

# Naos Raptor 20A: Non-Isolated DC-DC Power Modules

4.5V<sub>dc</sub>–14V<sub>dc</sub> input; 0.59V<sub>dc</sub> to 6V<sub>dc</sub> output; 20A Output Current

RoHS Compliant

TUNABLE  
LOOP™



## Description

The Naos Raptor 20A SIP power modules are non-isolated dc-dc converters in an industry standard package that can deliver up to 20A of output current with a full load efficiency of 91% at 3.3V<sub>dc</sub> output voltage ( $V_{IN} = 12V_{dc}$ ). These modules operate over a wide range of input voltage ( $V_{IN} = 4.5V_{dc}$ –13.8V<sub>dc</sub>) and provide a precisely regulated output voltage from 0.59V<sub>dc</sub> to 6V<sub>dc</sub>, programmable via an external resistor. Features include remote On/Off, adjustable output voltage, over current and over temperature protection. A new feature, the Tunable Loop™, allows the user to optimize the dynamic response of the converter to match the load.

## Applications

- Distributed power architectures
- Intermediate bus voltage applications
- Telecommunications equipment

- Servers and storage applications
- Networking equipment

## Features

- Compliant to RoHS Directive 2011/65/EU and amended Directive (EU) 2015/863 (Z versions)
- Compliant to REACH Directive (EC) No 1907/2006
- Compatible in a Pb-free or SnPb wave-soldering environment (Z versions)
- Wide input voltage range (4.5V<sub>dc</sub>–14V<sub>dc</sub>)
- Output voltage programmable from 0.59V<sub>dc</sub> to 6V<sub>dc</sub> via external resistor
- Tunable Loop™ to optimize dynamic output voltage response
- Fixed switching frequency
- Output overcurrent protection (non-latching)
- Over temperature protection
- Remote On/Off
- Remote Sense
- Power Good Signal
- Small size: 36.8 mm x 15.5 mm x 9.2 mm (1.45 in. x 0.61 in. x 0.36 in)
- Wide operating temperature range (-40°C to 85°C)
- ANSI/UL\* 62368-1 and CAN/CSA† C22.2 No. 62368-1 Recognized, DIN VDE‡ 0868-1/A11:2017 (EN62368-1:2014/A11:2017)
- ISO\*\* 9001 and ISO 14001 certified manufacturing facilities

# Technical Specifications (continued)

## Absolute Maximum Ratings

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Device	Symbol	Min	Max	Unit
Input Voltage	All	$V_{IN}$	-0.3	15	$V_{dc}$
Continuous					
Operating Ambient Temperature (see Thermal Considerations section)	All	$T_A$	-40	85	°C
Storage Temperature	All	$T_{stg}$	-55	125	°C

## Electrical Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

Parameter	Device	Symbol	Min	Typ	Max	Unit
Operating Input Voltage	All	$V_{IN}$	4.5	12.0	13.8	$V_{dc}$
Maximum Input Current ( $V_{IN} = V_{IN,MIN}$ to $V_{IN,max}$ , $I_O = I_{O,max}$ , $V_{O,set} = 3.3V_{dc}$ )	All	$I_{IN,max}$			20	$A_{dc}$
Input No Load Current ( $V_{IN} = 12V_{dc}$ , $I_O = 0$ , module ON)	$V_{O,set} = 0.6 V_{dc}$	$I_{IN,No load}$		50		mA
	$V_{O,set} = 5.0V_{dc}$	$I_{IN,No load}$		110		mA
Input Stand-by Current ( $V_{IN} = 12V_{dc}$ , module disabled)	All	$I_{IN,stand-by}$		6.08		mA
Inrush Transient	All	$I^2t$			1	$A^2s$
Input Reflected Ripple Current, peak-to-peak (5Hz to 20MHz, 1μH source impedance; $V_{IN,min}$ to $V_{IN,max}$ , $I_O = I_{O,max}$ ; See Test configuration section)	All			34.4		mA <sub>p-p</sub>
Input Ripple Rejection (120Hz)	All			43		dB
Output Voltage Set point (with 0.5% tolerance for external resistor used to set output voltage )	All	$V_{O,set}$	-1.5		+1.5%	% $V_{O,set}$
Output Voltage (Over all operating input voltage, resistive load, and temperature conditions until end of life)	All	$V_{O,set}$	-3.0	—	+3.0	% $V_{O,set}$
Adjustment Range Selected by an external resistor	All	$V_O$	0.59		6	$V_{dc}$
Output Regulation (for $V_O \geq 2.5V$ )						
Line ( $V_{IN} = V_{IN,MIN}$ to $V_{IN,MAX}$ )	All		-0.2	—	+0.2	% $V_{O,set}$
Load ( $I_O = I_{O,min}$ to $I_{O,max}$ )	All			—	0.8	% $V_{O,set}$
Output Regulation (for $V_O < 2.5V$ )						
Line ( $V_{IN} = V_{IN,MIN}$ to $V_{IN,MAX}$ )	All		-5	—	+5	mV
Load ( $I_O = I_{O,min}$ to $I_{O,max}$ )	All				20	mV

# Technical Specifications (continued)

## Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Typ	Max	Unit
Output Ripple and Noise on nominal output ( $V_{IN}=V_{IN,nom}$ and $I_O=I_{O,min}$ to $I_{O,max}$ , $C_{out} = 0\mu F$ )						
Peak-to-Peak (5Hz to 20MHz bandwidth)	$V_O = 0.59V$		—		20	mV <sub>pk-pk</sub>
Peak-to-Peak (5Hz to 20MHz bandwidth)	$V_O = 1.2V$		—		23	mV <sub>pk-pk</sub>
Peak-to-Peak (5Hz to 20MHz bandwidth)	$V_O = 1.8V$		—		25	mV <sub>pk-pk</sub>
Peak-to-Peak (5Hz to 20MHz bandwidth)	$V_O = 2.5V$		—		30	mV <sub>pk-pk</sub>
Peak-to-Peak (5Hz to 20MHz bandwidth)	$V_O = 3.3V$		—		40	mV <sub>pk-pk</sub>
Peak-to-Peak (5Hz to 20MHz bandwidth)	$V_O = 5.0V$		—		50	mV <sub>pk-pk</sub>
Peak-to-Peak (5Hz to 20MHz bandwidth)	$V_O = 6.0V$		—		60	mV <sub>pk-pk</sub>
External Capacitance <sup>1</sup> Without the Tunable Loop™						
ESR $\geq 1 m\Omega$	All	$C_{O,max}$	—	—	300	$\mu F$
With the Tunable Loop™						
ESR $\geq 0.15 m\Omega$	All	$C_{O,max}$	0	—	1500	$\mu F$
ESR $\geq 10 m\Omega$	All	$C_{O,max}$	0	—	10000	$\mu F$
Output Current	All	$I_O$	0	—	20	A <sub>dc</sub>
Output Current Limit Inception (Hiccup Mode)	All	$I_{O,lim}$		140		% $I_O$
Output Short-Circuit Current ( $V_O \leq 250mV$ ) ( Hiccup Mode )	All	$I_{O,s/c}$		1.1		A <sub>rms</sub>
Efficiency ( $V_{in} = 9V_{dc}$ )						
	$V_{O,set} = 0.59V_{dc}$	$\eta$		72.2		%
$V_{IN} = 12V_{DC}$ , $T_A = 25^\circ C$	$V_{O,set} = 1.2V_{dc}$	$\eta$		82.3		%
$I_O = I_{O,max}$ , $V_O = V_{O,set}$	$V_{O,set} = 1.8V_{dc}$	$\eta$		87.5		%
	$V_{O,set} = 2.5V_{dc}$	$\eta$		90.2		%
	$V_{O,set} = 3.3V_{dc}$	$\eta$		92.1		%
	$V_{O,set} = 5.0V_{dc}$	$\eta$		94.3		%
	$V_{O,set} = 6.0V_{dc}$	$\eta$		95.0		%
Switching Frequency	All	$f_{sw}$	—	600	—	kHz

<sup>1</sup> External capacitors may require using the new Tunable Loop™ feature to ensure that the module is stable as well as getting the best transient response. See the Tunable Loop™ section for details.

## General Specifications

Parameter	Min	Typ	Max	Unit
Calculated MTBF ( $V_{IN}=12V$ , $V_O=5V_{dc}$ , $I_O=0.8I_{O,max}$ , $T_A=40^\circ C$ ) Per Telcordia Issue 2, Method I Case 3		16,061,773		Hours
Weight	—	6.6(0.23)	—	g (oz.)

# Technical Specifications (continued)

## Feature Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbol	Min	Typ	Max	Unit
On/Off Signal Interface						
Signal referenced to GND)						
Logic High (On/Off pin open – Module ON)						
Input High Current	All	$I_{IH}$	0	—	0.5	mA
Input High Voltage	All	$V_{IH}$	1.0	—	12	V
Logic Low (Module OFF)						
Input Low Current	All	$I_{IL}$	—	—	200	$\mu$ A
Input Low Voltage	All	$V_{IL}$	-0.3	—	0.4	V
PwGood (Power Good)						
Signal Interface Open Collector/Drain						
PwGood = High = Power Good						
PwGood = Low = Power Not Good						
Logic level low voltage, $I_{sink} = 5$ mA			0		0.35	V
Sink Current, PwGood = low					10	mA
Turn-On Delay and Rise Times						
$(V_{IN}=V_{IN, nom}, I_O=I_{O, max}, V_O$ to within $\pm 1\%$ of steady state)						
Case 1: On/Off input is enabled and then input power is applied (delay from instant at which $V_{IN} = V_{IN, min}$ until $V_O = 10\%$ of $V_{O, set}$ )						
	All	$T_{delay}$		2	3	msec
Case 2: Input power is applied for at least one second and then the On/Off input is enabled (delay from instant at which On/Off is enabled until $V_O = 10\%$ of $V_{O, set}$ )						
	All	$T_{delay}$		2	3	msec
Output voltage Rise time (time for $V_O$ to rise from 10% of $V_{O, set}$ to 90% of $V_{O, set}$ )						
	All	$T_{rise}$		3	6	msec
Output voltage overshoot						
$I_O = I_{O, max}; V_{IN, min} - V_{IN, max}, T_A = 25$ °C					0.5	% $V_{O, set}$
Remote Sense Range	All		—	—	0.5	V
Over Temperature Protection ( see thermal considerations section)						
	All	$T_{ref}$		130		°C
Input Undervoltage Lockout						
Turn-on Threshold	All			4.2		$V_{dc}$
Turn-off Threshold	All			4.1		$V_{dc}$

### FOOTNOTES

\* UL is a registered trademark of Underwriters Laboratories, Inc.

† CSA is a registered trademark of Canadian Standards Association.

‡ VDE is a trademark of Verband Deutscher Elektrotechniker e.V.

“ ISO is a registered trademark of the International Organization of Standards

# Technical Specifications (continued)

## Characteristic Curves

The following figures provide typical characteristics for the Naos Raptor 20A module at 0.6V<sub>out</sub> and at 25°C.

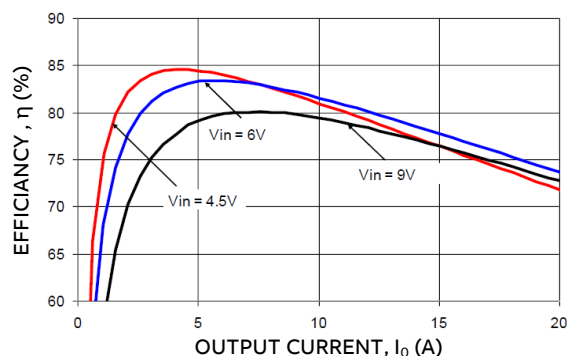


Figure 1. Converter Efficiency versus Output Current.

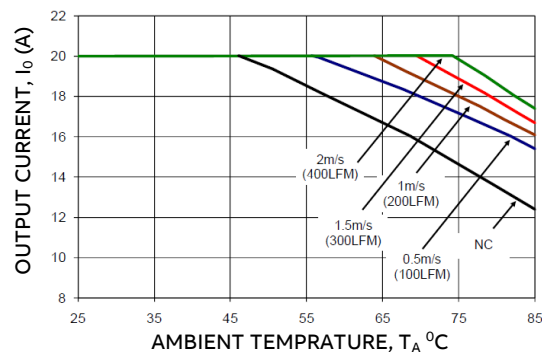


Figure 2. Derating Output Current versus Ambient Temperature and Airflow.

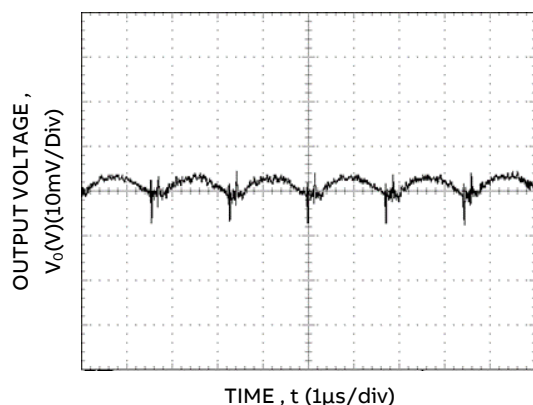


Figure 3. Typical output ripple and noise (V<sub>IN</sub> = 9V, I<sub>o</sub> = I<sub>o,max</sub>).

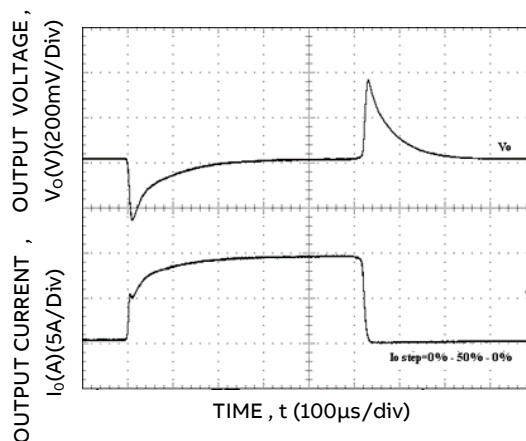


Figure 4. Transient Response to Dynamic Load Change from 0% to 50% to 0% with V<sub>IN</sub>=9V.

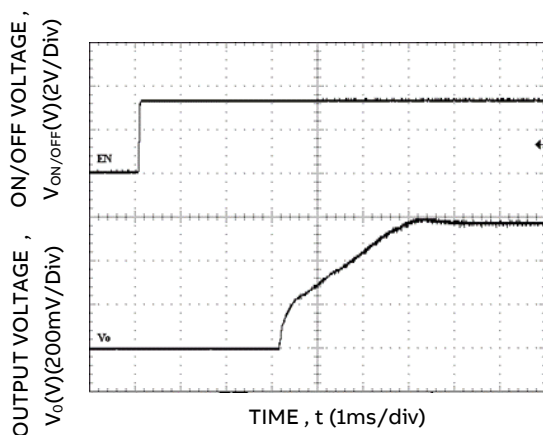


Figure 5. Typical Start-up Using On/Off Voltage (I<sub>o</sub> = I<sub>o,max</sub>).

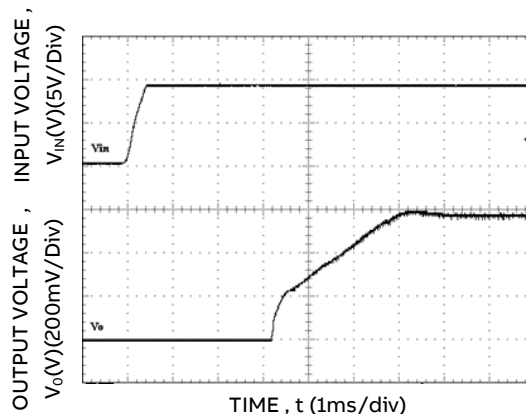


Figure 6. Typical Start-up Using Input Voltage (V<sub>IN</sub> = 9V, I<sub>o</sub> = I<sub>o,max</sub>).

## Technical Specifications (continued)

### Characteristic Curves (continued)

The following figures provide typical characteristics for the Naos Raptor 20A module at 1.2V<sub>out</sub> and at 25°C.

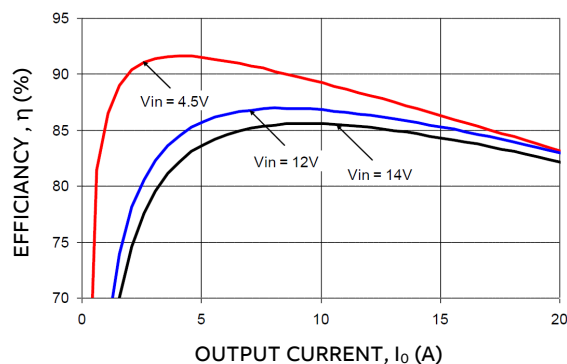


Figure 7. Converter Efficiency versus Output Current.

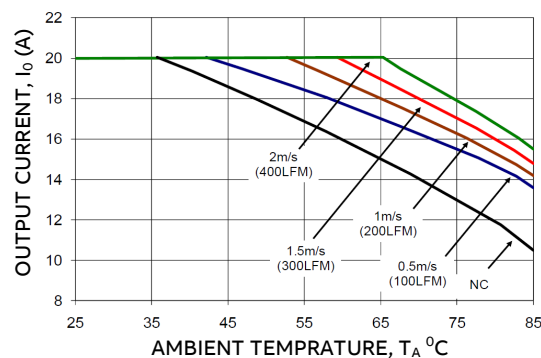


Figure 8. Derating Output Current versus Ambient Temperature and Airflow.

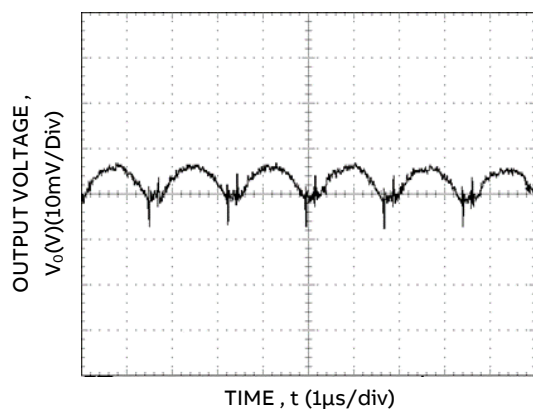


Figure 9. Typical output ripple and noise ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ).

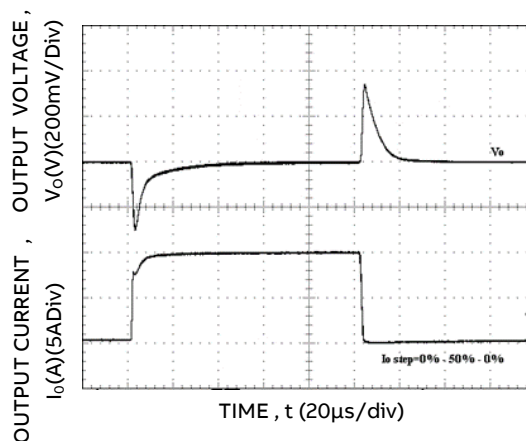


Figure 10. Transient Response to Dynamic Load Change from 0% to 50% to 0% with  $V_{IN} = 12V$ .

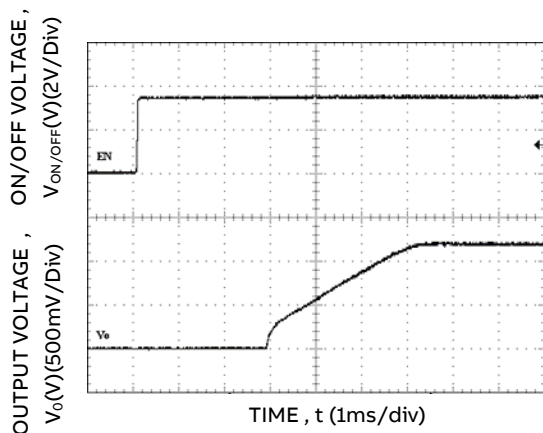


Figure 11. Typical Start-up Using On/Off Voltage ( $I_o = I_{o,max}$ ).

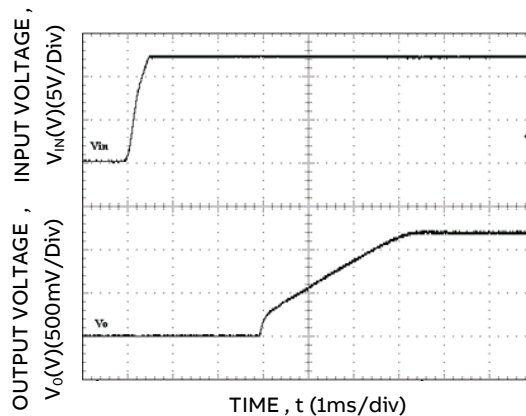


Figure 12. Typical Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ).

## Technical Specifications (continued)

### Characteristic Curves (continued)

The following figures provide typical characteristics for the Naos Raptor 20A module at 1.8V<sub>out</sub> and at 25°C.

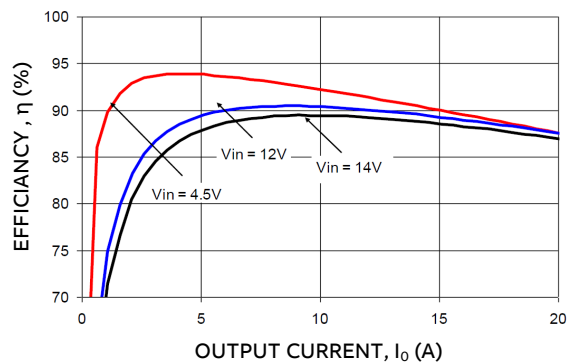


Figure 13. Converter Efficiency versus Output Current.

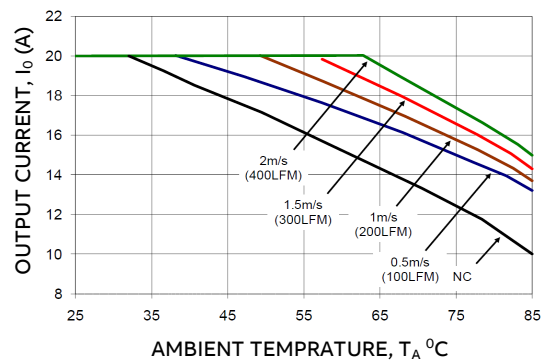


Figure 14. Derating Output Current versus Ambient Temperature and Airflow.

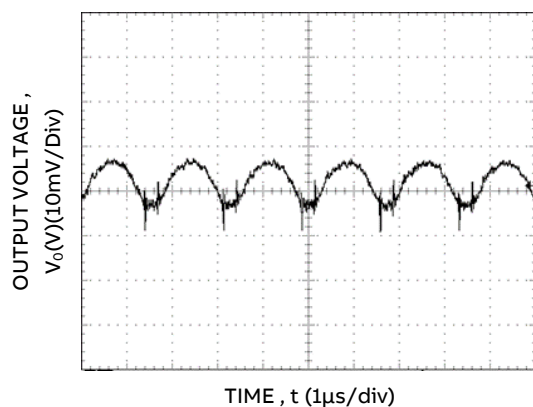


Figure 15. Typical output ripple and noise ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ).

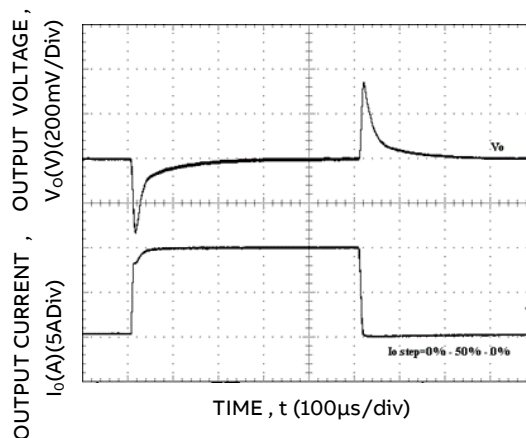


Figure 16. Transient Response to Dynamic Load Change from 0% to 50% to 0% with  $V_{IN} = 12V$ .

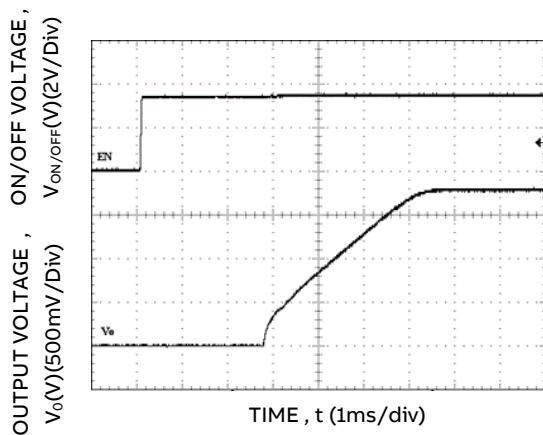


Figure 17. Typical Start-up Using On/Off Voltage ( $I_o = I_{o,max}$ ).

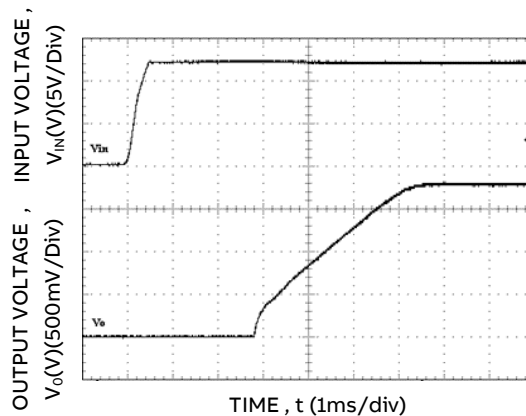


Figure 18. Typical Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ).

# Technical Specifications (continued)

## Characteristic Curves (continued)

The following figures provide typical characteristics for the Naos Raptor 20A module at 2.5V<sub>out</sub> and at 25°C.

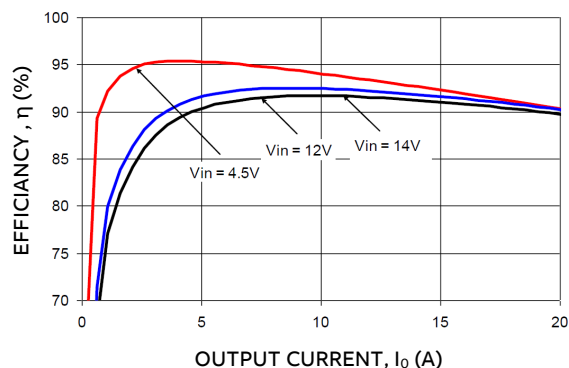


Figure 19. Converter Efficiency versus Output Current.

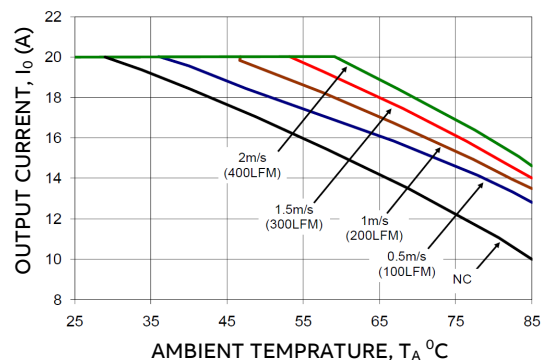


Figure 20. Derating Output Current versus Ambient Temperature and Airflow.

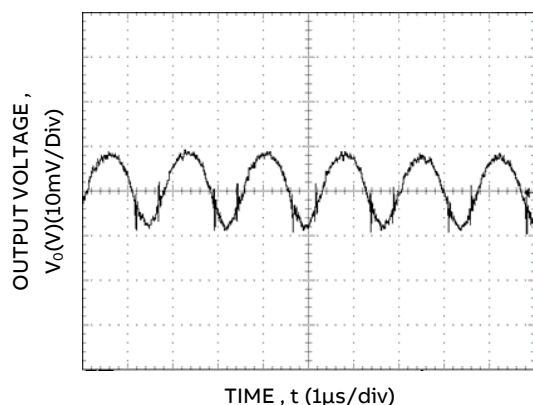


Figure 21. Typical output ripple and noise ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ).

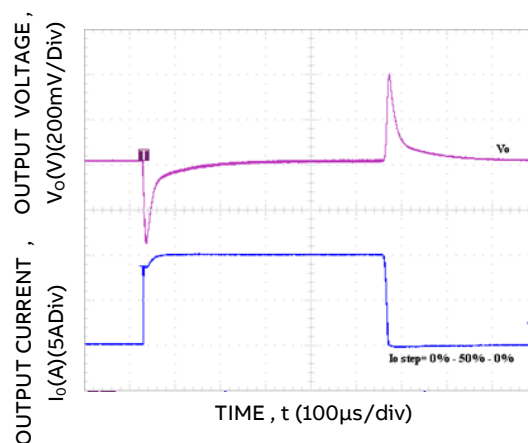


Figure 22. Transient Response to Dynamic Load Change from 0% to 50% to 0% with  $V_{IN}=12V$ .

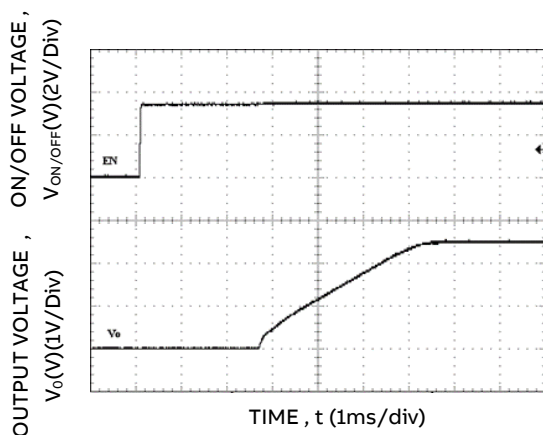


Figure 23. Typical Start-up Using On/Off Voltage ( $I_o = I_{o,max}$ ).

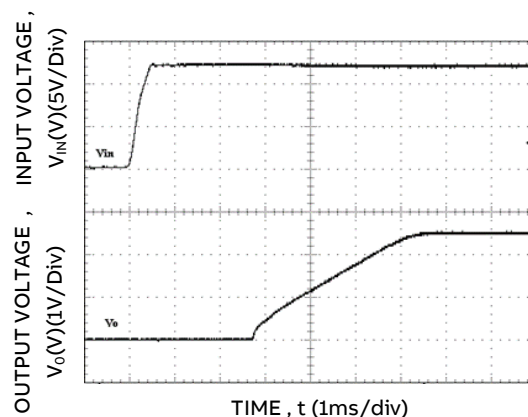


Figure 24. Typical Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ).



## Technical Specifications (continued)

### Characteristic Curves (continued)

The following figures provide typical characteristics for the Naos Raptor 20A module at 3.3V<sub>out</sub> and at 25°C.

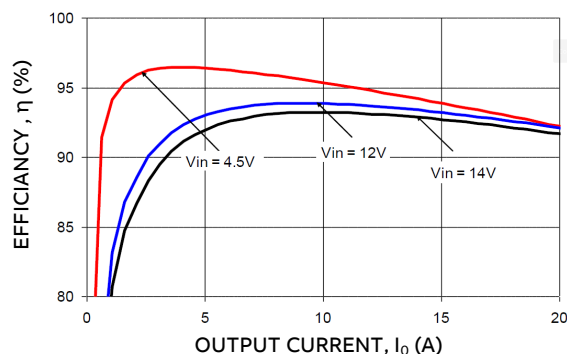


Figure 25. Converter Efficiency versus Output Current.

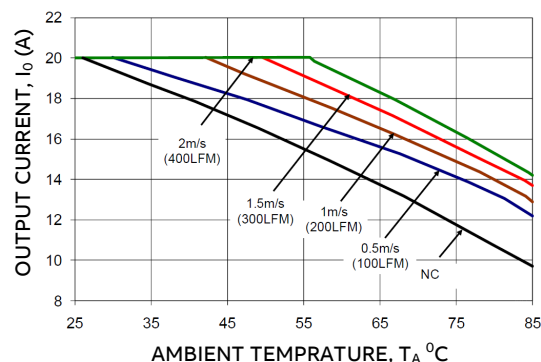


Figure 26. Derating Output Current versus Ambient Temperature and Airflow.

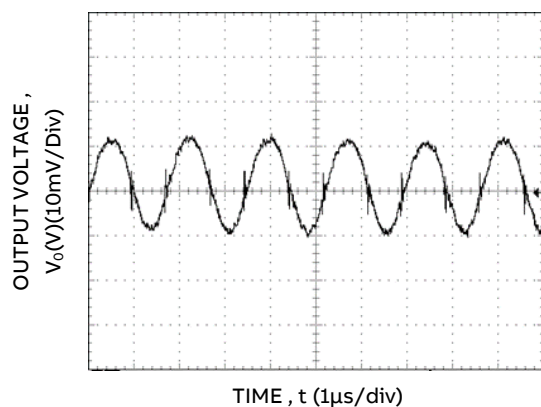


Figure 27. Typical output ripple and noise ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ).

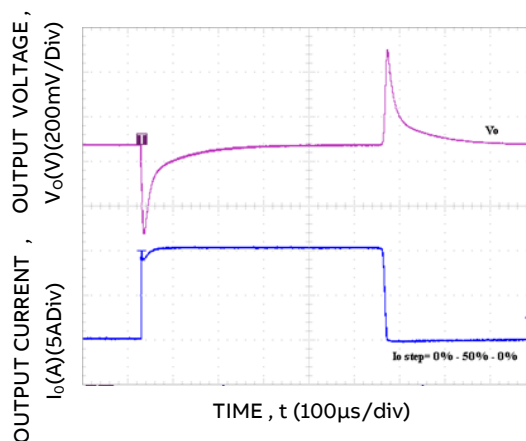


Figure 28. Transient Response to Dynamic Load Change from 0% to 50% to 0% with  $V_{IN} = 12V$ .

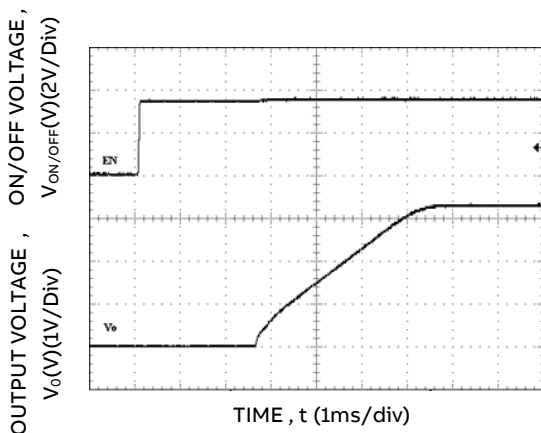


Figure 29. Typical Start-up Using On/Off Voltage ( $I_o = I_{o,max}$ ).

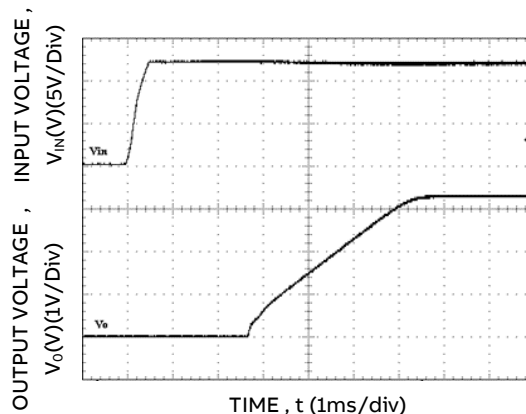


Figure 30. Typical Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ).

## Technical Specifications (continued)

### Characteristic Curves (continued)

The following figures provide typical characteristics for the Naos Raptor 20A module at  $5V_{out}$  and at  $25^{\circ}C$ .

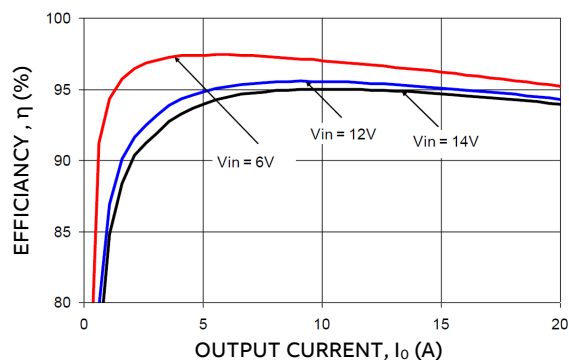


Figure 31. Converter Efficiency versus Output Current.

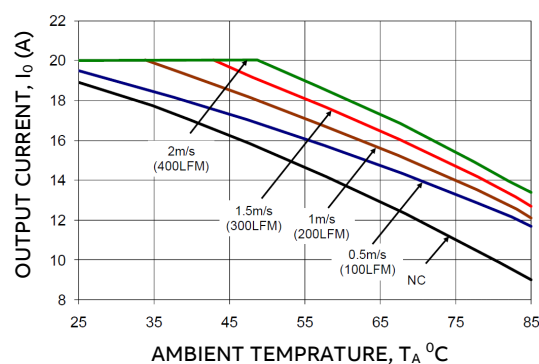


Figure 32. Derating Output Current versus Ambient Temperature and Airflow.

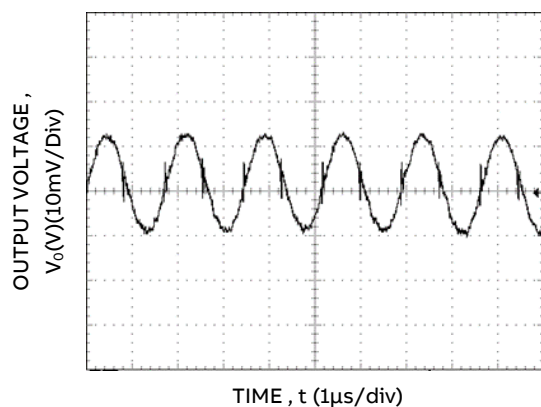


Figure 33. Typical output ripple and noise ( $V_{in} = 12V$ ,  $I_o = I_{o,max}$ ).

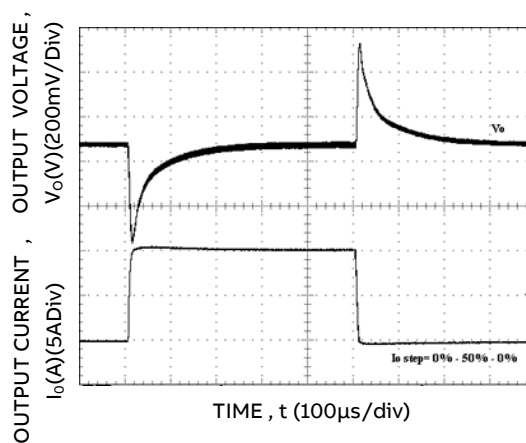


Figure 34. Transient Response to Dynamic Load Change from 0% to 50% to 0% with  $V_{in}=12V$ .

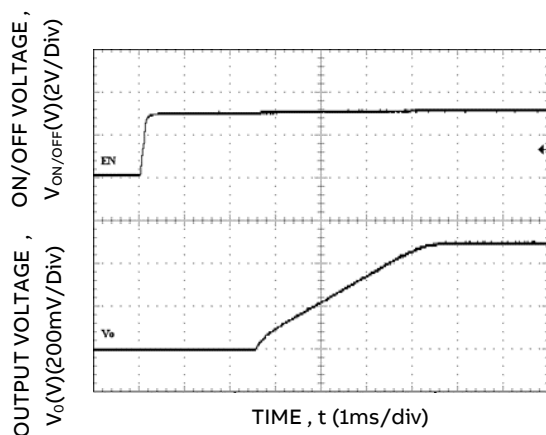


Figure 35. Typical Start-up Using On/Off Voltage ( $I_o = I_{o,max}$ ).

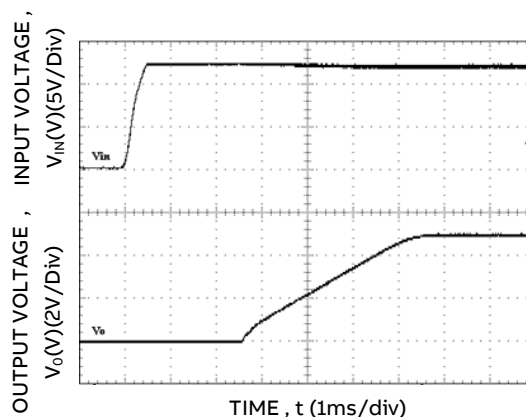


Figure 36. Typical Start-up Using Input Voltage ( $V_{in} = 12V$ ,  $I_o = I_{o,max}$ ).

## Technical Specifications (continued)

### Characteristic Curves (continued)

The following figures provide typical characteristics for the Naos Raptor 20A module at  $6V_{out}$  and at  $25^{\circ}C$ .

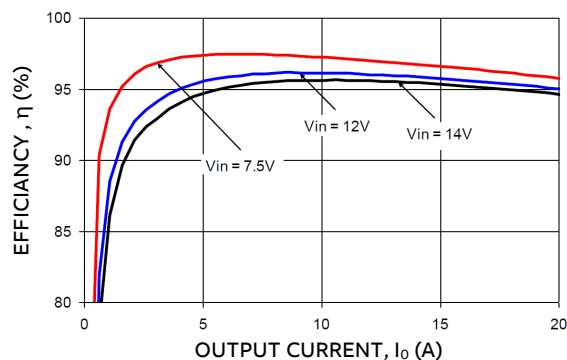


Figure 37. Converter Efficiency versus Output Current.

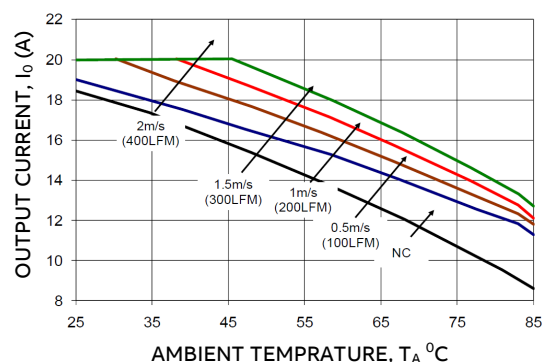


Figure 38. Derating Output Current versus Ambient Temperature and Airflow.

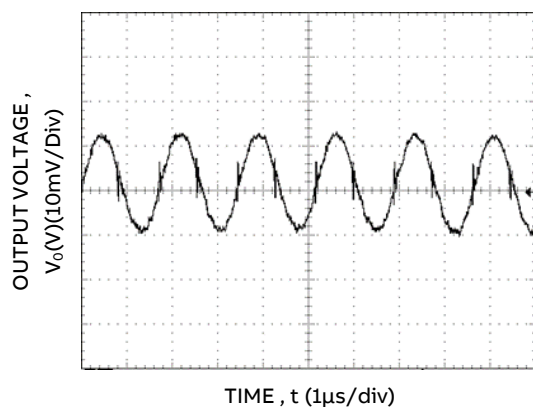


Figure 39. Typical output ripple and noise ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ).

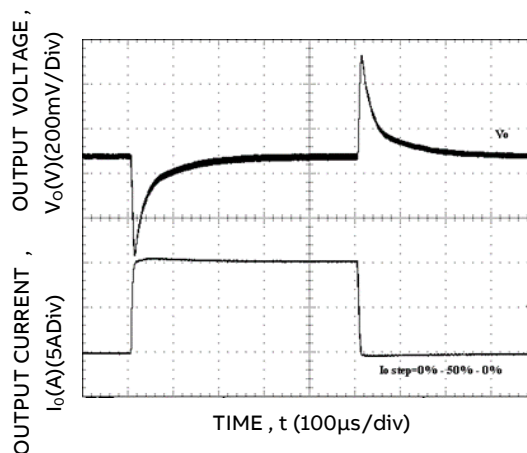


Figure 40. Transient Response to Dynamic Load Change from 0% to 50% to 0% with  $V_{IN}=12V$ .

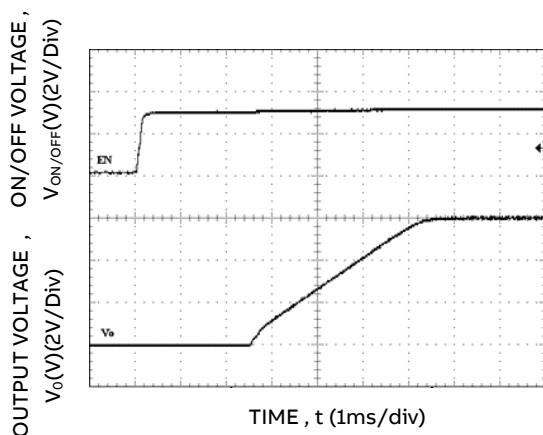


Figure 41. Typical Start-up Using On/Off Voltage ( $I_o = I_{o,max}$ ).

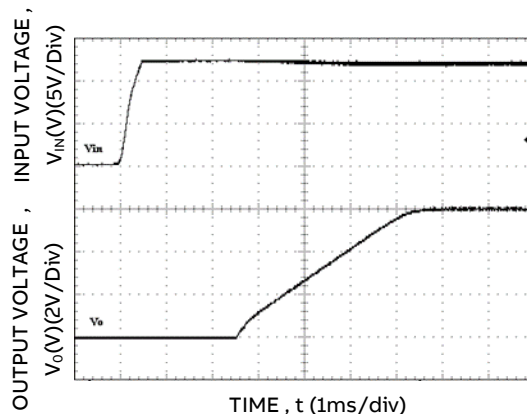


Figure 42. Typical Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_o = I_{o,max}$ ).

# Technical Specifications (continued)

## Test Configurations

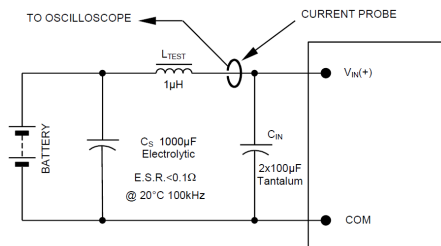


Figure 43. Input Reflected Ripple Current Test Setup.

NOTE: Measure input reflected ripple current with a simulated source inductance ( $L_{TEST}$ ) of  $1\mu H$ . Capacitor  $C_S$  offsets possible battery impedance. Measure current as shown above.

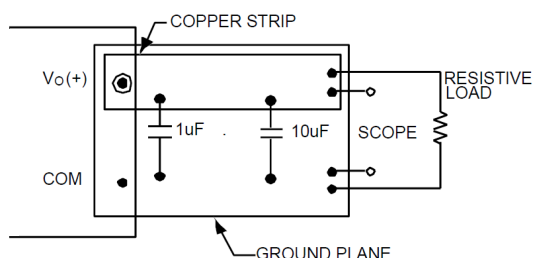


Figure 44. Output Ripple and Noise Test Setup.

NOTE: All voltage measurements to be taken at the module terminals, as shown above. If sockets are used then Kelvin connections are required at the module terminals to avoid measurement errors due to socket contact resistance.

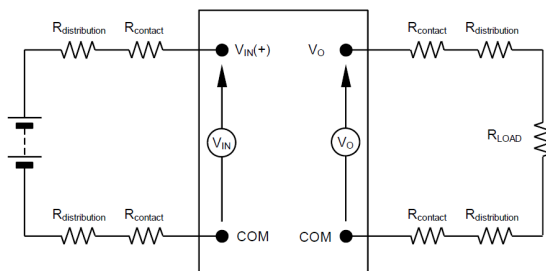


Figure 45. Output Voltage and Efficiency Test Setup.

NOTE: All voltage measurements to be taken at the module terminals, as shown above. If sockets are used then Kelvin connections are required at the module terminals to avoid measurement errors due to socket contact resistance.

$$\text{Efficiency } \eta = \frac{V_O \cdot I_O}{V_{IN} \cdot I_{IN}} \times 100\%$$

## Design Considerations

### Input Filtering

The Naos Raptor 20A module should be connected to a low- impedance source. A highly inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pin of the module, to minimize input ripple voltage and ensure module stability.

To minimize input voltage ripple, low-ESR ceramic or polymer capacitors are recommended at the input of the module. Figure 46 shows the input ripple voltage for various output voltages at 20A of load current with  $2 \times 22\mu F$  or  $4 \times 22\mu F$  ceramic capacitors and an input of 12V.

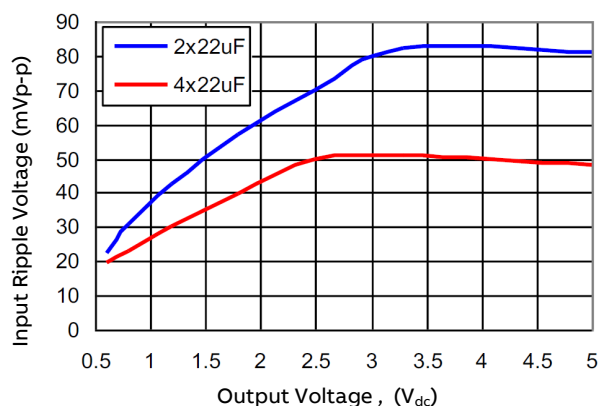


Figure 46. Input ripple voltage for various output voltages with  $2 \times 22\mu F$  or  $4 \times 22\mu F$  ceramic capacitors at the input (20A load). Input voltage is 12V.

### Output Filtering

The Naos Raptor 20A modules are designed for low output ripple voltage and will meet the maximum output ripple specification with no external capacitors. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR ceramic and polymer are recommended to improve the dynamic response of the module. For stable operation of the module, limit the capacitance to less than the maximum output capacitance as specified in the electrical specification table. Optimal performance of the module can be achieved by using the Tunable Loop™ feature described later in this data sheet.

# Technical Specifications (continued)

## Safety Considerations

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., UL ANSI/UL 62368-1 and CAN/CSA C22.2 No. 62368-1 Recognized, DIN VDE 0868-1/A11:2017 (EN62368-1:2014/A11:2017)

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV) or ES1, the input must meet SELV/ES1 requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV.

An input fuse for the module is recommended. Due to the wide input voltage and output voltage ranges of the module, different fuse ratings are recommended as shown in Table 1. These are suggested “maximum” fuse ratings. However, for optimum circuit protection, the fuse value should not be any larger than required in the end application. As an option to using a fuse, no fuse is required, if the module is

1. powered by a power source with current limit protection set point less than the protection device value listed in Table 1, and
2. the module is evaluated in the end-use equipment.

Input Voltage (V <sub>DC</sub> )	Output Voltage (V <sub>DC</sub> )			
	0.59 to 1.3	1.31 to 2.7	2.71 to 5.0	5.1 to 6
10.1 to 14	5A	10A	15A	20A
6.51 to 10	6.3A	15A	25A	30A
4.5 to 6.5	10A	20A	30A	NA

Table 1

## Feature Descriptions

### Remote On/Off

The Naos Raptor 20A power modules feature a remote On/Off pin with positive logic. If not using the On/Off pin, leave the pin open (the module will be ON, except for the -49 option modules where leaving the pin open will cause the module to remain OFF). The On/Off signal (V<sub>On/Off</sub>) is referenced to ground.

During a Logic High on the On/Off pin, the module remains ON. During Logic-Low, the module is turned OFF.

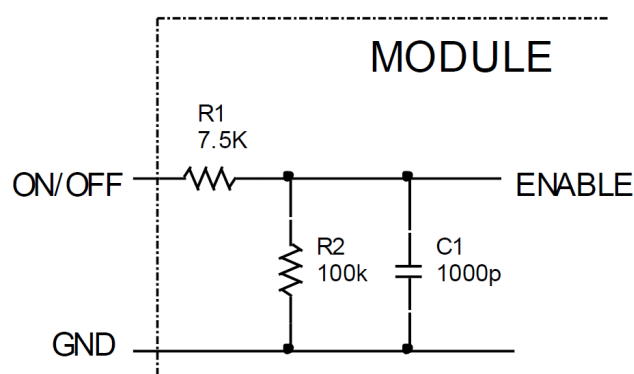


Figure 47. Remote On/Off Implementation. Resistor R1 is absent in the -49Z option modules.

### Overcurrent Protection

To provide protection in a fault (output overload) condition, the unit is equipped with internal current-limiting circuitry and can endure current limiting continuously. At the point of current-limit inception, the unit enters hiccup mode. The unit operates normally once the output current is brought back into its specified range. The typical average output current during hiccup is 10% of I<sub>o,max</sub>.

### Over Temperature Protection

To provide protection in a fault condition, the unit is equipped with a thermal shutdown circuit. The unit will shut down if the overtemperature threshold of 130°C is exceeded at the thermal reference point T<sub>ref</sub>. The thermal shutdown is not intended as a guarantee that the unit will survive temperatures beyond its rating. Once the unit goes into thermal shutdown, it will then wait to cool before attempting to restart.

# Technical Specifications (continued)

## Feature Descriptions (continued)

### Input Undervoltage Lockout

At input voltages below the input undervoltage lockout limit, module operation is disabled. The module will begin to operate at an input voltage above the undervoltage lockout turn-on threshold.

### Power Good

The Naos Raptor 20A modules provide a Power Good Status signal that indicates whether or not the power module is functioning properly.

PwGood is a power good signal implemented with an open- collector output to indicate that the output voltage is within the regulation limits of the power module. The PwGood signal will be de-asserted to a low state if any condition such as overtemperature, over-current, or over-voltage occurs which would result in the output voltage going out of range.

### Output Voltage Programming

The output voltage of the Naos Raptor 20A module can be programmed to any voltage from  $0.59V_{dc}$  to  $6V_{dc}$  by connecting a resistor between the Trim+ and Trim- pins of the module. Certain restrictions apply on the output voltage set point depending on the input voltage. These are shown in the Output Voltage vs. Input Voltage Set Point Area plot in Fig. 48. The Upper Limit curve shows that for output voltages of 0.9V and lower, the input voltage must be lower than the maximum of 14V. The Lower Limit curve shows that for output voltages of 3.8V and higher, the input voltage needs to be larger than the minimum of 4.5V.

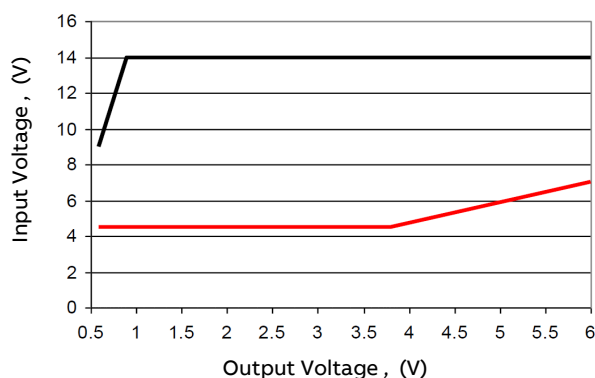


Figure 48. Output Voltage vs. Input Voltage Set Point Area plot showing limits where the output voltage can be set for different input voltages.

Without an external resistor between Trim+ and Trim- pins, the output of the module will be  $0.59V_{dc}$ . To calculate the value of the trim resistor,  $R_{trim}$  for a desired output voltage, use the following equation:

$$R_{trim} = \left[ \frac{1.182}{(V_o - 0.591)} \right] k\Omega$$

$R_{trim}$  is the external resistor in  $k\Omega$

$V_o$  is the desired output voltage

Table 2 provides  $R_{trim}$  values required for some common output voltages.

$V_{o, set} (V)$	$R_{trim} (\Omega)$
0.59	Open
1.0	2.89
1.2	1.941
1.5	1.3
1.8	0.978
2.5	0.619
3.3	0.436
5.0	0.268
6.0	0.219

Table 2

By using a  $\pm 0.5\%$  tolerance trim resistor with a TC of  $\pm 25ppm$ , a set point tolerance of  $\pm 1.5\%$  can be achieved as specified in the electrical specification. The POL Programming Tool available at [abbpowerconversion.com](http://abbpowerconversion.com) under the Design Tools section, helps determine the required trim resistor needed for a specific output voltage.

Note :  $V_{in} \geq 130\%$  of  $V_{out}$  at the module output pin

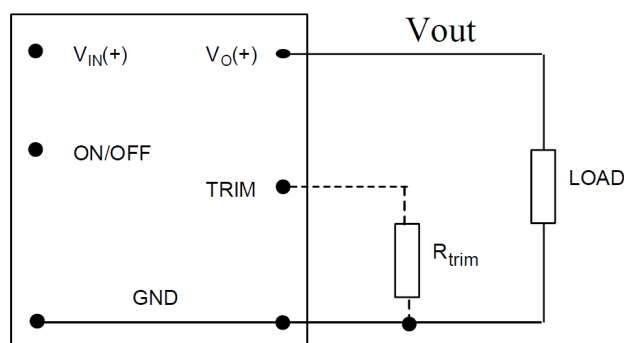


Figure 49. Circuit configuration for programming output voltage using an external resistor.



# Technical Specifications (continued)

## Feature Descriptions (continued)

### Voltage Margining

Output voltage margining can be implemented in the Naos Raptor 20A modules by connecting a resistor,  $R_{\text{margin-up}}$ , from the Trim+ pin to the Trim- pin for margining-up the output voltage and by connecting a resistor,  $R_{\text{margin-down}}$ , from the Trim+ pin to the output pin for margining-down. Figure 50 shows the circuit configuration for output voltage margining. The POL Programming Tool, available at [abbpowerconversion.com](http://abbpowerconversion.com) under the Design Tools section, also calculates the values of  $R_{\text{margin-up}}$  and  $R_{\text{margin-down}}$  for a specific output voltage and % margin. Please consult your local ABB CRITICAL POWER technical representative for additional details.

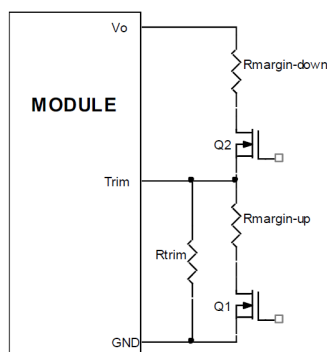


Figure 50. Circuit Configuration for margining Output voltage.

### Monotonic Start-up and Shutdown

The Naos Raptor 20A modules have monotonic start-up and shutdown behavior for any combination of rated input voltage, output current and operating temperature range.

### Tunable Loop™

The Naos Raptor 20A modules have a new feature that optimizes transient response of the module called Tunable Loop™. External capacitors are usually added to improve output voltage transient response due to load current changes. Sensitive loads may also require additional output capacitance to reduce output ripple and noise. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable.

To use the additional external capacitors in an optimal manner, the Tunable Loop™ feature allows the loop to be tuned externally by connecting a

series R-C between the SENSE and TRIM pins of the module, as shown in Fig. 51. This R-C allows the user to externally adjust the voltage loop feedback compensation of the module to match the filter network connected to the output of the module.

Recommended values of  $R_{\text{TUNE}}$  and  $C_{\text{TUNE}}$  are given in Tables 3 and 4. Table 3 lists recommended values of  $R_{\text{TUNE}}$  and  $C_{\text{TUNE}}$  in order to meet 2% output voltage deviation limits for some common output voltages in the presence of a 5A to 10A step change (50% of full load), with an input voltage of 12V. Table 4 shows the recommended values of  $R_{\text{TUNE}}$  and  $C_{\text{TUNE}}$  for different values of ceramic output capacitors up to 1000uF, again for an input voltage of 12V. The value of  $R_{\text{TUNE}}$  should never be lower than the values shown in Tables 3 and 4.

Please contact your ABB CRITICAL POWER technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external R-C to tune the module for best transient performance and stable operation for other output capacitance values

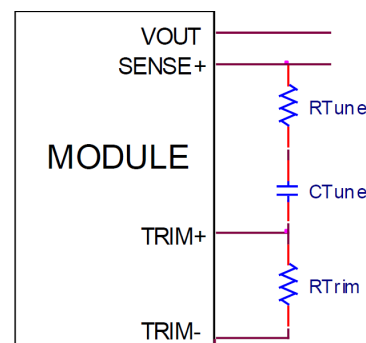


Figure 51. Circuit diagram showing connection of  $R_{\text{TUNE}}$  and  $C_{\text{TUNE}}$  to tune the control loop of the module.

$V_{\text{out}}$	5V	3.3V	2.5V	1.8V	1.2V	0.69V
$C_{\text{ext}}$	330μF Polymer	4x47μF + 330μF Polymer	2x47μF + 2x330μF Polymer	6x47μF + 3x330μF Polymer	7x330μF Polymer	23x330μF Polymer
$R_{\text{TUNE}}$	75	51	51	51	51	31
$C_{\text{TUNE}}$	100nF	150nF	220nF	330nF	330nF	330nF
$\Delta V$	94mV	66mV	50mV	36mV	24mV	12mV

Table 3. Recommended values of  $R_{\text{TUNE}}$  and  $C_{\text{TUNE}}$  to obtain transient deviation of 2% of  $V_{\text{out}}$  for a 10A step load with  $V_{\text{in}}=12V$ .

$C_{\text{ext}}$	2x47 μF	4x47 μF	6x47 μF	10x47 μF	20x47 μF	30x47 μF
$R_{\text{TUNE}}$	75	75	75	51	51	51
$C_{\text{TUNE}}$	15nF	27nF	33nF	47nF	68nF	82nF

Table 4. General recommended values of  $R_{\text{TUNE}}$  and  $C_{\text{TUNE}}$  for  $V_{\text{in}}=12V$  and various external ceramic capacitor combinations.

## Technical Specifications (continued)

### Thermal Considerations

Power modules operate in a variety of thermal environments; however, sufficient cooling should be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test set-up is shown in Figure 52. The preferred airflow direction for the module is in Figure 53.

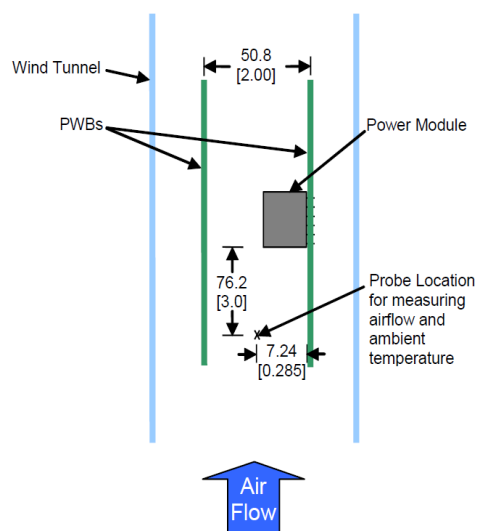


Figure 52. Thermal Test Set-up.

The thermal reference point,  $T_{ref}$  used in the specifications of thermal derating curves is shown in Figure 53. For reliable operation this temperature should not exceed 122°C.

The output power of the module should not exceed the rated power of the module ( $V_{o,set} \times I_{o,max}$ ).

Please refer to the Application Note “Thermal Characterization Process For Open-Frame Board-Mounted Power Modules” for a detailed discussion of thermal aspects including maximum device temperatures

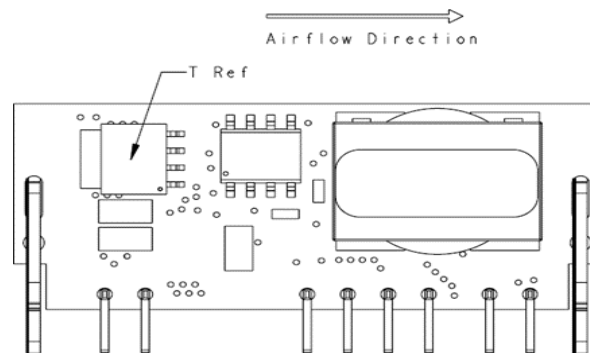


Figure 53. Temperature measurement location.

### Heat Transfer via Convection

Increased airflow over the module enhances the heat transfer via convection. Thermal derating curves showing the maximum output current that can be delivered at different local ambient temperatures ( $T_A$ ) for airflow conditions ranging from natural convection and up to 2m/s (400 ft./min) are shown in the Characteristics Curves section.

### Post solder Cleaning and Drying Considerations

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to the Board Mounted Power Modules: Soldering and Cleaning Application Note.

### Through-Hole Lead-Free Soldering Information

The RoHS-compliant through-hole products use the SAC (Sn/Ag/Cu) Pb-free solder and RoHS-compliant components. They are designed to be processed through single or dual wave soldering machines. The pins have an RoHS-compliant finish that is compatible with both Pb and Pb-free wave soldering processes. A maximum preheat rate of 3°C/s is suggested. The wave preheat process should be such that the temperature of the power module board is kept below 210°C. For Pb solder, the recommended pot temperature is 260°C, while the Pb-free solder pot is 270°C max. Not all RoHS-compliant through-hole products can be processed with paste-through-hole Pb or Pb-free reflow process. If additional information is needed, please consult with your ABB Power representative for more details.



# Technical Specifications (continued)

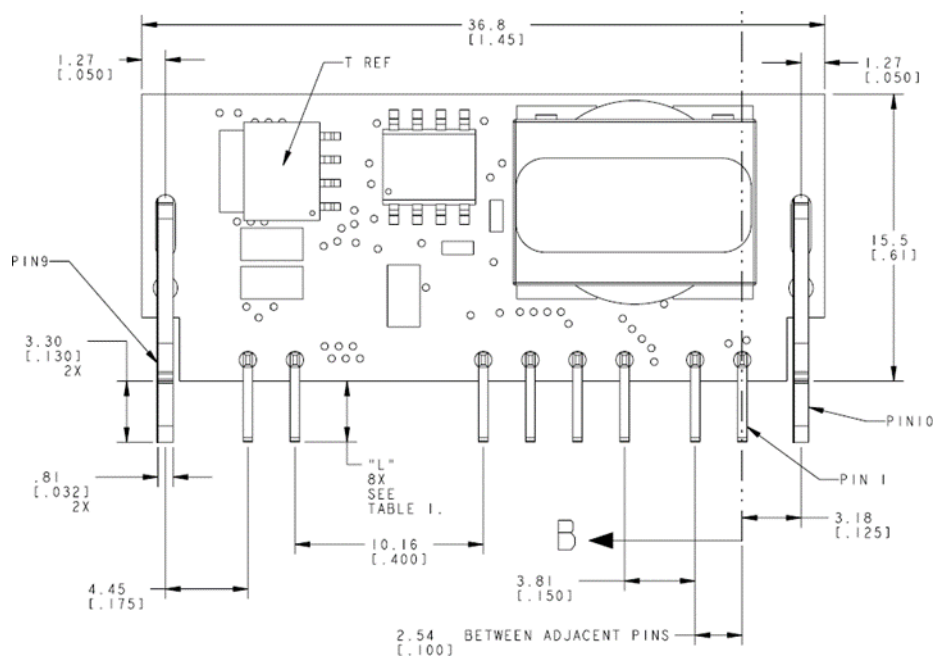
## Mechanical Outline

Dimensions are in millimeters and (inches).

Tolerances: x.x mm  $\pm$  0.5 mm (x.xx in.  $\pm$  0.02 in.) [unless otherwise indicated]

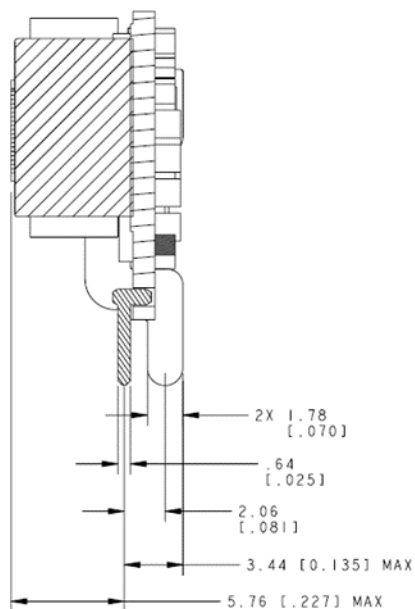
x.xx mm  $\pm$  0.25 mm (x.xxx in  $\pm$  0.010 in.)

Front view



$L = 3.30 \pm 0.5 [0.13 \pm 0.02]$

Side view



Pin Out

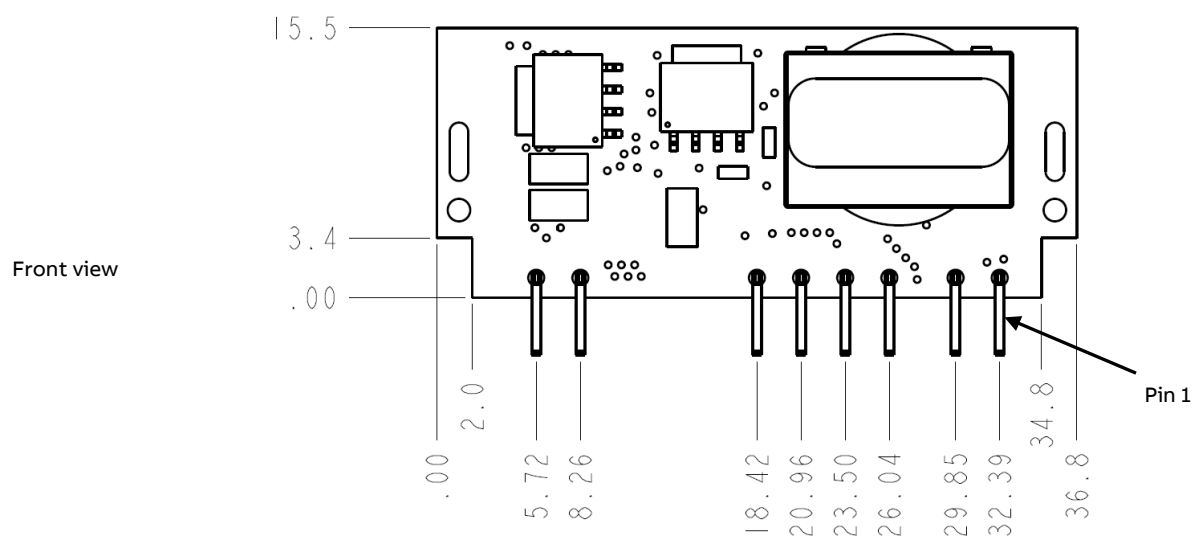
Pin	Function	Pin	Function
1	V <sub>out</sub>	6	V <sub>in</sub>
2	Trim +	7	Sense +
3	GND	8	Sense -
4	PwGood	9	TRIM -
5	On/Off	10	GND

## Technical Specifications (continued)

### Mechanical Outline - No Outrigger pins (- Y version)

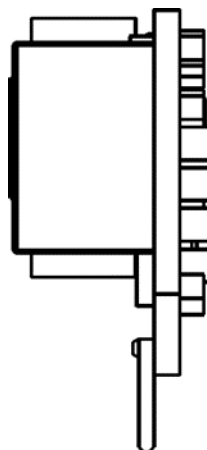
Dimensions are in millimeters and (inches).

Tolerances:     x.x mm  $\pm$  0.5 mm (x.xx in.  $\pm$  0.02 in.) [unless otherwise indicated]  
                      x.xx mm  $\pm$  0.25 mm (x.xxx in  $\pm$  0.010 in.)



$L = 3.30 \pm 0.5$  [0.13  $\pm$  0.02]

Side view



Pin Out

Pin	Function	Pin	Function
1	V <sub>out</sub>	6	V <sub>in</sub>
2	Trim +	7	Sense +
3	GND	8	Sense -
4	PwGood		
5	On/Off		

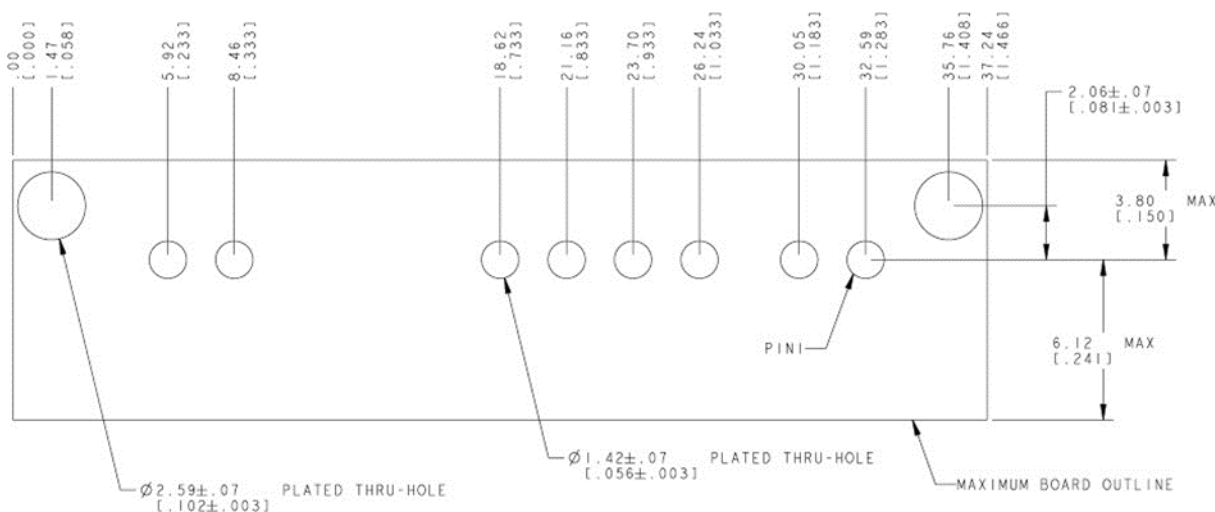
# Technical Specifications (continued)

## Recommended Pad Layout

Dimensions are in millimeters and (inches).

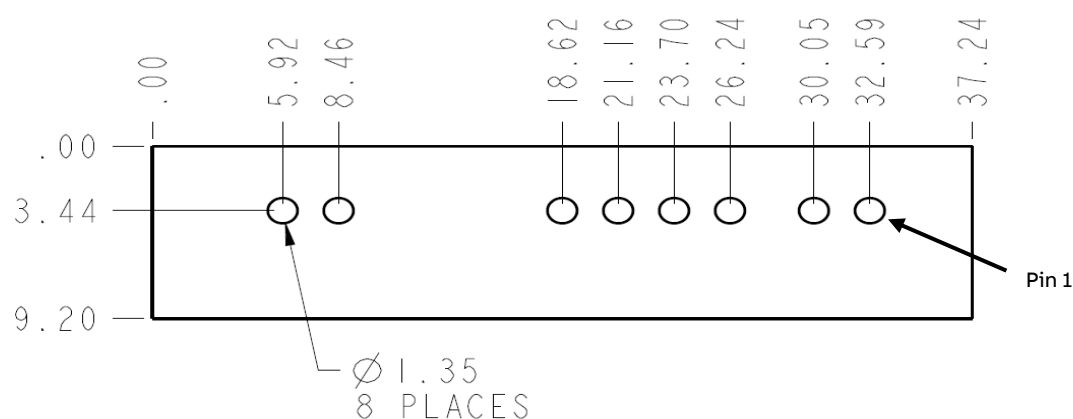
Tolerances: x.x mm  $\pm$  0.2 mm (x.xx in.  $\pm$  0.02 in.) [unless otherwise indicated]

x.xx mm  $\pm$  0.12 mm (x.xxx in  $\pm$  0.005 in.)



Pin	Function	Pin	Function
1	V <sub>out</sub>	6	V <sub>in</sub>
2	Trim +	7	Sense +
3	GND	8	Sense -
4	PwGood	9	TRIM -
5	On/Off	10	GND

## No Outtrigger pins (- Y version)



Pin	Function	Pin	Function
1	V <sub>out</sub>	6	V <sub>in</sub>
2	Trim +	7	Sense +
3	GND	8	Sense -
4	PwGood		
5	On/Off		

## Technical Specifications (continued)

### Ordering Information

Please contact your ABB Sales Representative for pricing, availability and optional features.

Device Code	Input Voltage Range	Output Voltage	Output Current	On/Off Logic	Connector Type	Ordering code
NSR020A0X43Z	4.5 – 13.8V <sub>dc</sub>	0.59 – 6V <sub>dc</sub>	20 A	Positive	SIP	CC109130911
NSR020A0X43-YZ	4.5 – 13.8V <sub>dc</sub>	0.59 – 6V <sub>dc</sub>	20 A	Positive	SIP	CC109156106

Table 5. Device Codes

Series generation	Output Current	Output voltage	Pin Length	On / Off logic	Sense	Default On/Off Condition	Options	ROHS Compliance
NSR	020A0	X		4				Z
	020A0 = 20A	X = programmable output	Blank = Standard 5=5.1mm 6=3.7mm 8=2.8mm	4 = positive No entry =negative	3 = Remote Sense Blank = without	Blank = Standard, ON when unconnected 2=Inverted On/Off	-Y = without outrigger pins	Z = ROHS6

Table 6. Device Options

### Contact Us

For more information, call us at

1-877-546-3243 (US)

1-972-244-9288 (Int'l)

## Change History (excludes grammar & clarifications)

Version	Date	Description of the change
3.3	12/23/2021	Updated as per template

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