CSSV1500 SERIES

Current Sensors Designed to Meet ASIL C Requirements

DESCRIPTION

The CSSV1500 Series Current Sensors are based on Honeywell's advanced multi-sensing scheme, a single power supply and an integrated CAN bus output. They are calibrated and temperature compensated using multipoint temperature characterization. This Honeywell's patented digital compensation technology enables a high degree of accuracy throughout the sensing range up to ±1500 A. The CSSV1500 Series is designed to meet Automotive Safety Integrity Level C (ASIL C) requirements for safety critical applications. These sensors have two independent sensing and data processing circuits for current sensing. The two processed data are checked for confidence. If they are within the set threshold range, the current data is outputted. If the threshold is exceeded, an alarm message is sent.

DIAGNOSTIC FUNCTIONALITY

The CAN output of the CSSV1500 Series offers fault detection and communication capability. Also, the digital CAN communication is nearly immune to electrical interference. Examples of sensor and host system faults include:

- Sensor fault
- Supply voltage over range
- Supply voltage under range

CUSTOMIZATION

The CSSV1500 Series may be customized to better meet application needs. Solutions may be tailored to exact specifications for improved time to market, lower total system costs and enhanced reliability.

DIFFERENTIATION

- Accuracy: Multi-point temperature characterization and calibration for improved accuracy over the temperature range
- Magnetic immunity: Sensing configuration and optimized magnetic circuit allow for enhanced performance in diverse magnetic environments
- ASIL-C Compliance: ASIL C for increased reliability in safety-critical applications

VALUE TO CUSTOMERS

- Accurate: Designed to enable precise battery state measurement for improved user experience
- Ease of use: Magnetic immunity allows for easy integration into different magnetic environments
- Easy system integration: CAN communication is transmitted using international road vehicle standard ISO 11898. CAN 2.0A is the default protocol

APPLICATIONS

- Current measurement for battery management systems in electrified vehicles (EV, HEV, PHEV, BEV)
- Current leakage detection and fault isolation in charging systems
- Current measurement in energy storage systems
- Fault detection in heavy industrial equipment





FEATURES

- Higher accuracy, lower temperature drift
- Enhanced EMC (Electromagnetic Compatibility) performance
- Designed to meet automotive Safety Integrity Level C (ASIL C) for the functional safety of road vehicle applications
- Reliable and stable CAN bus output
- Easy installation and software interface provide system integration convenience
- CE certification; REACH and RoHS compliant

PORTFOLIO

Honeywell offers a variety of current sensors for potential use in many applications. To view the entire product portfolio, click here.



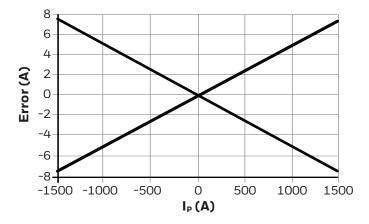
| TABLE 1. ABSOLUTE MAXIMUM RATINGS (not operating) | | | | | | |
|---|-------------------------|-----------|--------------------------|----------------------------------|--|--|
| Characteristic | Symbol | Unit | Parameter | Condition | | |
| Load dump over voltage | V_S | V | 35 | 400 ms | | |
| Over voltage | V_{S} | V | 24 20 | 10 min continuous | | |
| Reverse polarity | V_S | V | -24 | 10 min. | | |
| Supply voltage: minimum maximum | $V_{\rm S}$ $V_{\rm S}$ | V | 6 18 | continuous continuous | | |
| CAN operation: supply voltage under range alarm, no measurement supply voltage over range alarm, no measurement | V_{S} V_{S} | V | 5.5 to 5.9 18.5 to 24 | CAN continuous CAN continuous | | |
| Insulation resistance | R _{IS} | $M\Omega$ | 2000 | 500 V at 1 min. | | |
| Creepage distance | d_{Cp} | mm | 10 | _ | | |
| Clearance | d _{Cl} | mm | 10 | _ | | |
| RMS voltage for ac isolation voltage | - | KV | 5 | 50 Hz, 1 min. | | |
| Voltage for dc isolation voltage | _ | KV | 5 | 1 min. | | |

| TABLE 2. OPERATING SPECIFICATIONS IN NOMINAL RANGE (IPN) | | | | | | |
|--|--|-------------|------------------|------------------------------|------------------|---|
| Chavastavistis | Cymbol | I I to i t | : | Specification | 1 | Condition |
| Characteristic | Symbol | Unit | Min. | Тур. | Max. | Condition |
| Primary current, nominal measuring range (dc) | I _{PN} | А | -1500 | _ | 1500 | - |
| Supply voltage | V_{S} | V | 6 | 12 | 18 | _ |
| Supply voltage hysteresis: maximum minimum | V _{UP} V _{UP} V _{LOW} V _{LOW} | V V V | - - - - | 18.5 18.0 6.4 5.9 | - - - - | when V_C increases when V_C decreases when V_C increases when V_C decreases |
| Current consumption | I _C | mΑ | 40 | _ | 200 | V _S = 12 V, T = 25°C |
| Ambient operating temperature | T _A | °C [°F] | -40 [-40] | _ | 85 [185] | temperature range with accuracy guaranteed |
| High precision channel offset at I_p = 0 A | l _{os} | А | | ±0.1 | | T = -40°C to 85°C, $V_S = 9$ V to 16 V, ±3 sigma |
| High precision channel total accuracy: high at I_p = 0 A to 20 A high at 20 A < $I_p \le 1500$ A | I _{os} X _G | A — | -0.1 — | _ ±0.5% of I _P | +0.1 | T = -40°C to 85°C, V _S = 9 V to 16 V, ±3 sigma |
| Redundancy channel total accuracy: low at I_p = 0 A to 300 A low at I_p = 300 A to 1500 A | I _{os} X _G | A — | -15 - | – ±5% of I _P | +15 — | T = -40°C to 85°C, $V_S = 9$ V to 16 V, ±3 sigma |

| TABLE 3. MECHANICAL SPECIFICATIONS | | | | | |
|------------------------------------|---|--|--|--|--|
| Characteristic | Parameter | | | | |
| Housing material | PA66+GF25 (UL 94V - 0) | | | | |
| Mounting screws | M5, torque = 3,5 N m max. The installation bracket should have a flatness tolerance of $\pm 0,2$ mm. The size tolerances of the installation bracket and nut, as well as the use of installation tools and fixtures, have an impact on the maximum installation torque of the product. If there are any relevant design or process changes, it is advisable to implement them after verification. | | | | |
| Mating electrical connector | TE MPN 1473672-1 | | | | |

| TABLE 4. CERTIFICATIONS | | | | |
|-----------------------------------|-----------|--|--|--|
| Characteristic | Parameter | | | |
| Automotive Safety Integrity Level | ASIL C | | | |
| Pollution degree | PD2 | | | |

Figure 1. Error vs. Ip



| TABLE 5. ORDER GUIDE | | | | | |
|----------------------|---|--|--|--|--|
| Catalog Listing | Description | | | | |
| CSSV1500N-154 | CSSV1500N Series ASIL C current sensors, 1500 A, through-hole mounting with stainless steel bushing, 500 k baud rate, 3C4 CAN ID | | | | |
| CSSV1500N-155 | CSSV1500N Series ASIL C current sensors, 1500 A, through-hole mounting with stainless steel bushing, 500 k baud rate, 3C5 CAN ID | | | | |
| CSSV1500N-156 | CSSV1500N Series ASIL C current sensors, 1500 A, through-hole mounting with stainless steel bushing, 500 k baud rate, 3C6 CAN ID | | | | |
| CSSV1500N-154R | CSSV1500N Series ASIL C current sensors, 1500 A, through-hole mounting with stainless steel bushing, 500 k baud rate, 3C4 CAN ID, reverse current direction | | | | |
| CSSV1500N-155R | CSSV1500N Series ASIL C current sensors, 1500 A, through-hole mounting with stainless steel bushing, 500 k baud rate, 3C5 CAN ID, reverse current direction | | | | |
| CSSV1500N-156R | CSSV1500N Series ASIL C current sensors, 1500 A, through-hole mounting with stainless steel bushing, 500 k baud rate, 3C6 CAN ID, reverse current direction | | | | |

Figure 2. Nomenclature

| CS | S | V | 1500 | | N - | 1 | 5 | 4 | R |
|---------------------------------|-----------------|------------------------|--------------------|---|----------------------------|-------------|----------------|---------------------|----------------|
| Туре | Principle | Use | Rated Current | | Fixture Type | MCU Type | Baud Rate | CAN ID ¹ | Customization |
| Current Sensor | S ASIL C | V Designed for vehicle | 1500 1500 A | N | Through-hole mounting with | 1 MCU1 | 5 500 k | 4 3C4 | R ² |
| | | applications | | • | stainless steel bushing | | | 5 3C5 | |
| | | | | | - ctoot adoming | | | 6 3C6 | |

 $^{^1}$ Custom CAN IDs are available. Contact Honeywell Customer Service for more information. 2 Customization selection "R" indicates reverse current direction.

| TABLE 6. CAN BUS ELECTRICAL CHARACTERISTICS | | | | |
|---|-----------------------|--|--|--|
| Characteristic | Parameter | | | |
| Speed | See Figure 2 | | | |
| Protocol | version 2.0A | | | |
| Oscillator tolerance | 0.3125% | | | |
| Byte order | big endian (Motorola) | | | |

| TABLE 7. CAN FRAME LAYOUT | | | | | | | | | |
|---------------------------|------------------------------|----------|----|-----------|----------|--------------------------------|----------------------------------|----|--|
| Byte | SequenceCounterIP | | | Error Inf | ormation | StatusOutOf RangeIndication | StatusCurrent ValueIndication | | |
| Standard CAN Frame | | | | | | | | | |
| 0 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| High Prec | High Precision Current Value | | | | | | | | |
| 1 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | |
| 2 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | |
| 3 | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | |
| Low Precis | sion Curre | nt Value | | | | | | | |
| 4 | 39 | 38 | 37 | 36 | 35 | 34 | 33 | 32 | |
| 5 | 47 | 46 | 45 | 44 | 43 | 42 | 41 | 40 | |
| Software E | Build | | | | | | | | |
| 6 | 55 | 54 | 53 | 52 | 51 | 50 | 49 | 48 | |
| CRC_IP | | | | | | | | | |
| 7 | 63 | 62 | 61 | 60 | 59 | 58 | 57 | 56 | |

| TABLE 8. SIGNAL DESCRIPTION | | | | | | | |
|------------------------------|--|---|---------------------------------|--|--|--|--|
| Signal Name | Description | | | | | | |
| SequenceCounterIP | Initial value is 0, plus 1 every f | rame. Reset to 0 when the cour | nter reaches 14. | | | | |
| ErrorInformation | 9 | 01: Power in Under Voltage, 10: Power in Over Voltage, 11: Internal Error, 10 state, Current Value Output 0xFFFFFF/0xFFFF | | | | | |
| StatusOutOfRange | 0: Normal, 1: Out of Measure F | Range | | | | | |
| StatusCurrentValueInvalid | 0: Current Value is valid, 1: Cu | rrent Value is invalid | | | | | |
| | Unsigned number 24 bits, Unit: mA (offset 0x800000) When out of range occurs, becomes 0xFFFFFF, Ip_oc = 1550 A | | | | | | |
| | -1500 ≤ I _p ≤ +1500 | signal = I _p | accuracy = Spec | | | | |
| High Precision Current Value | -lp_oc ≤ l _p < -1500 | signal = I _p | accuracy = ±2% (for reference) | | | | |
| value | +1500 < lp ≤ l _p _oc | signal = I _p | accuracy = ±2% (for reference) | | | | |
| | lp < -lp_oc | signal = 0xFFFFFF | accuracy = NA | | | | |
| | lp > lp_oc | signal = 0xFFFFFF | accuracy = NA | | | | |
| | Unsigned number 16 bits, Uni | it: A (offset 0x8000) | | | | | |
| | When out of range occurs, becomes 0xFFFF, Ip_oc = 1550 A | | | | | | |
| | $-1500 \le I_p \le +1500$ | signal = I _p | accuracy = ±5% | | | | |
| Low Precision Current | -lp_oc ≤ l _p < -1500 | signal = I _p | accuracy = ±10% (for reference) | | | | |
| Value | +1500 < I _p ≤ Ip_oc | signal = I _p | accuracy = ±10% (for reference) | | | | |
| | lp < -l _p _oc | signal = 0xFFFF | accuracy = NA | | | | |
| | lp > l _p _oc | signal = 0xFFFF | accuracy = NA | | | | |
| Software Build | Software version | | | | | | |
| CRC_IP | 8 bit SAE J1850 CRC/AUTOSAR profile 1 DataId = Same as CAN ID; DataIdMode = E2E_P01_DATAID_BOTH | | | | | | |

Figure 3. Dimensional Drawings (For reference only: mm/IN)

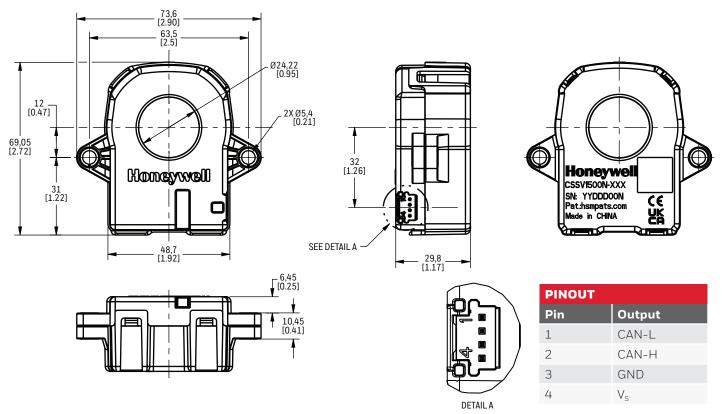


Figure 4. Part Marking Details

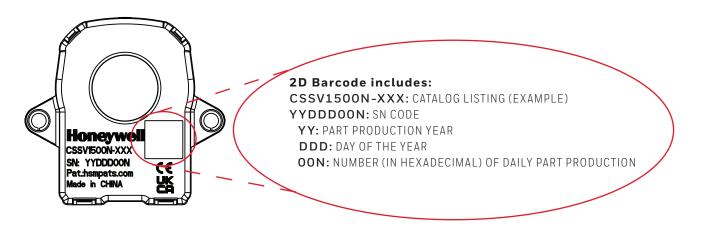
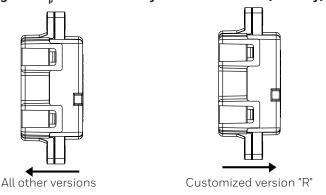


Figure 5. I_D Positive Primary Current Direction (Polarity)



| TABLE 9. EMC TEST SPECIFICATIONS | | |
|--|---------------|---|
| Test Name | Standard | Procedure |
| CISPR 25 Conducted RF Emissions - Voltage | CISPR25 | According to CISPR 25:2008 Commission Form of Testing |
| CISPR 25 Conducted RF Emissions - Current | CISPR25 | According to CISPR 25:2008 Commission Form of Testing |
| CISPR 25 Radiated Emissions - ALSE Method | CISPR25 | According to CISPR 25:2008 Commission Form of Testing |
| Transient Conduction Emission | ISO 7637-2 | According to ISO 7637-2 |
| Low Frequency Magnetic Field Emission | SAE J551-5 | According to SAE J551-5 |
| Bulk Current Injection (BCI) Test | ISO 11452-4 | According to ISO 11452-4 |
| Rf Anti-Interference - ALSE Method | ISO 11452-2 | According to ISO 11452-2 |
| Transient Disturbances Conducted along Supply Lines | ISO 7637-2 | According to ISO 7637-2 |
| Transient Disturbances Conducted along I/O or Sensor Lines | ISO 7637-3 | According to ISO 7637-3 |
| Low Frequency Field Interference | ISO 11452-8 | According to ISO 11452-8 |
| Electrostatic Discharge | ISO 10605 | Unpowered direct contact discharge: ±15 kV Unpowered air discharge: ±15 kV Powered-up direct contact discharge: ±8 kV Powered-up air discharge: ±15 kV |
| Portable Transmitter | ISO 11452-9 | According to ISO 11452-9 |
| Radio Frequency Electromagnetic Field | IEC 61000-4-3 | 10 V/m (80 MHz to 1 GHz), 3 V/m (1.4 GHz to 2 GHz), 1 V/m (2.0 GHz to 2.7 GHz) |
| Fast Transients Bursts Susceptibility Test | IEC 61000-4-4 | 2 kV Power port, 2 kV CAN signal and control port |
| Radio Frequency Continuous Conducted | IEC 61000-4-6 | 0.15 MHz to 80 MHz, 3 V 80% AM (1 kHz) |
| Radio Frequency Magnetic Field | IEC 61000-4-8 | 30 A/M |
| Radiated Disturbance (3M semi-anechoic chamber) | CISPR-11 | Group 1, Class A |

| TABLE 10. ENVIRONMENTAL TEST SPECIFICATIONS | | | | |
|---|---------------------------|--|--|--|
| Test Name | Standard | Procedure | | |
| Low Temperature Storage | ISO16750-4 | $48hr,85^{\circ}\text{C}$ power off. Performance test before and after test at 25°C and V_{s} nom. | | |
| High Temperature Storage | ISO16750-4 | $48\ hr,$ –40°C power off. Performance test before and after test at 25°C and V_S nom. | | |
| Thermal Cycle Test | ISO16750-4 | 120 cycles: one cycle contains –40°C (120 min soak) and 85°C (120 min soak). Transition time = 120 min. Performance test before and after test at 25°C and $V_{\rm S}$ nom. | | |
| High Temperature and Humidity Endurance | ISO16750-4 | 1000 hr, 85°C, 85% humidity, power on. Performance after test, from –40°C to 85°C, notify XG \leq 1 % | | |
| Vibration | IEC60068-2-64 | $5~Hz$ to $2000~Hz, 20~hr/axis, three axes with -40^{\circ}C/85^{\circ}C temperature cycle during test. Product power on. Performance test before and after test at 25^{\circ}C and V_{s} nom.$ | | |
| Mechanical Shock | ISO16750-3 | $500m/s,2,20$ each direction (60 total), half sine pulse. Product power on. Performance test before and after test at $25^{\circ}C$ and V_{s} nom. | | |
| Package Drop | ISTA-1A or GB/T 4857.5 | With final packaging, drop in direction at one corner, three edge, four face > total nine drops, one m on concrete floor. Performance test before and after test at 25°C and $V_{\rm S}$ nom. | | |
| Handling Drop | ISO 16750-3 | First fall of each DUT at a different dimensional axis. Second fall with the given DUT at the same dimensional axis but on the opposite side of the housing, from 1 m on concrete floor. Performance test before and after test at 25°C and $\mbox{V}_{\mbox{\scriptsize S}}$ nom. | | |
| Waterproof and Dust (and other Solid Intrusion) | ISO20653 | IP category: 40 | | |

| TABLE 11. ELECTRICAL TEST SPECIFICATIONS ¹ | | | | | |
|---|--------------------|---|--|--|--|
| Test Name | Standard | Procedure | | | |
| Long Time Overvoltage Test | ISO 16750-2 | Power supply at 18 V for 60 min. | | | |
| Superimposed Alternating Voltage | ISO 16750-2 | Test voltage $\rm U_{C}$ max $16V$ for $12V$ systems; ac voltage (sinusoidal): Severity 2, UPP = $4V$ | | | |
| Slow Decrease Fast Increase of Supply Voltage | ISO 16750-2-4.5 | According to ISO 16750-2-4.5 testing standard and Fig | | | |
| Reset Behavior at Voltage Drop | ISO16750-2-4.6.2.2 | See Fig. 6 | | | |
| Transient Overvoltage Test | ISO16750-2 | Power supply at 24 V for 10 min. | | | |
| Momentary Drop in Supply Voltage | ISO 16750-2-4.6.1 | U_{C} min to 4.5 V. See Fig. 4 | | | |
| Load Dump | ISO 16750-2-4.6.4 | Pulse described in Table 6. See Fig. 9 | | | |
| Reverse Voltage Test | ISO16750-2-4.7 | Power supply at -24 V for 10 min. | | | |
| Single Line Open Circuit Tests | ISO16750-2-4.9 | Connect sensor to 12 V power supply and power on the sensor. Disconnect Us, GND, CAN-H, and CAN-L in sequence. Each open circuit time: $60 \pm 1 \text{s}$ | | | |
| Connector Open Circuit Tests | ISO16750-2 | Connect sensor to 12 V power supply and power on the sensor. Disconnect connector. Each open circuit time: $10\pm1~\rm s$ | | | |
| Insulation Resistance Test | ISO 16750-2-4.12 | 500 Vdc for 60 s; Resistance criteria: >500 MOhm | | | |
| dc and ac Voltage Insulation Test | _ | Test Voltage: 5000Vdc and ac. Frequency: dc and $50{\sim}60\text{Hz}$. Test Duration: 60s | | | |

 $^{^{\}rm 1}\,\mbox{See}$ the applicable standard for all table and figure references.

NOTICE PRELIMINARY DOCUMENTATION

The information contained in this document is preliminary and for reference only. Preliminary means that the product described has not been or is currently being formally tested. Specifications are subject to change without notice. Reliance on the information contained herein is at the reader's own risk.

For more information

Honeywell Sensing & Safety
Technologies services its customers
through a worldwide network of sales
offices and distributors. For application
assistance, current specifications, pricing
or the nearest Authorized Distributor, visit
our website or call:

USA/Canada +1 302 613 4491 Latin America +1 305 805 8188 Europe +44 1344 238258 Japan +81 (0) 3-6730-7152 Singapore +65 6355 2828 Greater China +86 4006396841

WARRANTY/REMEDY

Honeywell warrants goods of its manufacture as being free of defective materials and faulty workmanship during the applicable warranty period. Honeywell's standard product warranty applies unless agreed to otherwise by Honeywell in writing; please refer to your order acknowledgment or consult your local sales office for specific warranty details. If warranted goods are returned to Honeywell during the period of coverage, Honeywell will repair or replace, at its option, without charge those items that Honeywell, in its sole discretion, finds defective.

The foregoing is buyer's sole remedy and is in lieu of all other warranties, expressed or implied, including those of merchantability and fitness for a particular purpose. In no event shall Honeywell be liable for consequential, special, or indirect damages.

While Honeywell may provide application assistance personally, through our literature and the Honeywell web site, it is buyer's sole responsibility to determine the suitability of the product in the application.

Specifications may change without notice. The information we supply is believed to be accurate and reliable as of this writing. However, Honeywell assumes no responsibility for its use.

⚠ WARNINGPERSONAL INJURY

DO NOT USE these products as safety or emergency stop devices or in any other application where failure of the product could result in personal injury.

Failure to comply with these instructions could result in death or serious injury.

⚠ WARNINGMISUSE OF DOCUMENTATION

- The information presented in this product sheet is for reference only. Do not use this document as a product installation guide.
- Complete installation, operation, and maintenance information is provided in the instructions supplied with each product.

Failure to comply with these instructions could result in death or serious injury.

Honeywell Sensing & Safety Technologies

830 East Arapaho Road Richardson, TX 75081 www.honeywell.com



Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

Honeywell:

CSSV1500N-155R CSSV1500N-154 CSSV1500N-155 CSSV1500N-154R CSSV1500N-156 CSSV1500N-156R