fulfill a brief high current demand, such as a high inrush current during the start-up. The detailed operation is explained as follows.

The OCP is activated when EN voltage is above its threshold. The OCP circuitry monitors the current of the Synchronous MOSFET through its $R_{ds(on)}$. When a new PWM pulse is requested by the control loop, if the current of Synchronous MOSFET exceeds the selected OCP limit, the TDA38827 skips the PWM pulse and extends the on-time of Synchronous MOSFET till the current drops below the OCP limit. The OCP operation is also illustrated in **Figure 12**. During OCP events, the valley of the inductor current is regulated around the OCP limit. But during the first switching cycle when the OCP is tripped, the valley of the inductor current can drop slightly below the OCP limit. It should be noted that OCP events do not pull the Pgood signal low unless the V_o drops below the Pgood turn-off threshold. If the OCP event persists, the output voltage can eventually drop below the Under Voltage Protection (UVP) threshold and trigger UVP. Then the TDA38827 enters a hiccup mode.

The OCP limits are thermally compensated. Please refer to the typical performance of OCP limits in **Figure 8**. The OCP limits specified in the Section 7.2 refer to the valley of the inductor current when OCP is tripped. Therefore, the corresponding output DC current can be calculated as follows:

$$I_{out_OCP} = I_{LIM} + \frac{\Delta i_L}{2}$$

Where: I_{out_OCP} = Output DC current when OCP is tripped. I_{LIM} = OCP limit specified in the Section 7.2, which is the valley of inductor current. Δi_L = Peak-peak inductor ripple current.

To avoid the inductor saturation during OCP events, the following criterion is recommended for the inductor saturation current rating.

$$I_{sat} \geq I_{LIM_max} + \Delta i_L$$

Where: I_{sat} is the inductor saturation current and I_{LIM_max} is the maximum spec of the OCP limit.

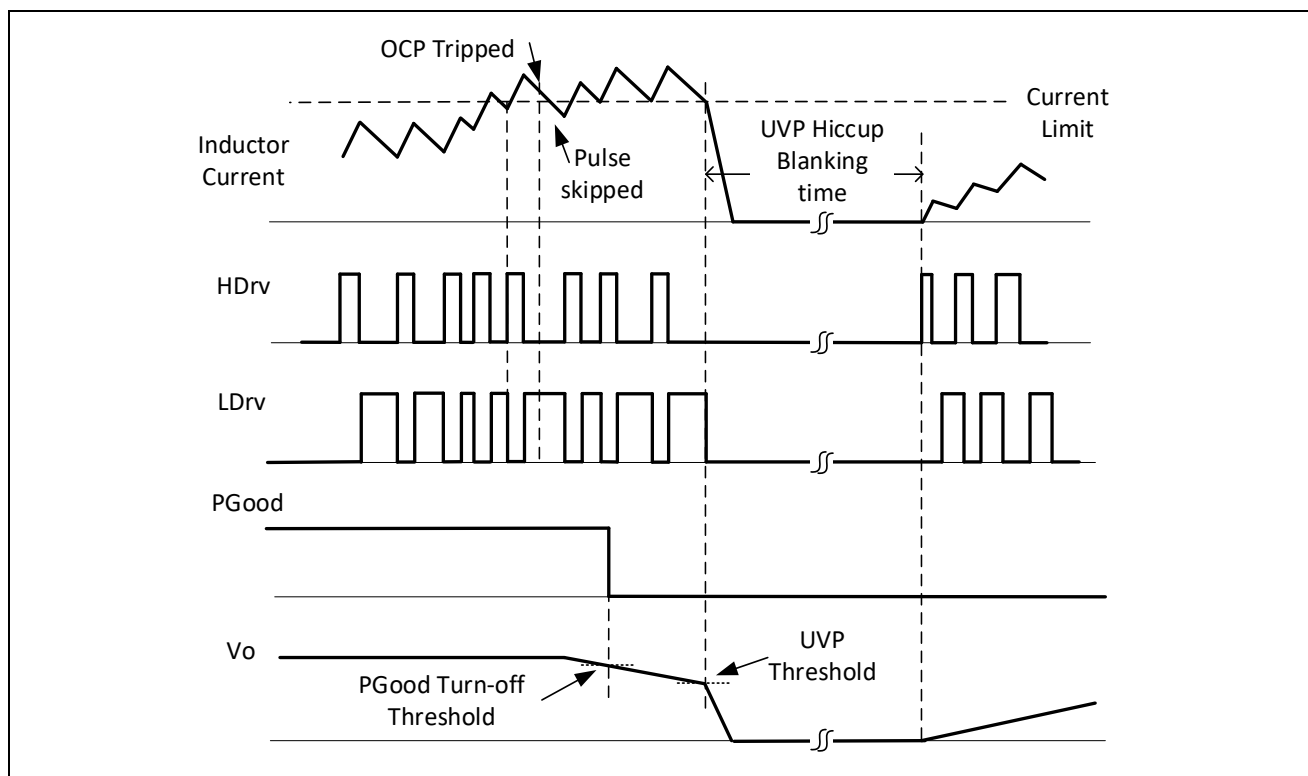


Figure 12 Cycle-by-cycle OCP response

12.9 Under Voltage Protection (UVP)

Under Voltage Protection (UVP) provides additional protection during OCP fault or other faults. UVP is activated when the soft-start voltage rises above 100 mV. UVP circuitry monitors the FB voltage. When it is below the UVP threshold for 5 μ s (typical), an under voltage trip signal asserts and both Control MOSFET and Synchronous MOSFET are turned off. The TDA38827 enters a hiccup mode with a blanking time of 20 ms, during which Control MOSFET and Synchronous MOSFET remain off. After the completion of blanking time, the TDA38827 attempts to recover to the nominal output voltage with a soft-start, as shown in [Figure 12](#). The TDA38827 will repeat hiccup mode and attempt to recover until UVP condition is removed.

12.10 Over Voltage Protection (OVP)

Over Voltage Protection (OVP) is achieved by comparing the VSNS voltage to an OVP threshold voltage. When the VSNS voltage exceeds the OVP threshold, an over voltage trip signal asserts after 7 μ s (typical) delay. Control MOSFET is latched off immediately and Pgood flags low. Synchronous MOSFET remains on to discharge the output capacitor. When FB voltage drops below around 115% of the reference voltage, Synchronous MOSFET turns off to prevent the complete depletion of the output capacitors. [Figure 13](#) illustrates the OVP operation. The OVP comparator becomes active when the EN signal is above the start threshold.

With SS/Latch pin, two OVP responses can be selected: Latch or No Latch, as shown in [Table 6](#). With a latched OVP response, Control FET remains latched off until either VCC voltage or EN signal is cycled. With an unlatched OVP response, the TDA38827 enters a hiccup mode. Control FET remains off for a blanking time of 20ms. After hiccup blanking time expires, the TDA38827 will try to restart with a soft-start. The TDA38827 can stay in the hiccup mode infinitely if over voltage fault persists.

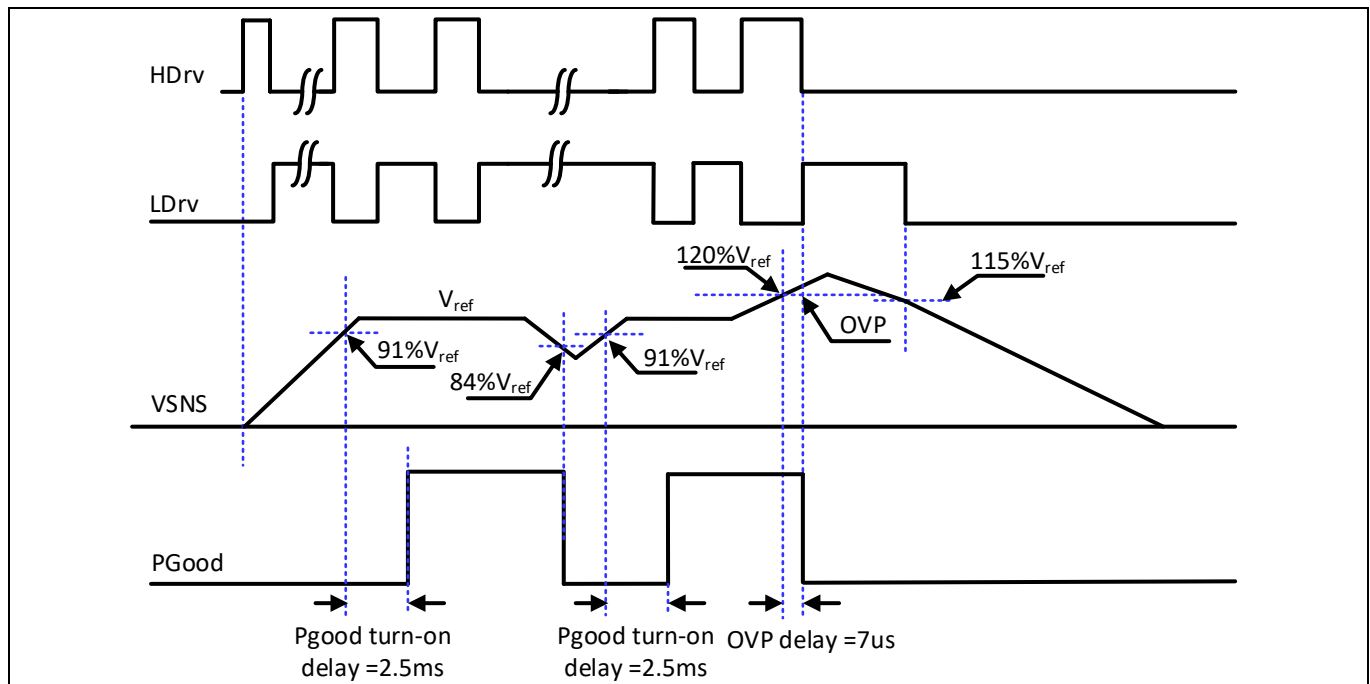


Figure 13 Over voltage protection response and Pgood behavior.

12.11 Over Temperature Protection (OTP)

Temperature of the controller is monitored internally. When the temperature exceeds the over temperature threshold, OTP circuitry turns off both Control and Synchronous MOSFETs, and resets the internal soft start. Automatic restart is initiated when the sensed temperature drops back into the operating range. The thermal shutdown threshold has a hysteresis of 20 °C.

12.12 Power Good (Pgood) output

The Pgood pin is the open drain of an internal NFET, and needs to be externally pulled high through a pull-up resistor. Pgood signal is high when three criteria are satisfied.

1. En signal and VCC voltage are above their respective thresholds.
2. No over voltage and over temperature faults occur.
3. V_o is within the regulation.

In order to detect if V_o is in regulation, Pgood comparator continuously monitors the VSNS voltage. When VSNS voltage ramps up above the upper threshold, Pgood signal is pulled high after 2.5 ms. When VSNS voltage drops below the lower threshold, Pgood signal is pulled low immediately. [Figure 13](#) illustrates the Pgood response.

During the start-up with a pre-biased voltage, Pgood signal is held low before the first PWM is generated and is then pulled high with 2.5 ms delay after VSNS voltage rises above the Pgood threshold. TDA38827 also integrates an additional PFET in parallel to the Pgood NFET, as shown in [Figure 2](#). This PFET allows Pgood signal to stay at logic low when the VCC voltage is not present, and Pgood pin is pulled up by an external bias voltage. Please refer to [Figure 10](#). Since Pgood PFET has relatively higher on resistance, a 50 kΩ pull-up resistor is needed for a Pgood bias voltage of 3.3 V to maintain the Pgood signal at logic low when Pgood PFET is on.

12.13 Minimum on – time and minimum off – time

The minimum on-time refers to the shortest time for Control MOSFET to be reliably turned on. The minimum off-time refers to the minimum time duration in which Synchronous FET stays on before a new PWM pulse is generated. The minimum off-time is needed for TDA38827 to charge the bootstrap capacitor, and to sense the current of the Synchronous MOSFET for OCP.

For applications requiring a small duty cycle, it is important that the selected switching frequency results in an on-time larger than the maximum spec of the minimum on-time in the Section 7.2. Otherwise the resulting switching frequency may be lower than the desired target. Following formula could be used to check for the minimum on-time requirement.

$$\frac{V_0}{kf_{sw} \times PV_{in}} > \max \text{ spec of } T_{on(\min)}$$

Where f_{sw} is the desired switching frequency. k is the variation of the switching frequency. As a rule of thumb, select $k = 1.25$ to ensure the design margin.

For applications requiring a high duty cycle, it is important to make sure a proper switching frequency is selected so that the resulting off-time is longer than the maximum spec of the minimum off-time in the Section 7.2, which can be calculated as shown below.

$$\frac{PV_{in} - V_0}{kf_{sw} \times PV_{in}} > \max \text{ spec of } T_{off(\min)}$$

Where f_{sw} is the desired switching frequency. k is the variation of the switching frequency. As a rule of thumb, select $k = 1.25$ to ensure the design margin.

Please note that with the increase of load current, f_{sw} will increase to maintain the V_0 regulation. Especially during a load transient, a fast large load increase could increase f_{sw} significantly for a short-period of time. Therefore extra design margin needs to be considered to cover the worst case scenario. Also note that OCP limit may be degraded when off-time is close to $T_{off(\min)}$.

The maximum duty cycle can be determined by the selected on-time and minimum off-time, as shown below.

$$D_{max} = \frac{T_{on}}{T_{on} + T_{off(\min)}}$$

12.14 Selection of feedforward capacitor and feedback resistors

A small MLCC capacitor, C_{ff} , is preferred in parallel with the top feedback resistor, R_{FB1} , to provide extra phase boost and to improve the transient load response, as shown in Figure 14. Following formula can be used to help select C_{ff} and R_{FB1} . The value of C_{ff} is recommended to be 100 pF or higher to minimize the impact of circuit parasitic capacitance. C_{ff} and R_{FB1} may be further optimized based on the transient load tests. Where L_o and C_o are the output LC filter of the buck regulator.

$$R_{FB1}C_{ff} = \frac{\sqrt{L_o C_o}}{m \times 4.9}$$

Table 7 Selection of m

V_o	m
$3\text{ V} \leq V_o \leq 6\text{ V}$	0.3
$1.2\text{ V} < V_o < 3\text{ V}$	0.5
$V_o \leq 1.2\text{ V}$	0.7

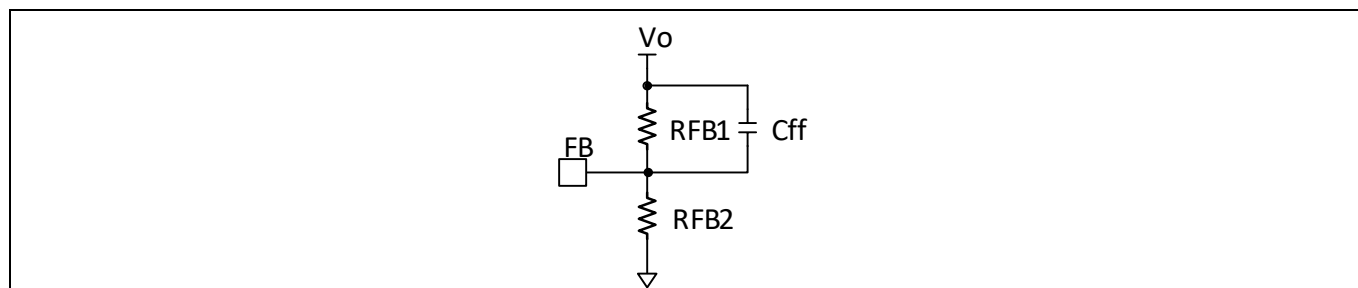


Figure 14 Configuration of feedforward capacitor, Cff.

12.15 Resistors for configuration pins

To properly configure SS/LATCH pin, TON/ MODE pin and ILIM pin, E96 resistors with $\pm 1\%$ tolerance must be used per Table 5, Table 6 and Section 7.2. If E12 resistor values are preferred, the E96 resistors can be replaced with two or three E12 resistors in series, as shown in Table 8. Note that the tolerance of E12 resistors must be $\pm 0.1\%$.

Table 8 Replacement of E96 configuration resistors with E12 resistors in series

E96 $\pm 1\%$	E12 $\pm 0.1\%$ ($R = R_{S1} + R_{S2}$ or $R_{S1} + R_{S2} + R_{S3}$)		
R (k Ω)	R_{S1} (k Ω)	R_{S2} (k Ω)	R_{S3} (k Ω)
4.53	2.7	1.8	N/A
1.50	1.5	0	N/A
5.76	5.6	0.15	N/A
2.49	1.8	0.68	N/A
7.32	6.8	0.56	N/A
3.45	3.3	0.15	N/A
8.87	8.2	0.68	N/A
10.5	10	0.47	N/A
12.1	12	0.1	N/A
21.5	18	3.3	N/A
14	10	3.9	N/A
24.9	22	2.7	N/A
16.2	15	1.2	N/A
28.7	27	1.8	N/A
21.5	18	3.3	0.18
24.9	22	2.7	0.18

13 Design example

In this section, an example is used to explain how to design a buck regulator with the TDA38827. The application circuit is shown in Figure 15. The design specifications are given below.

- $PV_{in} = 12\text{ V}$ ($\pm 10\%$)
- $V_o = 1.0\text{ V}$
- $I_o = 25\text{ A}$
- V_o ripple voltage = $\pm 1\%$ of V_o
- Load transient response = $\pm 3\%$ of V_o with a step load current = 9 A and slew rate = $30\text{ A}/\mu\text{s}$

13.1 Enabling the TDA38827

The TDA38827 has a precise Enable threshold voltage, which can be used to implement a UVLO of the input bus voltage by connecting the EN pin to PV_{in} with a resistor divider, as shown in Configuration 2 of Figure 9. The Enable feedback resistor, R_{EN1} and R_{EN2} , can be calculated as follows.

$$PV_{in(min)} \times \frac{R_{EN2}}{R_{EN1} + R_{EN2}} \geq V_{EN(max)}$$

$$R_{EN2} \geq R_{EN1} \times \frac{V_{EN(max)}}{PV_{in(min)} - V_{EN(max)}}$$

Where $V_{EN(max)}$ is the maximum spec of the En-start-threshold as defined in Section 7.2. For $PV_{in(min)} = 10.8\text{ V}$, select $R_{EN1} = 49.9\text{ k}\Omega$ and $R_{EN2} = 7.5\text{ k}\Omega$.

13.2 Programming the switching frequency and operation mode

The TDA38827 has very good efficiency performance and is suitable for high switching frequency operation. In this case, 800 kHz is selected to achieve a good compromise between the efficiency, passive component size and dynamic response. In addition, FCCM operation is selected to ensure a small output ripple voltage over the entire load range. To select 800 kHz and FCCM operation, the TON/MODE pin can be left floating or connect a $1.5\text{ k}\Omega$ resistor to GND per Table 5.

13.3 Selecting input capacitors

Without input capacitors, the pulse current of Control MOSFET is directly from the input supply power. Due to the impedance on the cable, the pulse current can cause disturbance on the input voltage and potential EMI issues. The input capacitors filter the pulse current, resulting in almost constant current from the input supply. The input capacitors should be selected to tolerate the input pulse current, and to reduce the input voltage ripple. The RMS value of the input ripple current can be expressed by:

$$I_{RMS} = I_o \times \sqrt{D \times (1 - D)}$$

$$D = \frac{V_o}{PV_{in}}$$

Where I_{RMS} is the RMS value of the input capacitor current. I_o is the output current and D is the Duty Cycle. For $I_o = 25\text{ A}$ and $D_{(max)} = 0.09$, the resulting RMS current flowing into the input capacitor is $I_{rms} = 7.2\text{ A}$.

To meet the requirement of the input ripple voltage, the minimum input capacitance can be calculated as follows.

$$C_{in(min)} > \frac{I_o \times (1 - D) \times D}{f_{sw} \times (\Delta PV_{in} - ESR \times I_o \times (1 - D))}$$

Where ΔPV_{in} is the maximum allowable peak-to-peak input ripple voltage, and ESR is the equivalent series resistor of the input capacitors. Ceramic capacitors are recommended due to low ESR, ESL and high RMS current capability. For $I_o = 25$ A, $f_{sw} = 800$ kHz, $ESR = 3$ m Ω , and $\Delta PV_{in} = 240$ mV, $C_{in(min)} > 15$ μ F. To account for the de-rating of ceramic capacitors under a bias voltage, 10 x 22 μ F/0805/25V MLCC are used for the input capacitors. In addition, a bulk capacitor is recommended if the input supply is not located close to the voltage regulator.

13.4 Inductor selection

The inductor is selected based on output power, operating frequency and efficiency requirements. A low inductor value results in a large ripple current, lower efficiency and high output noise, but helps with size reduction and transient load response. Generally, the desired peak-to-peak ripple current in the inductor (Δi) is found between 20% and 50% of the output current.

The inductor saturation current must be higher than the maximum spec of the OCP limit plus the peak-to-peak inductor ripple current. For some core material, inductor saturation current may decrease as the increase of temperature. So it is important to check the inductor saturation current at the maximum operating temperature.

The inductor value for the desired operating ripple current can be determined using the following relation:

$$L = (PV_{in(max)} - V_o) \times \frac{D_{min}}{\Delta i_{L(max)} \times F_{sw}}$$

$$D_{min} = \frac{V_o}{PV_{in(max)}}$$

$$I_{sat} \geq OCP_{max} + \Delta i_{L(max)}$$

Where: $PV_{in(max)}$ = Maximum input voltage; $\Delta i_{L(max)}$ = Maximum peak-to-peak inductor ripple current; OCP_{max} = maximum spec of the OCP limit as defined in Section 7.2; and I_{sat} = inductor saturation current. In this case, select inductor $L = 150$ nH to achieve $\Delta i_{L(max)} = 30\%$ of $I_{o(max)}$. The I_{sat} should be no less than 42 A.

13.5 Output capacitor selection

The output capacitor selection is mainly determined by the output voltage ripple and transient requirements.

To satisfy the V_o ripple requirement, C_o should satisfy the following criterion.

$$C_o > \frac{\Delta i_{Lmax}}{8 \times \Delta V_{or} \times f_{sw}}$$

Where ΔV_{or} is the desired peak-to-peak output ripple voltage. For $\Delta i_{L(max)} = 7.6$ A, $\Delta V_{or} = 20$ mV, $f_{sw} = 800$ kHz, C_o must be larger than 59 μ F. The ESR and ESL of the output capacitors, as well as the parasitic resistance or inductance due to PCB layout, can also contribute to the output voltage ripple. It is suggested to use Multi-Layer Ceramic Capacitor (MLCC) for their low ESR, ESL and small size.

To meet the transient response requirements, the output capacitors should also meet the following criterion.

$$C_o > \frac{L \times \Delta I_{o(max)}^2}{2 \times \Delta V_{oL} \times V_o}$$

Design example

Where ΔV_{OL} is the allowable V_o deviation during the load transient. $\Delta I_{o(max)}$ is the maximum step load current. Please note that the impact of ESL, ESR, control loop response, transient load slew rate, and PWM latency is not considered in the calculation shown above. Extra capacitance is usually needed to meet the transient requirements. As a rule of thumb, we can triple the C_o that is calculated above as a starting point, and then optimize the design based on the bench measurement. In this case, to meet the transient load requirement (i.e. $\Delta V_{OL} = 30$ mV, $\Delta I_{o(max)} = 9$ A), select $C_o = \sim 800$ μ F. For more accurate estimation of C_o , simulation tool should be used to aid the design.

13.6 Output voltage programming

Output voltage can be programmed with an external voltage divider. The FB voltage is compared to an internal reference voltage of 0.6 V. The divider ratio is set to provide 0.6 V at the FB pin when the output is at its desired value. The calculation of the feedback resistor divider is shown below.

$$V_o = V_{ref} \times \left(1 + \frac{R_{FB1}}{R_{FB2}}\right)$$

Where R_{FB1} and R_{FB2} are the top and bottom feedback resistors. Select $R_{FB1} = 7.5$ k Ω and $R_{FB2} = 11.3$ k Ω , to achieve $V_o = 1$ V. Same set of the resistor divider can be used at VSNS pin to achieve the same voltage scaling factor.

13.7 Feedforward capacitor

A small MLCC capacitor, C_{ff} , can be placed in parallel with the top feedback resistor, R_{FB1} , to improve the transient response. Based on Section 12.14, C_{ff} can be selected using the following formula.

$$R_{FB1} C_{ff} = \frac{\sqrt{L_o C_o}}{0.7 \times 4.9}$$

With $L_o = 150$ nH, $C_o = 800$ μ F and $R_{FB1} = 7.5$ k Ω , $C_{ff} = 470$ pF. C_{ff} can be further optimized on the bench test based on transient load response.

13.8 Bootstrap capacitor

For most applications, a 0.1 μ F ceramic capacitor is recommended for bootstrap capacitor placed between SW and BOOT Pin.

13.9 VIN and VCC/LDO bypass capacitor

Please see the recommendation in Section 12.7. A 10 μ F MLCC is selected for VCC/LDO bypass capacitor and a 4.7 μ F MLCC is selected for VIN bypass capacitor.

14 Application information

14.1 Application diagram

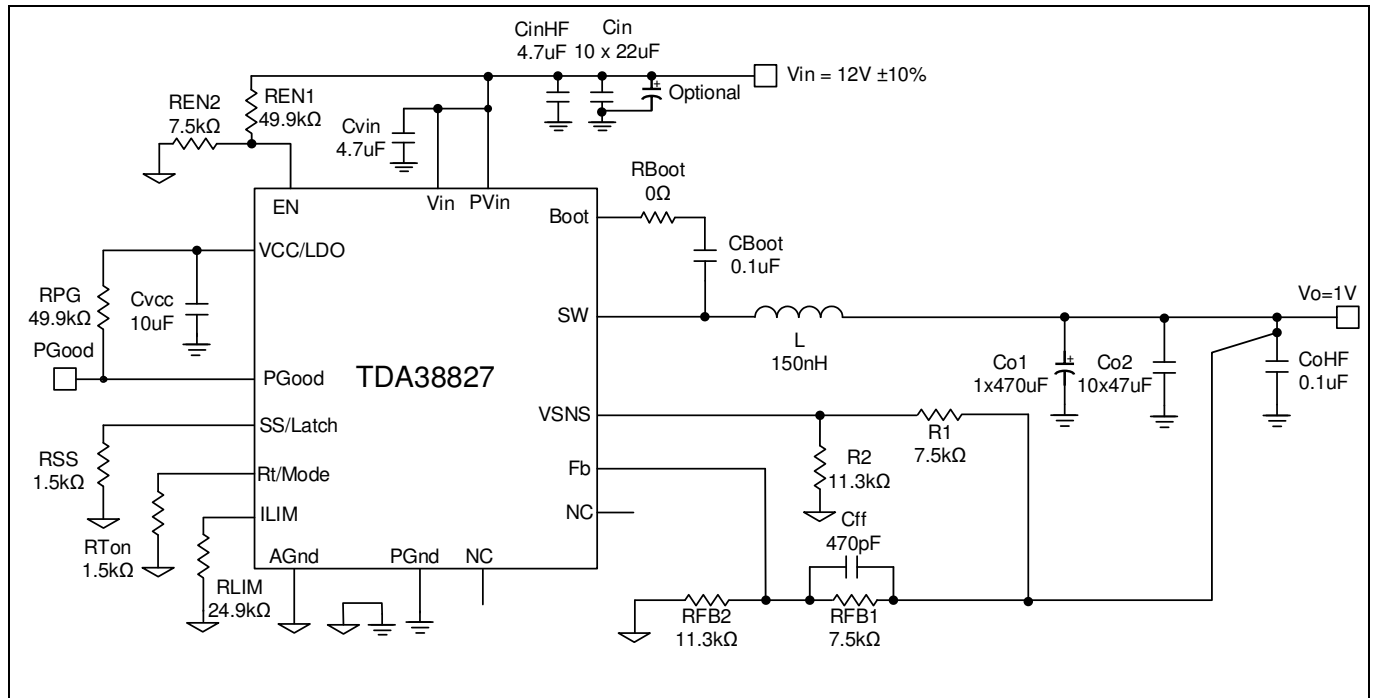


Figure 15 Application diagram of TDA38827. Pvin = 12 V, Vo = 1V, Io = 25 A, fsw = 800 kHz.

14.2 Typical operating waveforms

PVin = Vin = 12.0 V, Vo = 1 V, Io = 0 – 25 A, fsw = 800 kHz, Room Temperature, no airflow

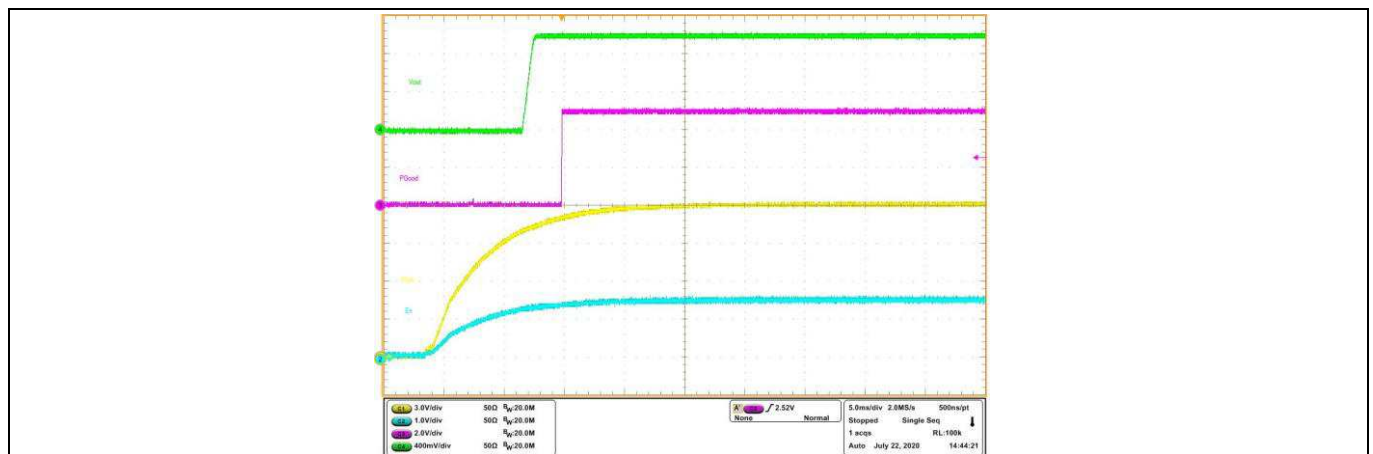


Figure 16 Start up at 25 A Load, (Ch1: PVin, Ch2: Enable, Ch3:PGGood,Ch4: Vout)

TDA38827 OptiMOS™ IPOL

25 A single-voltage synchronous Buck regulator

Application information

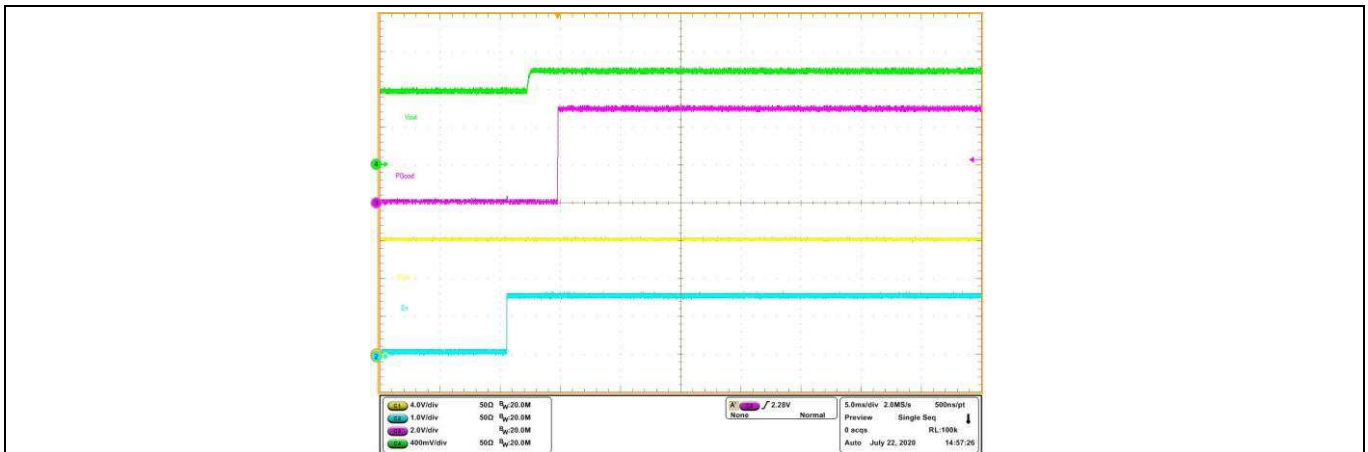


Figure 17 Pre-bias Start up at 0 A Load, (Ch1: PV_{in}, Ch2: Enable, Ch3:Pgood, Ch4: V_{out})

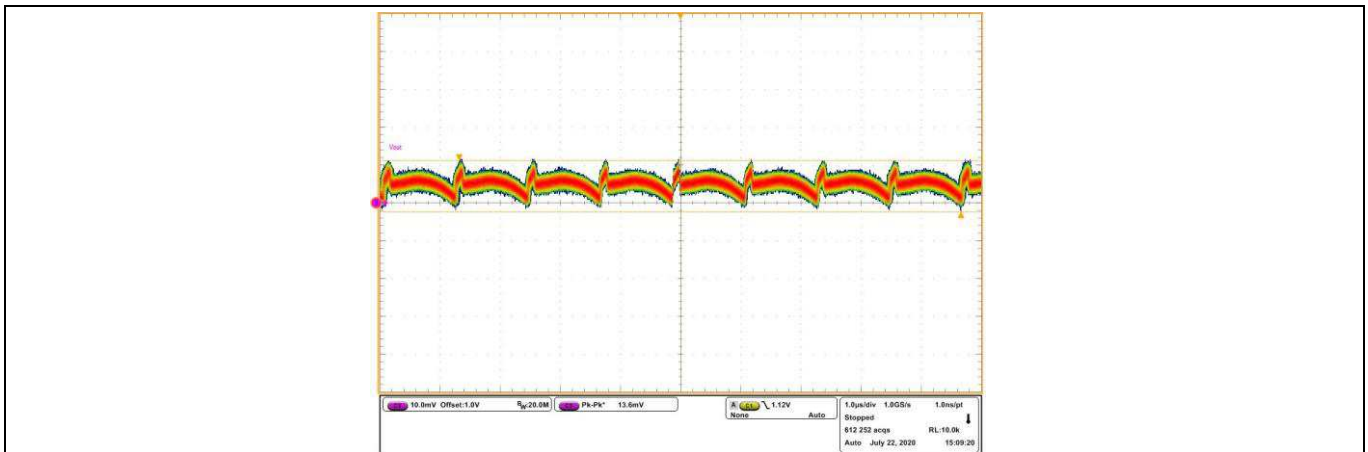


Figure 18 V_{out} ripple at 25 A Load, f_{sw} = 800 kHz, (Ch3: V_o)

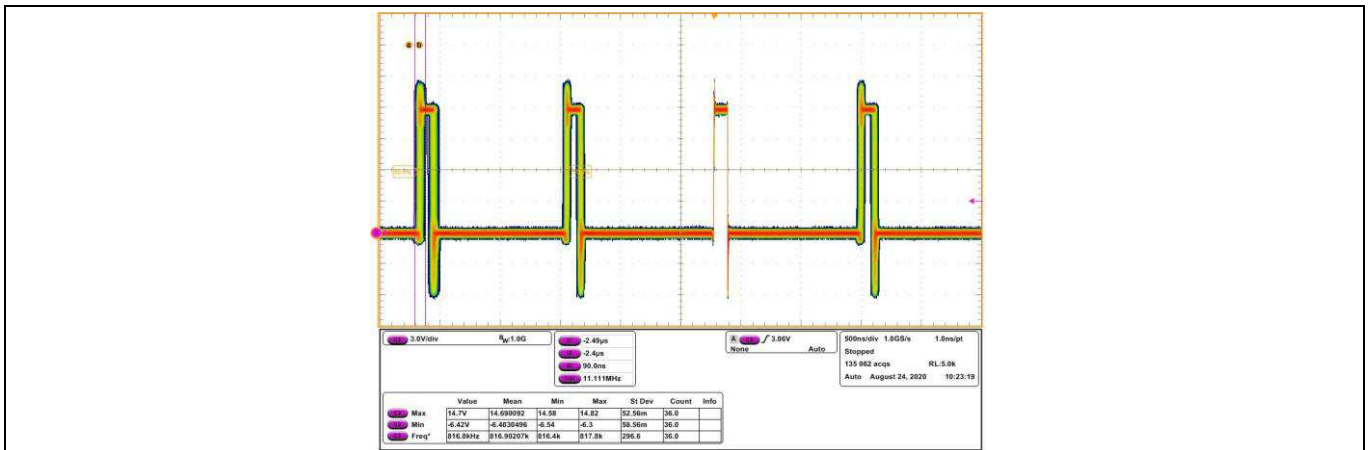


Figure 19 SW node, 25 A load, f_{sw} = 800 kHz

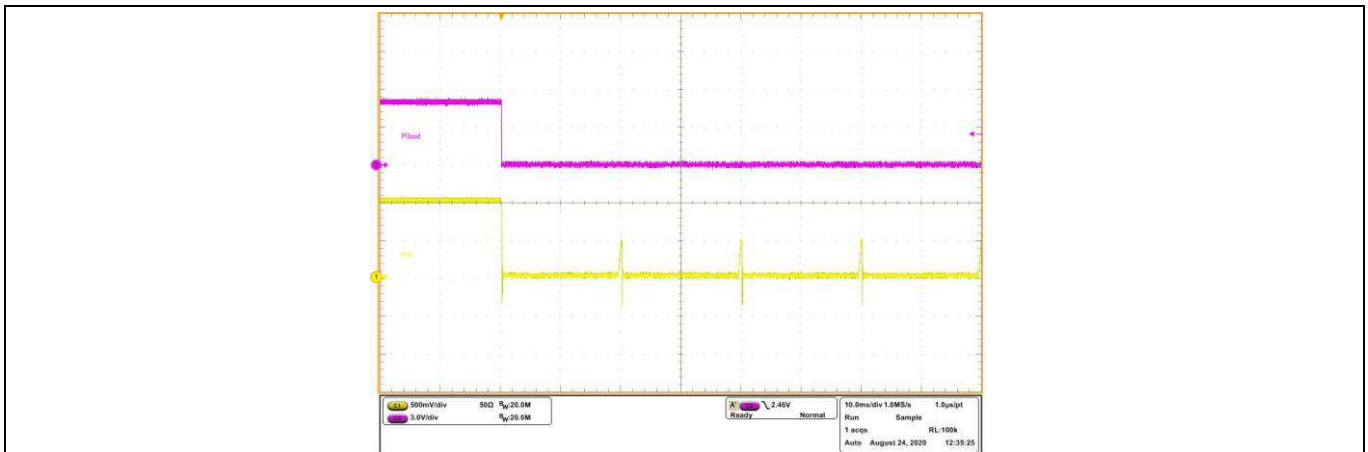


Figure 20 Short circuit and UVP (Hiccup), (Ch₁: V_o, Ch₃:Pgood)

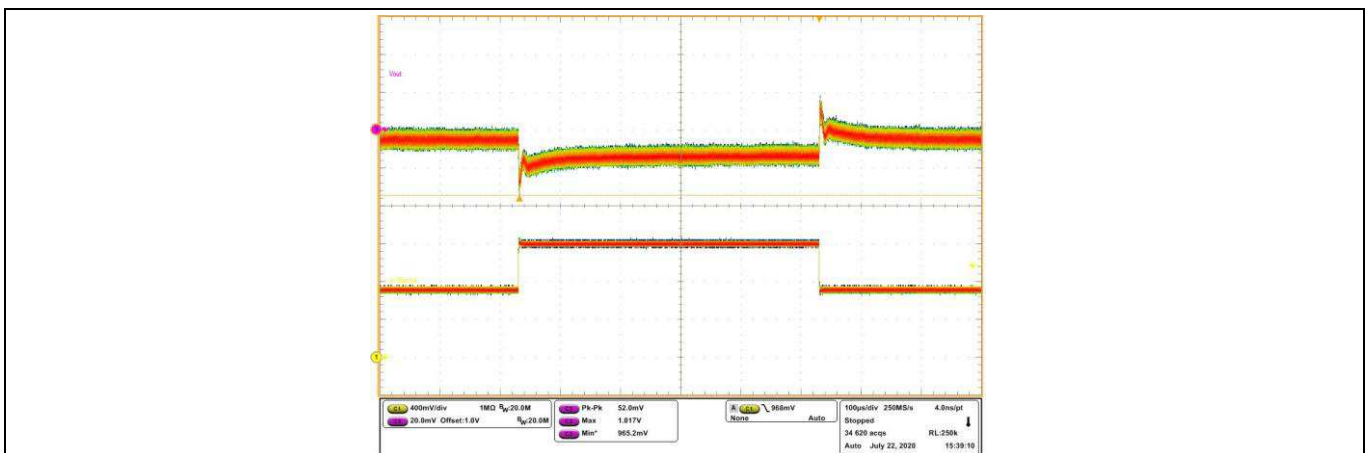


Figure 21 Transient response at 9 A step load current @ 30 A/μs slew rate: I_o = 16 A – 25 A, (Ch₁: V_o, Ch₄: I_o), pk-pk: 52 mV, fsw = 800 kHz



Figure 22 Thermal image of the board at 25 A load TDA38827 = 92°C, L = 65.7°C, fsw = 800 kHz, room temperature, natural convection

15 Layout recommendations

PCB layout is very important when designing high frequency switching converters. Layout will affect noise pickup and can cause a good design to perform with less than expected results. Following design guidelines are recommended to achieve the best performance.

- Bypass capacitors, including input/output capacitors, Vin and VCC bypass capacitors, should be placed near the corresponding pins as close as possible.
- Place bypass capacitors from TDA38827 power input (Drain of Control MOSFET) to PGND (Source of Synchronous MOSFET) to reduce noise and ringing in the system. The output capacitors should be terminated to a ground plane that is away from the input PGND to mitigate the switching spikes on the Vout. The Vin and VCC bypass capacitor should be terminated to PGND.
- Place a boot strap capacitor near the TDA38827 BOOT and SW pin as close as possible to minimize the loop inductance.
- SW node copper should only be routed on the top layer to minimize the impact of switching noises
- Connect AGND pin to the PGND pad through a single point connection. On the TDA38827 demo board, AGND pin is connected to the exposed AGND pad (Pin 23) and then connected to the internal PGND layer through the thermal via holes.
- Via holes can be placed on PVIN and PGND pads to aid thermal dissipation.
- Wide copper polygons are desired for Pvin and PGND connections in favor of power losses reduction and thermal dissipation. Sufficient via holes should be used to connect power traces between different layers.
- To implement the V_o sensing, following design guidelines should be followed, as illustrated in **Figure 23**.
 - The output voltage can be sensed from a high-frequency bypass capacitor of 0.1 μF or higher, preferably through a 15 mil PCB trace.
 - Keep the Vout sense line away from any noise sources and shield the sense line with ground planes.
 - The sense trace is connected to a feedback resistor divider with the lower resistor terminated at AGND pin.
- The En pin and configuration pins including SS/Latch, Rt/MODE, and ILIM should be terminated to a quiet ground. On the TDA38827 standard demo board, they are terminated to the PGND copper plane away from the power current flow. Alternatively, they can be terminated to a dedicated AGND PCB trace.

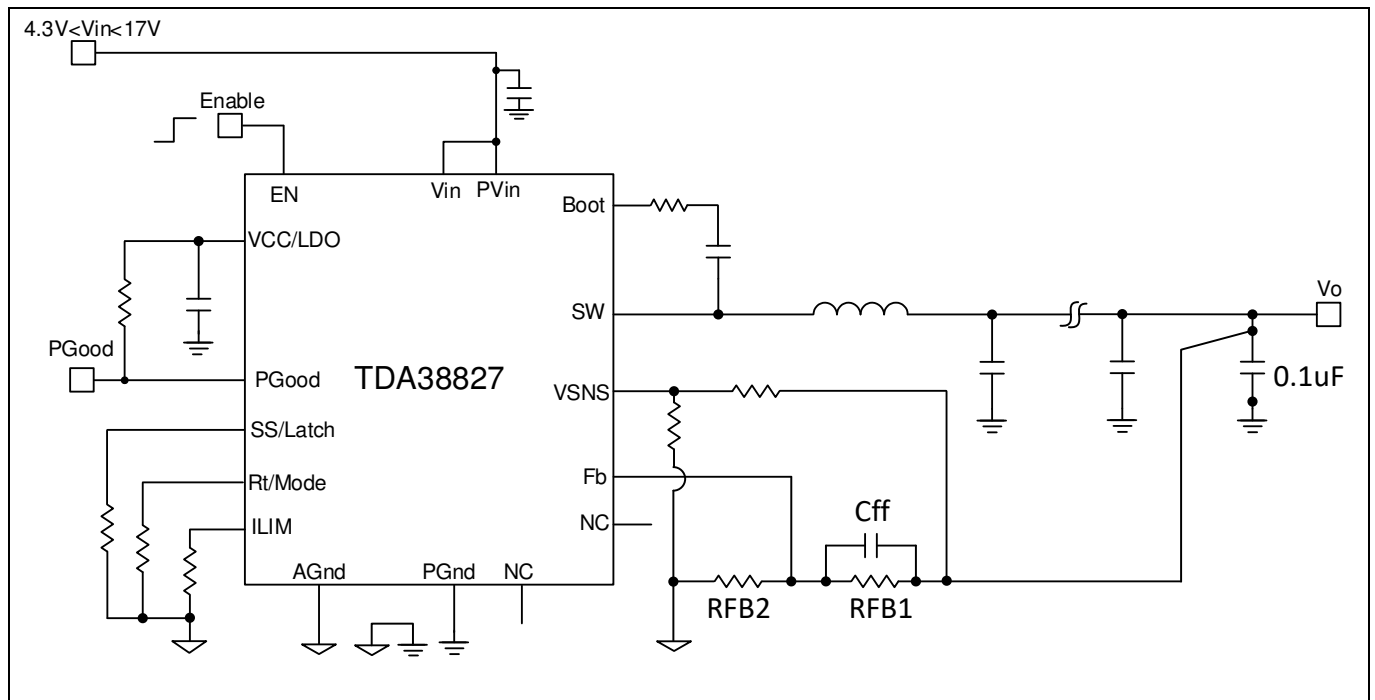


Figure 23 Single-ended V_o sense configuration

Following figures illustrate the PCB layout design of the TDA38827 standard demo board.

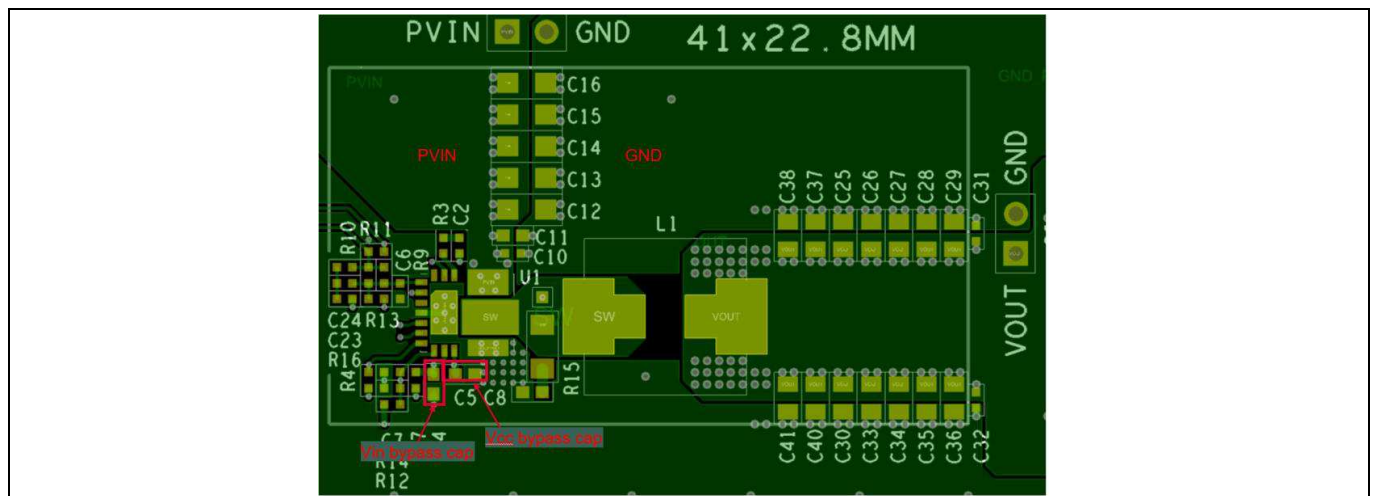


Figure 24 TDA38827 Demo Board – Top Layer

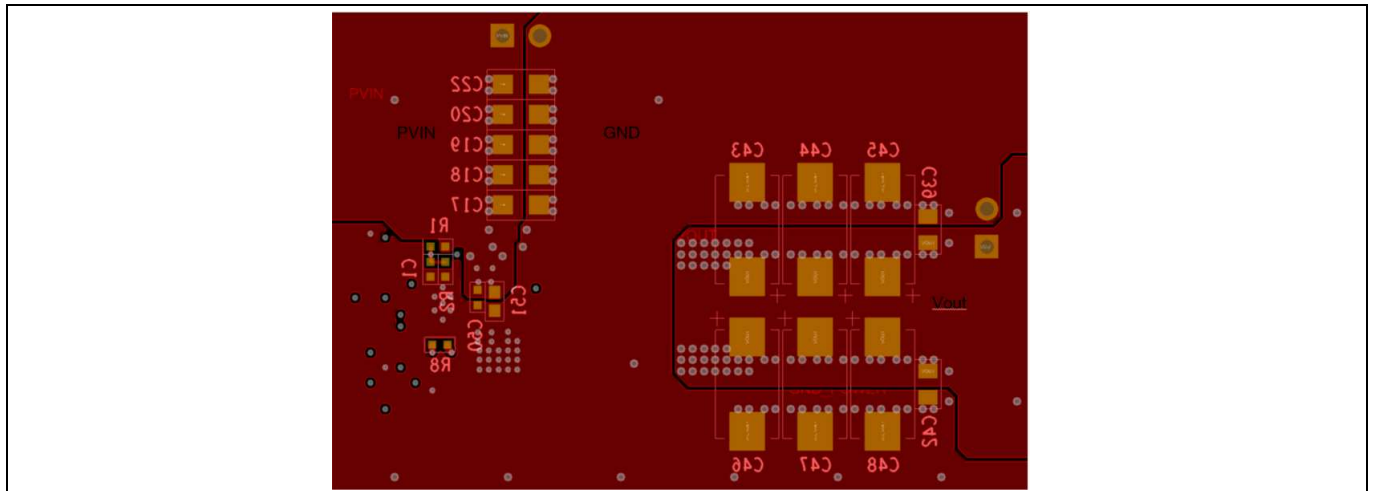


Figure 25 TDA38827 Demo Board – Bottom Layer

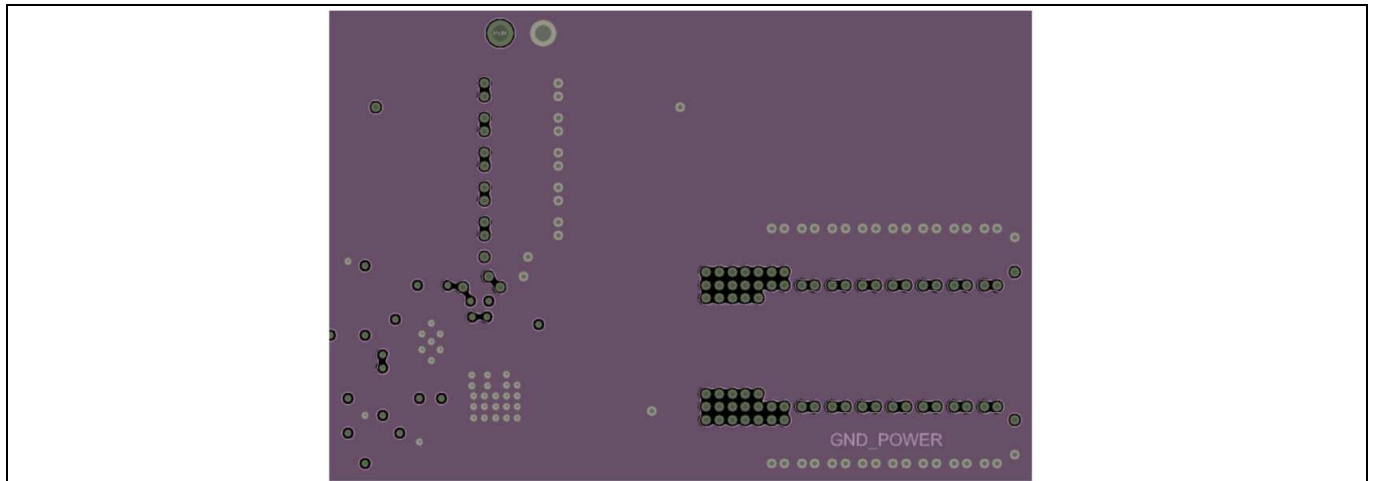


Figure 26 TDA38827 Demo Board – 2nd Layer (Ground)

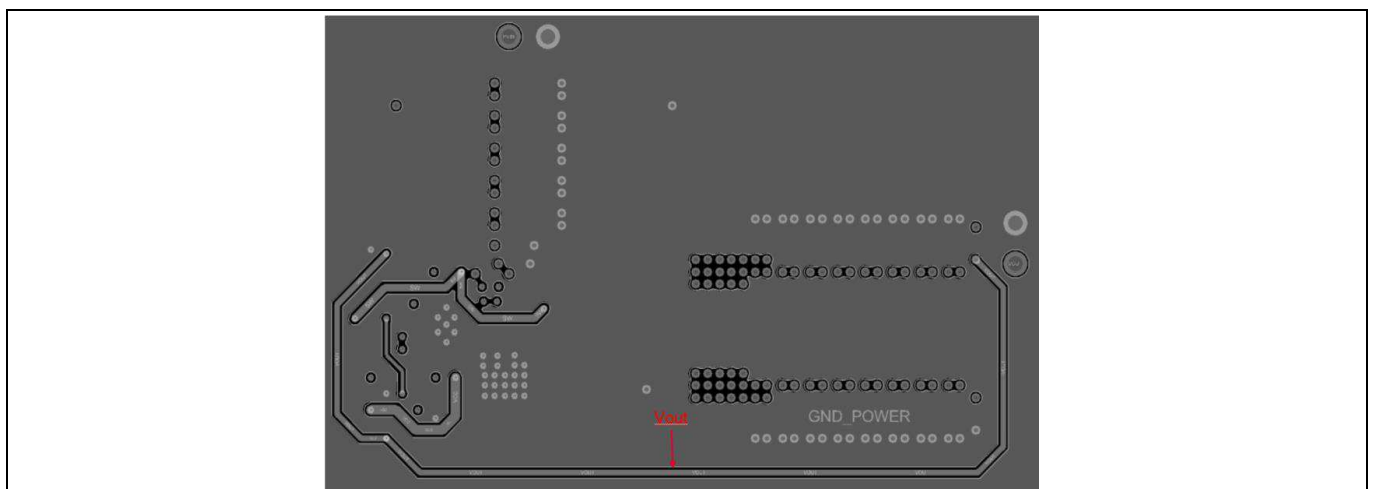


Figure 27 TDA38827 Demo Board – 3rd Layer (Ground & Signal)

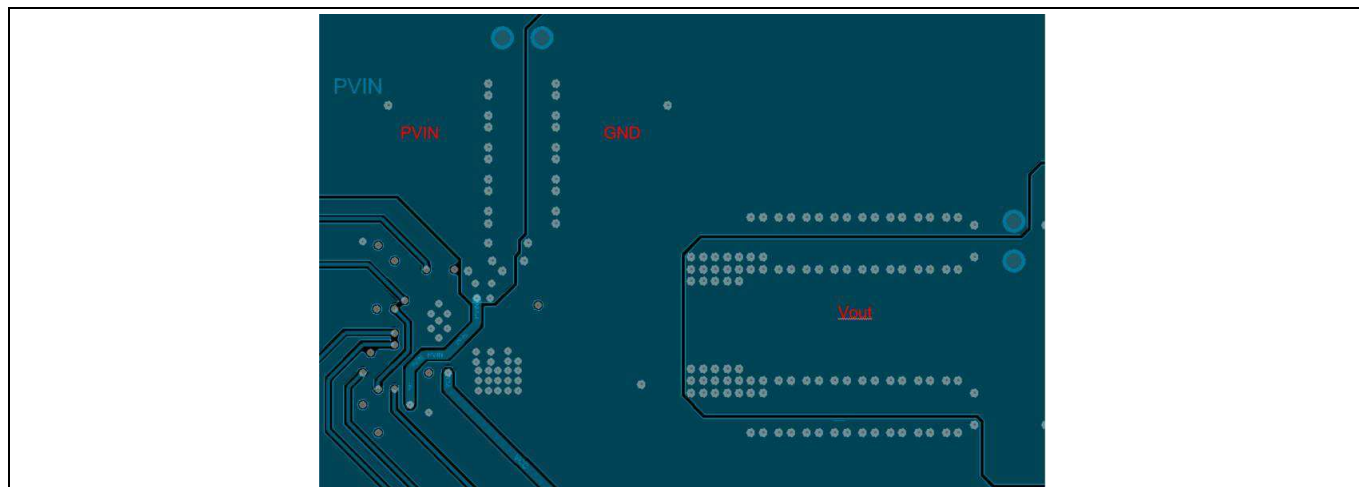


Figure 28 TDA38827 Demo Board – 4th Layer (Ground & Signal)

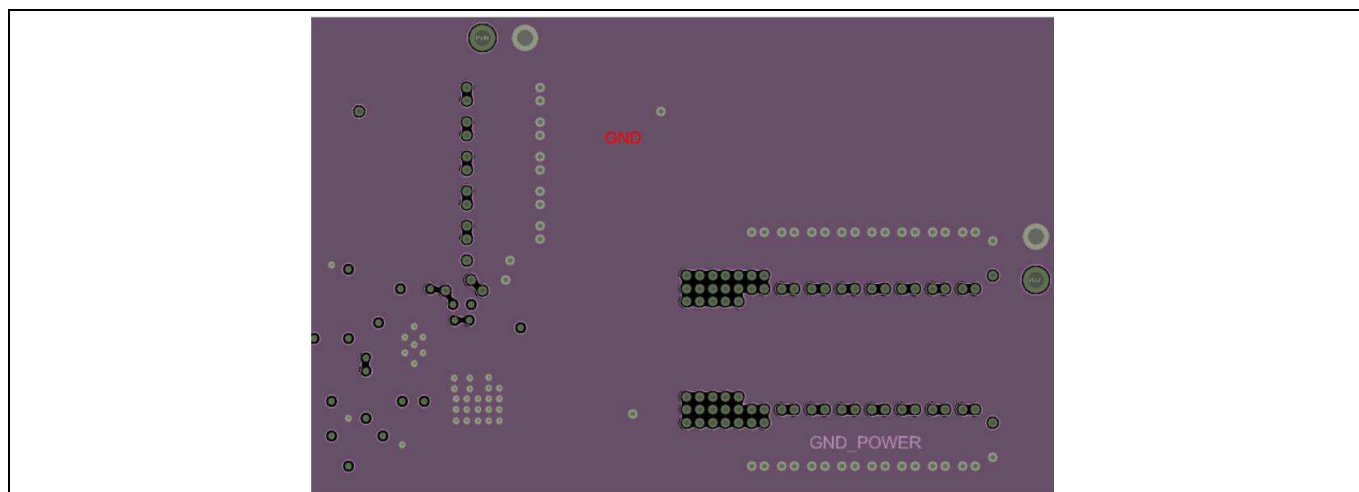


Figure 29 TDA38827 Demo Board – 5th Layer (Ground)

15.1 Solder mask

Evaluation has shown that the best overall performance is achieved using the substrate/PCB layout as shown in the following figures. PQFN devices should be placed to an accuracy of 0.050 mm on both X and Y axes. Self-centering behavior is highly dependent on solders and processes, and experiments should be run to confirm the limits of self-centering on specific processes.

Infinitec recommends that larger Power or Land Area pads are Solder Mask Defined (SMD). This allows the underlying copper traces to be as large as possible, which helps in terms of current carrying capability and device cooling capability. When using SMD pads, the underlying copper traces should be at least 0.05 mm larger (on each edge) than the openings in the solder mask. This allows for layers to be misaligned by up to 0.1 mm on both axes. Ensure that the solder resist in-between the smaller signal lead areas is at least 0.15 mm wide, due to the high x/y aspect ratio of the solder mask strip.

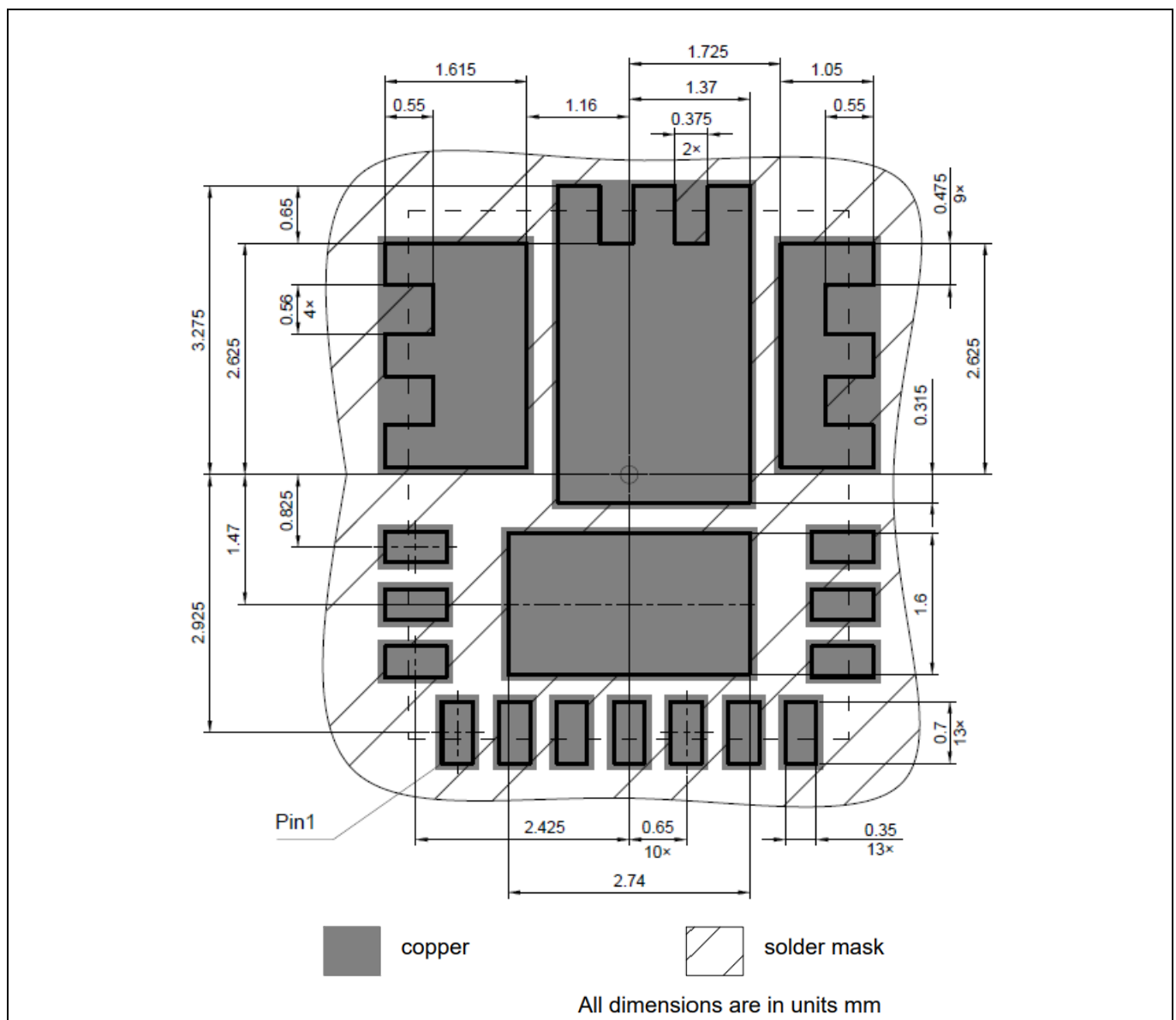


Figure 30 Solder mask (all dimensions in mm)

15.2 Stencil design

Stencils for PQFN packages can be used with thicknesses of 0.100-0.250 mm (0.004-0.010"). Stencils thinner than 0.100 mm are unsuitable because they deposit insufficient solder paste to make good solder joints with the ground pad; high reductions sometimes create similar problems. Stencils in the range of 0.125 mm-0.200 mm (0.005-0.008"), with suitable reductions, give the best results. A recommended stencil design is shown below. This design is for a stencil thickness of 0.127 mm (0.005"). The reduction should be adjusted for stencils of other thicknesses.

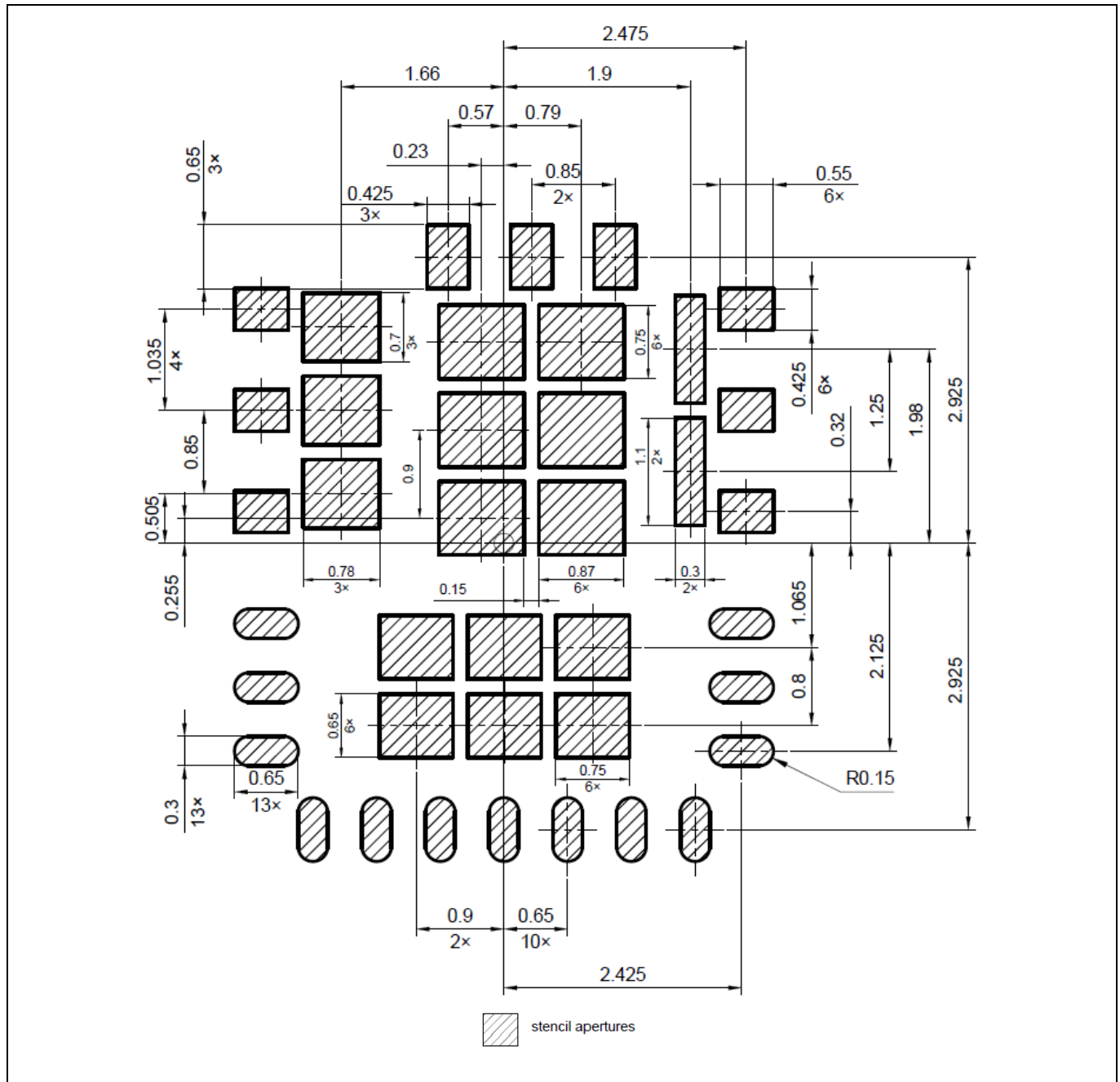


Figure 31 Stencil pad size and spacing (all dimensions in mm)

16.3 Tape and reel information

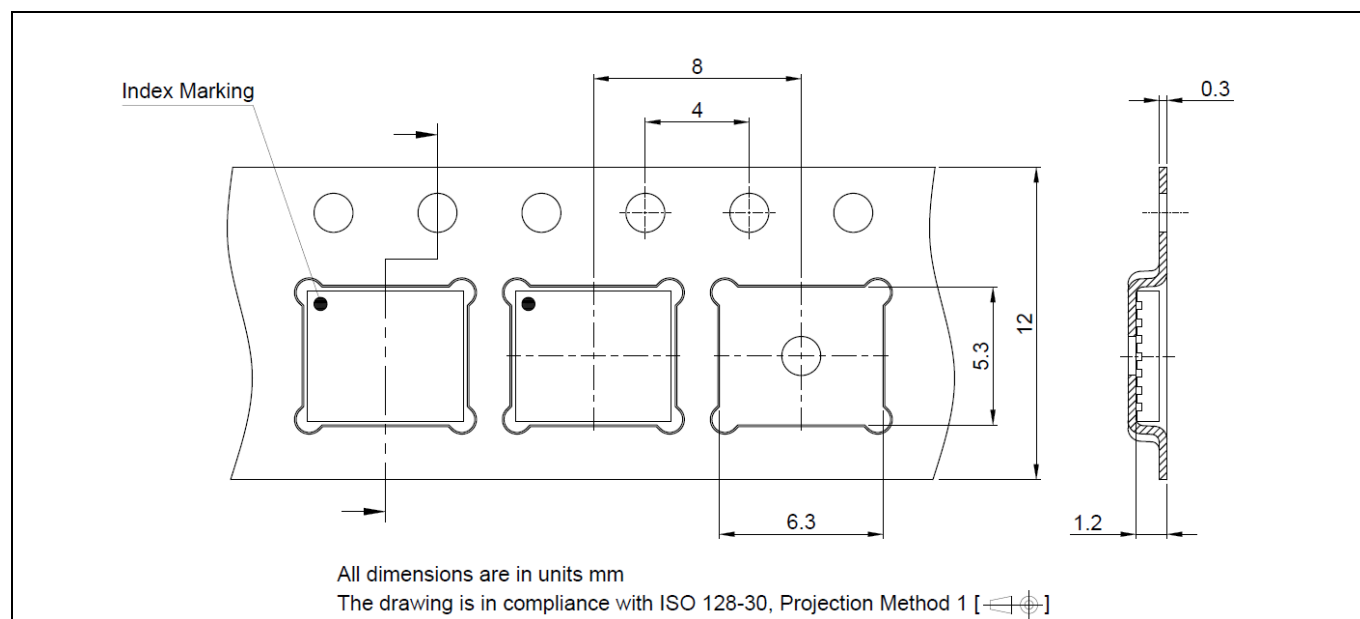


Figure 34 Pin 1 orientation in the tape

17 Environmental qualifications

Qualification Level		Industrial	
Moisture Sensitivity		QFN Package	JEDEC Level 2 @ 260 °C
ESD	Human Body Model	ANSI/ESDA/JEDEC JS-001, 2 (2000 V to < 4000 V)	
	Charged Device Model	ANSI/ESDA/JEDEC JS-002, C3 (≥ 1000 V)	
RoHS2 Compliant		This product is in compliance with EU Directive 2015/863/EU amending Annex II to EU Directive 2011/65/EU (RoHS) and contains Pb according RoHS exemption 7a, Lead in high melting temperature type solders.	

18 Evaluation boards and support documentation

Table 9 TDA38827 Evaluation Boards and User Guides

Evaluation board	Specifications	Website Address
EVAL_38827_1Vout	12 V±10%, 1 V, 25 A	www.infineon.com/EVAL_38827_1Vout

Table 10 TDA38827 Package Information

Device	Package Type	Website Address
TDA38827	PG-IQFN-22-2	https://www.infineon.com/cms/en/product/packages/PG-IQFN

Revision History

TDA38827

Revision: 2021-07-27, Rev. 2.3

Previous Revision

Revision	Date	Subjects (major changes since last revision)
2.0	2020-09-24	Release of final version, Change Pin numbering from 23 pins to 17 pins, to match with IR3894/5, IR3824/5/6/6A
2.1	2021-03-02	(1) Update ordering info; (2) Correct UVP activation threshold in section 12.9; (3) Correct test conditions of dead time in EC table
2.2	2021-04-17	1) Add max Vout of 6V to the recommended operating conditions; (2) Update note 8; (3) Correct typo in Table 7; (4) Add Fig 22.
2.3	2021-07-27	(1). Change typ value of top switch Rds(on) from 3.8mohm to 3.3mohm (2). Change test condition of OCP limit in EC table from VCC = 5.0V to int LDO (3). Update Fig 30, 31, 33, and 34 (4). Correct typo in Table 7

Trademarks

All referenced product or service names and trademarks are the property of their respective owners.

We Listen to Your Comments

Any information within this document that you feel is wrong, unclear or missing at all? Your feedback will help us to continuously improve the quality of this document. Please send your proposal (including a reference to this document) to:

erratum@infineon.com

Published by

Infineon Technologies AG

81726 München, Germany

© 2020 Infineon Technologies AG

All Rights Reserved.

Legal Disclaimer

The information given in this document shall in no event be regarded as a guarantee of conditions or characteristics ("Beschaffenheitsgarantie").

With respect to any examples, hints or any typical values stated herein and/or any information regarding the application of the product, Infineon Technologies hereby disclaims any and all warranties and liabilities of any kind, including without limitation warranties of non-infringement of intellectual property rights of any third party.

In addition, any information given in this document is subject to customer's compliance with its obligations stated in this document and any applicable legal requirements, norms and standards concerning customer's products and any use of the product of Infineon Technologies in customer's applications.

The data contained in this document is exclusively intended for technically trained staff. It is the responsibility of customer's technical departments to evaluate the suitability of the product for the intended application and the completeness of the product information given in this document with respect to such application.

Information

For further information on technology, delivery terms and conditions and prices please contact your nearest Infineon Technologies Office (www.infineon.com).

Warnings

Due to technical requirements, components may contain dangerous substances. For information on the types in question, please contact the nearest Infineon Technologies Office.

The Infineon Technologies component described in this Data Sheet may be used in life-support devices or systems and/or automotive, aviation and aerospace applications or systems only with the express written approval of Infineon Technologies, if a failure of such components can reasonably be expected to cause the failure of that life-support, automotive, aviation and aerospace device or system or to affect the safety or effectiveness of that device or system. Life support devices or systems are intended to be implanted in the human body or to support and/or maintain and sustain and/or protect human life. If they fail, it is reasonable to assume that the health of the user or other persons may be endangered.

Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

[Infineon:](#)

[TDA38827AUMA1](#)