4-20 mA vibration transmitter modules

iT150 series

SPECIFICATIONS

INPUT	
Sensor types	IEPE accelerometers, IEPE piezovelocity transducers, IEPE dual output (vibration and temperature) sensors
Sensor senstivities accepted:	
Accelerometer	10, 100, 500 mV/g
Piezovelocity	10, 100, 500 mV/ips
Dual output[1]	10 mV/°C
Frequency response:	
Acceleration[2]	0.2 Hz - 20 kHz (-3 dB, -0.1 dB)
Velocity	0.2 Hz - 5 kHz
Sensor powering:	
Open circuit voltage	24 VDC, ±5%
Constant-current	4.5 mA, ±20%
Maximum dynamic signal input, for linear response	20 Volts peak-to-peak
OUTPUT, 4-20 mA loop current	
Full scale, ±2%	see Ordering information on page 2
Output type	true RMS, equivalent peak, equivalent peak-peak, true peak
Maximum 4-20 mA loop load resistance	500 Ω
Accuracy	±0.2% of full scale
Turn on time	<30 seconds
OUTPUT, buffered dynamic	
Gain, RTI sensor	1.0 ±2%
Noise RTO, broadband, 1 Hz - 10 kHz, RMS	≤0.0001 Volts
Output type	DC-coupled
ENVIRONMENTAL	
Power:	
Voltage (Vin)	11 - 32 VDC
Current draw	125 mA at 24 VDC (3 watts max)
Temperature, operating, ambient	–40° to +70°C
PHYSICAL	
Mounting	snap into 35 mm DIN rail
Dimensions:	
Width	22.5 mm (0.86”)
Depth (front of BNC to back of DIN rail)	127 mm (4.98”)
Height	100 mm (3.90”)

Key features

- Temperature measurement
- Slim 22.5 mm case
- Front panel BNC for dynamic signal output
- Manufactured in ISO 9001 facility

For dimensions and ordering information, see page 2.

For system architecture, see page 3.

Notes: [1] Compatible with Wilcoxon models 786T and 787T (measurement range: 0° to 120°C, input signal: 0 - 1.2 VDC).

[2] True peak frequency response: 10 Hz to 25 kHz.

CE

Note: Due to continuous process improvement, specifications are subject to change without notice. This document is cleared for public release.

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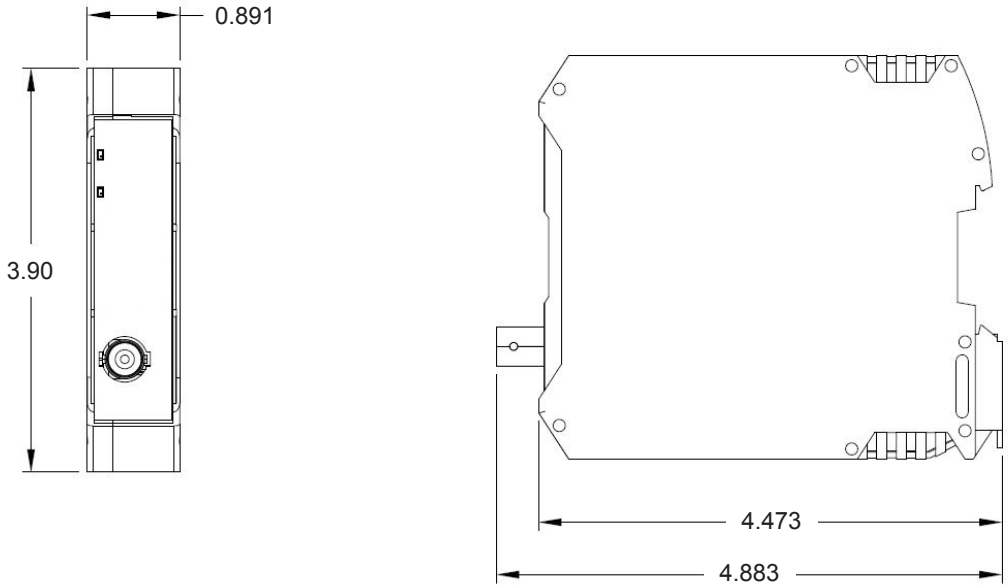
Dimensions



Ordering information

iT150 – ☐ – ☐ – ☐ – ☐ – ☐ – ☐ – ☐ – ☐

Input type	
A	Acceleration
V	Velocity

Sensitivity	
10	mV/g, mV/ips
100	
500	

Output type	
A	Acceleration
V	Velocity
D**	Displacement

Output type	Units	Full scale
A	g	**1, 5, 10, 20, 30, 50**
	m/s^2	**50, 100, 200, 300, 500**
V	ips	**0.5, 1, 2, 3, 5**
	mm/s	**15, 20, 25, 30, 45, 50, 100**
D**	mils	**10, 20, 25, 100**
	mm	**0.2, 0.5, 1, 2, 3, 4, 5**

Detector type	
RMS	True RMS
P	Peak (equiv.)
PP	Peak-to-peak (equiv.)
TP*	True peak (10-25,000 Hz)

Output type	Units
A	**g**
	m/s/s (m/s^2)
V	**ips**
	mm/s
D**	**mils****
	mm

Detector type	Output type	F_{MIN} (Hz) – F_{MAX} (Hz)	
RMS Peak Peak-to-peak	A, V, D**	**0.2 – 200**	
		0.5 – 500	
	A, V	**1 – 1,000**	
		10 – 1,000	ISO 10816-3
		2 – 2,000	
		5 – 5,000	
	A	**10 – 10,000**	
		20 – 20,000	
True peak*	A	**10 – 25,000**	
		F_{MIN} fixed with F_{MAX} (select desired frequency range)	

Selectable parameters are in **bold.**

Notes:

* True peak detection option available for Input/Output type “A” only.

** Displacement output option available for Input type “V” only.

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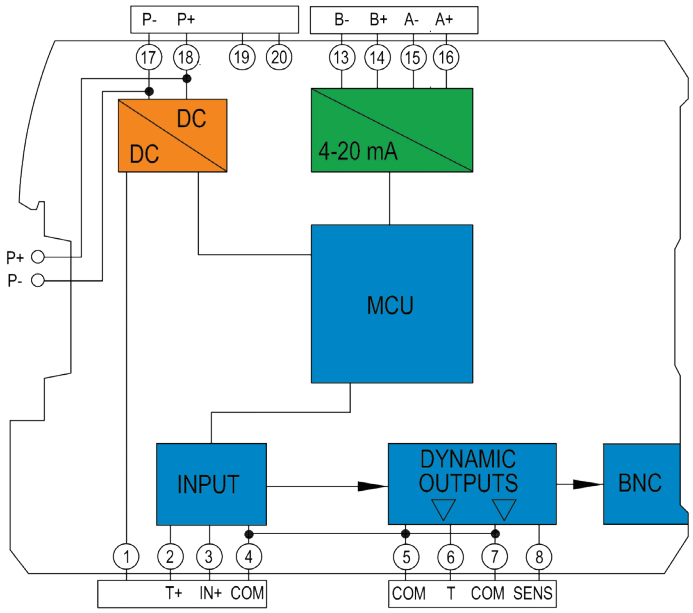
System architecture

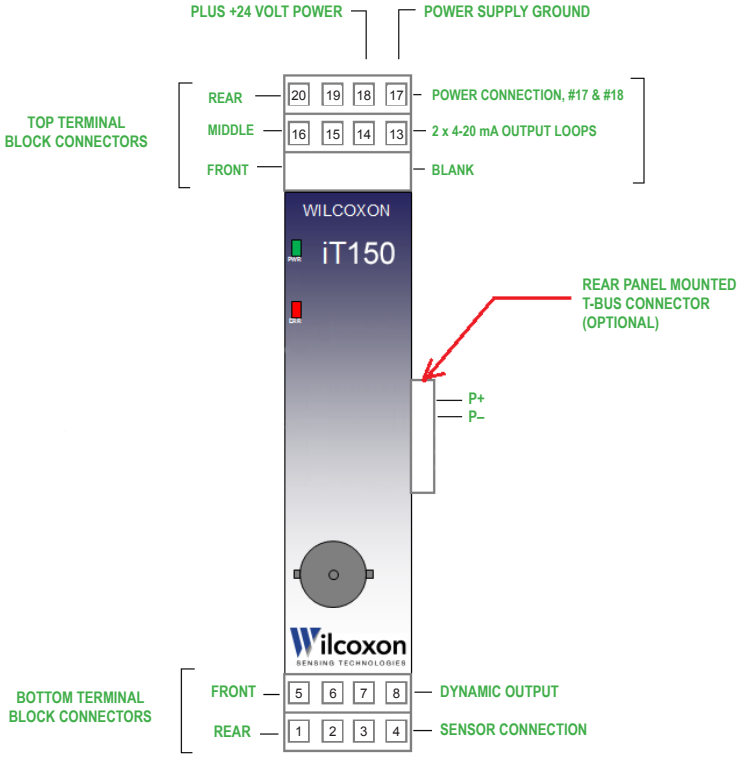


Power input

4-20 mA outputs

Input/output µprocessor

IO Port	Terminal numbers and signal assignments
Vibration sensor	1 - No connection 2 - Temperature sensor (in T+) 3 - Signal in / Sensor Power (IN+) 4 - Circuit common (COM)
Temperature dynamic output	5 - Circuit common (COM) 6 - Temperature out (T)
Sensor dynamic output	7 - Circuit common (COM) 8 - Sensor out (SENS)
4-20 mA Loop B Temperature	13 - B- 14 - B+
4-20 mA Loop A Vibration	15 - A- 16 - A+
Power input	17 - P- 18 - P+
Not used	19 20



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