

#### **DATASHEET**

# JRCW450U Orca\* Series; DC-DC Converter Power Modules

## 36-75 V<sub>dc</sub> Input; 48V<sub>dc</sub> Output; 450W Output

#### **RoHS Compliant**



## **Applications**

- RF Power Amplifier
- Wireless Networks
- Switching Networks

#### **Features**

- Compliant to RoHS Directive 2011/65/EU and amended Directive (EU) 2015/863 (-Z versions)
- Compliant to REACH Directive (EC) No 1907/2006
- High power density: 166 W/in<sup>3</sup>
- Very high efficiency: >94% Typ at Full Load
- Industry standard half-brick pin-out
- Low output ripple and noise
- Industry standard half-brick footprint 57.7mm x 60.7mm x 12.8mm (2.27" x 2.39" x 0.504")
- Remote Sense
- 2:1 input voltage range
- Single tightly regulated output

## Description

The JRCW450U Orca series of dc-dc converters are a new generation of isolated, very high efficiency DC/DC power modules providing up to 450W output power in an industry standard half-brick size footprint, which makes it an ideal choice for high voltage and high power applications. Threaded-through holes are provided to allow easy mounting or addition of a heat sink for high-temperature applications. The output is fully isolated from the input, allowing versatile polarity configurations and grounding connections.

### **Options**

- Output OCP/OVP auto restart
- Shorter pins
- Unthreaded heat sink holes
- Constant switching frequency
- Constant Current Overcurrent limit
- Latch after short circuit fault shutdown
- Over temperature protection auto restart
- Output voltage adjustment trim, 28.8V<sub>dc</sub> to 57.6V<sub>dc</sub>
- Wide operating case temperature range (-40°C to 100°C)
- CE mark meets 2006/95/EC directives§
- ANSI/UL\* 62368-1 and CAN/CSA† C22.2 No. 62368-1 Recognized, DIN VDE‡ 0868-1/A11:2017 (EN62368-1:2014/A11:2017)
- ISO\*\* 9001 and ISO 14001 certified manufacturing facilities

See footnotes on page no. :- 2



# **Technical Specifications**

## **Absolute Maximum Ratings**

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Device	Symbol	Min	Max	Unit
Input Voltage					
Continuous	All	V <sub>IN</sub>	-0.3	80	$V_{dc}$
Transient, operational (≤100 ms)	All	$V_{\text{IN,trans}}$	-0.3	100	$V_{dc}$
Operating Case Temperature	All	т	-40	100	°C
(See Thermal Considerations section, Figure 16)	All	T <sub>c</sub>	-40	100	C
Storage Temperature	All	$T_{stg}$	-55	125	°C
I/O Isolation Voltage: Input to Case, Input to Output	All	-	-	1500	$V_{dc}$
Output to Case	All	-	-	500	$V_{dc}$

## **Electrical Specifications**

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

Parameter	Device	Symbol	Min	Тур	Max	Unit
Operating Input Voltage (see Figure 12 for V <sub>IN MIN</sub> when using trim-up feature)	All	V <sub>IN</sub>	36	48	75	$V_{dc}$
Maximum Input Current						
(V <sub>IN</sub> =36V to 75V, I <sub>O</sub> =I <sub>O, max</sub> )	All	I <sub>IN,max</sub>			14.0	$A_{dc}$
Inrush Transient	All	l²t			2	A <sup>2</sup> s
Input Reflected Ripple Current, peak-to-peak						
(5Hz to 20MHz, 12µH source impedance; V <sub>IN</sub> =0V to 75V, I <sub>o</sub> = I <sub>omax</sub> ;see Figure 7)	All				20	mA <sub>p-p</sub>
Input Ripple Rejection (120Hz)	All			40		dB

#### CAUTION: This power module is not internally fused. An input line fuse must always be used.

This power module can be used in a wide variety of applications, ranging from simple standalone operation to being an integrated part of complex power architecture. To preserve maximum flexibility, internal fusing is not included. Always use an input line fuse, to achieve maximum safety and system protection. The safety agencies require a time-delay or fast-acting fuse with a maximum rating of 25 A in the ungrounded input connection (see Safety Considerations section). Based on the information provided in this data sheet on inrush energy and maximum do input current, the same type of fuse with a lower rating can be used. Refer to the fuse manufacturer's data sheet for further information.

#### Footnotes

<sup>\*</sup>Trademark of the OmniOn Electric Company

<sup>#</sup>UL is a registered trademark of Underwriters Laboratories, Inc.

<sup>&</sup>lt;sup>†</sup> CSA is a registered trademark of Canadian Standards Association.

<sup>&</sup>lt;sup>‡</sup> VDE is a trademark of Verband Deutscher Elektrotechniker e.V.

<sup>&</sup>quot;ISO is a registered trademark of the International Organization of Standards



# **Electrical Specifications** (continued)

Parameter	Device	Symbol	Min	Тур	Max	Unit
Output Voltage Set-point	All	\ /	/7.0	/0	/0.0	\/
(V <sub>IN</sub> =V <sub>IN,nom</sub> , I <sub>O</sub> =I <sub>O,max</sub> , T <sub>C</sub> =25°C)		$V_{O,  set}$	47.0	48	49.0	$V_{dc}$
Output Voltage Set-Point Total Tolerance						
(Over all operating input voltage, resistive load, and	All	Vo	47.0	-	49.0	$V_{dc}$
temperature conditions until end of life)						
Output Regulation	. 11					
Line $(V_{IN}=V_{IN, min} \text{ to } V_{IN, max})$	All		-	0.1	0.2	$%V_{o,set}$
Load (I <sub>O</sub> =I <sub>O, min</sub> to I <sub>O, max</sub> )	AII AII		-	0.1	0.2	$%V_{o,set}$
Temperature (T <sub>c</sub> = -40°C to +100°C) Output Ripple and Noise on nominal output	All		-	0.25	0.5	%V <sub>o,set</sub>
$(V_{IN}=V_{IN, nom} \text{ and } I_{O}=I_{O, min} \text{ to } I_{O, max})$						
RMS (5Hz to 20MHz bandwidth)	All		-	100	125	mV <sub>rms</sub>
Peak-to-Peak (5Hz to 20MHz bandwidth)	All		-	300	400	$mV_{pk-pk}$
External Capacitance (ESR > 10 $m\Omega$ ) <sup>1</sup>	All	Co	440		6500	μF
Output Power (V <sub>o</sub> =48V to 57.6V)	All	P <sub>O,max</sub>	-	-	450	W
Output Current	All	Io	0		9.4	A <sub>dc</sub>
Output Current Limit Inception (Constant current until	All	I <sub>O, lim</sub>	11.0		12.2	A <sub>dc</sub>
V <sub>o</sub> <v<sub>trimMIN ,duration &lt;4s)</v<sub>		IO, lim	11.0	_		Adc
Output Short Circuit Current (Vo≤ 0.25Vdc)	All	I <sub>O, sc</sub>			15	$A_{rms}$
Efficiency	All	η	93.5	94.0		%
$V_{IN} = V_{IN, nom}$ , $T_c = 25$ °C $I_O = I_{O, max}$ , $V_O = V_{O, set}$	ΑII	'1	95.5	54.0	1	70
Switching Frequency		$f_{sw}$	-	180	-	kHz
Dynamic Load Response						
$(\Delta I_o/\Delta t=1A/10ms; V_{in}=V_{in,nom}; Tc=25^{\circ}C; Tested with a 470 \mu F$						
aluminum and a 10 µF ceramic capacitor across the load.)						
Load Change from I <sub>o</sub> = 50% to 75% of I <sub>o,max</sub> :						
Peak Deviation		$V_{pk}$	-	2	3	%V <sub>O, set</sub>
Settling Time (Vo<10% peak deviation)		t <sub>s</sub>	-	1.5	-	ms
Load Change from I <sub>o</sub> = 25% to 50% of I <sub>o,max</sub> :				2	7	0/1/
Peak Deviation	All	$V_{pk}$	-	2	3	$%V_{O, set}$
Settling Time (Vo<10% peak deviation)		ts	-	1.5	-	ms

 $<sup>^1</sup>$ Note: use a minimum 2 x 220uF output capacitor. Recommended capacitor is Nichicon CD series, 220uF/35V. If the ambient temperature is less than -  $20^{\circ}$ C, use more than 3 of recommended minimum capacitors. When starting into maximum external capacitor, do not simultaneously apply a Constant Current electronic load set to greater than 0.5 x  $I_{OMAX}$ , or delay application of full CC load until Vo >1.0V.

# **Isolation Specifications**

Parameter	Symbol	Min	Тур	Max	Unit
Isolation Capacitance	C <sub>iso</sub>	-	15	-	nF
Isolation Resistance	R <sub>iso</sub>	10	-	-	МΩ

# **General Specifications**

Parameter	Device	Symbol	Min	Тур	Max	Unit
Calculated Reliability based upon Telcordia SR-332 Issue 3: Method I		FIT		136.3		10 <sup>9</sup> /Hours
Case 3 ( $I_0$ =80% $I_{0,max}$ , $T_A$ =40°C, airflow = 200 lfm, 90% confidence)	All	MTBF		7,338,052		Hours
Weight	All		68	76.4	84	g
Weight	All		2.40	2.69	2.96	OZ.

JRCW450U\_DS



# **Feature Specifications**

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbol	Min	Тур	Max	Unit
Remote On/Off Signal Interface	Device	Эуппэон		1319	Max	OTHE
$(V_{IN}=V_{IN, min}$ to $V_{IN, max}$ ; open collector or equivalent,						
Signal referenced to V <sub>IN</sub> - terminal)						
Negative Logic: device code suffix "1"						
Logic Low = module On, Logic High = module Off						
Positive Logic: No device code suffix required						
Logic Low = module Off, Logic High = module On						
Logic Low - Remote On/Off Current	All	I <sub>on/off</sub>	_	-	1.0	mA
Logic Low - On/Off Voltage	All	V <sub>on/off</sub>	0	-	0.8	$V_{dc}$
Logic High Voltage – (Typ = Open Collector)	All	V <sub>on/off</sub>	4		5	$V_{dc}$
Logic High maximum allowable leakage current	All	I <sub>on/off</sub>	-	-	50	μA
Turn-On Delay and Rise Times						
(V <sub>in</sub> =V <sub>in,nom</sub> , I <sub>O</sub> =I <sub>O, max</sub> , 25°C)						
Case 1: $T_{delay}$ = Time until $V_O$ = 10% of $V_{O,set}$ from application of	All	т	100	120	150	mc
V <sub>in</sub> with Remote On/Off set to ON	All	T <sub>delay</sub>	100	120	150	ms
Case 2: $T_{delay}$ = Time until $V_O$ = 10% of $V_{O,set}$ from application of						
Remote On/Off from Off to On with $V_{\text{in}}$ already applied for at	All	T <sub>delav</sub>	15	20	25	ms
least one second.	All	I delay	13	20	23	1115
$T_{rise}$ = time for $V_O$ to rise from 10% of $V_{O,set}$ to 90% of $V_{O,set}$ .	All	$T_{rise}$	40	60	80	
Synchronous Rectifier Activation Level and Delay*						
Minimum I <sub>OUT</sub> to activate synch rectifier mode		I <sub>OUT,SYNC</sub>	2.4			Α
Minimum time to activate synch rectifier mode (I <sub>OUT</sub> > I <sub>OUT,SYNC</sub> )		T <sub>SYNC</sub>	1			ms
Output Voltage Overshoot					3	% V <sub>O, set</sub>
(I <sub>O</sub> =80% of I <sub>O, max</sub> , T <sub>A</sub> =25°C)					3	70 <b>V</b> O, set
Output Voltage Adjustment						
(See Feature Descriptions):						
Output Voltage Remote-sense Range	A 11				2	0/1/
(only for No Trim or Trim down application )	All	$V_{\text{sense}}$			2	$%V_{o,nom}$
Output Voltage Set-point Adjustment Range (trim)	All	$V_{trim}$	28.8	-	57.6	$V_{dc}$
Output Overvoltage Protection (T <sub>A</sub> =25C)	All	$V_{O, limit}$	60	-	65	$V_{dc}$
Over Temperature Protection	A.I.I	_	100	33.5	120	°C
(See Feature Descriptions, Figure 16)	All	$T_{ref}$	108	115	120	ى ر
Input Under Voltage Lockout						
Turn-on Threshold	All	V	33	35	36	$V_{dc}$
Turn-off Threshold	All	V <sub>IN, UVLO</sub>	30	32	33	$V_{dc}$
Hysteresis	All		2.5	3	3.5	$V_{dc}$
Input Over voltage Lockout	A !!			00	66	
Turn-on Threshold	All	V <sub>IN, OVLO</sub>	77	80 97.5	82 86	$V_{dc}$
Turn-off Threshold Hysteresis	All All		80 2.5	83.5 3	5	V <sub>dc</sub> V <sub>dc</sub>
Hysteresis	7		ر.	ر	ر	v dc

<sup>\*</sup>Note: Module has internal circuit that inhibits output synchronous rectifier mode, during module startup, until IouT> IouT,SYNC for time > TSYNC. Once output synchronous mode is activated, module remains in synchronous rectifier mode, even if load is reduced to OA,until module output is turned off using on/off pin or loss of input voltage.

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### **Characteristic Curves**

The following figures provide typical characteristics for the JRCW450U (48V, 9.4A) at 25°C. The figures are identical for either positive rnegative Remote On/Off logic.

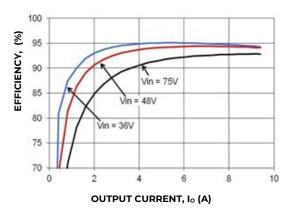


Figure 1. Converter Efficiency versus Output Current.

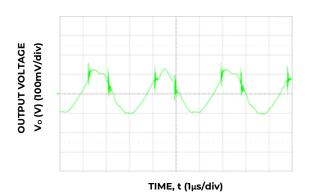


Figure 2. Typical output ripple and Noise at Room Temperatureand 48Vin; Io = Io,max; Co,ext = 440µF.

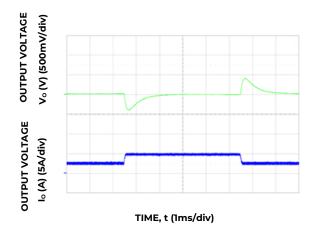


Figure 3. Dynamic Load Change Transient Response from 25% to 50% to 25% of Full Load at Room Temperature and 48 Vin; 0.1A/uS, Co,ext = 440µF.

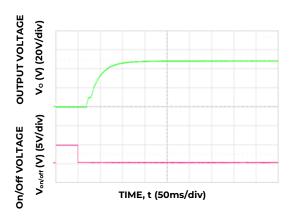


Figure 4. Typical Start-Up Using negative Remote On/Off;  $C_{o, ext} = 440 \mu F. \label{eq:continuous}$ 

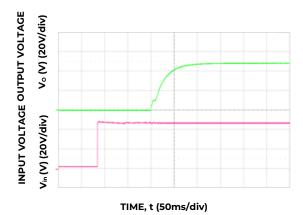


Figure 5. Typical Start-Up from VIN, on/off enabled prior to  $$V_{IN}$$  Step;  $C_{o,ext}$  = 470  $\mu F.$ 

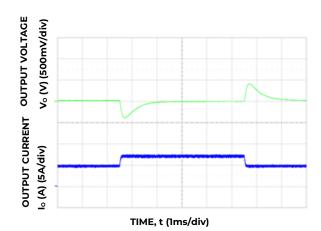


Figure 6. Typical Dynamic Load Change Transient Response from 50 %to 75% to 50% of Full Load at Room Temperature and 48 V<sub>in:</sub>0.1A/uS, C<sub>o.ext</sub> = 440µF.

### **Test Considerations**

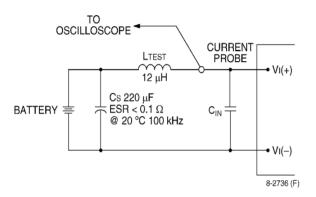


Figure 7. Input Reflected Ripple Current Test Setup.

Note: Measure the input reflected-ripple current with a simulated source inductance (LTEST) of 12  $\mu$ H. Capacitor C<sub>s</sub> offsets possible battery impedance. Measure the current, as shown above.

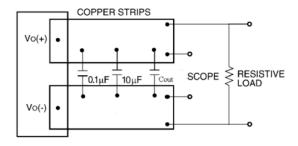


Figure 8. Output Ripple and Noise Test Setup

Note: Use a  $C_{out}$  (470  $\mu F$  Low ESR aluminum or tantalum capacitor typical), a 0.1  $\mu F$  ceramic capacitor and a 10  $\mu F$  ceramic capacitor, and Scope measurement should be made using a BNC socket. Position the load between 51 mm and 76 mm (2 in. and 3 in.) from the module.

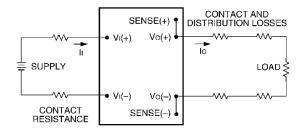


Figure 9. Output Voltage and Efficiency Test Setup.

Note: All measurements are taken at the module terminals. When socketing, place Kelvin connections at module terminals to avoid measurement errors due to socket contact resistance.



$$\eta = \left( \frac{[V_0(+) - V_0(-)]I_0}{[V_1(+) - V_1(-)]I_1} \right) \times 100 \%$$

### **Design Considerations**

#### Input Source Impedance

The power module should be connected to a low ac-impedance source. A highly inductive source impedance can affect the stability of the power module. For the test configuration in Figure 7, a 470  $\mu F$  Low ESR aluminum capacitor, CIN , mounted close to the power module helps ensure the stability of the unit.

Consult the factory for further application guidelines.

#### **Output Capacitance**

The JRCW450U power module requires a minimum output capacitance of 440 $\mu$ F Low ESR aluminum capacitor, C<sub>out</sub> to ensure stable operation over the full range of load and line conditions, see Figure 8. If the ambient temperature is under - 20°C, it is required to use at least 3 pcs of minimum capacitors inparallel. In general, the process of determining the acceptable values of output capacitance and ESR is complex and is load-dependent.

### **Safety Considerations**

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., UL ANSI/UL\* 62368-1 and CAN/CSA+ C22.2 No. 62368-1 Recognized, DIN VDE 0868-1/ A11:2017 (EN62368-1:2014/A11:2017)

For end products connected to  $-48V_{dc}$ , or  $-60V_{dc}$  nominal DC MAINS (i.e. central office dc battery plant), no further fault testing is required.

\*Note: -60V dc nominal battery plants are not available in the U.S. or Canada.

For all input voltages, other than DC MAINS, where the input voltage is less than  $60V_{dc}$ , if the input meets all of the requirements for SELV/ES1, then:

 The output may be considered SELV/ES1. Output voltages will remain within SELV/ES1 limits even with internally- generated non-SELV/ES1 voltages. Single component failure and fault tests were performed in the power converters.

One pole of the input and one pole of the output are to be grounded, or both circuits are to be kept floating, to maintain the output voltage to ground voltage within ELV or SELV/ES1 limits. However, SELV/ES1 will not be maintained if  $V_I(+)$  and  $V_O(+)$  are grounded simultaneously.





### Safety Considerations (continued)

For all input sources, other than DC MAINS, where the input voltage is between 60 and 75V<sub>dc</sub> (Classified as TNV-2 in Europe), the following must be meet, if the converter's output is to be evaluated for SELV/ES1:

- The input source is to be provided with reinforced insulation from any hazardous voltage, including the ac mains.
- One Vi pin and one Vo pin are to be reliably earthed, or both the input and output pins are to be kept floating.
- Another SELV/Es1 reliability test is conducted on the whole system, as required by the safety agencies, on the combination of supply source and the subject module to verify that under a single fault, hazardous voltages do not appear at the module's output.

All flammable materials used in the manufacturing of these modules are rated 94V-0, or tested to the UL60950 A.2 for reduced thickness.

The input to these units is to be provided with a maximum 25 A fast-acting or time-delay fuse in the ungrounded input connection.

To ensure safety compliance, the temperatures at Tref1, Tref2, or Tref3 should (Figure 16) not exceed the limits as specified in this table for  $V_{in}$  = 36 to 75V.

Trefl or Tref2	Tref3
90°C	130°C

#### **Feature Description**

### Remote On/Off

Two remote on/off options are available. Positive logic turns themodule on during a logic high voltage on the ON/OFF pin, and off during a logic low. Negative logic remote On/Off, device code suffix "1", turns the module off during a logic high and on during a logic low.

To turn the power module on and off, the user must supply a switch (open collector or equivalent) to control the voltage ( $V_{on/off}$ ) between the ON/OFF terminal and the  $V_{IN}(-)$  terminal (see Figure 10). Logic low is  $OV \leq V_{on/off} \leq 0.8V$ . The maximum  $I_{on/off}$  during a logic low is 1mA, the switch should be maintain alogic low level whilst sinking this current.

During a logic high, the typical maximum Von/off generated by the module is 5V, and the maximum allowable leakage current at  $V_{on/off} = 5V$  is  $50\mu$ A.

If not using the remote on/off feature:

For positive logic, leave the ON/OFF pin open.

For negative logic, short the ON/OFF pin to V<sub>IN</sub>(-).

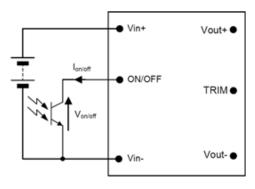


Figure 10. Circuit configuration for using Remote On/Off Implementation.

#### **Overcurrent Protection**

To provide protection in a fault output overload condition, the module is equipped with internal current limiting protection circuitry, and can endure continuous overcurrent by providing constant current output, for up to 4 seconds, as long as the output voltage is greater than  $V_{\text{trimMIN}}$ . If the load resistance is too low to support  $V_{\text{trimMIN}}$  in an overcurrent condition or a short circuit load condition exists, the module will shut down immediately.

A latching shutdown option is standard. Following shutdown, the module will remain off until the module is reset by either cycling the input power or by toggling the on/off pin for one second.

An auto-restart option (4) is also available in a case where an auto recovery is required. If overcurrent greater than 12A persists for few milli-seconds, the module will shut down and auto restart until the fault condition is corrected. If the output overload condition still exists when the module restarts, it will shut down again. This operation will continue indefinitely, until the overcurrent condition is corrected.

#### **Over Voltage Protection**

The output overvoltage protection consists of circuitry that monitors the voltage on the output terminals. If the voltage on the output terminals exceeds the over voltage protection threshold, then the module will shut down and latch off. The overvoltage latch is reset by either cycling the input power for one second or by toggling the on/off signal for one second. The protection mechanism is such that the unit can continue in this condition until the fault is cleared.

An auto-restart option (4) is also available in a case where an auto recovery is required.



#### Feature Description (continued)

#### Remote Sense

Remote sense minimizes the effects of distribution losses by regulating the voltage at the remote-sense connections (see Figure 11). For No Trim or Trim down application, the voltage between the remote-sense pins and the output terminals must not exceed the output voltage sense range given in the Feature Specifications table i.e.:

 $[V_o(+)-V_o(-)] - [SENSE(+) - SENSE(-)] \le 2\% \text{ of } V_{o,nom}$ 

The voltage between the Vo(+) and Vo(-) terminals must not exceed the minimum output overvoltage shut-down value indicated in the Feature Specifications table. This limit includes any increase in voltage due to remote-sense compensation and output voltage set-point adjustment (trim). See Figure 11. If notusing the remote-sense feature to regulate the output at the point of load, then connect SENSE(+) to  $V_{\circ}(+)$  and SENSE(-) to  $V_{\circ}(-)$  at the module. Although the output voltage can be increased by both the remote sense and by the trim, the maximum increase for the output voltage is not the sum of both. The maximum increase is the larger of either the remote sense or the trim. The amount of power delivered by the module is defined as the voltage at the output terminals multiplied by the output current. When using remote sense and trim: the output voltage of the module can be increased, which at the same output current would increase the power output of the module. Care should be taken to ensure that the maximum output power of the module remains at or below the maximum rated power.

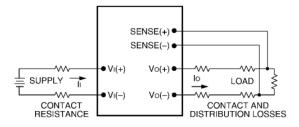


Figure 11. Effective Circuit Configuration for Single-Module Remote-Sense Operation Output Voltage.

#### **Output Voltage Programming**

Trimming allows the user to increase or decrease the output voltage set point of a module. Trimming down is accomplished by connecting an external resistor between the TRIM pin and the SENSE(-) pin. Trimming up is accomplished by connecting external resistor between the SENSE(+) pin and TRIM pin.

The trim resistor should be positioned close to the module. Certain restrictions apply to the input voltage lower limit when trimming the output voltage to the maximum. See Figure 12 for the allowed input to output range when using trim. If not using the trim down feature, leave the TRIM pin open.

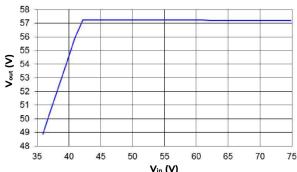


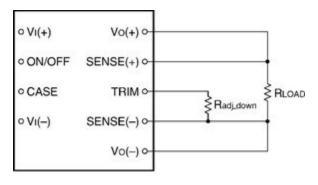
Figure 12. Output Voltage Trim Limits vs. Input Voltage.

### Trim Down - Decrease Output Voltage

With an external resistor ( $R_{adj\_down}$ ) between the  $T_{RIM}$  and SENSE(-) pins, the output voltage set point ( $V_{o,adj}$ ) decreases (see Figure 13). The following equation determines the required external-resistor value to obtain a percentage output voltage change of  $\Delta$ %.

For output voltages: V<sub>O,nom</sub> = 48V

Without -T O	ption	With -T Option			
$R_{adj-down} = \begin{bmatrix} 100 \\ \hline \Delta\% \end{bmatrix}$	-2 KΩ	$R_{adj\text{-}down} = \begin{bmatrix} 1000 \\ \Delta\% \end{bmatrix} - 11 K\Omega$			
Where,		•			
Δ% =	V <sub>o,nom</sub> - V	/desired x100			
V <sub>desired</sub> = Desired output voltage set point (V).					





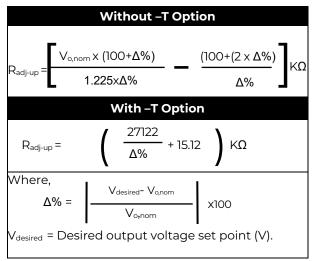
### Feature Description (continued)

### Trim Up – Increase Output Voltage

With an external resistor (Radj\_up) connected between the SENSE(+) and TRIM pins, the output voltage set point  $(V_{o,adj})$  increases (see Figure 14).

The following equation determines the required external-resistor value to obtain a percentage output voltage change of  $\Delta\%$ .

For output voltages: V<sub>O,nom</sub> = 48V



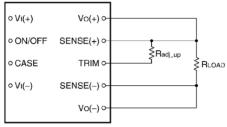


Figure 14.

#### Circuit Configuration to Increase Output Voltage.

The voltage between the Vo(+) and Vo(-) terminals must not exceed the minimum output overvoltage shut- down value indicated in the Feature Specifications table. This limit includes any increase in voltage due to remote- sense compensation and output voltage set-point adjustment (trim). See Figure 11.

Although the output voltage can be increased by both the remote sense and by the trim, the maximum increase for the output voltage is not the sum of both.

The maximum increase is the larger of either the remote sense or the trim.

The amount of power delivered by the module is defined as the voltage at the output terminals multiplied by the output current. When using remote sense and trim, the output voltage of the module can be increased, which the same output current would increase the power output of the module.

Care should be taken to ensure that the maximum output power of the module remains at or below the maximum rated power.

#### **Examples:**

To trim down the output of a nominal 48V module, without –T option, to 40V

$$\Delta\% = \left(\frac{48V - 40V}{48V}\right) \times 100$$

 $\Delta$ % = 16.7%

$$R_{adj-down} = \begin{bmatrix} 100 \\ \hline 16.7 \end{bmatrix} - 2 K\Omega$$

To  $t_{\text{rim}}$  down the output of a nominal 48V module, without –T option, to 52.8V

$$R_{adj-down} = 4.0k\Omega$$

$$\Delta\% = \left(\frac{52.8V - 48V}{48V}\right) \times 100$$

$$R_{\text{adj-up}} = \begin{bmatrix} 48x & (100+10) \\ \hline 1.225x10 \end{bmatrix} \times \Omega$$

 $R_{adj-up} = 419.0 \text{k}\Omega$  Active Voltage Programming

For the JRCW450Ux a Digital-Analog converter (DAC), capable ofboth sourcing and sinking current can be used to actively set theoutput voltage, as shown in Figure 15. The value of RG will be dependent on the voltage step and range of the DAC and the desired values for trim-up and trim-down  $\Delta$ %. Please contact your OmniOn technical representative to obtain more details on the selection for this resistor.

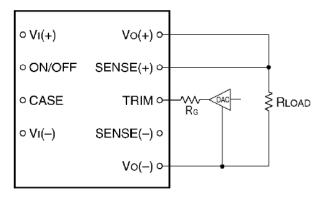


Figure 15. Circuit Configuration to Actively Adjust the Output Voltage



### Feature Description (continued)

#### **Over Temperature Protection**

The JRCW450U module provides a non-latching over temperature protection. A temperature sensor monitors the operating temperature of the converter. If the reference temperature, TREF 1, (see Figure 16) exceeds a threshold of 115 °C (typical), the converter will shut down and disable the output. When the base plate temperature has decreased by approximately 1-2 °C the converter will automatically restart.

#### **Tunable Loop**

The JRCW0450U-T modules have a new feature that optimizes transient response of the module called Tunable Loop.

External capacitors are usually added to the output of the module for two reasons: to reduce output ripple and noise and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance couldalso cause the module to become unstable.

The Tunable Loop allows the user to externally adjust the voltage control loop to match the filter network connected to the output of the module. The Tunable Loop is implemented byconnecting a series R-C between the SENSE(+) and TRIM pins of the module, as shown in Fig. 16. This R-C allows the user to externally adjust the voltage loop feedback compensation of the module.

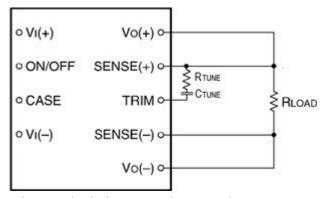


Figure 16. Circuit diagram showing connection of RTUNE and CTUNE to tune the control loop of the module.

Table 1 shows the recommended values of  $R_{\text{TUNE}}$  and  $C_{\text{TUNE}}$  for different values of ceramic output capacitors up to 8000 $\mu$ F that might be needed for an application to meet output ripple and noise requirements.

Cout(µF)	1100	2200	4400	6600	8800
ESR (mΩ)	60	30	15	10	7.5
R <sub>TUNE</sub>	TBD	TBD	TBD	TBD	TBD
C <sub>TUNE</sub>	TBD	TBD	TBD	TBD	TBD

Table 1. General recommended values of  $R_{\text{TUNE}}$  and  $C_{\text{TUNE}}$  for  $V_{\text{out}}$ =48V and various external ceramic capacitor combinations.

Please contact your OmniOn technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external R-C to tune the module for best transient performance and stable operation for other output capacitance values.

#### Thermal Considerations

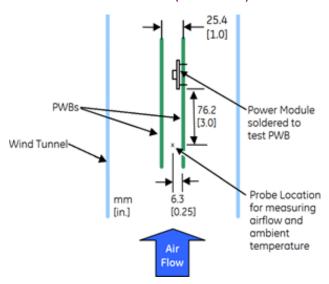
The power modules operate in a variety of thermal environments; however, sufficient cooling should be provided to help ensure reliable operation of the unit. Heat-dissipating components inside the unit are thermally coupled to the case. Heat is removed by conduction, convection, and radiation to the surrounding environment. Proper cooling can be verified by measuring the case temperature. Peak temperature (TREF) occurs at the position indicated in Figure 16.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability.

The thermal data presented here is based on physical measurements taken in a wind tunnel, using automated thermo-couple instrumentation to monitor key component temperatures: FETs, diodes, control ICs, magnetic cores, ceramic capacitors, opto-isolators, and module pwb conductors, while controlling the ambient airflow rate and temperature. For a given airflow and ambient temperature, the module output power is increased, until one (or more) of the components reaches its maximum derated operating temperature, as defined in IPC-9592. This procedure is then repeated for a different airflow or ambient temperature until a family of module output derating curves is obtained.



### Thermal Considerations (continued)



For reliable operation with Vin=48V this temperature should not exceed 100°C at either  $T_{REF1}$  or  $T_{REF2}$ , or 130°C at  $T_{REF3}$  for applications using forced convection airflow without heat sink, or in cold plate applications. The temperatures at either  $T_{REF1}$  or TREF2 should not exceed 90°C, when using a lin. heat sink in forced convection airflow. The output power of the module should not exceed the rated power for the module as listed in the ordering Information table. Although the maximum  $T_{REF}$  temperature of the power modules is discussed above, you can limit this temperature to a lower value for extremely high reliability.

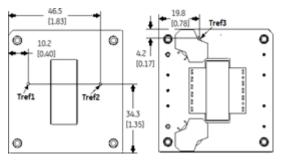


Figure 16. Case  $(T_{REF})$  Temperature Measurement Location (top view).

### **Thermal Derating**

Thermal derating is presented for different applications in Figure 17, 18 and 19. The JRCW450U module is mounted in a traditional open chassis or cards with forced air flow. The module is cooled by heat removal into a forced airflow that passes through the interior of the module and over the top base plate and/or attached heat sink. Conduction cooled thermal derating is presented in Figure 20.

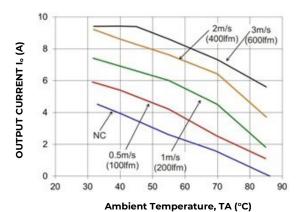


Figure 17. Derating Output Current vs. local Ambient temperature and Airflow, No Heat sink, Vin=48V, airflowfrom Vi(-) to Vi(+).

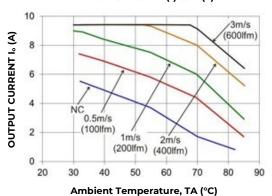
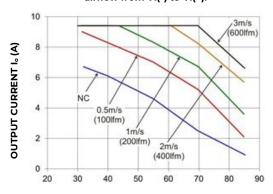


Figure 18. Derating Output Current vs. local Ambient temperature and Airflow, 0.5" Heat sink, Vin=48V, airflow from Vi(-) to Vi(+).



Ambient Temperature, TA (°C)

Figure 19. Derating Output Current vs. local Ambient temperature and Airflow, 1.0" Heat sink, Vin=48V, airflow from Vi(-) to Vi(+).



### Thermal Considerations (continued)

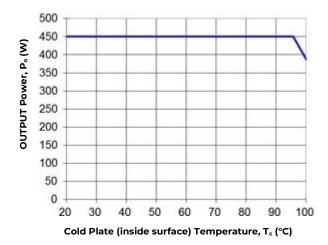


Figure 20. Derating Output Power in conduction cooling (coldplate) applications, Vin=48V.

### **Layout Considerations**

The JRCW450U power module series are constructed using a single PWB with integral base plate; as such, component clearance between the bottom of the power module and the mounting (Host) board is limited. Avoid placing copper areas on the outer layer directly underneath the power module.

### **Post Solder Cleaning and Drying Considerations**

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to OmniOn Board Mounted Power Modules: Soldering and Cleaning Application Note.

### Through-Hole Lead-Free Soldering Information

The RoHS-compliant through-hole products use the SAC (Sn/Ag/Cu) Pb-free solder and RoHS-compliant components. They are designed to be processed through single or dual wave soldering machines. The pins have a RoHS-compliant finish that is compatible with both Pb and Pb-free wave soldering processes. A maximum preheat rate of 3°C/s is suggested. The wave preheat process should be such that the temperature of the power module board is kept below 210°C. For Pb solder, the recommended pot temperature is 260°C, while the Pb-free solder pot is 270°C max. The JRCW450U cannot be processed with paste-throughhole Pb or Pb-free reflow process. If additional information is needed, please consult with your OmniOn representative for more details.

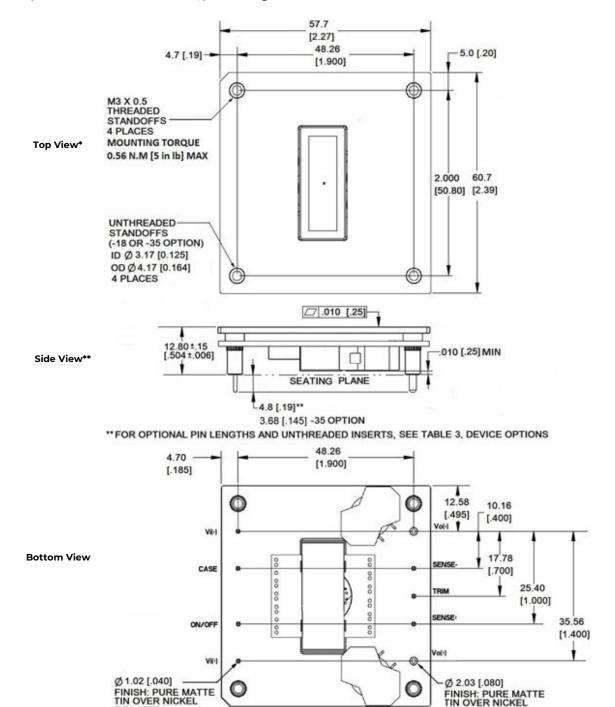


## **Mechanical Outline for Through-Hole Module**

Dimensions are in millimeters and [inches].

Tolerances: x.x mm ±0.5 mm [x.xx in. ± 0.02 in.] (Unless otherwise indicated) x.xx mm ± 0.25 mm [x.xxx in ± 0.010 in.]

<sup>\*</sup>Top side label includes OmniOn name, product designation and date code.



7 PLACES

FINISH: PURE MATTE TIN OVER NICKEL 2 PLACES



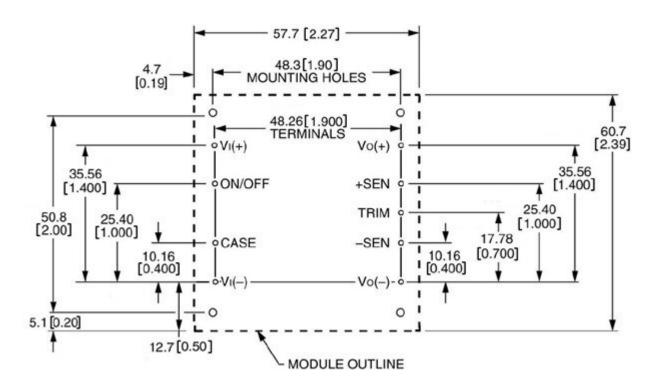
## Mechanical Outline for Through-Hole Module (continue)

Pin	Description
1	Vin(+)
2	ON/OFF
3	Baseplate
4	Vin(-)
5	Vout(-)
6	SENSE(-)
7	TRIM
8	SENSE(+)
9	Vout(+)

# **Recommended Pad Layout for Through Hole Module**

Dimensions are in millimeters and [inches].

Tolerances: x.x mm  $\pm$ 0.5 mm [x.xx in.  $\pm$  0.02 in.] (Unless otherwise indicated) x.xx mm  $\pm$  0.25 mm [x.xxx in  $\pm$  0.010 in.]





# **Ordering Information**

Please contact your OmniOn Sales Representative for pricing, availability and optional features.

Input Vol	tage	Output Voltage	Output Current	Efficiency	Connector Type	Product codes	Ordering Codes
48V (36-7	5V <sub>dc</sub> )	48V	9.4A	94%	Through hole	JRCW450U641Z	CC109168992
48V (36-7	5V <sub>dc</sub> )	48V	9.4A	94%	Through hole	JRCW450U64-18Z	150022105
48V (36-7	5V <sub>dc</sub> )	48V	9.4A	94%	Through hole	JRCW450U64-35Z	150034270
48V (36-7	5V <sub>dc</sub> )	48V	9.4A	94%	Through hole	JRCW450U641-18Z	150021936
48V (36-7	5V <sub>dc</sub> )	48V	9.4A	94%	Through hole	JRCW450U641-TZ	CC109168984
48V (36-7	5V <sub>dc</sub> )	48V	9.4A	94%	Through hole	JRCW450U64-18TZ	CC109172838

**Table 2. Device Codes** 

	Characteristic	Character and position	Definition
	Form Factor	J	J = Half Brick
gs	Family Designator	RC	RC = Orca Family
Ratings	Input Voltage	W	W = Wide Range, 36V-75V
ř	Output Power	450	450 = 450 Watts Maximum Output Power
	Output Voltage	U	U = 48.0V nominal
	Pin Length	6 8	Omit= Default Pin Length shown in mechanical Outline Figures 6 = Pin Length: 3.68 mm ±0.25mm (0.145 in.÷0.010 in.) 8 = Pin Length: 2.97 mm ±0.25mm (0.110 in.±0.010 in.)
	Action following		Omit = Latching Mode
	Protective Shutdown	4	4 = Auto– restart following shutdown (Overcurrent/ Overvoltage)
v	On/Off Logic	1	Omit = Positive Logic 1 = Negative Logic
Options			-
Opt	Customer Specific	XY	XY = Customer Specific Modified Code, Omit for Standard Code
	Customer specific	35	35 = Unthreaded insert standoffs, 4 places, and Uncut Pin length = 6 Option
	Mechanical Features	18	Omit = M3 x 0.5 threaded heat sink insert standoffs, 4 places 18 = Unthreaded insert standoffs, 4 places
	Tunable Loop ™	Т	Internal Compensation network optimized for Tunable Loop ™ applications
	RoHS	Z	Omit = RoHS 5/6 Lead Based Solder Used Z = RoHS Complaint

#### **Table 3. Device Options**

### **Contact Us**

For more information, call us at +1-877-546-3243 (US)

+1-972-244-9288 (Int'l)



# **Change History (excludes grammar & clarifications)**

Revision	Date	Description of the change
1.5	04-27-2022	Updated as per template , ROHS
1.6	12/01/2023	Updated as per OmniOn template



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