

Acceleration loop powered sensors with dynamic vibration output

PC420A-DA dual output series

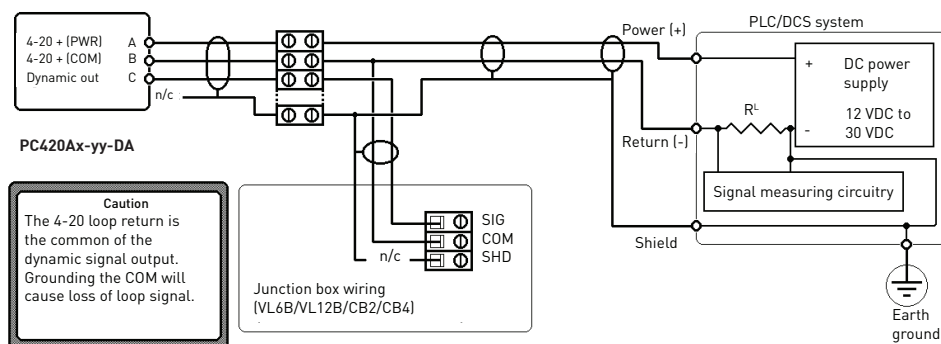
Wilcoxon's 4-20 mA vibration sensors integrate easily with an existing PLC, DCS or SCADA system. The PC420A-DA series dual output sensors provide 24/7 monitoring of overall machine vibration for continuous trending, alerting users to changing machine conditions and helping to guide maintenance in prioritizing the need for service. The choice of true RMS, true peak or peak output allows you to choose the sensor that best fits your industrial requirements. The sensor's 4-20 mA output is proportional to acceleration vibration. The dynamic output signal is derived from an internal buffered amplifier and requires that the 4-20 mA loop be powered.



Table 1: PC420Ax-yy-DA dual output model selection guide

x (4-20 mA output type)	yy (4-20 mA full scale)	DA (dynamic output)
R = RMS output	05 = 5 g (49 m/sec ²)	DA = acceleration, 100 mV/g
P = calculated peak output	10 = 10 g (98 m/sec ²)	
TP = true peak output	20 = 20 g (196 m/sec ²)	

Wiring diagram



Note: Dynamic output must be galvanically isolated when connected to an on time system.

Certifications



Key features

- Choice of peak equivalent, true RMS or true peak output
- Dynamic signal output allows for in-depth analysis
- Easily integrated into existing process control systems
- Manufactured in an approved ISO 9001 facility

Note: Due to continuous process improvement, specifications are subject to change without notice. This document is cleared for public release.

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SPECIFICATIONS

Output, 4-20 mA:

Full scale, 20 mA, $\pm 5\%$	see Table 1 on page 1	
Frequency response:	$\pm 10\%$ ± 3 dB	10 Hz - 1.0 kHz 4.0 Hz - 2.0 kHz
Repeatability	$\pm 2\%$	
Transverse sensitivity, max	5%	

Dynamic output:

Sensitivity, $\pm 10\%$	100 mV/g	
Full scale	20 g	
Frequency response, ± 3 dB	2.5 Hz - 10 kHz	
Amplitude nonlinearity, max	1%	
Resonant frequency, mounted, nominal	25 kHz	
Transverse sensitivity, max	5%	

Power requirements (2-wire loop power):

Voltage at sensor terminals	12 - 30 VDC	
Loop resistance ¹ at 24 VDC, max	700 Ω	
Turn on time, 4-20 mA loop	< 30 sec	
Dynamic output, bias output voltage	+3.3 VDC, re: connector pin B	

Dynamic output noise, equiv. g:		
2.5 Hz - 10 kHz	2 mg	

Grounding	case isolated, internally shielded	
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Temperature range	-40° to +85°C	
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Vibration limit	250 g peak	
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Shock limit	2,500 g peak	
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Sealing	hermetic	
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Sensing element design	PZT ceramic / shear	
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Weight	162 grams	
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Case material	316L stainless steel	
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Mounting	1/4-28 tapped hole	
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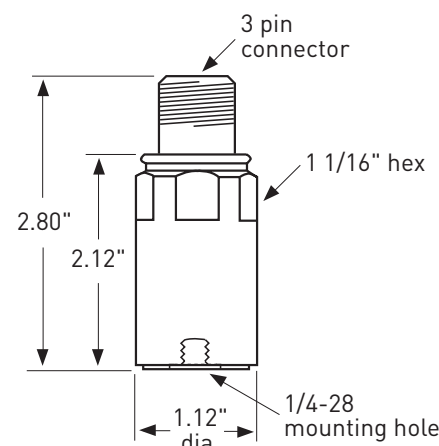
Output connector	3 pin, MIL-C-5015 style	
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Mating connector	R6G type	
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Recommended cabling	J9T3A (3-conductor shielded, yellow Teflon jacket)	
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Accessories supplied: SF6 mounting stud; calibration data (level 2)

Connections	
Function	Connector pin
loop positive (+)	A
loop negative (-), dynamic common	B
dynamic output	C
ground	shell



Notes: ¹ Maximum loop resistance (R_L) can be calculated by:

$$R_L = \frac{V_{DC \text{ power}} - 10 \text{ V}}{20 \text{ mA}}$$

DC supply voltage	R_L (max resistance) ²	R_L (minimum wattage capability) ³
12 VDC	100 Ω	1/8 watt
20 VDC	500 Ω	1/4 watt
24 VDC	700 Ω	1/2 watt
26 VDC	800 Ω	1/2 watt
30 VDC	1,000 Ω	1/2 watt

² Lower resistance is allowed, greater than 10 Ω recommended.

³ Minimum R_L wattage determined by: $(0.0004 \times R_L)$.

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