

# XENSIV™ PAS CO2

## Description

Infineon has leveraged its knowledge in sensors and MEMS technologies to develop a disruptive gas sensor for CO<sub>2</sub> sensing. The XENSIV™ PAS CO<sub>2</sub> is a real CO<sub>2</sub> sensor in an exceptionally small form factor based on the photoacoustic spectroscopy (PAS) principle.

Infineon's MEMS microphone, which is optimized for low-frequency operation, detects the pressure change generated by CO<sub>2</sub> molecules within the sensor cavity. CO<sub>2</sub> concentration is then delivered in the form of a direct ppm readout thanks to the integrated microcontroller. Highly accurate CO<sub>2</sub> readings are guaranteed.



## Features

- **Operating range:** 0 ppm to 32000 ppm
- **Accuracy:**  $\pm$  (30 ppm +3%) of reading between 400 ppm and 5000 ppm
- **Lifetime:** 10 years
- **Operating temperature:** 0-50°C
- **Operating relative humidity:** 0% to 85% (Non-condensing)
- **Interface:** I2C, UART, and PWM
- **Supply voltage:** 12.0 V for the emitter and 3.3 V for other components
- **Average power consumption:** Typically, 30 mW at 1 measurement/minute
- **Package dimension:** 13.8 x 14 x 7.5 mm<sup>3</sup>

## Potential applications

High accuracy, compact size, and SMD capability make the XENSIV™ PAS CO<sub>2</sub> ideal for indoor air quality monitoring solutions in the market with numerous potential applications.

- **Building automation:** Demand Controlled Ventilation, Air Handler Units, Air Exchanger
- **Home appliances:** Air purifiers, Air Conditioner
- **Smart home IoT devices:** Thermostat, Speaker, Baby monitors, Personal assistants, Indoor Air Quality Monitor, Smart lighting.
- **City management/ CO<sub>2</sub> emissions control:** Outdoor lighting, Bus stop stations, Advertising billboards.
- **In-cabin air quality monitoring unit**



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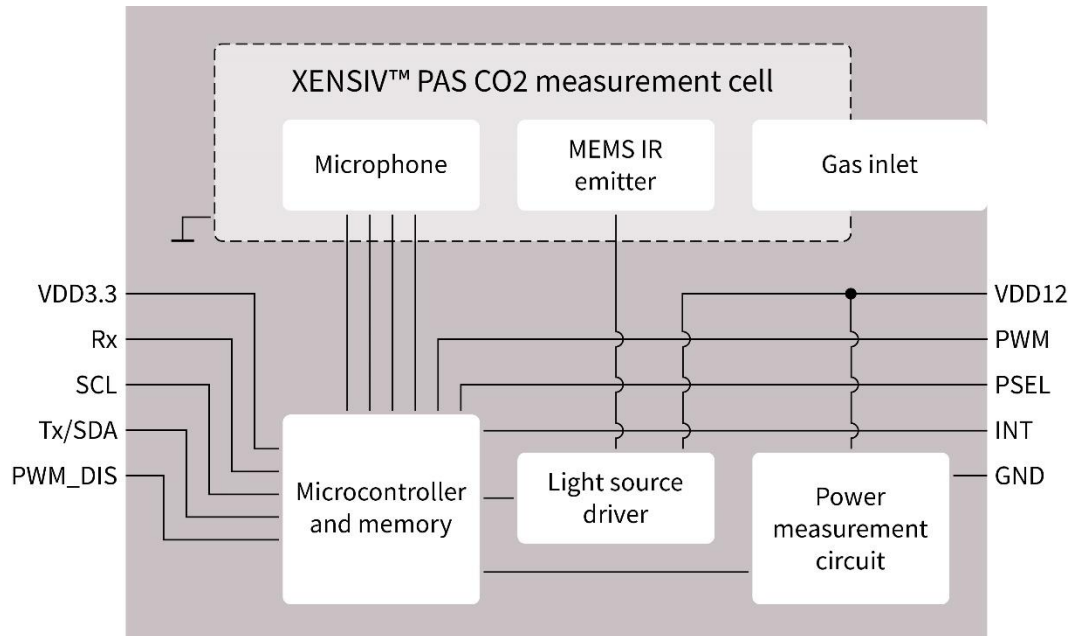
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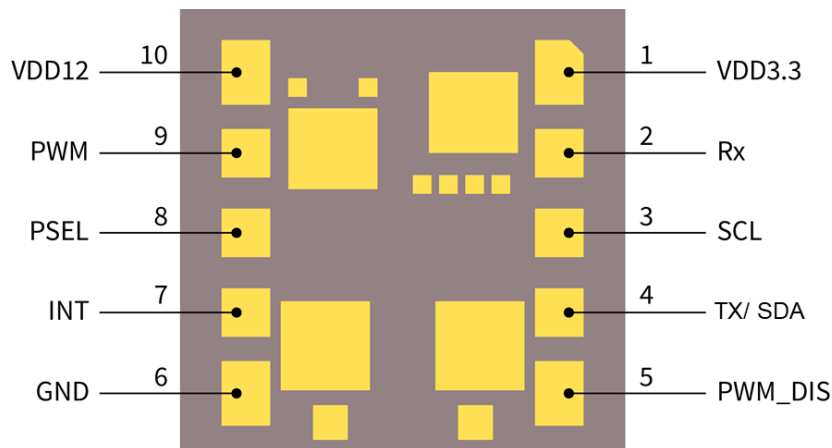
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## 1 Block diagram



**Figure 1** Block diagram of XENSIV™ PAS CO2

## 2 Pin-out diagram



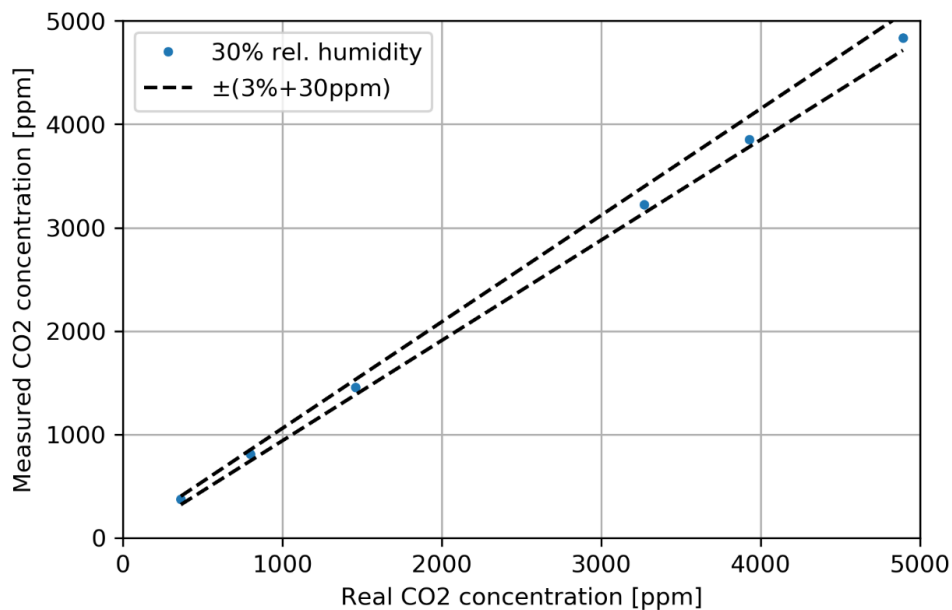
**Figure 2 Pin-out diagram (Bottom view)**

**Table 1**

| PIN | Symbol  | Type                | Description                                                     |
|-----|---------|---------------------|-----------------------------------------------------------------|
| 1   | VDD3.3  | Power supply (3.3V) | 3.3V digital power supply                                       |
| 2   | Rx      | Input/ Output       | UART receiver pin (3.3V domain)                                 |
| 3   | SCL     | Input/ Output       | I2C clock pin (3.3V domain)                                     |
| 4   | TX/ SDA | Output              | UART transmitter pin (3.3V domain) / I2C data pin (3.3V domain) |
| 5   | PWM_DIS | Input               | PWM disable input pin (3.3V domain)                             |
| 6   | GND     | Ground              | Ground                                                          |
| 7   | INT     | Output              | Interrupt output pin (3.3V domain)                              |
| 8   | PSEL    | Input               | Communication interface select input pin (3.3V domain)          |
| 9   | PWM     | Output              | PWM output pin (3.3V domain)                                    |
| 10  | VDD12   | Power supply (12V)  | 12V power supply for the IR emitter                             |

### 3 The typical sensor response to the CO<sub>2</sub> concentration change

Measurement condition: VDD12 = 12V, VDD3.3=3.3V, T<sub>amb</sub> = 25°C, P = 1013 hPa and rH = 30%



**Figure 3** The typical sensor response to the CO<sub>2</sub> concentration change.

## 4 Characteristics and parameters

### 4.1 Specification

#### 4.1.1 Operating range

All parameters specified in the following sections refer to these operating conditions unless otherwise specified.

**Table 2 Operating range**

| Parameter                                       | Symbol            | Values |      |       | Unit | Note or Test Condition         |
|-------------------------------------------------|-------------------|--------|------|-------|------|--------------------------------|
|                                                 |                   | Min.   | Typ. | Max.  |      |                                |
| CO <sub>2</sub> measurement range <sup>1)</sup> | C <sub>CO2</sub>  | 0      |      | 32000 | ppm  | Functional measurement range   |
| Ambient temperature <sup>1)</sup>               | T <sub>amb</sub>  | 0      |      | 50    | °C   |                                |
| Relative humidity <sup>1)</sup>                 | rH                | 0      |      | 85    | %    | Non-condensing                 |
| Pressure <sup>1)</sup>                          | p                 | 750    | 1013 | 1150  | hPa  |                                |
| Supply voltage <sup>1)</sup>                    | VDD3.3            | 3      | 3.3  | 3.6   | V    |                                |
|                                                 | VDD12             | 10.8   | 12   | 13.2  | V    |                                |
| Lifetime <sup>1)</sup>                          | T <sub>life</sub> |        | 10   |       | Year | Depends on the mission profile |

Note: 1) Not subject to production test. This parameter is verified by design/ characterization.

#### 4.1.2 Timing characteristics

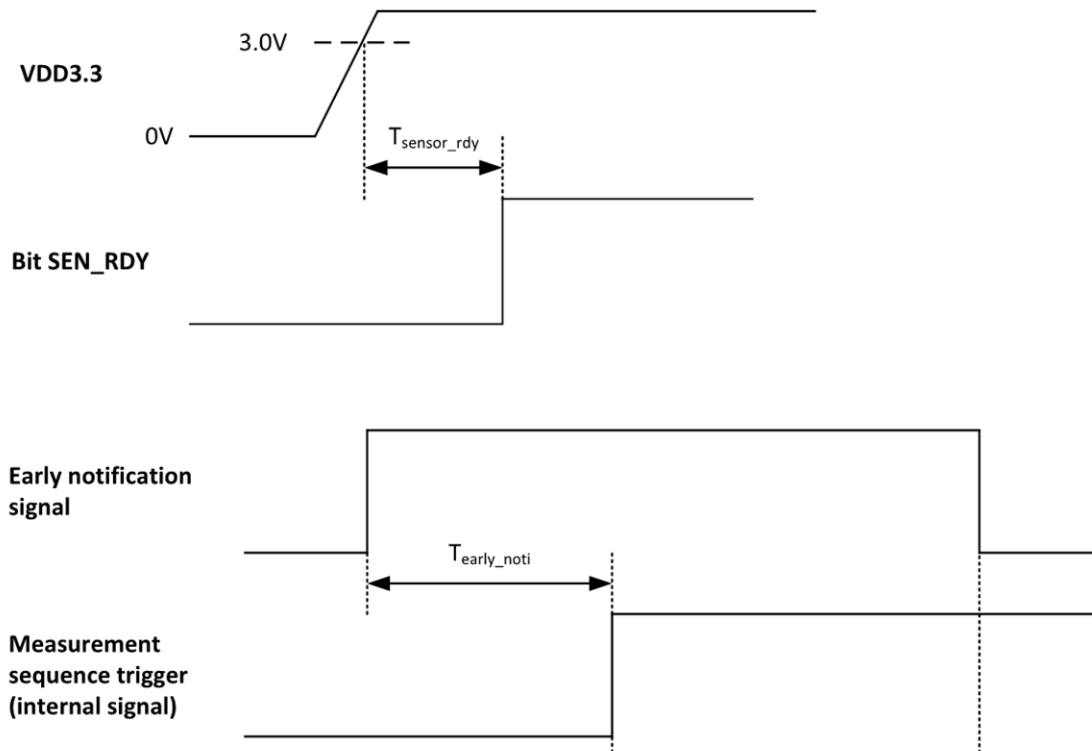
**Table 3 Timing characteristics**

| Parameter                                    | Symbol                  | Values |      |      | Unit | Note or Test Condition |
|----------------------------------------------|-------------------------|--------|------|------|------|------------------------|
|                                              |                         | Min.   | Typ. | Max. |      |                        |
| Sampling time <sup>1)</sup>                  | T <sub>sampling</sub>   | 5      |      | 4095 | s    |                        |
| Time to sensor ready <sup>1)</sup>           | T <sub>sensor_rdy</sub> |        |      | 1    | s    |                        |
| Time to early notification <sup>1), 2)</sup> | T <sub>early_noti</sub> |        | 2    |      | s    |                        |
| I2C Clock frequency <sup>1)</sup>            | f <sub>I2C</sub>        |        | 100  |      | kHz  |                        |
|                                              |                         |        | 400  |      |      |                        |
| PWM frequency <sup>1)</sup>                  | f <sub>pwm</sub>        |        | 80   |      | Hz   |                        |
| UART baud rate <sup>1)</sup>                 | f <sub>baud</sub>       |        | 9.6  |      | kBps |                        |

Note: 1) Not subject to production test. This parameter is verified by design/ characterization.

2) Relevant for continuous mode of operation.

Typical measurement timing sequence has been illustrated in figure 4.



**Figure 4** Illustration of the timing characteristic parameters

### 4.1.3 Absolute maximum ratings

Absolute maximum ratings are verified by design/ characterization, and not tested during production.

**Table 4 Absolute Maximum Ratings<sup>1)</sup>**

| Parameter                   | Symbol               | Values |      |      | Unit | Note or Test Condition |
|-----------------------------|----------------------|--------|------|------|------|------------------------|
|                             |                      | Min.   | Typ. | Max. |      |                        |
| MSL Level                   | MSL                  |        | 3    |      |      |                        |
| Maximum ambient temperature | T <sub>amb_max</sub> | -10    |      | 60   | °C   |                        |
| Maximum relative humidity   | rH <sub>max</sub>    | 0      |      | 95   | %    |                        |
| 12V Supply voltage          | V <sub>VDD12</sub>   | 9.6    |      | 14.4 | V    |                        |
| 3.3V Supply voltage         | V <sub>VDD3.3</sub>  | 3.0    |      | 3.6  | V    |                        |
| Storage temperature         | T <sub>s</sub>       | -30    |      | 85   | °C   |                        |
| Reflow temperature          | T <sub>r</sub>       |        |      | 245  | °C   | JEDEC J-STD-020E       |
| ESD Human Body Model        | V <sub>ESD_HBM</sub> | -2     |      | 2    | kV   | HBM (JS001)            |
| ESD Charge Discharge Model  | V <sub>ESD_CDM</sub> |        |      | 500  | V    | CDM (JS002)            |

Note: 1) Stresses above the values listed as "Absolute Maximum Ratings" may cause permanent damage to the devices. Exposure to absolute maximum rating conditions for extended period of time may affect device reliability.

### 4.1.4 The current rating and power consumption

The current rating refers to 1 measurement/ minute as a typical sampling frequency. All parameters specified in table 5 refer to the following operating conditions unless otherwise specified:

VDD3.3 = 3.3V, VDD12 = 12V, T<sub>amb</sub> = 25°C, % rH = 30 %, p = 1013 hPa.

**Table 5 Current rating**

| Parameter                     | Symbol                | Pin    | Values |      |      | Unit | Note or Test Condition |
|-------------------------------|-----------------------|--------|--------|------|------|------|------------------------|
|                               |                       |        | Min.   | Typ. | Max. |      |                        |
| Peak current <sup>1)</sup>    | I <sub>peak 12</sub>  | VDD12  |        | 130  | 150  | mA   |                        |
| Peak current <sup>1)</sup>    | I <sub>peak 3.3</sub> | VDD3.3 |        | 10   |      | mA   |                        |
| Average current <sup>1)</sup> | I <sub>avg 12</sub>   | VDD12  |        | 0.8  |      | mA   |                        |
| Average current <sup>1)</sup> | I <sub>avg 3.3</sub>  | VDD3.3 |        | 6.1  |      | mA   |                        |
| Average power <sup>1)</sup>   | P <sub>avg</sub>      |        |        | 30   |      | mW   |                        |

Note: 1) Not subject to production test. This parameter is verified by design/ characterization.

Power consumption can be optimized further. For more details please refer to our application note section at the product [web page](#).

### 4.1.5 CO<sub>2</sub> Transfer Function

All parameters specified in the following sections refer to the operating conditions unless otherwise specified:

VDD3.3 = 3.3V, VDD12 = 12V, T<sub>amb</sub> = 25°C, % rH = 30 %, p = 1013 hPa.

**Table 6 CO<sub>2</sub> Transfer Function**

| Parameter                        | Symbol               | Values                 |     |                       | Unit    | Conditions                                           |
|----------------------------------|----------------------|------------------------|-----|-----------------------|---------|------------------------------------------------------|
|                                  |                      | Min.                   | Typ | Max.                  |         |                                                      |
| Accuracy                         | Acc                  | -30 ppm- 3% of reading |     | +30 ppm+3% of reading | ppm     | C <sub>CO2</sub> : 400 - 5000 ppm                    |
| Response time <sup>1)</sup>      | T <sub>63</sub>      |                        | 90  |                       | s       |                                                      |
| Repeatability <sup>1)</sup>      | R                    |                        |     | 10                    | ppm     | 3σ                                                   |
| Pressure stability <sup>1)</sup> | p <sub>error</sub>   |                        | 0.1 |                       | %/hPa   | Without pressure compensation feature enabled        |
|                                  |                      |                        | 0   |                       |         | With pressure compensation feature enabled           |
| Drift <sup>1)</sup>              | d <sub>error</sub>   |                        |     | 1                     | %/ year | At 1 meas/ min with ABOC enabled in continuous mode. |
| Acoustic stability <sup>1)</sup> | SPL <sub>error</sub> | 3                      | 6   | 15                    | ppm     | Up to 95 dB for Pink noise from 100 Hz to 10 kHz.    |

Note: 1) Not subject to production test. This parameter is verified by design/ characterization.

## 4.1.6 Peripheral timing

### 4.1.6.1 I2C Timing

Table 7 I2C Standard mode timing

| Parameter                                        | Symbol          | Values |      |      | Unit | Note or Test Condition |
|--------------------------------------------------|-----------------|--------|------|------|------|------------------------|
|                                                  |                 | Min.   | Typ. | Max. |      |                        |
| Fall time of both SDA and SCL                    | t <sub>1</sub>  |        |      | 300  | ns   |                        |
| The rise time of both SDA and SCL                | t <sub>2</sub>  |        |      | 1000 | ns   |                        |
| Data hold time                                   | t <sub>3</sub>  | 0      |      |      | μs   |                        |
| Data set-up time                                 | t <sub>4</sub>  | 250    |      |      | ns   |                        |
| LOW period of SCL clock                          | t <sub>5</sub>  | 4.7    |      |      | μs   |                        |
| HIGH period of SCL clock                         | t <sub>6</sub>  | 4.0    |      |      | μs   |                        |
| Hold time for a (repeated) START condition       | t <sub>7</sub>  | 4.0    |      |      | μs   |                        |
| Set-up time for (repeated) START condition       | t <sub>8</sub>  | 4.7    |      |      | μs   |                        |
| Set-up time for STOP condition                   | t <sub>9</sub>  | 4.0    |      |      | μs   |                        |
| Bus free time between a STOP and START condition | t <sub>10</sub> | 4.7    |      |      | μs   |                        |
| Capacitive load for each bus line                | C <sub>b</sub>  |        |      | 400  | pF   |                        |

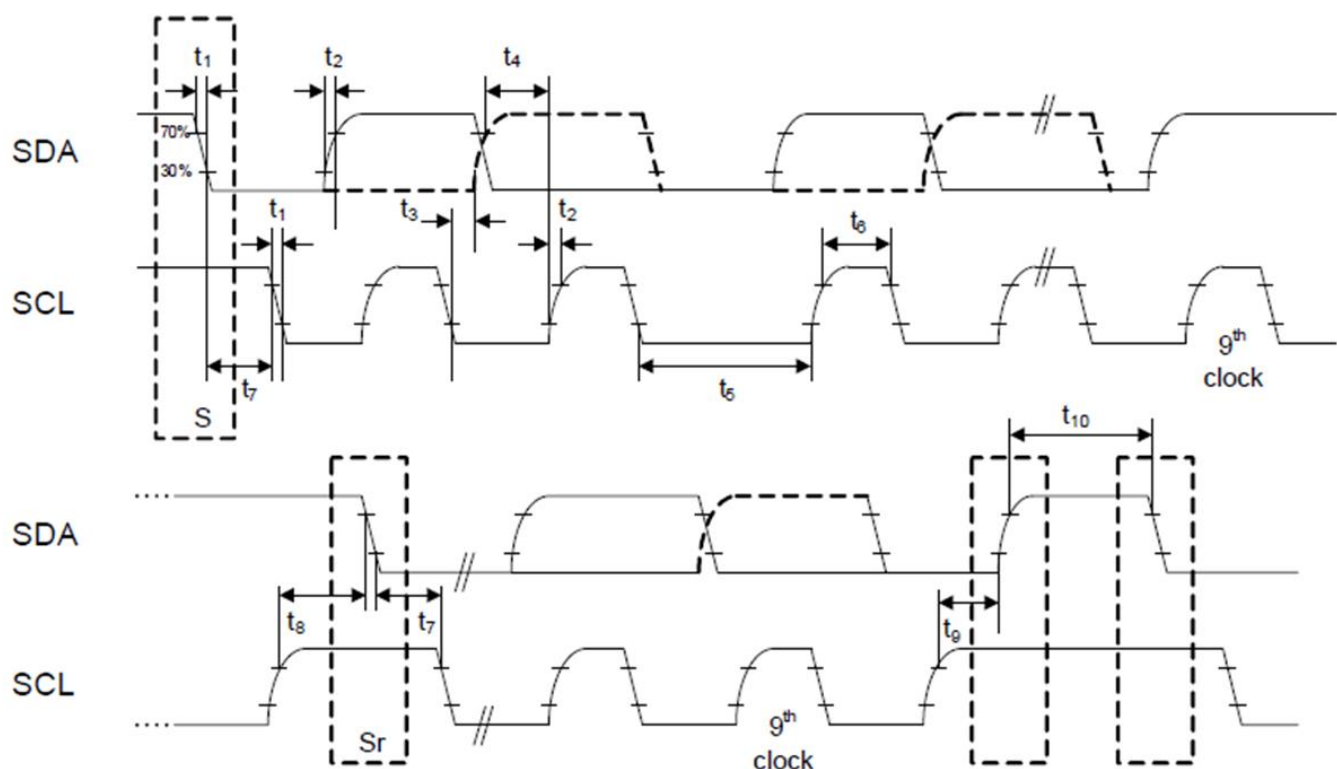


Figure 5 Standard I2C mode timing.

#### 4.1.6.2 UART characteristics

The main characteristics of the UART interface are described below:

- Point to point operation – no bus support.
- Slave operation only.
- $f_{\text{baud}} = 9.6\text{kBps}$
- Format: 1 start bit, 8 Data bits, no parity bit, 1 stop bit.
- Supports direct connection with terminal program.

For further details on UART and I2C communication protocol, please refer to our application note section in the product webpage.

## 4.2 Application Circuit Example

Typical application circuits for I2C and UART has been presented in the figure 6 and figure 7 respectively.

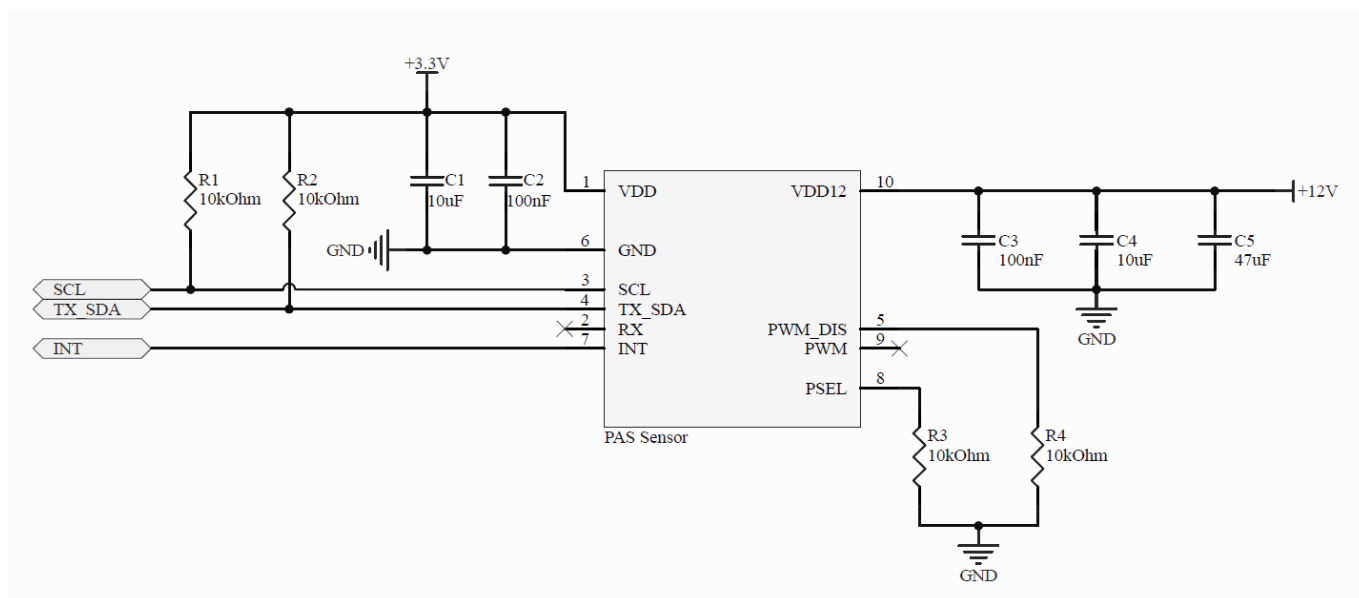
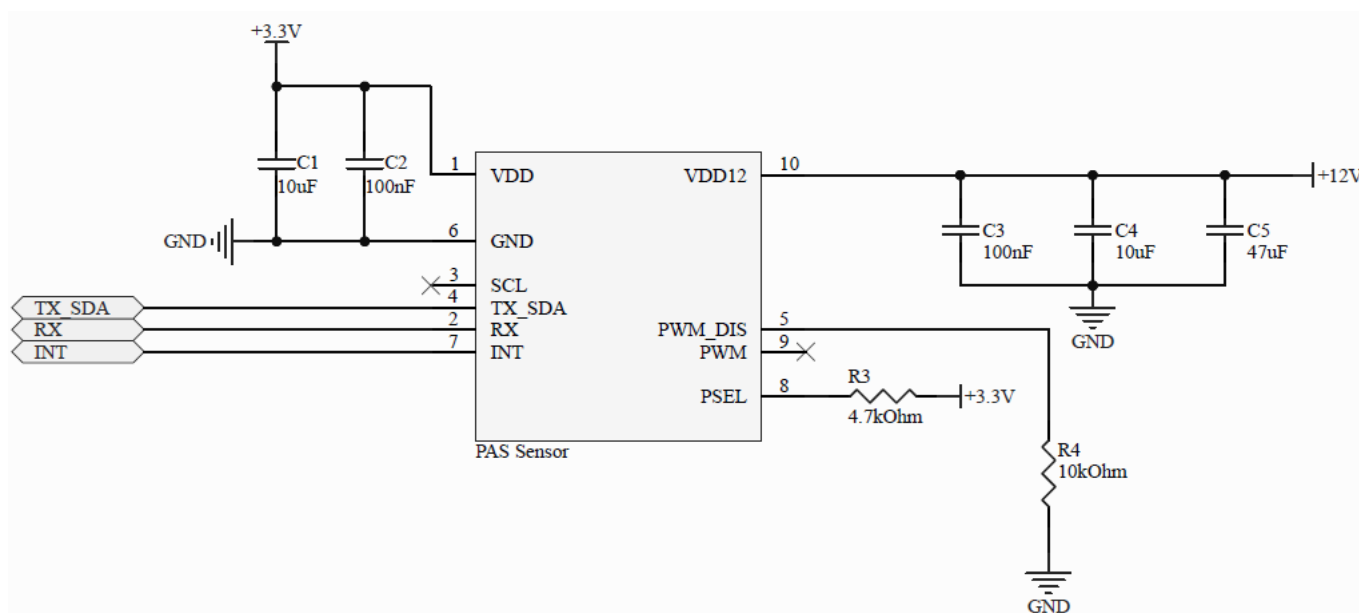


Figure 6 Application circuit example for I2C



**Figure 7** Application circuit example for UART

### 4.3 Functional description

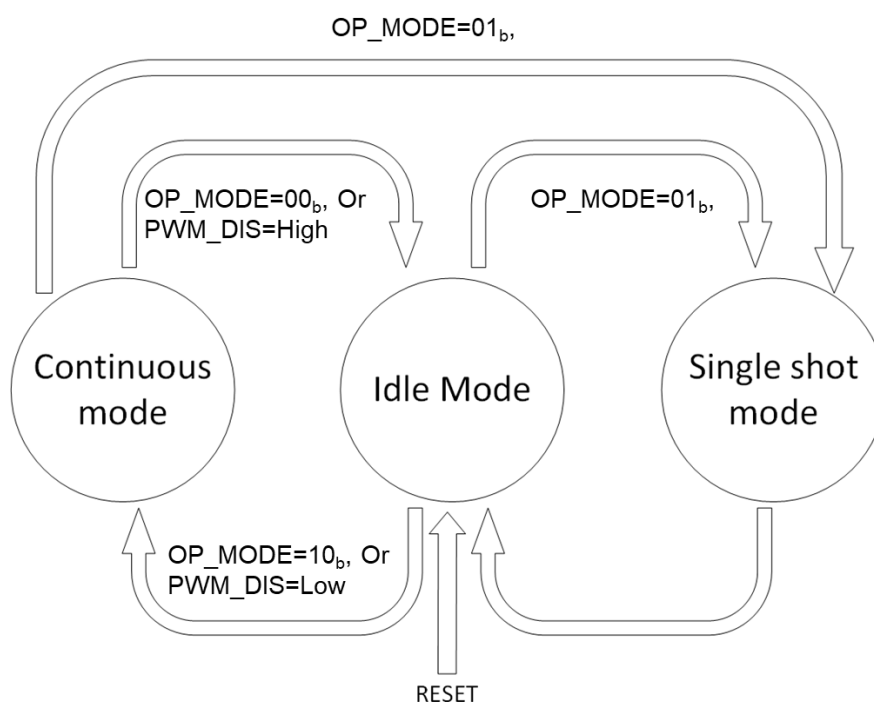
This section describes the operation of the sensor while measuring CO<sub>2</sub> concentrations. At any moment the device can be in one out of two different states: active and inactive. At active state, the CPU controlling the device is operating and can perform tasks such as: running a measurement sequence, serving an interrupt, etc. When the device has no specific task to perform, it goes to an inactive state. A transition from active to inactive state may occur at the end of a measurement sequence. In an inactive state, the CPU controlling the device is in sleep mode to optimize power consumption. Several events can wake up the device: the reception of a message on the serial communication interface, a falling edge on pin **PWM\_DIS**, the internal generation of a measurement request in continuous measurement mode.

#### 4.3.1 Operating Modes

The operating mode can be programmed via the serial communication interface by using the bit field **MEAS\_CFG.OP\_MODE**.

The sensor module supports three operating modes:

- **Idle mode:** The device does not perform any CO<sub>2</sub> concentration measurement. The device remains inactive until it becomes active shortly to serve interrupts before going back to an inactive state.
- **Continuous mode:** In this mode, the device periodically triggers a CO<sub>2</sub> concentration measurement sequence. Once a measurement sequence is completed, the device goes back to an inactive state and wakes up automatically for the next measurement sequence. The measurement period is programmable from 5 sec to 4095 sec.
- **Single-shot mode:** In this mode, the device triggers a single measurement sequence. At the end of the measurement sequence, the device goes back automatically to idle mode.



**Figure 8** Operating mode transition

### 4.3.2 Data post-processing

Once the CO<sub>2</sub> concentration data has been acquired, several post-processing schemes can be applied to improve the sensor performance.

- **Pressure compensation**

The CO<sub>2</sub> concentration value acquired by the sensor is dependent on the external atmospheric pressure. To compensate for this effect, the application system can provide the value of the atmospheric pressure by writing into the specific registers, i.e. **PRESSREF\_H** and **PRESSREF\_L**. At the end of a measurement sequence, the device reads the pressure value and applies for compensation on the CO<sub>2</sub> concentration value before storing it into the result registers.

- **Automatic Baseline Offset Correction**

To correct slow drifts caused by aging during operation, the device supports Automatic Baseline Offset Compensation. Every week of operation, the device computes an offset to correct the baseline of the device. The device must be in contact with the reference concentration (e.g. fresh air at 400 ppm of CO<sub>2</sub> concentration) at least 30 minutes per operating week to make sure proper baseline compensation. The device supports different configurations for compensation. **The ABOC setpoint may only be set between 350 and 1500 ppm.**

- **Forced compensation**

Forced compensation provides a means to speed up the offset compensation process. Before forced compensation is enabled, the device shall be physically exposed to the reference CO<sub>2</sub> concentration. The device will use the 3 next measurements to calculate the compensation offset. The user shall ensure constant exposure to the reference CO<sub>2</sub> concentration during that time. It is recommended to operate at 1 measurement per 10 seconds while implementing the forced compensation scheme. When the 3 measurement sequences are completed, the device automatically reconfigures itself with the newly computed offset applied to the subsequent CO<sub>2</sub> concentration measurement results.

### 4.3.3 Alarm Threshold

The device can be configured to perform an alarm threshold check each time a new CO<sub>2</sub> concentration data is acquired. At the end of each measurement sequence, the computed CO<sub>2</sub> value (after all applicable offset compensations) is compared to the concatenated value in **ALARM\_TH\_H** and **ALARM\_TH\_L**. In case of a threshold violation, the sticky bit **MEAS\_STS.ALARM** is set. This also sets pin **INT** to active level if configured as Alarm. Bit **MEAS\_STS.ALARM** is cleared by reading register **MEAS\_STS.ALARM\_CLR**.

## 4.4 Advanced functionality

### Monitoring mechanism

The device supports several mechanisms to monitor the correct operation of the sensor.

Table 7

| Mechanism                         | Description                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |
|-----------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Sensor Ready status               | After each power-on reset, bit <b>SENS_STS.SEN_RDY</b> is set to confirm that the sensor has initialized correctly.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |
| Scratchpad register               | <p>To check the integrity of the communication layer of the serial communication interface, register <b>SCRATCH_PAD</b> can be used. This register can use this memory field to write any value and verify that the data received by the device is correct.</p> <p>It can also be used to verify that a soft reset has been executed, using the following sequence:</p> <ol style="list-style-type: none"> <li>1. The user writes a non-default value to register <b>SCRATCH_PAD</b>.</li> <li>2. The user reads back register <b>SCRATCH_PAD</b> to verify the writ commend has been correctly executed.</li> <li>3. The user writes register <b>SENS_RST</b> to trigger a soft reset.</li> <li>4. The user reads register <b>SCRATCH_PAD</b> to verify that it has been reset to its default value.</li> </ol> |
| VDD12V verification               | At power-up and the beginning of each measurement sequence, the device measures automatically the voltage at <b>VDD12</b> . If the measured voltage exceeds the specified operating range of the device, bit <b>SENS_STS.ORVS</b> is set. The measurement sequence is however completed normally. Bit <b>SENS_STS.ORVS</b> can be cleared by setting bit <b>SENS_STS.ORVS_CLR</b>                                                                                                                                                                                                                                                                                                                                                                                                                                |
| Internal temperature verification | At the beginning of each measurement sequence, the device measures automatically its internal temperature. If the measured temperature exceeds the specified operating ranged of the device, sticky bit <b>SENS_STS.ORTMP</b> is set. The measurement sequence is however completed normally. Bit <b>SENS_STS.ORTMP</b> can be cleared by setting bit <b>SENS_STS.ORTMP_CLR</b> .                                                                                                                                                                                                                                                                                                                                                                                                                                |

### 4.5 Digital interface

The XENSIV™ PAS CO<sub>2</sub> supports I2C, UART, and PWM. The communication protocols have been covered in separate application notes.

#### 4.5.1 I2C interface

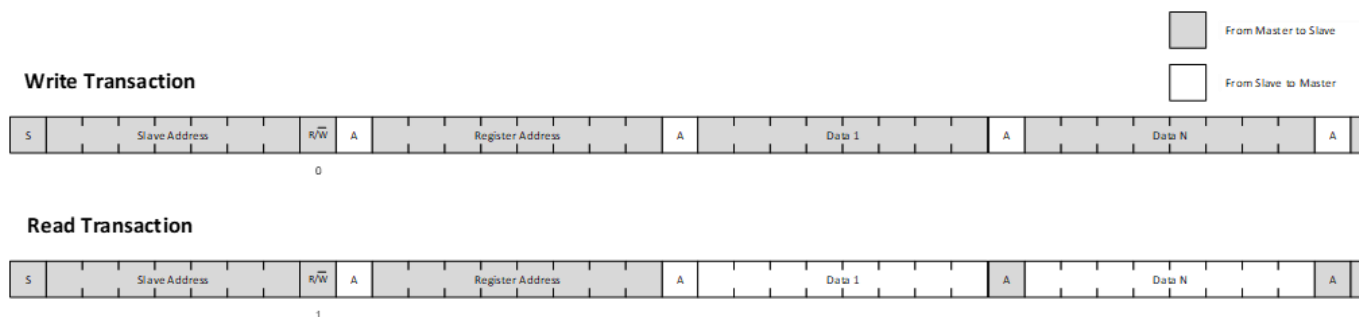
The device complies with the I2C protocol. When I2C is selected as a serial communication interface, the device acts as an I2C slave. The main characteristics of the interface are described below:

- Slave mode only.
- I2C Clock frequency: 100 kHz and 400 kHz
- 7-bit slave address: 0x28
- No CRC.
- The device supports clock stretching.
- 8bit addressing mode supported (7bit address + RW)
- Bulk read and write supported (device auto-increments automatically the address).
- Address 0x00 not supported.

Further details of the protocol are covered in the separate application note.

#### 4.5.2 I2C transaction format

The I2C transaction has the following structure: a start condition followed by four bytes followed a stop condition.



**Figure 9 I2C write and read transaction**

**Table 8**

| Byte | Description     | Value                              | Comments                                                             |
|------|-----------------|------------------------------------|----------------------------------------------------------------------|
|      | Start condition |                                    |                                                                      |
| 1    | Header          | (Slave Address << 1)   R/W         |                                                                      |
| 2    | First data-byte | As per user request/register value | Read: data provided by the slave<br>Write: data provided by the user |
| N+2  | Data byte N     | As per user request/register value | Read: data provided by the slave<br>Write: data provided by the user |
|      | End condition   |                                    |                                                                      |

### 4.5.3 UART Interface

When UART is selected as a serial communication interface, the device acts as a UART slave. The device operates via UART for point-to-point communication. Bus operation is not supported. As a result, it is recommended that the master uses a time-out mechanism. The basic format of a valid UART frame is 1 start bit, 8 data bits, no parity bit, and 1 stop bit. The master combines several UART frames into a message (read or write). The combination of master request and slave answer defines a transaction. The main characteristics of the interface are described below:

- Point to point operation – no bus support.
- Slave operation only.
- UART clock frequency = 9.6 kHz
- Format: 1 start bit, 8 Data bits, no parity bit, 1 stop bit. Supports direct connection with a terminal program.

For further details on UART communication, please have a look at the application note section on the product website 'www.infineon.com/CO2'.

### 4.6 Register map

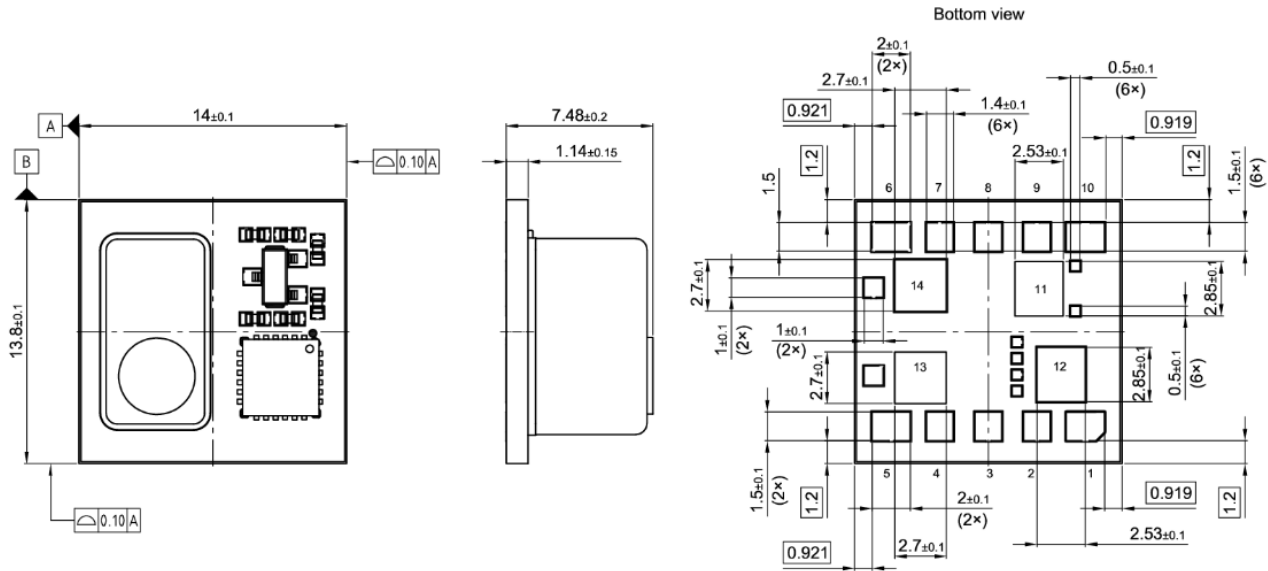
| Name        | Address             | Bit 7                                                                                              | Bit 6            | Bit 5           | Bit 4          | Bit 3          | Bit 2          | Bit 1            | Bit 0           | Reset |
|-------------|---------------------|----------------------------------------------------------------------------------------------------|------------------|-----------------|----------------|----------------|----------------|------------------|-----------------|-------|
| PROD_ID     | 0x00                | PROD<br>r                                                                                          |                  |                 | REV<br>r       |                |                |                  |                 | 0x4A  |
| SENS_STS    | 0x01                | SEN_RDY<br>rh                                                                                      | PWM_DIS_ST<br>rh | ORTMP<br>rhs    | ORVS<br>rhs    | ICCER<br>rhs   | ORTMP_CLR<br>w | ORVS_CLR<br>w    | ICCER_CLR<br>w  | 0xC0  |
| MEAS_RATE_H | 0x02                | VAL<br>rwh                                                                                         |                  |                 |                |                |                |                  |                 | 0x00  |
| MEAS_RATE_L | 0x03                | VAL<br>rwh                                                                                         |                  |                 |                |                |                |                  |                 | 0x3C  |
| MEAS_CFG    | 0x04                | 0<br>rw                                                                                            |                  | PWM_OUTEN<br>rw | PWM_MODE<br>rw | BOC_CFG<br>rwh |                | OP_MODE<br>rwh   |                 | 0x24  |
| CO2PPM_H    | 0x05                | VAL<br>r                                                                                           |                  |                 |                |                |                |                  |                 | 0x00  |
| CO2PPM_L    | 0x06                | VAL<br>r                                                                                           |                  |                 |                |                |                |                  |                 | 0x00  |
| MEAS_STS    | 0x07                | 0<br>rw                                                                                            |                  | Res<br>rh       | DRDY<br>rhs    | INT_STS<br>rhs | ALARM<br>rhs   | INT_STS_CLR<br>w | ALARM_CLR<br>w  | 0x00  |
| INT_CFG     | 0x08                | 0<br>rw                                                                                            |                  |                 | INT_TYP<br>rw  | INT_FUNC<br>rw |                |                  | ALARM_TYP<br>rw | 0x11  |
| ALARM_TH_H  | 0x09                | VAL<br>rw                                                                                          |                  |                 |                |                |                |                  |                 | 0x00  |
| ALARM_TH_L  | 0x0A                | VAL<br>rw                                                                                          |                  |                 |                |                |                |                  |                 | 0x00  |
| PRESS_REF_H | 0x0B                | VAL<br>rwh                                                                                         |                  |                 |                |                |                |                  |                 | 0x03  |
| PRESS_REF_L | 0x0C                | VAL<br>rwh                                                                                         |                  |                 |                |                |                |                  |                 | 0xF7  |
| CALIB_REF_H | 0x0D                | VAL<br>rwh                                                                                         |                  |                 |                |                |                |                  |                 | 0x01  |
| CALIB_REF_L | 0x0E                | VAL<br>rwh                                                                                         |                  |                 |                |                |                |                  |                 | 0x90  |
| SCRATCH_PAD | 0x0F                | VAL<br>rw                                                                                          |                  |                 |                |                |                |                  |                 | 0x00  |
| SENS_RST    | 0x10                | SRTRG<br>w                                                                                         |                  |                 |                |                |                |                  |                 | 0x00  |
| Reserved    | 0x11<br>...<br>0x14 | Reserved registers<br>Read & Write access to those registers generate a communication error        |                  |                 |                |                |                |                  |                 |       |
| Reserved    | 0x15<br>...<br>0xFF | Reserved registers<br>Read & Write access to those registers generate a non-acknowledge condition. |                  |                 |                |                |                |                  |                 |       |

Complete 'Register map description' has been covered in a separate application note in the product webpage.

## **5 Assembly instruction**

XENSIV™ PAS CO2 modules are classified to be Moisture-Sensitivity Level 3 (MSL 3). The maximum reflow temperatures during board assembly must not exceed the classification profile as stated in IPC/JEDEC J-STD-020E with a peak temperature of below 245°C with one possible reflow cycle. Please also refer to the product barcode label that can be found on the packing material.

## 6 Package information



All dimensions are in units mm  
The drawing is in compliance with ISO 128-30, Projection Method 1   
Drawing according to ISO 8015, general tolerances ISO 2768-mK

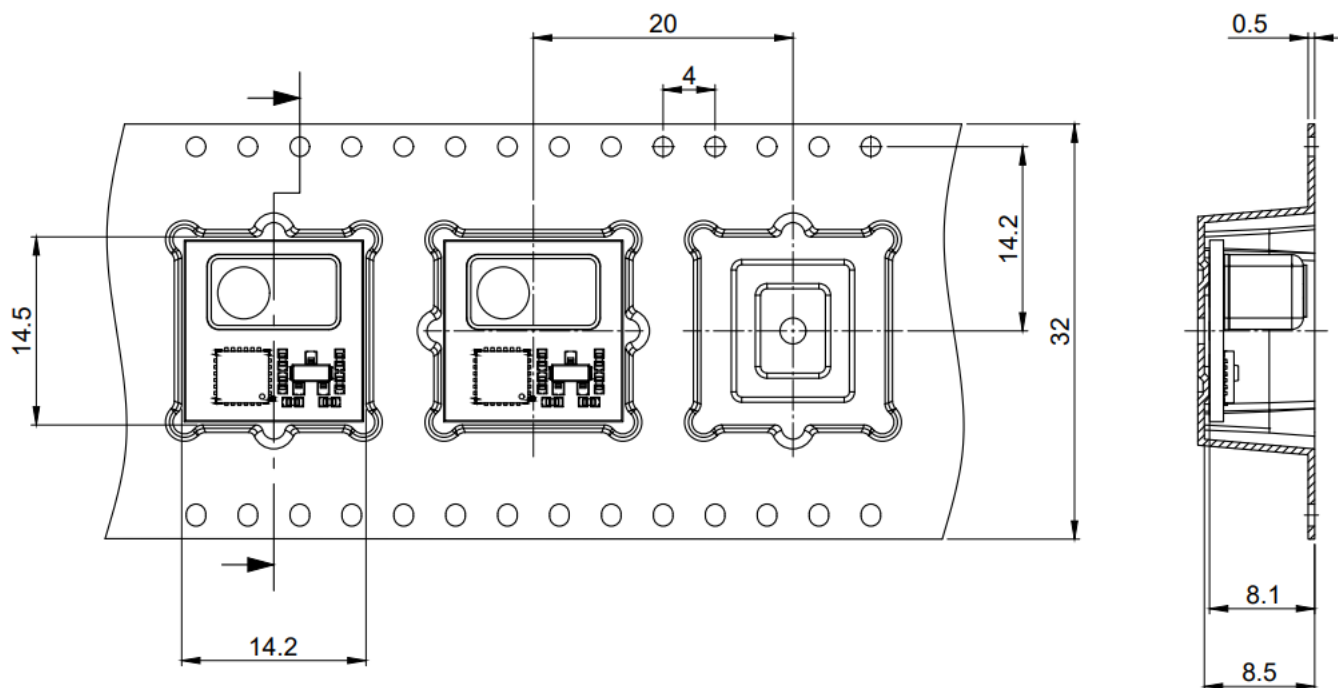
**Figure 10**      **Package dimensions of XENSIV™ PAS CO2.**

## **7 Footprint and stencil recommendation**

The board pad and stencil aperture recommendations can be found in the package data base that is available on the Infineon package web page (<https://www.infineon.com/packages>). The package type of XENSIV™ PAS CO2 is LG-MLGA-14-1. Please search for the specific package name within the data base, which will then show an example of the footprint layout, stencil recommendation and board assembly recommendation within the download section.

## 8 Packing for shipment

The device will be shipped in tape and reel. Each tape and reel consist of 300 parts.



All dimensions are in units mm

The drawing is in compliance with ISO 128-30, Projection Method 1 [  ]

**Figure 11** Tape and reel packing of XENSIV™ PAS CO2

## 9 Revision history

**Table 9**      **Datasheet versions tracking**

| Reference | Description                              | Date       |
|-----------|------------------------------------------|------------|
| 0.1       | First copy of the preliminary datasheet  | 13.10.2020 |
| 0.2       | Second copy of the preliminary datasheet | 25.06.2021 |
| 1.0       | First release of the datasheet           | 17.01.2022 |

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