

CAR0812FP series rectifier

Input: $85V_{AC}$ to $264V_{AC}$; Output: $12V_{DC}$ @ 850W; 3.3 V_{DC} or 5 V_{DC} @ 1A



Description

The CAR0812FP series of rectifiers provide highly efficient isolated power from world-wide commercial AC mains. Offered in the industry standard compact 1U form factor, these rectifiers complement the CAR0812DC converter line, providing comprehensive solutions for systems connected either to commercial ac mains or 48/60V_{DC} power plants. This plug and play approach, between AC and DC input units, has significant advantages since systems can be readily reconfigured by simply replacing the power supply.

The high-density, front-to-back airflow is designed for minimal space utilization and is highly expandable for future growthThe industry standard PMBus compliant I²C communications buss offers a full range of control and monitoring capabilities. The SMBAlert signal pin alerts customers automatically of any state change within the power supply.

Applications

- 12V_{DC} distributed power architectures
- Datacom and Telecom applications
- Mid to high-end Servers
- Enterprise Networking

Features

- Universal input with PFC
- Constant power characteristic
- 2 front panel LEDs LED1 input
 LED2 [output, fault, over temp]
- Remote ON/OFF control of the 12V_{DC} output
- Remote sense on the 12V_{DC} output
- No minimum load requirements
- Active load sharing (single wire)
- Hot Plug-ability
- Efficiency: typically 92.5% @ 50% load and 90.0% @ 20% load
- Standby orderable either as 3.3V_{DC} or 5V_{DC}

- Network Attached Storage
- Telecom Access Nodes
- Routers/Switches
- ATE Equipment
- Auto recoverable OC & OT protection
- Operating temperature: -10 70°C (de-rated above 50°C)
- Digital status & control: I²C and PMBus serial bus
- UL and cUL approved to UL/CSA†62368-1, TUV (EN62368-1), CE§Mark
- EMI: class A or B FCC docket 20780 part 15, EN55032
- Meets EN6100 immunity and transient standards
- Shock & vibration: NEBS GR-63-CORE, level 3
- Compliant to RoHS Directive 2011/65/EU and amended Directive (EU) 2015/863
- Compliant to REACH Directive (EC) No 1907/2006

See Footnote on Page No.6 Page 1

Technical Specifications



Absolute Maximum Ratings

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Symbol	Min	Max	Unit
Input Voltage :Continues	V_{IN}	0	264	V_{AC}
Operating Ambient Temperature	T _A	-10	70¹	°C
Storage Temperature	T_{stg}	-40	85	°C
I/O Isolation voltage to Frame (100% factory Hi-Pot tested for 1s)			2600	V _{DC}

¹Derated above 50°C at 2.5%/°C

Electrical Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, load, and temperature conditions.

INPUT

Parameter	Symbol	Min	Тур	Max	Unit
Operational Range	V_{IN}	85 ²	110/230	264	V_{AC}
Frequency Range	F _{IN}	47	50/60	63	Hz
Main Output Turn OFF	V _{IN}	68		75	V _{AC}
Main Output Turn ON	V _{IN}	76		84	V _{AC}
Maximum Input Current V _{IN} = 100V _{AC}				11	^
(V _{OUT} =V _O , _{max} , I _{OUT} =I _O , _{max}) V _{IN} = 180V _{AC}	I _{IN}			6.1	Аас
Cold Start Inrush Current	I _{IN}			40	A _{peak}
Efficiency(T _{AMB} =25°C, V _{OUT} = 12V _{DC} , I _O , _{max})			230V 115V		
100% load			90 87		
75% load	_		91 89		0/
50% load	η		92.5 90		%
20% load			90 88		
10% load			82.5 83		
Power Factor (V _{IN} =230V _{AC} , I _{OUT} =I _O , _{max})	PF		0.99		
Holdup time ³	Т		12		ms
(TAMB 25°C, Vout= 12VDC, IOUT=IO, max)			12		1113
Early warning prior to output falling below regulation	Т	2			ms
Leakage Current (V_{in} = 250 V_{AC} , F_{in} = 60Hz)	I _{IN}		3		A _{DC}
Isolation Input/Output		3000			V_{AC}
Input/Frame		1500			V_{AC}
Output/Frame		100			V_{DC}

 $^{^{2}}$ Unit derates to 750W below 90V $_{\text{ac}}.$

12Vdc MAIN OUTPUT

Parameter	Symbol	Min	Тур	Max	Unit
Output Power V _{IN} > 90VAC	W	0	-	850	W
V _{IN} ≤ 90VAC	VV	0	-	750	VV
Set point	\/	11.9	12.00	12.1	V_{DC}
Overall regulation (line, load, temperature)	V _{OUT}	-2		+2	%
Ripple and noise ⁴	Vout			120	mV_{p-p}
Turn-ON overshoot	VOUT			+3	%

⁴ Measured across a 10µf electrolytic and a 0.1µf ceramic capacitors in parallel. 20MHz bandwidth

 $^{^{3}}$ 12V output can decay down to 10.8V



Electrical Specifications (continued)

12V_{dc} MAIN OUTPUT (continued)

Parameter	Symbol	Min	Тур	Max	Unit
Turn-ON delay				2	sec
Remote ON/OFF delay time	Т			40	ms
Turn-ON rise time (10 – 90% of V _{OUT})				50	ms
Transient response 50% step [10%-60%, 50% - 100%] (di/dt - 1A/		-5		+5	%V _{OUT}
μs, recovery 500μs)	Vout	ף		13	70 V OUT
Programmable range (hardware & software)	1 001	10.8		13.2	V_{DC}
Overvoltage protection, latched		17 [145	1E E	
(recovery by cycling OFF/ON via hardware or software)		13.5	14.5	15.5	V_{DC}
Output current	I _{OUT}	0		71	A _{DC}
Current limit, Hiccup (programmable level)]	106		125	% of FL
Active current share – greater than 20% load		-5		+5	% of FL

STANDBY OUTPUT

Parameter	Symbol	Min	Тур	Max	Unit
Set point	V _{out}		3.3/5.0		V_{DC}
Overall regulation (load, temperature, aging)	V _{OUT}	-5		+5	%
Ripple and noise				50	mV _{p-p}
Output current	l _{out}	0		1	A _{DC}
Isolation Output/Frame		100			V_{DC}

General Specifications

Parameter	Min	Тур	Max	Units	Notes
Reliability		300,000 100,000			Full load, 25°C per Bellcore RPP Full load, 50°C per Bellcore RPP
Service Life		10		Yrs	Full load, excluding fans
Weight		1.09(2.4)		Kgs (Lbs)	

Feature Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Symbol	Min	Тур	Max	Unit
Remote ON/OFF (Needs to be pulled HI via an external resistor)					
Logic High (Module ON)	I _{IH}		-	20	μΑ
	VIH	$0.7V_{\text{DD}}$	-	12	V _{DC}
Logic Low (Module OFF)	I₁∟	-	-	1	mA
	VIL	0	-	0.8	V_{DC}
Output Voltage programming (Vprog)					
[internally 1k pull up to 3.3V]					
Equation: V _{OUT} = 10.8 + (V _{prog} -0.96)					
V _{prog} range	V_{prog}	0	-	2.5	V_{DC}
Programmed output voltage range	V_{OUT}	10.8	-	13.2	V_{DC}
Voltage adjustment resolution (8-bit A/D)	V _{OUT}	-	10	-	mV_{DC}
Output configured to 13.2V _{DC}	V_{prog}	2.5		3.0	V_{DC}
Output configured to the 12V _{DC} set-point	V_{prog}	3.0	-	-	V_{DC}





Feature Specifications (continued)

Parameter	Symbol	Min	Тур	Max	Unit
Enable [short pin controlling presence of the 12V _{DC} output]					
12V output OFF	Vı	0.7V _{DD}	-	12	V_{DC}
12V output ON	Vı	0	-	0.8	V_{DC}
Write protect (Wp)					
Write protect enabled	Vı	0.7V _{DD}	-	12	V_{DC}
Write protect disabled	V_{l}	0	-	0.8	V_{DC}
INPUT-OK (Needs to be pulled HI via an external resistor)					
Logic High (Input within normal range)	I _{OH}		-	20	μΑ
	Vон	0.7V _{DD}	-	12	V_{DC}
Logic Low (Input out of range)	loL	-	-	4	mA
	V_{OL}	0	-	0.4	V_{DC}
DC-OK (Needs to be pulled HI via an external resistor)					
Logic High (Output voltage is present)	I _{OH}		-	20	μΑ
	V _{OH}	$0.7V_{DD}$	-	12	V_{DC}
Logic Low (Output voltage is not present)	I _{OL}	-	-	4	mA
	V_{OL}	0	-	0.4	V_{DC}
Over Temperature Warning (Needs to be pulled HI via an external					
resistor)					
Logic High (temperature within normal range)	I _{OH}		-	20	μΑ
	V _{OH}	$0.7V_{DD}$	-	12	V_{DC}
Logic Low (temperature is too high)	I _{OL}	-	-	4	mA
	V_{OL}	0	-	0.4	V_{DC}
Delayed shutdown after Logic Low transition	T_{delay}	10			sec
Fault (Needs to be pulled HI via an external resistor)					
Logic High (No fault is present)	I _{OH}		-	20	μΑ
	V _{OH}	$0.7V_{DD}$	-	12	V_{DC}
Logic Low (Fault is present)	I _{OL}	-	-	4	mA
	V_{OL}	0	-	0.4	V_{DC}
PS Present (Needs to be pulled HI via an external resistor)					
Logic High (Power supply is not plugged in)					
Logic Low (Power supply is present)	VIL	0	-	0.1	V_{DC}
SMBAlert# (Interrupt) (Needs to be pulled HI via an external					
resistor)					
Logic High (No Alert - normal)	I _{OH}		-	20	μΑ
	V_{OH}	$0.7V_{DD}$	-	12	V_{DC}
Logic Low (Alert is set)	I _{OL}	-	-	4	mA
	V _{OL}	0	-	0.4	V_{DC}
Output current monitor (Imon)					
Resolution			40		mV/A
Accuracy, load greater than 25%		-10		10	%
Measurement range	I _o	0		25	Apc
Analog output range	V_{mon}	0		5	V _{DC}
Sourced output current	I _o			5	mA _{DC}



Digital Interface Specifications

Parameter	Conditions	Symbol	Min	Тур	Max	Unit
PMBus Signal Interface Characteristics						
Input Logic High Voltage (CLK, DATA)		V _{IH}	2.1		3.6	V_{DC}
Input Logic Low Voltage (CLK, DATA)		VIL	0		0.8	V_{DC}
Input high sourced current (CLK, DATA)		I _{IH}	0		10	μA
Output Low sink Voltage (CLK, DATA, SMBALERT#)	I _{OUT} =3.5mA	V _{OL}			0.4	V_{DC}
Output Low sink current (CLK, DATA, SMBALERT#)		I _{OL}	3.5			mA
Output High open drain leakage current (CLK,DATA, SMBALERT#)	V _{OUT} =3.6V	Іон	0		10	μA
PMBus Operating frequency range	Slave Mode	F _{PMB}	10		400	kHz
Measurement System Characteristics (all measurement tole	erances are typi	cal estimati	ons unde	r normal o	perating co	nditions)
Clock stretching		t _{STRETCH}			25	ms
IOUT measurement range	Linear	IRNG	0		80	ADC
IOUT measurement accuracy 25°C		IACC	-5		+5	%
VOUT measurement range	Linear	VOUT	0		14	VDC
		(rng)				
VOUT measurement accuracy		VOUT	-5		+5	%
		(acc)				
Temp measurement range	Linear	Temp	0		120	°C
		(rng)				
Temp measurement accuracy ⁵		Temp	-5		+5	%
	1	(acc)	_			
IIN measurement range	Linear	IIN(rng)	0		15	AAC
IIN measurement accuracy		IIN(acc)	-5		+5	%
VIN measurement range	Linear	VIN(rng)	0		300	VAC
VIN measurement accuracy		VIN(acc)	-5		+5	%
PIN measurement range	Linear	PN(rng)	0		1000	W
PIN measurement accuracy		PIN(acc)	-5		+5	%
Fan Speed measurement range	Linear		0		30k	RPM
Fan Speed measurement accuracy			-10		10	%
Fan speed control range	Linear		0		100	%

 $^{^{\}rm 5}$ Temperature accuracy reduces non-linearly with decreasing temperature

Environmental Specifications

Parameter	Min	Тур	Max	Units	Notes
Ambient Temperature	-10 ⁶		70	°C	Derated above 50°C - normal air above 40°C - reverse air
Storage Temperature	-40		85	°C	
Operating Altitude			2250/7382	m/ft	
Non-operating Altitude			8200/30k	m/ft	
Power Derating with Temperature			2.5	%/°C	50°C to 70°C- normal air 40°C to 60°C – reverse air
Power Derating with Altitude			2.0	°C/301 m °C/1000 ft	Above 2250 m/7382 ft
Acoustic noise			55	dbA	Full load
Over Temperature Protection		125/110		°C	Shutdown / restart
Humidity Operating Storage	30 10		95 95	%	Relative humidity, non-condensing
Shock and Vibration acceleration			6	Grms	NEBS GR-63-CORE, Level 3, 20- 2000Hz, min 30 minutes
Earthquake Rating	4			Zone	NEBS GR-63-CORE, all floors, Seismic Zone 4 Designed and tested to meet NEBS specifications.

⁶ Designed to start at an ambient down to -40°C; meet spec after □ 30 min warm up period, may not meet operational limits below -10°C.



EMC Compliance

Parameter	Criteria	Standard	Level	Test
	EN55022, FCC Docket 20780 part Conducted emissions 15, subpart J		A – Z01A	0.15 – 30MHz
AC input ⁷	Corradoted erriissions	EN61000-3-2	B – Z01B	0 – 2 KHz
,	Radiated emissions	EN55032	A – Z01A	30 – 10000MHz
	Tradiated erriissions	21103002	B – Z01B	30 10000141112
			Α	-30%, 10ms
	Voltage dips	EN61000-4-11	В	-60%, 100ms
				-100%, 5sec
AC	Voltage surge EN61000-4-5		A	2kV, 1.2/50µs, common
input		ENG1000 / E	_ ^	mode
immunity		EN01000-4-3	A	1kV, 1.2/50µs, differential
			^	mode
	Fast transients	EN61000-4-4	В	5/50ns, 2kV (common
	l ast transients	L1101000-4-4		mode)
	Conducted RF fields	EN61000-4-6	Α	130dBµV, 0.15-80MHz,
	conducted Ki ficias	21401000 4 0		80% AM
Enclosure		EN61000-4-3	Α	10V/m, 80-1000MHz, 80%
immunity	Radiated RF fields		, ,	AM
		ENV 50140	А	
	ESD	EN61000-4-2	В	4kV contact, 8kV air

⁷ TheZ01A module meets class A emissions, theZ01B module meets class B emissions (see ordering section)

FOOTNOTES

- * UL is a registered trademark of Underwriters Laboratories, Inc.
- $^{\scriptsize \dagger}$ CSA is a registered trademark of Canadian Standards Association.
- [‡] VDE is a trademark of Verband Deutscher Elektrotechniker e.V.
- § Intended for integration into end-user equipment. All the required procedures for CE marking of end-user equipment should be followed. (The CE mark is placed on selected products.)
- ** ISO is a registered trademark of the International Organization of Standards.
- + PMBus name and logo are registered trademarks of the System Management Interface Forum (SMIF)



Control and Status

Control hierarchy: Some features, such as output voltage, can be controlled both through hardware and firmware. For example, the output voltage is controlled both by the signal pin (V_{prog}) and the PMBus command, $(Vout_command)$.

Using output voltage as an example; the Vprog signal pin has ultimate control of the output voltage until the V_{prog} is either > $3V_{DC}$ or a no connect. When the programming signal via V_{prog} is either a no connect or > $3V_{DC}$, it is ignored, the output voltage is set at its nominal $12V_{DC}$ and the unit output voltage can be controlled via the PMBus command, (Vout_command).

Analog controls: Details of analog controls are provided in this data sheet under Signal Definitions.

Common ground: All signals and outputs are referenced to Output return. These include 'V_{stb} return' and 'Signal return'.

Control Signals

Voltage programming (V_{prog}): An analog voltage on this signal can vary the output voltage \pm 10% of nominal, from 10.8V_{DC} to 13.2V_{DC}. The equation of this signal is:

 V_{OUT} = 10.8 + (V_{prog} * 0.96) where V_{prog} = 0 to 2.5 V_{DC}

Between 2.5 and 3V the output stays at $13.2V_{DC}$. If V_{prog} is > 3V, or left open, the programming signal is ignored and the unit output is set at the setpoint of $12V_{DC}$.

Load share (Ishare): This is a single wire analog signal that is generated and acted upon automatically by power supplies connected in parallel. The Ishare pins should be tied together for power supplies if active current share among the power supplies is desired. No resistors or capacitors should get connected to this pin.

Remote ON/OFF: Controls presence of the 12VDC output voltage. This is an open collector, TTL level control signal that needs to be pulled HI externally through a resistor.

A turn OFF command either through this signal (Remote ON/OFF) or firmware commanded would turn OFF the 12V output.

Enable: This is a short signal pin that controls the presence of the $12V_{DC}$ main output. This pin should be connected to 'output return' on the system side of the output connector. The purpose of this pin is to ensure that the output turns ON after engagement of the power blades and turns OFF prior to disengagement of the power blades.

Write protect (WP): This signal protects the contents of the EEPROM from accidental over writing. When left open the EEPROM is write protected. A LO (TTL compatible) permits writing to the EEPROM. This signal is pulled HI internally by the power supply.

Fan speed control: The speed of the fan can be increased above that point that is required for internal cooling. The speed of the fan cannot be decreased below internal cooling requirements.

Status signals

Output current monitor (I_{mon}): A voltage level proportional to the delivered output current is present on this pin. The signal level is 0.04V per amp ± 0.25V.

Input OK: A TTL compatible status signal representing whether the input voltage is within the anticipated range. This signal needs to be pulled HI externally through a resistor.

DC OK: A TTL compatible status signal representing whether the output voltage is present. This signal needs to be pulled HI externally through a resistor

Over temp warning: A TTL compatible status signal representing whether an over temperature exists. This signal needs to be pulled HI externally through a resistor.

If an over temperature should occur, this signal would pull LO for approximately 10 seconds prior to shutting down the power supply. The unit would restart if internal temperatures recover within normal operational levels. At that time the signal reverts back to its open collector (HI) state.

Fault: A TTL compatible status signal representing whether a Fault occurred. This signal needs to be pulled HI externally through a resistor.

This signal activates for OTP, OVP, OCP, INPUT fault or No output.

PS_Present: This pin is connected to 'output return' within the power supply. Its intent is to indicate to the system that a power supply is present. This signal may need to be pulled HI externally through a resistor.

Interrupt (SMBAlert): A TTL compatible status signal, representing the SMBusAlert# feature of the PMBus compatible i2C protocol in the power supply. This signal needs to be pulled HI externally through a resistor.

Serial Bus Communications

The I²C interface facilitates the monitoring and control of various operating parameters within the unit and transmits these on demand over an industry standard I²C Serial bus.

All signals are referenced to 'Signal Return'.

Device addressing: The microcontroller (MCU) and the EEPROM have the following addresses:

Device	Address		Address Bit Assignments (Most to Least Significant)						
MCU	0xBx	1	0	1	1	A2	A1	A0	R/W
Broacast	0x00	0	0	0	0	0	0	0	0
EEPROM	0xAx	1	0	1	0	A2	A1	ΑO	R/W

Address lines (A2, A1, A0): These signal pins allow up to eight (8) modules to be addressed on a single I²C bus. The pins are pulled HI internal to the power supply. For a logic LO these pins should be connected to 'Output Return'

Serial Clock (SCL): The clock pulses on this line are generated by the host that initiates communications across the I²C Serial bus. This signal requires an external pull-up to 3.3V.

Serial Data (SDA): This line is a bi-directional data line. This signal requires an external pull-up to 3.3V.

Digital Feature Descriptions

PMBus[™] compliance: The power supply is fully compliant to the Power Management Bus (PMBus[™]) rev1.2 requirements.

Manufacturer specific commands located between addresses 0xD0 to 0xEF provide instructions that either do not exist in the general PMBus specification or make the communication interface simpler and more efficient.



Master/Slave: The 'host controller' is always the MASTER. Power supplies are always SLAVES. SLAVES cannot initiate communications or toggle the Clock. SLAVES also must respond expeditiously at the command of the MASTER as required by the clock pulses generated by the MASTER.

Clock stretching: The 'slave' µController inside the power supply may initiate clock stretching if it is busy and it desires to delay the initiation of any further communications. During the clock stretch the 'slave' may keep the clock LO until it is ready to receive further instructions from the host controller. The maximum clock stretch interval is 25ms.

The host controller needs to recognize this clock stretching, and refrain from issuing the next clock signal, until the clock line is released, or it needs to delay the next clock pulse beyond the clock stretch interval of the power supply.

Note that clock stretching can only be performed after completion of transmission of the 9th ACK bit, the exception being the START command.

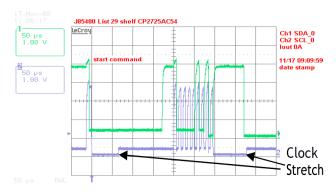


Figure 1. Example waveforms showing clockstretching.

I²C Bus Lock-Up detection: The device will abort any transaction and drop off the bus if it detects the bus being held low for more than 35ms.

Communications speed: Both 100kHz and 400kHz clock rates are supported. The power supplies default to the 100kHz clock rate. The minimum clock speed specified by SMBus is 10 kHz.

Packet Error Checking (PEC): Although the power supply will respond to commands with or without the trailing PEC, it is highly recommended that PEC be used in all communications. The integrity of communications is compromised if packet error correction is not employed. There are many functional features, including turning OFF the main output, that should require validation to ensure that the correct command is executed.

PEC is a CRC-8 error-checking byte, based on the polynomial $C(x) = x^8 + x^2 + x + 1$, in compliance with PMBusTM requirements. The calculation is based in all message bytes, including the originating write address and command bytes preceding read instructions. The PEC is appended to the message by the device that supplied the last byte.

SMBAlert#: The µC driven SMBAlert# signal informs the 'master/host' controller that either a STATE or ALARM change has occurred. Normally this signal is HI. The signal will change to its LO level if the power supply has changed states and the signal will be latched LO until the power supply either receives a 'clear' instruction as outlined below or executes a READ STATUS_WORD. If the alarm state is still present after the STATUS registers were reset, then the signal will revert back into its LO state again and will latch until a subsequent reset signal is received from the host controller.

The signal will be triggered for any state change, including the following conditions;

- V_{IN} under or over voltage
- V_{out} under or over voltage
- I_{OUT} over current
- Over Temperature warning or fault
- Fan Failure
- Communication error
- PEC error
- Invalid command
- Internal faults

The power supply will clear the SMBusAlert# signal (release the signal to its HI state) upon the following events:

- Receiving a CLEAR_FAULTS command
- The main output recycled (turned OFF and then ON) via the ENABLE signal pin
- The main output recycled (turned OFF and then ON) by the OPERATION command



• Execution of a READ of the STATUS_WORD register Global broadcast: This is a powerful command because it can instruct all power supplies to respond simultaneously in one command. But it does have a serious disadvantage. Only a single power supply needs to pull down the ninth acknowledge bit. To be certain that each power supply responded to the global instruction, a READ instruction should be executed to each power supply to verify that the command properly executed. The GLOBAL BROADCAST command should only be executed for write instructions to slave devices.

Read back delay: The power supply needs at least 2 seconds to configure the status registers into their final state. For example, a 2 second delay is required prior to reading back status information after a clear_faults has been issued to clear the status registers.

Successive read backs: Successive read backs to the power supply should not be attempted at intervals faster than every one second. This time interval is sufficient for the internal processors to update their data base so that successive reads provide fresh data.

PMBusTM Commands

Standard instruction: Up to two bytes of data may follow an instruction depending on the required data content. Analog data is always transmitted as LSB followed by MSB. PEC is optional and includes the address and data fields.

1	8		1	8				1	
S	Slave addr	Wr	Α	Command Code			9	Α	
8			8			1	8	1	1
Lo	w data byte	High data byte			Α	PEC	A	Р	

☐Master to Slave

■Slave to Master

SMBUS annotations; S – Start , Wr – Write, Sr – re-Start, Rd – Read, A – Acknowledge, NA – not-acknowledged, P – Stop

READ request depending on the required data content. Analog data is always transmitted as LSB followed by MSB. PEC is mandatory and includes the address and

Standard READ: Up to two bytes of data may follow a

data fields. PEC is optional and includes the address and data fields.

-	'/		ı	1 8				l	
S	Slave addres	ss '	Wr	Vr A Command Code				Α	
1	7	1		1		8		1	
Sr Slave Address			R	d	Α		LSB		Α
	8	1		8			1		1
	MSB		PEC			No-ack	ack		



Block instruction: When writing or reading more than two bytes of data at a time BLOCK instructions for WRITE and READ commands must be used instead of the Standard Instructions.

Block write format:

1		7			1			8			1
S	Slave	ve address			A		\cup	comr	ode	Α	
	8			1	8			1	8		1
By	yte cour	1t = N		А	Dat	:a 1		Α	Data 2		Α
	8	1		8		1			8	1	1
		Α	D	ata	48	Α			PEC		Р

Block read format:

1		7		1		1				8			1	
S	Slav	e ac	ldre	SS	W	′r	Α			Command Code				Α
	1					7						1		1
	Sr		SI	ave	Add	dre	SS		Rd				Α	
	<u> </u>													
		8			1	8 1		8			1			
Е	Byte c	oun [.]	t = N	_	Α		Dat	a 1		Α	Data	a 2		Α
	8 1				8 1		8		1		1			
A				Data	48	1	Pata 48 A			PEC		NoAck		

Linear Data Format: The definition is identical to Part II of the PMBus Specification. All standard PMBus values, with the exception of output voltage related functions, are represented by the linear format described below. Output voltage functions are represented by a 16 bit mantissa. Output voltage has a E=9 constant exponent.

The Linear Data Format is a two byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent or scaling factor, its format is shown below.

	Data Byte High								Data Byte Low							
Bit	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
	Exponent (E)								М	ant	iss	a (N	1)			

The relationship between the Mantissa, Exponent, and Actual Value (V) is given by the following equation:

V =M * 2^E

Where:

V is the value

M is the 11-bit, two's complement mantissa

E is the 5-bit, two's complement exponent

PMBus[™] Command set:

PIVIBUS	Command			
Com	nmand	Hex Code	Data Byte	Function
Operation		01		Output ON/OFF
				09, output ON
ON_OFF_cd	onfig	02	1	default
Clear_faults	5	03	0	Clear Status
Write_prote		10	1	Write control
Store_defau		11	0	Store permanently
Restore_de		12	0	Reset defaults
Capability		19	1	30h, 400kHz, SMBAlert
Vout_mode		20	1	Vout constants
Vout_comr	nand	21	2	Set Vout
Vout_OV_fa		40	2	Set OV fault limit
	ault_response	41	1	
Vout_OV_w	/arn_limit	42	2	Set OV warn limit
Vout_UV_w		43	2	Set UV warn limit
Vout_UV_fa		44	2	
	ult_response	45	1	
lout_OC_fa		46	2	
	ult_response	47	1	Latch or hiccup
lout_OC_wa		4A	2	Set OC warn limit
OT_fault_lir	nit	4F	2	102C, reverse air 91C
OT_fault_re		50	1	Latch or hiccup
OT_warn_li		51	2	Set OT warn limit
UT_warn_lii		52	2	
UT_fault_lir		53	2	
UT_fault_re		54	1	
Vin_OV_fau	ılt limit	55	2	
Vin_OV_wa	rn limit	57	2	Set OV warn limit
Vin_UV_wa		58	2	Set UV warn limit
Vin_UV_fau		59	2	Set UV shutdown
Status_byte		78	1	
Status_wor		79	2	
Status_Vou		7A	1	
Status_lout		7B	1	
Status_inpu		7C	1	
Status_tem		7D	1	
Status_CM		7E	1	
Status_oth		7F	1	
Status_mf		80	1	
Status_far		81	1	
Read_Vin		88	2	Read input voltage
Read_lin		89	2	Read input current
Read_Vou	t	8B	2	Read output voltage
Read_lout		8C	2	Read output current
Read_tem		8D	2	Read Temperature
Read_fan_		90	2	In RPM
Read_fan_		91	2	In RPM
Read_Pou		96	2	
Read_Pin		97	2	
PMBus revi	ision	98	1	
Mfr_ID		99	5	FRU_ID
Mfr_mode	·	9A	15	FRU_ID
Mfr_revision		9B	4	FRU_ID
Mfr_location		9C	4	FRU_ID
Mfr_date		9D	6	FRU_ID
Mfr_serial		9E	15	FRU_ID
Mfr_Vin_m	nin	AO	2	85V (linear format)
/	•			(23344)





PMBusTM Command set (continued)

		`	,
Command	Hex Code	Data Byte	Function
Mfr_Vin_max	A1	2	264V (linear format)
Mfr_lin_max	A2	2	I3A (linear format)
Mfr_Pin_max	A3	2	950W (linear format)
Mfr_Vout_min	A4	2	10V (linear format)
Mfr_Vout_max	A5	2	15V (linear format)
Mfr_lout_max Mfr_Pout_max	A6 A7	2	71A (linear format) 850W (linear format)
Mfr_Tambient_max	A8	2	70C (linear format)
Mfr_Tambient_min	A9	2	-10C (linear format)
User_data_00	BO	48	User memory space
User_data_01	B1	48	User memory space
FRW_revision	D0	1	
Ilimit_control_I ² C	D3	2	Ilimit set (1/100A)
Vout_control_ I ² C	D4	2	Vout set (1/512V)
Vout_offset	D5	1	
Fan_duty_cycle	D6	1	Duty_cycle in %
Fan_speed	D7	1	Control duty cycle in %
Vprog_ext	D8	2	3.3/1023
Read_Vout_ I ² C	EO	2	1/512V
Read_lout_ I ² C	E1	2	1/100A
Read_TS_ I ² C	E2	2	Heat sink temp °C
CMD_OFF_ I ² C	E3	2	01-OFF, 00-ON
OTF_limit_I ² C	E4	2	OT fault limit °C
OTF_recovery_ I ² C	E5	2	OT fault recovery °C
DCOKHI_ I ² C	E6	2	High OV fault (1/512V)
DCOKLO_I ² C	E7	2	Low OV fault (1/512V)
Read_Vin_ I ² C	ED	2	Vin (1/100V)
Read_lin_ I ² C	EE	2	lin (1/100A)
Read_Pin_ I ² C	EF	2	Pin

Status Register Bit Allocation:

Register	Hex Code	Data Byte	Function
		7	Busy
		6	DC_OFF
		5	Output OV Fault detected
		4	Output OC Fault detected
Status_Byte	78	3	Input UV Fault detected
		2	Temp Fault/warning detected
		1	CML (communication fault) detected
		0	None of Below
		7	OV Fault/Warning detected
		6	OC Fault/Warning detected
		5	Input Fault/Warning detected
Status_word (includes	79	4	Mfr_specific register change detected
Status_byte)		3	DC_OFF
		2	Fan Fault or Warning detected
		1	Other fault
		0	Unknown

Register	Hex	Data	Function
	Code	Byte 7	Vout OV Fault
		6	Vout OV Warning
		5	Vout UV Warning
		4	Vout UV Fault
Status_Vout	7A	3	N/A
		2	N/A
		1	N/A
		0	N/A
		7	IOUT OC Fault
		6	N/A
		5	IOUT OC Warning
Ctatus laut	70	4	N/A
Status_lout	7B	3	N/A
		2	N/A
		1	N/A
		0	N/A
		7	Vin OV Fault
		6	Vin OV Warning
		5	Vin UV Warning
		4	Vin UV Fault
Status_input	7C	3	N/A
		2	N/A
		1	N/A
		0	N/A
		7	OT Fault
		6	OT Warning
		5	N/A
Status_	7D	4	N/A
temperature		3 2	N/A
		1	N/A
		· ·	N/A N/A
		0	Invalid/Unsupported
		7	Command
		6	Invalid/Unsupported Data
		5	Packet Error Check Failed
		4	Memory Fault Detected
Status_cml	7E	3	Processor Fault Detected
		2	Reserved
			Other Communications
		1	Fault
		0	Other Memory or Logic Fault
	80	7	3.3V_fault
		6	N/A
		5	Interrupt
Status_mfr_spec		4	Fault detected
ific		3	PS_remote_OFF
		2	DC_fault
		1	INPUT_fault
		0	1-Low line
	81	7	N/A
		6	N/A
		5	N/A
Status_fan_1_2		4	N/A
		3	Fan 1 Speed Overridden
		2	Fan 2 Speed Overridden
		1	N/A





Command Descriptions

Operation (01): By default the Power supply is turned ON at power up as long as Power ON/OFF signal pin is active HI. The Operation command is used to turn the Power Supply ON or OFF via the PMBus. The data byte below follows the OPERATION command.

FUNCTION	DATA BYTE
Unit ON	80
Unit OFF	00

To **RESET** the power supply cycle the power supply OFF, waitat least 2 seconds, and then turn back ON. All alarms and shutdowns are cleared during a restart.

Clear_faults (03): This command clears all STATUS and FAULT registers and resets the SMBAlert# line.

If a fault still persists after the issuance of the clear_faults command the specific registers indicating the fault are resetand the SMBAlert# line is activated again.

WRITE_PROTECT register (10): Used to control writing to the PMB us device. The intent of this command is to provide protection against accidental changes. All supported command parameters may have their parameters read, regardless of the write_protect settings. The contents of this register can be stored to non-volatile memory using the Store_default_code command. The default setting of this register is disable_all_writes except write_protect 0x80h.

FUNCTION	DATA BYTE
Enable all writes	00
Disable all writes except write_protect	80
Disable all writes except write_protect and OPERATION	40

Vout_Command (21): This command is used to change theoutput voltage of the power supply. Changing the output voltage should be performed simultaneously to all power supplies operating in parallel using the Global Address (Broadcast) feature. If only a single power supply is instructed to change its output, it may attempt to source all the required power which can cause either a power limit or shutdown condition. Software programming of output voltage permanently overrides the set point voltage configured by the V_{prog} signal pin. The program no longer looks at the 'V_{prog} pin' and will not respond to any hardware voltage settings. If power is removed from the µController it will reset itself intoits default configuration looking at the V_{prog} signal for output voltage control. In many applications, the V_{prog}

pin is used for setting initial conditions, if different that the factory setting. Software programming then takes over once I2C communications are established.

Vout_OV_warn_limit (42): OV_warning is extremely usefulbecause it gives the system controller a heads up that the output voltage is drifting out of regulation and the power supply is close to shutting down. Preamative action maybe taken before the power supply would shut down and potentially disable the system.

OC and OT_fault_ response (47, 50): The default responsefor both OC and OT is auto_restart (hiccup). Each register, individually, can be reconfigured into a latched state. Latched and hiccup are the only

supported states.

Restart after a latch off: Either of four restart possibilities are available. The hardware pin Remote ON/OFF may be turned OFF and then ON. The unit may be commanded to restart via i2c through the Operation command by first turning OFF then turning ON . The third way to restart is to remove and reinsert the unit. The fourth way is to turn OFF and then turn ON ac power to the unit. The fifth way is by changing firmware from latch off to restart. Each of these commands must keep the power supply in the OFF state for at least 2 seconds, with the exception of changing to restart. A power system that is comprised of a number of power supplies could have difficulty restarting after a shutdown event because of the non-synchronized behavior of the individual power supplies. Implementing the latch-off mechanism permits a synchronized restart that guarantees the simultaneous restart of the entire system.

A synchronous restart can be implemented by;

- Issuing a GLOBAL OFF and then ON command to all power supplies,
- Toggling Off and then ON the Remote ON/OFF signal
- 3. Removing and reapplying input commercial power to theentire system.

The power supplies should be turned OFF for at least 20 – 30 seconds in order to discharge all internal bias supplies andreset the soft start circuitry of the individual power supplies.

Auto_restart: Auto-restart is the default configuration forrecovering from over-current and over-temperature shutdowns.

An overvoltage shutdown is followed by three attempted restarts, each restart delayed 1 second, within a 1 minute window. If within the 1 minute window three attempted restarts failed, the unit will latch OFF. If less than 3 shutdowns occur within the 1 minute window then the count for latch OFF resets and the 1 minute window startsall over again.



Vin_UV_warn_limit (58): This is another warning flag indicating that the input voltage is decreasing dangerously close to the low input voltage shutdown level.

Status_word (79): returns two bytes of information. The upper byte bit functionality is tabulated in the Status_word section. The lower byte bit functionality is identical to Status_byte.

Fan_speed (D7): This register can be used to 'read' the fan speed in adjustment percent (0 – 100%) or set the fan speed in adjustment percent (0 – 100%). The speed of the fan cannot be reduced below what the power supply requires for its operation. The register value is the percent number, it is not in linear format.

Invalid commands or data: The power supply notifies the MASTER if a non-supported command has been sent or invalid data has been received. Notification is implemented by setting the appropriate STATUS and ALARM registers and setting the SMBAlert# flag.

Control and Read accuracy:

The estimates below are believed to be reasonable under most operating conditions. However, these are typical numbers and not hard bound values that cannot be exceeded. In most nominal operating conditions the returned values are significantly better than these estimates.

Note that temperature measurements are accurate around the shutdown limits and they get increasingly less accurate as the temperature level decreases.

FUNCTION	ACCURACY
Vout_command	± 2%
Vout_OV_fault_limit	± 3%
lout_OC_warn_limit	± 4% of FL
OT_warn_limit	±5°C
Vin_UV_warn_limit	± 3%
Vin_UV_fault_limit	± 3%
Read_Vin	± 3%
Read_Vout	± 2%
Read_lout	± 4% of FL
Read_temperature	±5°C

EEPROM

The microcontroller has 96 bytes of EEPROM memory available for the system host.

Another separate EEPROM IC will provide another 128 bytes of memory with write protect feature. Minimum information to be included in this separate EEPROM: model number, revision, date code, serial number etc.

LEDs

Two LEDs are located on the front faceplate. The AC_OK LED provides visual indication of the INPUT signal function. When the LED is ON GREEN the power supply input is within normal design limits.

The second LED DC/FLT is a tri-state LED. When GREEN there are no faults and DC output is present. When AMBER a fault condition exists but the power supply still provides output power. When RED then a fault condition exists and the power supply does not provide output power.

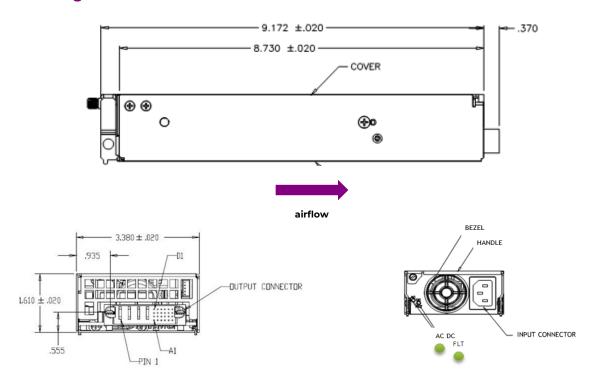
Alarm Table

		LED Indicator		Monitoring Signals				
Test Condition		LEDIAC	Tri-Color LED2 DC / FLT	FAULT	DC OK	INPUT OK	ТЕМР ОК	
1	Normal Operation	Green	Green	High	High	High	High	
2	Low or NO INPUT	Off	Red	Low	Low	Low	High	
3	OVP	Green	Red	Low	Low	High	High	
4	Over Current	Green	Red	Low	Low	High	High	
5	Temp Alarm Warning	Green	Orange	High	High	High	Low	
6	Fault Over Temp	Green	Red	Low	Low	High	Low	
7	Remote ON/OFF	Green	Red	Low	Low	High	High	

Notes: Test condition #2 had 2 modules plug in. One module is running and the other one is with no AC.



Outline Drawing



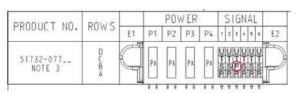
No handle, ac inlet – replace with wire extension with stress relief. 16ga -

Connector Pin Assignments

Input Mating Connector: IEC320, C13 type

Output Connector: FCI Berg P/N: 51732-077LF (replaces 51722-10402400ABLF)

Mating connector: 51762-10402400ABLF



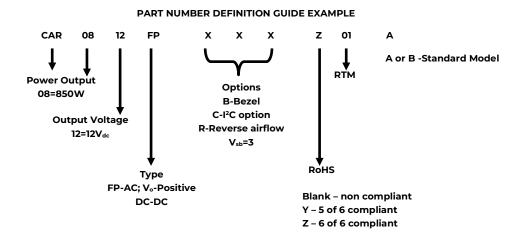
Pin	Function	Pin	Function	Pin	Function	Pin	Function
A1	VSTDBY [3.3V]	B1	Fault	C1	ISHARE	D1	V_{Prog}
A2	VSTDBY [3.3V] Return	B2	l Monitor (IMON)	C2	N/C	D2	OVP Test Point
A3	Signal Return	В3	Enable	C3	Over Temp Warning	D3	Remote ON/OFF
A4	Write Protect (WP)	В4	PS Present	C4	I ² C Address (A0)	D4	DCOK
A5	Remote Sense (+)	B5	SDA (I ² C bus)	C5	I ² C Address (A1)	D5	INPUT OK
A6	Remote Sense (-)	В6	SCL (I ² C bus)	C6	I ² C Address (A2)	D6	SMBAlert#/Interrupt
	`						
P1	+VOUT	P2	+VOUT	P3	Output Return	P4	Output Return



Ordering Information

Please contact your OmniOn Sales Representative for pricing, availability and optional features.

PRODUCT	DESCRIPTION	PART NUMBER
850W Rectifier	+12VOUT, 3.3VSTDBY, with face plate, PMBus interface, RoHS 6 of 6, Class A EMI	CAR0812FPBXXZ01A
850W Rectifier	+12VOUT, 3.3VSTDBY, with face plate, PMBus, RoHS 6 of 6, Class B EMI	CAR0812FPBXXZ01B
I X5UW DECTITION	+12VOUT, 3.3VSTDBY,no face plate, PMBus, reverse airflow, ROHS 6 of 6, Class A EMI	CAR0812FPBRXZ01A
850W Rectifier	+12VOUT, 3.3VSTDBY,no face plate, PMBus, reverse airflow, ROHS 6 of 6, Class B EMI	CAR0812FPBRXZ01B



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Change History (excludes grammar & clarifications)

Revision	Date	Description of the change
6.3	12/09/2021	Updated as per template
6.4	03/03/2023	Deleted Obsolete Products
6.5	12/16/2023	Updated as per OmniOn template



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