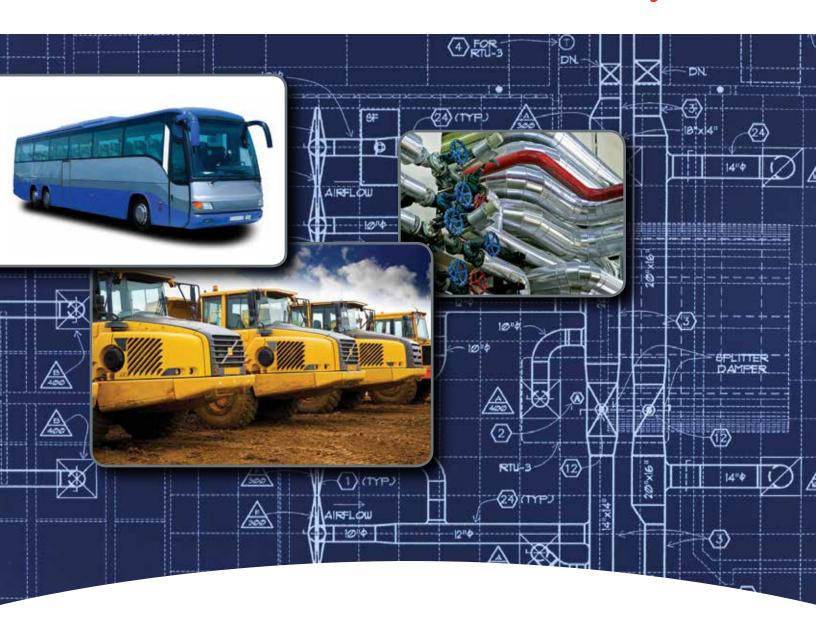
Honeywell



Hall-effect Rotary Position Sensors
RTY Series with Integral Actuator
RTP Series with External Actuator



RTY Series and RTP Series Hall-effect Rotary Position Sensors

The RTY Series and RTP Series Hall-effect Rotary Position Sensors provide non-contact sensing in harsh transportation and industrial applications at a competitive cost.

- RTY Series: These shaft activated products are available in two versions: an integral shaft with or without a lever. The lever may allow customers to reduce the number of mechanical linkages required for their applications, which may reduce the cost of the overall customer solution.
- RTP Series: Takes non-contact sensing to the next level by separating the magnet from the sensor body. The absence of the actuator shaft removes the wear and tear on the bearings caused by radial forces. A choice of a bare or a housed magnet is available.

These products use a magnetically biased, Hall-effect integrated circuit (IC) to sense rotary movement of the actuator over a set operating range. Rotation of the actuator changes the magnet's position relative to the IC. The resulting flux density change is converted to a linear output.

The IC, together with conditioning and protection circuitry, is sealed in an IP69K-qualified rugged package for durability in most harsh environments.

Eight operating ranges from 50° to 360° are tolerant to over-travel and allow use in most common applications. Low voltage and high voltage versions cover an input voltage range of 4.5 Vdc to 30 Vdc.

Honeywell's industry-leading capabilities in research and development provide the customer with known quality and support.

Features

- True, non-contact operation
- 35 M cycle product life (RTY Series); unlimited rotation (RTP Series)
- Solid-state Hall-effect technology
- Rugged IP69K-sealed package with integral connector
- Automotive-grade EMI/EMC testing, integrated reverse polarity, and short circuit protection
- Industry-standard AMP termination, 32 mm mounting pitch,
 North American or European pinout styles, and compact package
- Eight operating ranges up to 360°

Potential Applications

TRANSPORTATION

- Position and movement detection (pedals, throttles, gear shift, levers, steering, linkages, and hitches) in trucks, buses, off-road vehicles, cranes, and industrial/ construction/agricultural vehicles and equipment)
- Suspension/kneeling position (buses, trucks)
- Tilt/trim position (boat engines, tilling equipment)

INDUSTRIAL

- Valve control
- HVAC damper control
- Irrigation equipment pivot control

Table 1. Electrical Specifications

Chavastavistis	RTY S	Series	RTP Series		
Characteristic	LV (Low Voltage)	LV (Low Voltage) HV (High Voltage)		HV (High Voltage)	
Supply voltage	5 ±0.5 Vdc	10 Vdc to 30 Vdc	5 ±0.5 Vdc	10 Vdc to 30 Vdc	
Supply current: normal during output to ground short	20 mA max. 25 mA max.	32 mA max. 47 mA max.	20 mA max. 25 mA max.	32 mA max. 47 mA max.	
Output: standard inverted	0.5 Vdc to 4.5 Vdc ratiometric 4.5 Vdc to 0.5 Vdc ratiometric	0.5 Vdc to 4.5 Vdc non-ratiometric 4.5 Vdc to 0.5 Vdc non-ratiometric	0.5 Vdc to 4.5 Vdc ratiometric 4.5 Vdc to 0.5 Vdc ratiometric	0.5 Vdc to 4.5 Vdc non-ratiometric 4.5 Vdc to 0.5 Vdc non-ratiometric	
Output signal delay	4 ms typ.				
Overvoltage protection	10 Vdc	_	10 Vdc	_	
Reverse polarity protection	-10 Vdc	-30 Vdc	-10 Vdc	-30 Vdc	
Output to ground short circuit protection	continuous				
Resolution	12 bit				
Output load resistance (pull down to ground)	10 kOhm typ.				
EMI: radiated immunity	100 V/m per ISO11452-2 fr	om 200 MHz to 1000 MHz	100 V/m per ISO11452-2 from 200 MHz to 1000 MHz		
conducted immunity	100 mA BCI per ISO11452-4 from 1 MHz to 200 MHz	100 mA BCI per ISO11452-4 from 1 MHz to 400 MHz	1 100 mA BCl per ISO11452-4 100 mA BCl per ISO from 1 MHz to 200 MHz from 1 MHz to 40		
EMC	exceeds CE requirements				

Table 2. Mechanical Specifications

Charastariatia	RTY Series		RTP Series		
Characteristic	LV (Low Voltage)	HV (High Voltage)	LV (Low Voltage)	HV (High Voltage)	
Expected life	35 M cycles		infinite rotation		
Air gap: bare magnet actuator housed magnet actuator misalignment	_ _ _		3,00 mm \pm 0.5 mm [0.12 in \pm 0.02 in] 2,00 mm \pm 0.5 mm [0.08 in \pm 0.02 in] 2,00 mm [0.08 in] max.		
Material: shaft magnet sensor housing housed magnet overmold sensor/housed magnet bushing sensor bushing	PBT -	ss steel plastic ss steel	NdFeB PBT plastic PPS plastic brass		
Mating connector	AMP Superseal 282087-1				
Mechanical end stop	no				
Mounting screw sizes: sensor to mounting surface	G .	ss steel M5 screws and n] OD washers	9 '	steel M4 X 0.7 screws and	
lever to mounting surface	non-magnetic stainless steel M6 screws,		_		
housed magnet actuator to actuator mounting shaft	_		non-magnetic, stainless steel M3 X 0.5 plain cup point set screws		
Approvals	CE				

RTY Series and RTP Series

Table 3. Environmental Specifications

Characteristic	RTY Series		RTP Series		
Characteristic	LV (Low Voltage)	HV (High Voltage)	LV (Low Voltage)	HV (High Voltage)	
Operating temperature range	-40 °C to 125 °C [-40 °F to 257 °F]				
Ingress protection	IP69K				
Media compatibility	heavy transportation fluids				
Shock ¹	50 G peak				
Vibration ¹	20 G peak				
Salt fog		ncentration 5% ±1% for 240 hr per SAE J1455 bare magnet: 96 hr for as per ASTM B Section 4.3.3.1 (at 5.0 Vdc, 38 °C [100 F °]) housed magnet: 240 hr per ASTM B1			

¹ Does not apply RTY Series sensor shaft with lever.



NOTICE

Ferrous material or magnet material more than 300 Gauss within 10 mm [0.39 in] from sensor boundary may impact sensor performance.

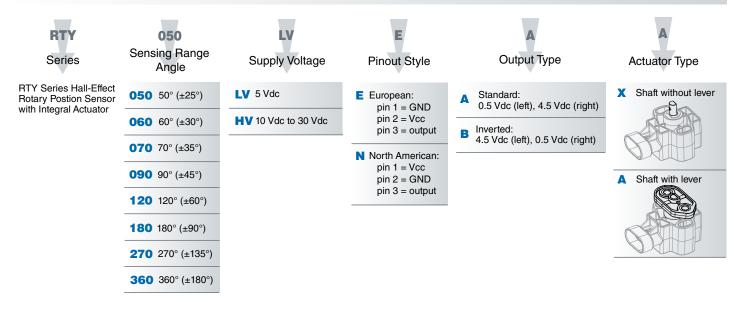
Figure 1. All Available Configurations

Series	Actuator Type	Series	Actuator Type		
	Integral shaft without lever		Separate bare magnet		
RTY	Integral shaft with lever	RTP	Separate housed magnet		

Figure 2. Product Nomenclature

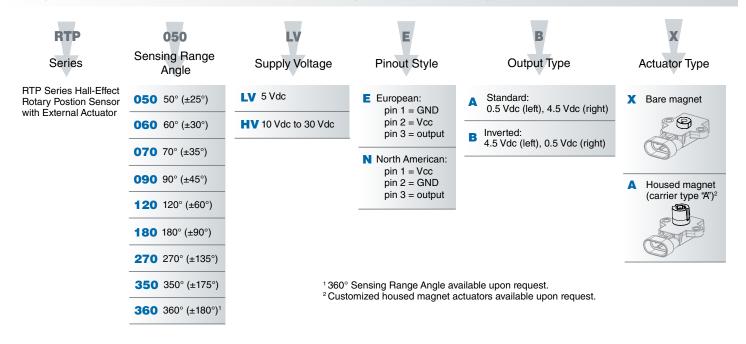
RTY Series

For example, **RTY050LVEAA** defines an RTY Series Hall-Effect Rotary Position Sensor, 50° (±25°) sensing range angle, 5 Vdc supply voltage, European pinout style, 4.5 Vdc (left), 0.5 Vdc (right) output type, shaft without lever actuation type



RTP Series

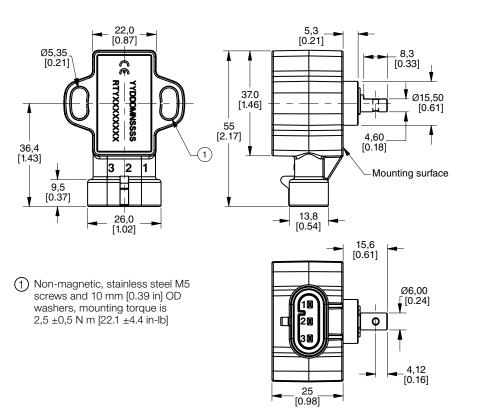
For example, RTP050LVEBX defines an RTP Series Hall-Effect Rotary Position Sensor, 50° (±25°) sensing range angle, 5 Vdc supply voltage, European pinout style, inverted 4.5 Vdc (left), 0.5 Vdc (right) output type, bare magnet actuator type



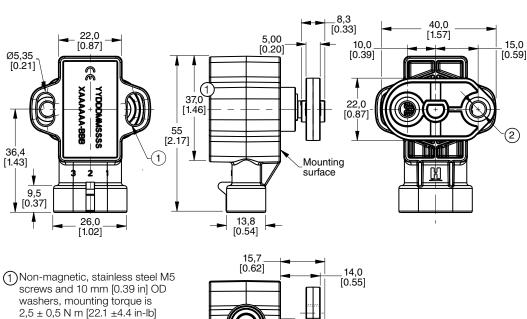
RTY Series and RTP Series

Figure 3. RTY Series Mounting Dimensions (For reference only: mm [in.])

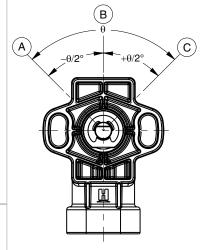
Sensor without lever



Sensor with lever



Output diagram



Standard Output

- (A) = Left output: 0.5 Vdc
- (B) = Zero reference
- (C) = Right output: 4.5 Vdc

Inverted Output

- (A) = Left output: 4.5 Vdc
- (B) = Zero reference
- © = Right output: 0.5 Vdc

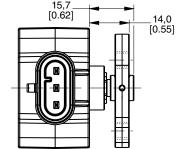
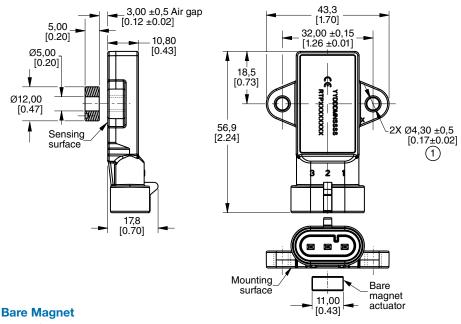
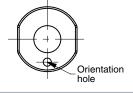


Figure 4. RTP Series Mounting Dimensions (For reference only: mm [in].)

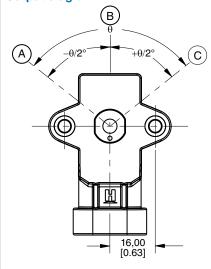
Sensor with bare magnet actuator





(1) Non-magnetic, stainless steel M4 X 0.7 screws and 8 mm [0.39 in] OD washers, torque is 2,0 \pm 0,2 N m [17.7 ±1.8 in-lb].

Output diagram



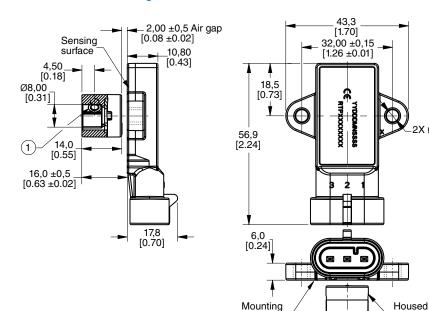
Standard Output

- (A) = Left output: 0.5 Vdc
- = Zero reference
- (C) = Right output: 4.5 Vdc

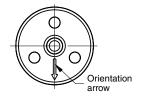
Inverted Output

- (A) = Left output: 4.5 Vdc
- (B) = Zero reference
- (C) = Right output: 0.5 Vdc

Sensor with housed magnet actuator



Housed Magnet



(1) Non-magnetic, stainless steel M3 X 0.5 plain cup point set screws, torque is 0,5 N m to 0,6 N m [4.42 in-lb to 5.31 in-lb]

Ø15,00

[0.59]

(2) Non-magnetic, stainless steel M4 X 0.7 screws and 8 mm [0.31 in] OD washers, torque is 2,0 \pm 0,2 N m [17.7 ±1.8 in-lb].

surface

Output Diagram

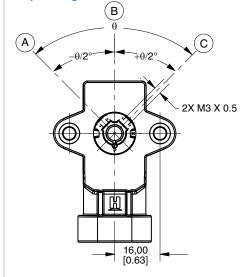
2X Ø4,30 ±0,5

magnet

actuator

[0.17±0.02]

(2)



Standard Output

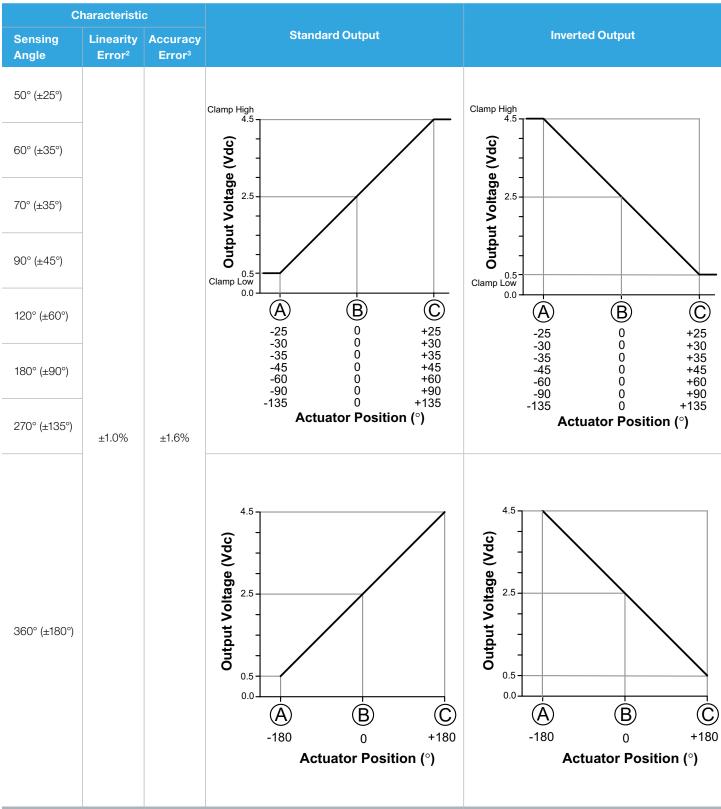
- = Left output: 0.5 Vdc
- = Zero reference
- (C) = Right output: 4.5 Vdc

Inverted Output

- (A) = Left output: 4.5 Vdc
- (B) = Zero reference
- (C) = Right output: 0.5 Vdc

RTY Series and RTP Series

Table 4 RTY Series Functional Characteristics¹

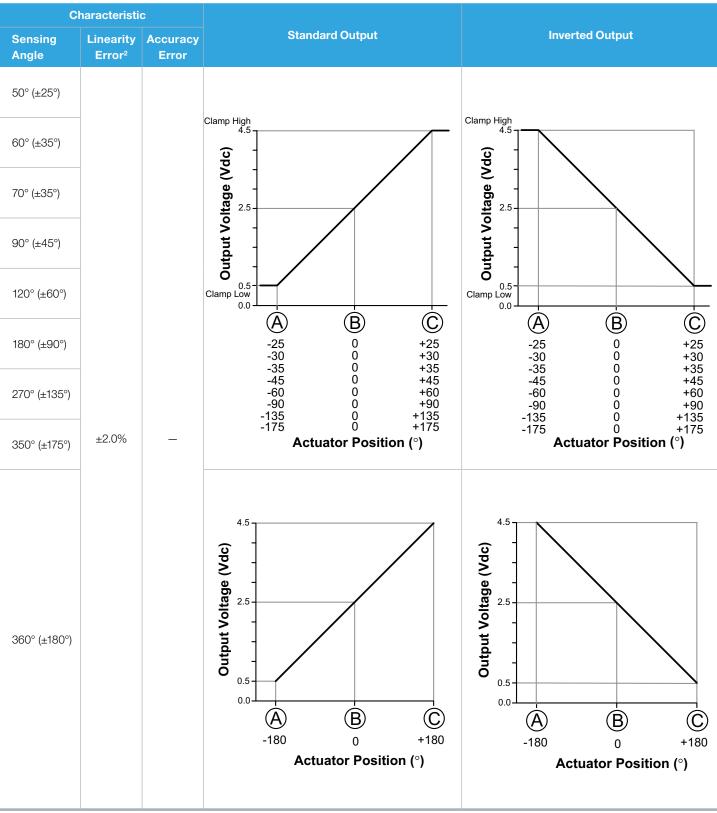


¹ See Figure 3 for references to (A) (B) (C).

² Linearity error is the deviation of the measured value from the best fit line and is the quotient of the measured output ratio deviation from the best fit line at the measured temperature to the best fit line output ratio span at the measured temperature.

³ Accuracy is measured as a deviation from the index line, where the index line is defined as the line with the ideal slope and sensor output voltage corrected at 0° position for its ideal value at 25 °C ±5 °C. Accuracy is valid only when the sensor output is correct at 0° position for its ideal value in the application.

Table 5. RTP Series Functional Characteristics¹



¹ See Figure 4 for references to (A) (B) (C).

² Linearity error is the deviation of the measured value from the best fit line and is the quotient of the measured output ratio deviation from the best fit line at the measured temperature to the best fit line output ratio span at the measured temperature.

ADDITIONAL INFORMATION

The following associated literature is available at sensing.honeywell.com:

- Product Range Guide
- Product Line Guide
- Installation Instructions
- Application Note

▲ WARNING PERSONAL INJURY

DO NOT USE these products as safety or emergency stop devices or in any other application where failure of the product could result in personal injury.

Failure to comply with these instructions could result in death or serious injury.

AWARNING

MISUSE OF DOCUMENTATION

- The information presented in this datasheet is for reference only. Do not use this document as a product installation guide.
- Complete installation, operation, and maintenance information is provided in the instructions supplied with each product.

Failure to comply with these instructions could result in death or serious injury.

WARRANTY/REMEDY

Honeywell warrants goods of its manufacture as being free of defective materials and faulty workmanship. Honeywell's standard product warranty applies unless agreed to otherwise by Honeywell in writing; please refer to your order acknowledgement or consult your local sales office for specific warranty details. If warranted goods are returned to Honeywell during the period of coverage, Honeywell will repair or replace, at its option, without charge those items it finds defective. The foregoing is buyer's sole remedy and is in lieu of all other warranties, expressed or implied, including those of merchantability and fitness for a particular purpose. In no event shall Honeywell be liable for consequential, special, or indirect damages.

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Specifications may change without notice. The information we supply is believed to be accurate and reliable as of this printing. However, we assume no responsibility for its use.

Find out more

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RTY060HVNAX RTY070LVEAX	RTY070HVEAX	RTY070LVNAX	RTY070HVNAX	RTY090LVEAX	RTY090HVEAX
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RTY360LVEAX RTY360HVEAX	RTY360LVNAX	RTY360HVNAX	RTY180LVEAA	RTY360LVNAA	RTY090LVNAA
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