4.5Vdc -14Vdc input; 0.5Vdc to 2.0Vdc output; 80A Output Current

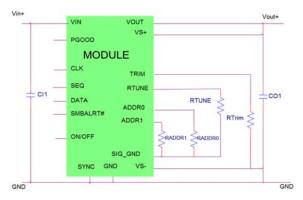


RoHS Compliant

Applications

GF

- Networking equipment
- **Telecommunications equipment**
- Servers and storage applications
- Distributed power architectures
- Intermediate bus voltage applications
- Industrial equipment



Features

- Compliant to RoHS II EU "Directive 2011/65/EU"
- Compatible in a Pb-free or SnPb reflow environment (Z versions)
- Compliant to IPC-9592 (September 2008), Category 2, Class II
- Wide Input voltage range (4.5Vdc-14Vdc)
- Output voltage programmable from 0.6Vdc to 2.0Vdc via external resistor. Digitally adjustable down to 0.5Vdc output.
- Digital interface through the PMBus[™] # protocol
- Digital Tunable Loop™ to optimize dynamic output voltage response
- Remote On/Off
- **Digital Sequencing**
- Power Good signal
- Fixed switching frequency with capability for external synchronization
- Ability to sink and source current
- Output overcurrent protection (non-latching)
- Over temperature protection
- Cost efficient open frame design
- Small size: 33.02mm x 22.86mm x 12.7mm [1.3" × 0.9" × 0.5"]
- Wide operating temperature range [-40°C to 85°C]
- UL* 60950-1 2nd Ed. Recognized, CSA[†] C22.2 No. 60950-1-07 Certified, and VDE[‡] (EN60950-1 2nd Ed.) Licensed
- ISO** 9001 and ISO 14001 certified manufacturing facilities

Description

The 80A Digital GigaDLynx™ power modules are non-isolated dc-dc converters that deliver up to 80A of output current. These modules operate over a wide range of input voltage (V_{IN} =4.5Vdc - 14Vdc) and provide a precisely regulated output voltage from 0.6Vdc to 2Vdc, programmable via an external resistor and/or PMBus control. Features include a digital interface using the PMBus protocol, remote On/Off, adjustable output voltage, over current, over voltage and over temperature protection. The PMBus interface supports many commands to both control and monitor the module. The module also includes the Digital Tunable Loop™ feature that allows the user to optimize the dynamic response of the converter with reduced amounts of output capacitance leading to savings on cost and PWB area.

* UL is a registered trademark of Underwriters Laboratories, Inc.

- CSA is a registered trademark of Canadian Standards Association
- VDE is a trademark of Verband Deutscher Elektrotechniker e.V. ** ISO is a registered trademark of the International Organization of Standards

The PMBus name and logo are registered trademarks of the System Management Interface Forum (SMIF)



4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Absolute Maximum Ratings

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the technical requirements. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Device	Symbol	Min	Max	Unit
Input Voltage	All	V _{IN}	-0.3	15	V
Continuous					
SEQ, ADDR0, ADDR1, RTUNE, VTRACK				2.0	V
VS+	All			3.0	V
ON/OFF				15	V
SYNC, CLK, DATA, SMBALERT#, PGOOD	All			5.5	V
Operating Ambient Temperature (see Thermal Considerations section)	All	T _A	-40	85	°C
Storage Temperature	All	T _{stg}	-55	125	°C

Electrical Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

Parameter	Device	Symbol	Min	Тур	Max	Unit
Operating Input Voltage	All	VIN	4.5		14	Vdc
Maximum Input Current	All	I _{IN,max}			46	Adc
(V_{IN}=4.5V to 14V, $I_0=I_{0, max}$)						
Input No Load Current	V _{O,set} = 0.6 Vdc	I _{IN,No load}		145		mA
$(V_{IN} = 12Vdc, I_0 = 0, module enabled)$	V _{0,set} = 2.0Vdc	I _{IN1No} load		190		mA
Input Stand-by Current ($V_{IN} = 12Vdc$, module disabled)	All	I _{IN,stand-by}		45		mA
Inrush Transient	All	l²t		1		A ² s
Input Noise on nominal output (VIN=VIN, nom and IO=IO, min to IO,max, Cin = 6 x 22µF + 1 x 470uF} Peak-to-Peak (Full Bandwidth)	All				500	mVpp
Input Reflected Ripple Current, peak-to-peak (5Hz to 20MHz, 1µH source impedance; V_{IN} =0 to 14V, Io= I _{Omax} ; See Test Configurations)	All			40		mAp-p
Input Ripple Rejection (120Hz)	All			-55		dB
Output Voltage Set-point (with 0.1% tolerance for external	0 to 70°C	V _{0. set}	-0.5		+0.5	% V _{0, set}
resistor used to set output voltage)	-40 to +85°C	V O, set	-0.8		+0.8	70 V U, set
Voltage Regulation ¹						
Line Regulation	(V _{IN} =V _{IN, min} to V _{IN, max})			3		mV
Load (I ₀ =I _{0, min} to I _{0, max}) Regulation	All			3		mV

¹Worst case Line and load regulation data, all temperatures, from design verification testing as per IPC9592.

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Тур	Max	Unit
Adjustment Range (selected by an external resistor) (Some output voltages may not be possible depending on the input voltage – see Feature Descriptions Section)	All	Vout	0.6		2.0	Vdc
PMBus Adjustable Output Voltage Range	All	V _{O,adj}	0.5	-	2.0	Vdc
PMBus Output Voltage Adjustment Step Size	All			0.233		%V _{0,set}
Remote Sense Range	All				0.4	Vdc
Output Ripple and Noise on nominal output $(V_{IN}=V_{IN,nom} \text{ and } I_{O}=I_{O,min} \text{ to } I_{O,max} \text{ Co} = 6 \times 47 \mu \text{F} + 4 \times 0.1 \mu \text{F},$ Cin = 6 × 22 µF + 1 × 470 µF						
Peak-to-Peak (Full bandwidth)					30	$mV_{\text{pk-pk}}$
RMS (Full bandwidth)	All				12	mV _{rms}
External Capacitance						
Minimum output capacitance (ESR \geq 3 m Ω)	All	C _{0,min}	470	_	—	μF
Maximum output capacitance (ESR \geq 3 m Ω)	All	C _{0, max}	—	_	16000	μF
Output Current (in either sink or source mode)	All	lo	0		80	Adc
Output Current Limit Inception (Hiccup Mode) (current limit does not operate in sink mode)	All	IO, lim		91		Adc
Output Short-Circuit Current	All	I _{O, s/c}		14.6		Arms
(V₀≤260mV) (Hiccup Mode)						
Efficiency	V _{O,set} = 0.6Vdc	η		82.4		%
V _{IN} = 12Vdc, T _A =25°C	V _{0, set} = 0.8Vdc	η		85.7		%
Io=Io, max, Vo= Vo,set	V _{O,set} = 1.0Vdc	η		88.1		%
	V _{O,set} = 1.2Vdc	η		89.6		%
	V _{O, set} = 1.5Vdc	η		91.2		%
	V _{O,set} = 2.0Vdc	η		92.8		%
Switching Frequency	All	f _{sw}	-	400	-	kHz
Frequency Synchronization	All					
Synchronization Frequency Range	All		-10		+10	%
High-Level Input Voltage	All	V _{IH,SYNC}	2.0			V
Low-Level Input Voltage	All	VIL,SYNC			0.4	V
Minimum Pulse Width, SYNC	All	t _{sync}	50			ns

General Specifications

Parameter	Device	Min	Тур	Max	Unit
Calculated MTBF (I_0=0.8I_0, $_{max},$ T_A=40°C) Telecordia Issue 3 Method 1 Case 3	All		39,165,215		Hours
Weight			22.5(0.793)		g (oz.)

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Feature Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbol	Min	Тур	Max	Unit
On/Off Signal Interface						
$(V_{IN}=V_{IN, min} to V_{IN, max}; open collector or equivalent,$						
Signal referenced to GND)						
Device Code with no suffix - Negative Logic (See Ordering Information)						
(On/OFF pin is open collector/drain logic input with						
external pull-up resistor; signal referenced to GND)						
Logic High (Module OFF)						
Input High Current	All	Ін	_	_	1	mA
Input High Voltage	All	VIH	2	_	V _{IN, max}	Vdc
Logic Low (Module ON)						
Input low Current	All	lıL	_	_	10	μA
Input Low Voltage	All	VIL	-0.2	_	0.4	Vdc
Device Code with suffix "4" - Positive Logic (See Ordering Information)						
(On/OFF pin is open collector/drain logic input with						
external pull-up resistor; signal referenced to GND)						
Logic High (Module ON)						
Input High Current	All	Ін	_	_	10	uA
Input High Voltage	All	Vін	2	_	V _{IN, max}	Vdc
Logic Low (Module OFF)						
Input low Current	All	lil	_	_	300	μA
Input Low Voltage	All	VIL	-0.2	_	0.4	Vdc
Turn-On Delay and Rise Times						
$(V_{IN}=V_{IN, nom, I_0}=I_{0, max}, V_0$ to within ±1% of steady state)						
Case 1: On/Off input is enabled and then input power is applied (delay from instant at which $V_{\rm IN}$ = $V_{\rm IN,min}$ until Vo = 10% of Vo, set)	All	Tdelay	_	5.0	_	ms
Case 2: Input power is applied for at least one second and then the On/Off input is enabled (delay from instant at which Von/Off is enabled until $V_0 = 10\%$ of $V_{0, set}$)	All	Tdelay	_	500	_	μs
Output voltage Rise time (time for V_0 to rise from 10% of V_0 , set to 90% of V_0 , set)	All	Trise	_	2.0	_	msec
Output voltage overshoot (T_A = 25°C V_{IN} = V_{IN, min} to V_{IN, max}, I_O = I_{O, min} to I_{O, max}) With or without maximum external capacitance		Output			3.0	% V _{O,} set
Over Temperature Protection (See Thermal Considerations section)	Vin ≤ 6.5V	T _{ref}		105		°C
over remperatore i rotection (see merma considerations section)	Vin > 6.5V	i rer		125		C
PMBus Over Temperature Warning Threshold*	Vin ≤ 6.5V	Twarn		95		°C
PMBus Over Temperature Warning Threshold*	Vin > 6.5V	I WARN		115		C
Tracking Accuracy (V_{IN, min} to V_{IN, max}; I_{O, min} to I_{O, max} VSEQ < V_{O})						
(Power-Up: 0.5V/ms)	All	Vseq –Vo			100	mV
(Power-Down: 0.5V/ms)	All	Vseq –Vo			100	mV
Input Undervoltage Lockout						
Turn-on Threshold	All				4.5	Vdc
Turn-off Threshold	All		4.1			Vdc
Hysteresis	All			0.25		Vdc
PMBus Adjustable Input Under Voltage Lockout Thresholds	All		4.5		14	Vdc
Resolution of Adjustable Input Under Voltage Threshold	All				10	mV

* Over temperature Warning – Warning may not activate before alarm and unit may shut down before warning.

80A GigaDLynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Feature Specifications (cont.)

Parameter	Device	Symbol	Min	Тур	Max	Units
PGOOD (Power Good)						
Signal Interface, $V_{supply} \le 5VDC$						
Overvoltage threshold for PGOOD ON	All			108		%V _{0, set}
Overvoltage threshold for PGOOD OFF	All			110		%V _{O, set}
Undervoltage threshold for PGOOD ON	All			92		%V _{O, set}
Undervoltage threshold for PGOOD OFF	All			90		%V _{0, set}
Sink/source current capability into PGOOD pin	All				2	mA

* Over temperature Warning – Warning may not activate before alarm and unit may shut down before warning.

80A GigaDLynx™: Non-Isolated DC-DC Power Modules

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Digital Interface Specifications

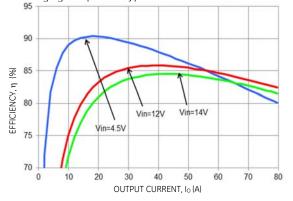
Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Conditions	Symbol	Min	Тур	Max	Unit
PMBus Signal Interface Characteristics						
Input High Voltage (CLK, DATA)		Vін	2.0			V
Input Low Voltage (CLK, DATA)		VIL			0.8	V
Output current – low (CLK, DATA, SMBALERT#)		I _{OL}			2	mA
PMBus Operating frequency range	Slave Mode	Fpmb	10	400	500	kHz
Data hold time		thd:dat	300			ns
Data setup time		tsu:dat	100			ns
Clock low time-out		ttimeout		25	35	ms
Clock low period		tlow	1.3			μs
Clock high period		tніgн	0.6			μs
Clock or data fall time		tr			300	ns
Clock or data fall time		t _R			300	ns
Internal Pull-up resistors on DATA, CLK and SMBALRT pins				50K		Ω
Measurement System Characteristics						
Read delay time		t DLY	153	192	231	μs
Output current measurement range		I _{RNG}	0		100	А
Output current measurement resolution		IRES		197		mA
Output current measurement gain accuracy	0°C to 85°C	lacc			±5	% of Io,max
output current medsarement gain accuracy	-40°C to +85°C	TACC	-3		+7	A
Output current measurement offset		I _{OFST}		0.2		А
V _{OUT} measurement range		Vout	0.5		2.0	V
V _{OUT} measurement resolution		V _{OUT(res)}		0.7		mV
V _{OUT} measurement accuracy		V _{OUT(gain)}		±1		%
V _{OUT} measurement offset		V _{OUT(ofst)}	-5		5	mV
V _{IN} measurement range		VIN(rng)	0		14	V
V _{IN} measurement resolution		V _{IN(res)}		7.0		mV
V _{IN} measurement accuracy		VIN		±1		%

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Characteristic Curves

The following figures provide typical characteristics for the 80A Digital GigaDLynx™ at 0.6Vo and 25°C.



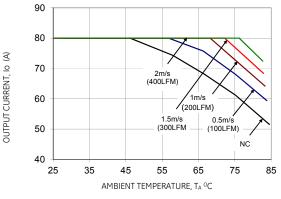
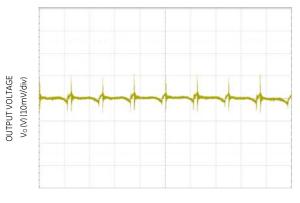


Figure 1. Converter Efficiency versus Output Current.



TIME, t (1µs/div)

Figure 3. Typical output ripple and noise (C_0= $6x47\mu F$ ceramic, V_IN = 12V, I_0 = I_{0,max}).

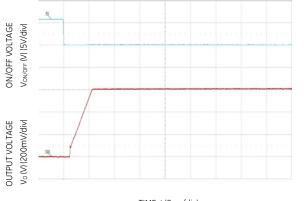
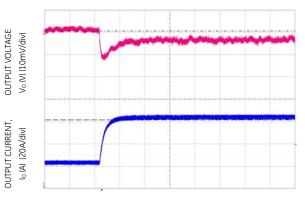


Figure 2. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (50µs /div)

Figure 4. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 36x 47µF + 14x 1000µF, R_{TUNE} = $4.22k\Omega$



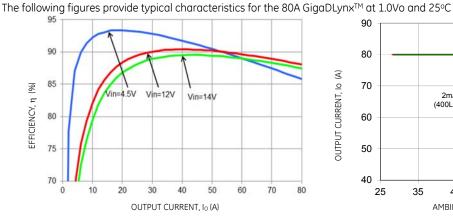
TIME, t (2ms/div)

Figure 5. Typical Start-up Using On/Off Voltage ($I_0 = I_{0,max}$).

Figure 6. Typical Start-up Using Input Voltage (V $_{\rm IN}$ = 12V, $I_{\rm o}$ = $I_{\rm o,max}$).

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Characteristic Curves



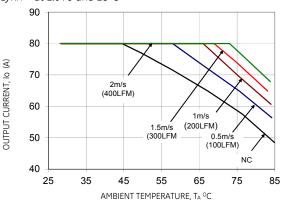
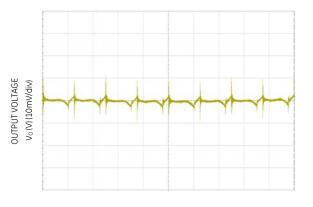


Figure 7. Converter Efficiency versus Output Current.



TIME, t (1µs/div)

Figure 9. Typical output ripple and noise (C_O= 6x47 μF Ceramic, V_IN = 12V, I_o = I_{o,max,}).

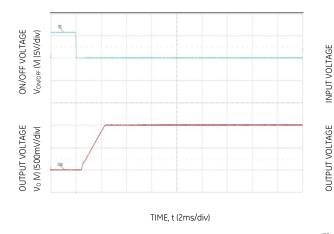
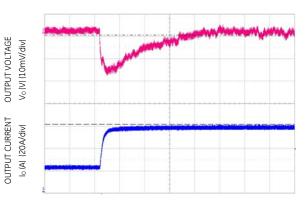


Figure 11. Typical Start-up Using On/Off Voltage (Io = Io,max).

Figure 8. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (50µs /div)

Figure 10. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 30x 47 μ F + 11x 1000 μ F, R_{TUNE} = 3.74k\Omega

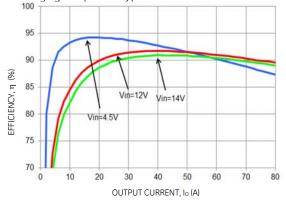


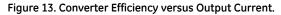
Figure 12. Typical Start-up Using Input Voltage (VIN = 12V, I_o = I_{o,max}).

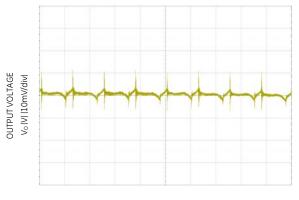
4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Characteristic Curves

The following figures provide typical characteristics for the 80A Digital GigaDLynx™ at 1.2Vo and 25℃.







TIME, t (1µs/div)

Figure 15. Typical output ripple and noise ($C_0=6x47\mu F$ ceramic, $V_{IN} = 12V$, $I_0 = I_{0,max}$,).

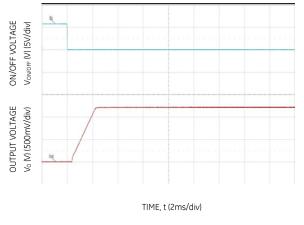


Figure 17. Typical Start-up Using On/Off Voltage (Io = Io,max).

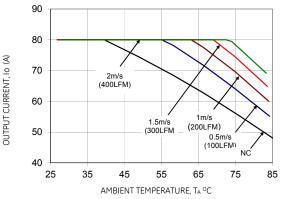
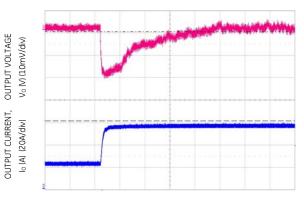


Figure 14. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (50µs /div)

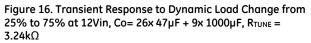


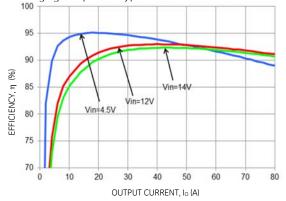


Figure 18. Typical Start-up Using Input Voltage (V $_{\rm IN}$ = 12V, $I_{\rm o}$ = $I_{\rm o,max}$).

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Characteristic Curves

The following figures provide typical characteristics for the 80A Digital GigaDLynx™ at 1.5Vo and 25°C.



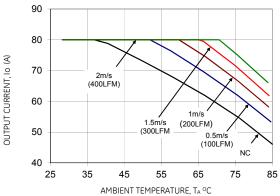


Figure 19. Converter Efficiency versus Output Current.

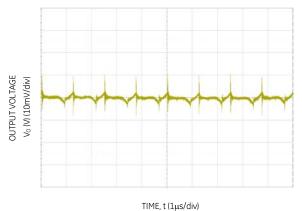
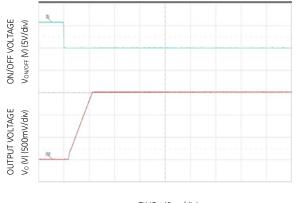


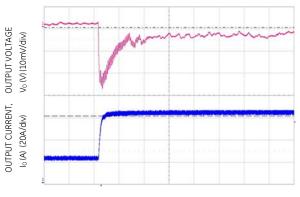
Figure 21. Typical output ripple and noise (C_0 = 6x47 μ F

ceramic, $V_{IN} = 12V$, $I_0 = I_{0,max}$,).



TIME, t (2ms/div)

Figure 20. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (50µs /div)

Figure 22. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 25x 47 μ F + 8x 1000 μ F, R_{TUNE} = 6.81k Ω



Figure 23. Typical Start-up Using On/Off Voltage (Io = Io,max).

Figure 24. Typical Start-up Using Input Voltage ($V_{IN} = 12V$, $I_0 = I_{0,max}$).

1m/s (200LFM)

80A GigaDLynx[™]: Non-Isolated DC-DC Power Modules

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Characteristic Curves

The following figures provide typical characteristics for the 80A Digital GigaDLynx™ at 2.0Vo and 25°C.

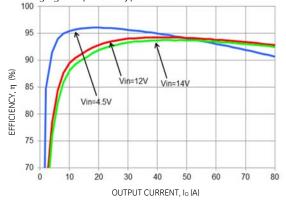
90

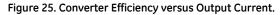
80

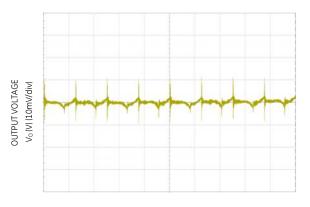
70

60

2m/s (400LFM)

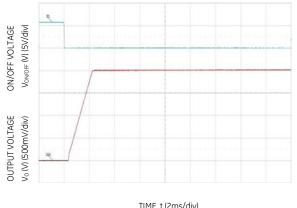




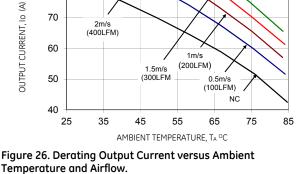


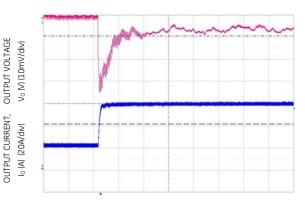
TIME, t (1µs/div)

Figure 27. Typical output ripple and noise ($C_0=6x47\mu F$ ceramic, VIN = 12V, Io = Io,max,).

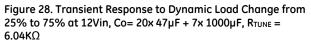


TIME, t (2ms/div)









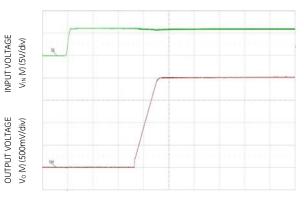


Figure 29. Typical Start-up Using On/Off Voltage (Io = Io,max).

Figure 30. Typical Start-up Using Input Voltage (VIN = 12V, Io = lo,max).

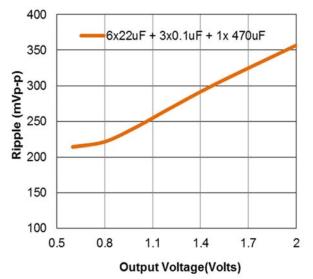
4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

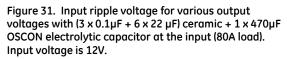
Design Considerations

Input Filtering

The 80A GigaDLynx[™] module must be powered from a low-impedance source. An inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pins of the module, to minimize input ripple voltage and ensure module stability.

To minimize input voltage ripple, ceramic capacitors are recommended at the input of the module. Figure 31 shows the input ripple voltage for various output voltages at 80A of load current with $6x22 \ \mu\text{F} + 3x0.1 \ \mu\text{F} + 1x470 \ \mu\text{F}$ OSCON electrolytic capacitor at an input of 12V.





Output Filtering

These modules are designed for low output ripple voltage and will meet the maximum output ripple specification with minimum of $6x47\mu$ F ceramic capacitors at the output of the module. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR polymer and ceramic capacitors are recommended to improve the dynamic response of the module.

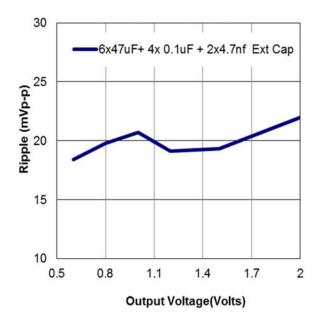


Figure 32. Output ripple voltage for various output voltages with external $6 \times 47 \mu F + 4 \times 0.1 \mu F + 2 \times 4.7 n F$ ceramic capacitors at the output (80A load). Input voltage is 12V.

Safety Considerations

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., ANSI/UL 60950-1 2nd Revised October 14, 2014, CSA C22.2 No. 60950-1-07, Second Ed. + A2:2014 (MOD), DIN EN 60950-1:2006 + A11:2009 + A1:2010 + A12:2011, + A2:2013 (VDE0805 Teil 1: 2014-08)(pending).

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV), the input must meet SELV requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV.

For input voltages greater than 7V, single external 40A 465 Series Fast Acting Littelfuse fuse on the ungrounded input pin is recommended. For input voltages less than 7V, two 30A 678 Series Bel Fast Acting Fuses in parallel is recommended.

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Analog Feature Descriptions

Remote On/Off

GE

The GigaDLynx 80A module can be turned ON and OFF either by using the ON/OFF pin (Analog interface) or through the PMBus interface (Digital). The module can be configured in a number of ways through the PMBus interface to react to the ON/OFF input:

- Module ON/OFF is controlled only through the analog interface (digital interface ON/OFF commands are ignored)
- Module ON/OFF is controlled only through the PMBus interface (analog interface is ignored)
- Module ON/OFF is controlled by either the analog or digital interface

The default state of the module (as shipped from the factory) is to be controlled by the analog interface only. If the digital interface is to be enabled, or the module is to be controlled only through the digital interface, this change must be made through the PMBus. These changes can be made and written to non-volatile memory on the module so that it is remembered for subsequent use.

Analog On/Off

The 80A GigaDLynx[™] power modules feature an On/Off pin for remote On/Off operation. With the Negative Logic On/Off option, (see Ordering Information), the module turns OFF during logic High and ON during logic Low. The On/Off signal should be always referenced to ground. Leaving the On/Off pin disconnected will turn the module ON when input voltage is present. With the positive logic on/off option, the module turns ON during logic high and OFF during logic low.

Digital On/Off

Please see the Digital Feature Descriptions section.

Monotonic Start-up and Shutdown

The module has monotonic start-up and shutdown behavior on the output voltage for any rated input voltage, output voltage and current, and operating temperature.

Startup considerations at Low Temperature.

GDT080 is able to handle specified full-load start-up for ambient temperatures above or equal to -10°C. Below -10°C ambient temperature, the load has to be limited to 75% of specified full-load.

Startup into Pre-biased Output

The module can start into a pre-biased output as long as the pre-bias voltage is 0.5V less than the set output voltage.

Analog Output Voltage Programming

The output voltage of the module is programmable to any voltage from 0.6 to 2.0 Vdc by connecting a resistor between the Trim and VS- pins of the module as shown in Fig 33.

Without an external resistor between the Trim and VS- pins, the output of the module will be 0.6 Vdc. The value of the

trim resistor, R_{TRIM} for a desired output voltage, should be selected as per the following equation:

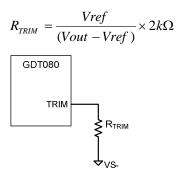


Figure 33. Circuit configuration for programming output voltage using an external resistor.

 R_{TRIM} is the external resistor in $k\Omega$

Vout is the desired output voltage.

Vref = 0.6V

Table 1 provides Rtrim values required for some common output voltages.

Table	1
-------	---

V _{O, set} (V)	R _{TRIM} (ΚΩ)
0.6	Open
0.8	6.0
1.0	3.0
1.2	2.0
1.5	1.33
2.0	0.866

Digital Output Voltage Adjustment

Please see the Digital Feature Descriptions section.

Remote Sense

The power module has a differential Remote Sense feature to minimize the effects of distribution losses by regulating the voltage between the sense pins (VS+ and VS-). The voltage drop between the sense pins and the VOUT and GND pins of the module should not exceed 0.4V.

Output Voltage Sequencing

The power module includes a sequencing feature, EZ-SEQUENCE that enables users to implement various types of output voltage sequencing in their applications. This is accomplished via an additional sequencing pin. This pin is disabled as a factory default setting, **if using this feature it should be enabled using the MFR_FEATURES_CONTROL (E7h) command**. When not using the sequencing feature, leave it unconnected and leave the default setting unchanged.

The voltage applied to the SEQ pin should be scaled down by the same ratio as used to scale the output voltage down to the reference voltage of the module. This is accomplished by an external resistive divider connected across the sequencing voltage before it is fed to the SEQ pin as shown

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

in Fig 34. In addition, a small capacitor (suggested value 100pF) should be connected across the lower resistor R1.

For all DLynx modules, the minimum recommended delay between the ON/OFF signal and the sequencing signal is 10ms to ensure that the module output is ramped up according to the sequencing signal. This ensures that the module soft-start routine is completed before the sequencing signal is allowed to ramp up.

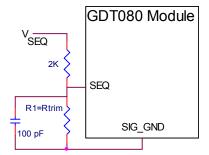


Figure 34. Circuit showing connection of the sequencing signal to the SEQ pin.

When the scaled down sequencing voltage is applied to the SEQ pin, the output voltage tracks this voltage until the output reaches the set-point voltage. The final value of the sequencing voltage must be set higher than the set-point voltage of the module. The output voltage follows the sequencing voltage on a one-to-one basis. By connecting multiple modules together, multiple modules can track their output voltages to the voltage applied on the SEQ pin.

The module's output can track the SEQ pin signal with slopes of up to 0.5V/msec during power-up or power-down.

To initiate simultaneous shutdown of the modules, the SEQ pin voltage is lowered in a controlled manner. The output voltage of the modules tracks the voltages below their setpoint voltages on a one-to-one basis. A valid input voltage must be maintained until the tracking and output voltages reach ground potential.

Digital Compensator

The GDT080 module uses digital control to regulate the output voltage. As with all POL modules, external capacitors are usually added to the output of the module for two reasons: to reduce output ripple and noise (see Figure 32 for example data) and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable. In the GDT080, using a feature called the Digital Tunable Loop™, the digital compensation can be adjusted externally to optimize transient response and also ensure stability for a wide range of external capacitance, as well as with different types of output capacitance. This is done by allowing the user to select among several pre-tuned compensation choices to select the one most suited to the transient response needs of the load. Figure 35 shows how the resistor RTune is connected

between the RTUNE and GND pins to select the appropriate pre-tuned compensation.

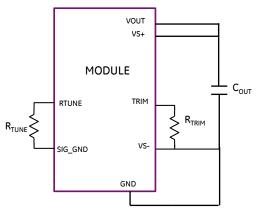


Figure 35. Circuit diagram showing connection of R_{TUNE} to tune the control loop of the module.

Recommended values of R_{TUNE} for different output capacitor combinations are given in Table 2. The GDT080 pre-tuned compensation can be divided into four different banks (COMP0, COMP1, COMP2 and COMP3) that are available to the user to compensate the control loop for various values and combinations of output capacitance and to obtain reliable and stable performance under different conditions. Each bank consists of seven different sets of compensation coefficients pre-calculated for different values of output capacitance. The four banks are set up as follows:

- COMP0: Recommended for the case where all of the output capacitance is composed of only ceramic capacitors. The range of external output capacitance is from the required minimum value of 470µF to a maximum of 7500µF.
- COMP1: For the most commonly used mix of ceramic and polymer type capacitors that have higher output capacitance in a smaller size and for output voltages between 0.6V to 1.2V. The range of output capacitance is from 470µF to a maximum of 15,692µF. This is the combination of output capacitance and compensation that can achieve the best transient response at lowest cost and smallest size. For example, with the maximum output capacitance of 15,692µF, and selecting RTUNE = $4.22k\Omega$, transient deviation can be as low as 15mV, for a 50% load step (0 to 40A).
- COMP2: Same range and types of capacitance as COMP1, but for an output voltage range from 1.2V to 2V.
- COMP3: Suitable also for a mix of ceramic and higher ESR polymers or electrolytic capacitors such as OSCON.

Selecting RTUNE according to Table 2 will ensure stable operation of the module with sufficient stability margin as well as yield optimal transient response.

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Output Capacitance Type	Number of Output Capacitors**	Total Output Capacitance (µF)**	Compensation Bank	R _{TUNE} resistor (kΩ)
Ceramic	18 x 47µ	846	Comp 0	0
Ceramic	18 x 47µ + 9 x 100µ	1746	Comp 0	0.392
Ceramic	18 x 47µ + 16 x 100µ	2446	Comp 0	0.576
Ceramic	18 x 47µ + 22 x 100µ	3046	Comp 0	0.787
Ceramic	18 x 47µ + 40 x 100µ	4846	Comp 0	1
Ceramic	18 x 47µ + 52 x 100µ	6046	Comp 0	1.24
Ceramic	18 x 47µ + 83 x 100µ	9146	Comp 0	1.5
Ceramic + Polymer	16 x 47µ + 2 x 1000µ	2752	Comp 1	1.78
Ceramic + Polymer	16 x 47µ + 3 x 1000µ	3752	Comp 1	2.1
Ceramic + Polymer	16 x 47µ + 5 x 1000µ	5752	Comp 1	2.43
Ceramic + Polymer	16 x 47µ + 7 x 1000µ	7752	Comp 1	2.8
Ceramic + Polymer	16 x 47µ + 9 x 1000µ	9752	Comp 1	3.24
Ceramic + Polymer	18 x 47µ + 12 x 1000µ	12,486	Comp 1	3.74
Ceramic + Polymer	18 x 47µ + 14 x 1000µ	14,846	Comp 1	4.22
Ceramic + Polymer	16 x 47µ + 2 x 1000µ	2752	Comp 2	4.75
Ceramic + Polymer	16 x 47µ + 3 x 1000µ	3752	Comp 2	5.36
Ceramic + Polymer	16 x 47µ + 5 x 1000µ	5752	Comp 2	6.04
Ceramic + Polymer	16 x 47µ + 7 x 1000µ	7752	Comp 2	6.81
Ceramic + Polymer	16 x 47µ + 9 x 1000µ	9752	Comp 2	7.68
Ceramic + Polymer	18 x 47µ + 12 x 1000µ	12,846	Comp 2	8.66
Ceramic + Polymer	18 x 47µ + 14 x 1000µ	14,846	Comp 2	9.53
Ceramic + Electrolytic	16 x 47µ + 4 x 470µ	2632	Comp 3	10.5
Ceramic + Electrolytic	16 x 47µ + 7 x 470µ	4042	Comp 3	11.8
Ceramic + Electrolytic	16 x 47µ + 9 x 470µ	4982	Comp 3	13
Ceramic + Electrolytic	18 x 47µ + 14 x 470µ	7246	Comp 3	14.3
Ceramic + Electrolytic	18 x 47µ + 20 x 470µ	10,246	Comp 3	15.8
Ceramic + Electrolytic	18 x 47µ + 24 x 470µ	12,126	Comp 3	17.4
Ceramic + Electrolytic	18 x 47µ + 30 x 470µ	14,946	Comp 3	19.1

Table 2. Recommended RTUNE Compensation

** Total output capacitance includes the capacitance inside the module of value $8 \times 47 \mu$ F (3m Ω ESR).

Note: The capacitors used in the digital compensation Loop tables are 47μ F/3 m Ω ESR ceramic, 100μ F/3.2m Ω ceramic, 1000μ F/6m Ω ESR polymer capacitor and 470μ F/9m Ω ESR Polymer capacitor.

In applications with tight output voltage limits in the presence of dynamic current loading, additional output capacitance will be required. Table 3 lists recommended values of R_{TUNE} in order to meet 2% output voltage deviation limits for some common output voltages in the presence of a 40A to 80A step change (50% of full load), with an input voltage of 12V.

Please contact your GE technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external RTUNE to tune the module for best transient performance and stable operation for other output capacitance values. Simulation models are also available via the GE Power Module Wizard to predict stability characteristics and transient response. Table 3. Recommended values of R_{TUNE} to obtain transient deviation of 2% of Vout for a 40A step load with Vin=12V.

Vo	2V	1.2V	0.6V
	14x47uF +	28x47uF +	36x47uF +
Co	5x1000µF	9x1000µF	14x1000µF
	polymer	polymer	polymer
R _{TUNE} (kΩ)	9.53	3.24	4.22
∆V (mV)	32	19.8	12

Power Module Wizard

GE offers a free web based easy to use tool that helps users simulate the Tunable Loop performance of the GDT080. Go to <u>http://qe.transim.com/pmd/Home</u> and sign up for a free account and use the module selector tool. The tool also offers downloadable Simplis/Simetrix models that can be used to assess transient performance, module stability, etc.

GE

80A GigaDLynx[™]: Non-Isolated DC-DC Power Modules

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Digital Output Voltage Margining

Please see the Digital Feature Descriptions section.

Overcurrent Protection (OCP)

To provide protection in a fault (output overload) condition, the unit has internal current-limiting circuitry on the output and can endure current limiting continuously. The module overcurrent response is non-latching shutdown with automatic recovery. The Overcurrent Protection response time is programmable via the PMBus through manufacturer-specific commands. The unit operates normally once the output current is brought back into its specified range.

Load Transient Considerations

The GDT080 module can achieve 100% load transient above -10°C ambient temperature. Below -10°C ambient temperature, the load transient is limited to a maximum of 75% of specified full load current.

Digital Sequencing

The module supports digital sequencing operation. Both ratiometric and simultaneous sequencing are supported.

Overtemperature Protection

To provide protection in a fault condition, the unit has a thermal shutdown circuit. The unit will shut down if the overtemperature threshold of 125°C (typ) is exceeded at the thermal reference point T_{ref} . Once the unit goes into thermal shutdown it will wait to cool before attempting to restart. The overtemperature threshold is dependent on input voltage, with the 125°C value applicable for input voltages > 6.5V and is changed to 105°C for input voltages ≤ 6.5V.

Digital Temperature Status via PMBus

Please see the Digital Feature Descriptions section.

Digitally Adjustable Output Over and Under Voltage Protection

Please see the Digital Feature Descriptions section.

Input Undervoltage Lockout

At input voltages below the input undervoltage lockout limit, module operation is disabled. The module will begin to operate at an input voltage above the undervoltage lockout turn-on threshold.

Digitally Adjustable Input Undervoltage Lockout

Please see the Digital Feature Descriptions section.

Digitally Adjustable Power Good Thresholds

Please see the Digital Feature Descriptions section.

Power Good

The module provides a Power Good (PGOOD) signal that goes high to indicate output voltage being within a specified range. The signal is implemented as push-pull circuit with an internal pull-up resistor of 20K to 3.3V. The PGOOD signal is de-asserted to a low state if any condition such as overtemperature, overcurrent or loss of regulation occurs that would result in the output voltage going outside the specified thresholds. The default PGOOD thresholds are \pm 15%.

The PGOOD terminal should be connected through a pullup resistor (suggested value $100 \text{K}\Omega$) to a source of 5VDC or lower.

Synchronization

The module switching frequency can be synchronized to an external signal within the specified range. Synchronization is done by applying the external signal to the SYNC pin of the module as shown in Fig. 36, with the converter being synchronized by the rising edge of the external signal. The Electrical Specifications table specifies the requirements of the external SYNC signal. If using this feature it should be enabled using the MFR_FEATURES_CONTROL (E7h) command. If the SYNC pin is not used, leave the default setting unchanged and the module runs at the default switching frequency.

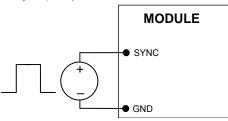


Figure 36. External source connections to synchronize switching frequency of the module.

Measuring Output Current, Output Voltage and Input Voltage

Please see the Digital Feature Descriptions section.

GE

80A GigaDLynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Digital Feature Descriptions

PMBus Interface Capability

The 80A Digital GigaDLynx[™] power modules have a PMBus interface that supports both communication and control. The modules supports a subset of version 1.1 of the PMBus specification (see Table 6 for a list of the specific commands supported). Most module parameters can be programmed using PMBus and stored as defaults for later use.

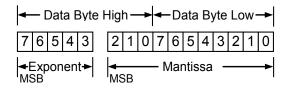
All communication over the module PMBus interface will work with or without Packet Error Checking (PEC) . The module generates the correct PEC byte for all transactions, and checks the PEC byte if sent by the master.

The module also supports the SMBALERT# response protocol whereby the module alerts the bus master if it wants to talk. For more information on the SMBus alert response protocol, see the System Management Bus (SMBus) specification.

The module has non-volatile memory that is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory, only those specifically identified as capable of being stored are saved (see Table 6 for which command parameters can be saved in non-volatile storage).

PMBus Data Format

For commands that set thresholds, voltages or report such quantities, the module supports the "Linear" data format among the three data formats supported by PMBus. The Linear Data Format is a two byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent. The format of the two data bytes is shown below:



The value is of the number is then given by Value = Mantissa x 2 Exponent

PMBus Addressing

The power module is addressed through the PMBus using a device address. The module supports 128 possible addresses (0 to 127 in decimal) which can be set using resistors connected from the ADDR0 and ADDR1 pins to SIG_GND. Note that some of these addresses (0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11 12, 40, 44, 45, 55 in decimal) are reserved according to the SMBus specification and may not be useable. The address is set in the form of two octal (0 to 7) digits, with each pin setting one digit. The ADDR1 pin sets the high order digit and ADDR0 sets the low order digit. The resistor values suggested for each digit are shown in Table 4 (E96 series resistors are recommended). Note that if either

address resistor value is outside the range specified in Table 4, the module will respond to address 127.

Tab	le 4
-----	------

PMBus Address Table								
	ADDR1 Resistor Values							
ADDR0 Resistor Values	0	680	1.2K	1.8K	2.7K	3.9K	4.7K	5.6K
0	64	16	32	48	64	80	96	112
680	1	17	33	49	65	81	97	113
1.2K	2	18	34	50	66	82	98	114
1.8K	3	19	35	51	67	83	99	115
2.7K	4	20	36	52	68	84	100	116
3.9K	5	21	37	53	69	85	101	117
4.7K	6	22	38	54	70	86	102	118
5.6K	7	23	39	55	71	87	103	119
6.8K	8	24	40	56	72	88	104	120
8.2K	9	25	41	57	73	89	105	121
10K	10	26	42	58	74	90	106	122
12K	11	27	43	59	75	91	107	123
15K	12	28	44	60	76	92	108	124
18K	13	29	45	61	77	93	109	125
22K	14	30	46	62	78	94	110	126
27K	15	31	47	63	79	95	111	127

Both 100kHz and 400kHz bus speeds are supported by the module. Connection for the PMBus interface should follow the High Power DC specifications given in section 3.1.3 in the SMBus specification V2.0 for the 400kHz bus speed or the Low Power DC specifications in section 3.1.2.

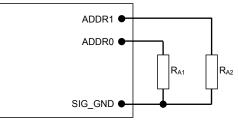


Figure 37. Circuit showing connection of resistors used to set the PMBus address of the module.

PMBus Enabled On/Off

The output of the module can be turned on and off via the PMBus interface. The OPERATION command is used to actually turn the module on and off via the PMBus, while the ON_OFF_CONFIG command configures the combination of analog ON/OFF pin input and PMBus commands needed to turn the module on and off. Bit [7] in the OPERATION command data byte enables the module, with the following functions:

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

0	:	Output is disabled
---	---	--------------------

1 : Output is enabled

This module uses the lower five bits of the ON_OFF_CONFIG data byte to set various ON/OFF options as follows:

Bit Position	4	3	2	1	0
Access	r/w	r/w	r/w	r/w	r
Function	PU	CMD	CPR	POL	CPA
Default Value	1	0	1	1	0

PU: Sets the default to either operate any time input power is present or for the ON/OFF to be controlled by the analog ON/OFF input and the PMBus OPERATION command. This bit is used together with the CP, CMD and ON bits to determine startup.

Bit Value	Action
0	Module powers up any time power is present regardless of state of the analog ON/OFF pin
1	Module does not power up until commanded by the analog ON/OFF pin and the OPERATION command as programmed in bits [2:0] of the ON_OFF_CONFIG register.

CMD: The CMD bit controls how the device responds to the OPERATION command.

Bit Value	Action
0	Module ignores the ON bit in the OPERATION command
1	Module responds to the ON bit in the OPERATION command

CPR: Sets the response of the analog ON/OFF pin. This bit isused together with the CMD, PU and ON bits to determine startup.

Bit Value	Action
0	Module ignores the analog ON/OFF pin, i.e. ON/OFF is only controlled through the PMBUS via the OPERATION command
1	Module requires the analog ON/OFF pin to be asserted to start the unit

PMBus Adjustable Soft Start Rise Time

The soft start rise time of module output is adjustable in the module via PMBus. The TON RISE command can set the rise time in ms, and allows choosing soft start times between 200µs and 14ms.

Output Voltage Adjustment Using the PMBus

The VOUT_SCALE_MONITOR parameter is important for a number of PMBus commands related to output voltage trimming, margining, over/under voltage protection and the PGOOD thresholds. The output voltage of the module is determined by the value of the RTrim resistor connected between TRIM pin and analog ground VS-, as specified earlier in the data sheet. The information on the output voltage divider ratio is conveyed to the module through the

VOUT SCALE MONITOR parameter. The read-out of output voltage also depends on VOUT_SCALE_MONITOR. If the correct VOUT SCALE MONITOR is not used, the output voltage read-out will be wrong. The VOUT_SCALE_MONITOR parameter is defined by the ratio of internal reference of the controller to the nominal output voltage selected by RTrim resistor.

VOUT_SCALE_MONITOR = $\frac{0.000}{\text{Nominal Output Voltage}}$

0.6V

For example, for a nominal output voltage of 1.2V, the VOUT SCALE MONITOR is equal to 0.5. Table 5 below defines values of VOUT SCALE MONITOR to the various nominal output voltages.

V _{O, set} (V)	VOUT_SCALE_MONITOR
0.6	1
0.8	0.75
1.0	0.6
1.2	0.5
1.5	0.4
2.0	0.3

Table 5

When PMBus commands are used to trim or margin the output voltage, the value of VREF is what is changed inside the module, which in turn changes the regulated output voltage of the module.

The nominal output voltage of the module is adjustable with a minimum step size of 1.406mV over a ± 25% range from nominal using the VOUT_TRIM command over the PMBus.

Output Voltage Margining Using the PMBus

Output voltage of the module can also be margined via PMBus commands. The command VOUT MARGIN HIGH sets the margin high voltage, while the command VOUT MARGIN LOW sets the margin low voltage. Both the VOUT_MARGIN_HIGH and VOUT_MARGIN_LOW commands use the "Linear" mode. Two bytes are used for data. The actual margined output voltage is determined by the resistor on the TRIM, which as explained earlier is taken into consideration by VOUT_SCALE_MONITOR command. The module then sets the output voltage to the margined high or low voltage levels using the OPERATION command. Bits [7:4] are used to enable margining as follows:

1001: Vout set to VOUT MARGIN LOW (Ignore Fault) 1010: Vout set to VOUT MARGIN HIGH (Ignore Fault)

Temperature Status via PMBus

The module provides information related to temperature of the module through standardized PMBus commands. Commands READ TEMPERATURE1, READ TEMPERATURE 2 are mapped to module temperature and internal temperature of the PWM controller, respectively. The temperature readings are returned in °C and are two bytes.

PMBus Adjustable Output Over and Under Voltage Protection

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

The module has output over and under voltage protection capability. The PMBus command VOUT_OV_FAULT_LIMIT is used to set the output over voltage threshold. The default value is configured to be 115% of the commanded output. The command VOUT_UV_FAULT_LIMIT sets the threshold that detects an output under voltage fault. The default values are 85% of the commanded output voltage. Both commands use two data bytes formatted in the Linear format.

PMBus Adjustable Input Undervoltage Lockout

The module allows adjustment of the input under voltage lockout and hysteresis. The command VIN_ON allows setting the input voltage turn on threshold, while the VIN_OFF command sets the input voltage turn off threshold. For both the VIN_ON and VIN_OFF commands, possible values are 4.5V to 14V. Both VIN_ON and VIN_OFF commands use the "Linear" format with two data bytes.

Measurement of Output Current, Output Voltage, Input Voltage and output power

The module can measure key module parameters such as output current, output voltage and input voltage and provide this information through the PMBus interface.

Measuring Output Current Using the PMBus

The module measures output current by using the inductor winding resistance as a current sense element. The inductor winding resistance is then multiplied by the current gain factor that will be used to scale the measured voltage into a current reading. This gain factor is the argument of the IOUT_CAL_GAIN command, and consists of two bytes in the Linear data format. During manufacture, each module is calibrated by measuring and storing the current gain factor into non-volatile storage.

The current measurement accuracy is also improved by each module being calibrated during manufacture with the offset in the current reading. The IOUT_CAL_OFFSET command is used to store and read the current offset. The READ_IOUT command provides tmodule average output current information. This command only supports positive output current, i.e. current sourced from the module. If the converter is sinking current a reading of 0 is provided. The READ_IOUT command returns two bytes of data in the Linear data format.

Measuring Output Voltage Using the PMBus

The module provides output voltage information using the READ_VOUT command. The command returns two bytes of data in Linear format

Measuring Input Voltage Using the PMBus

The module provides input voltage information using the READ_VIN command. The command returns two bytes of data in the Linear format.

Reading the Status of the Module using the PMBus

The module supports a number of status information commands implemented in PMBus. A 1 in the bit position indicates the fault that is flagged. STATUS_BYTE : Returns one byte of information with a summary of the most critical device faults.

Bit Position	Flag	Default Value
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

STATUS_WORD : Returns two bytes of information with a summary of the module's fault/warning conditions. Low Byte

Bit Default Flag Position Value Х 0 7 6 OFF 0 VOUT Overvoltage 5 0 4 IOUT Overcurrent 0 VIN Undervoltage 3 0 2 Temperature 0 CML (Comm. Memory Fault) 0 1 0 None of the above 0

High Byte

Bit Position	Flag	Default Value
7	VOUT fault or warning	0
6	IOUT fault	0
5	VIN Fault	0
4	X	0
3	PowerGOOD	0
2	Fan Fault	0
1	Shortciruit	0
0	Х	0

STATUS_VOUT : Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	VOUT OV Fault	0
6	Х	0
5	Х	0
4	VOUT UV Fault	0
3	Х	0
2	Х	0
1	X	0
0	X	0

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

STATUS_IOUT : Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	IOUT OC Fault	0
6	Х	0
5	Х	0
4	Х	0
3	Х	0
2	Х	0
1	Х	0
0	Х	0

STATUS_INPUT : Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	VIN_OV_FAULT	0
6	Х	0
5	Х	0
4	VIN_UV_FAULT	0
3	Х	0
2	Х	0
1	Х	0
0	Х	0

STATUS_TEMPERATURE : Returns one byte of information relating to the status of the module's temperature related faults.

Bit Position	Flag	Default Value
7	OT Fault	0
6	OT Warning	0
5	Х	0
4	Х	0
3	Х	0
2	Х	0
1	Х	0
0	X	0

STATUS_CML : Returns one byte of information relating to the status of the module's communication related faults.

Bit Position	Flag	Default Value
7	Invalid/Unsupported Command	0
6	Invalid/Unsupported data	0
5	Packet Error Check Failed	0
4	Memory Fault	0
3	Х	0
2	Х	0
1	Х	0
0	Х	0

MFR_VIN_MIN : Returns minimum input voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -2, and lower 11 bits are mantissa in two's complement format – fixed at 12)

MFR_VOUT_MIN : Returns minimum output voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -10, and lower 11 bits are mantissa in two's complement format – fixed at 614)

MFR_SPECIFIC_00 : Returns information related to the type of module and revision number. Bits [7:2] in the Low Byte indicate the module type (xxxxxx corresponds to the PLX002 series of module), while bits [7:3] indicate the revision number of the module.

	Low Byte						
Bit Position	Flag						
7:2	Module Name	XXXXXX					
1:0	Reserved	10					

High Byte											
Bit Position	Flag	Default Value									
7:3	Module Revision Number	None									
2:0	Reserved	000									

Writing to OTP (One Time Programmable) Memory

The GDT080 EEPROM memory can be completely written in entirety, for example, using STORE_DEFAULT_ALL command, only four times. During the situation of partial rewrites, for example, when trying to store only four commands using STORE_DEFAULT_CODE command four times in succession, numerous writes are possible within the confines of available memory.

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Summary of Supported PMBus Commands

Please refer to the PMBus 1.2 specification for more details of these commands.

Table 6

Hex Code	Command				Brief	Descrip	otion					Non-Volatile Memory Storage	
		Turn Module on or o	off. Also	used to	o margir	n the ou	tput vo	tage					
		Format			ι	Jnsigne	d Binar	/					
01	OPERATION	Bit Position	7	6	5	4	3	2	1	0			
01		Access	r/w	r	r/w	r/w	r/w	r/w	r	r			
		Function	On	Х			rgin		Х	Х			
		Default Value	0	0	0	0	0	0	Х	Х			
		Configures the ON/ commands	OFF fun	ictionali	-			-	ON/OF	F pin an	d PMBus		
		Format					d Binar		1				
02	ON_OFF_CONFIG	Bit Position	7	6	5	4	3	2	1	0		YES	
		Access	r	r	r	r/w	r/w	r/w	r/w	r			
		Function	Х	Х	Х	pu	cmd	cpr	pol	сра			
		Default Value	0	0	0	1	0	1	1	1			
03	CLEAR_FAULTS		ear any fault bits that may have been set, also releases the SMBALERT# signal if the evice has been asserting it.										
	Used to control writing to the module via PMBus. Copies the current register setting in the module whose command code matches the value in the data byte into non-volatile												
		memory (EEPROM)	on the r	nodule							1		
		Format	_				d Binar		-				
		Bit Position	7	6	5	4	3	2	1	0			
		Access Function	r/w	r/w	r/w	X	X	X	X	X			
		Default Value	bit7 0	bit6 0	bit5 0	X	X	X	X	X			
10	WRITE_PROTECT	Bit5: 0 – Enables all	-	-	•			\wedge	^	\wedge		YES	
		and ON_OF Bit 6: 0 - Enables al 1 - Disables al OPERATION Bit7: 0 - Enables all 1 - Disables all (bit5 and bit	 1 - Disables all writes except the WRITE_PROTECT, OPERATION and ON_OFF_CONFIG (bit 6 and bit7 must be 0) Bit 6: 0 - Enables all writes as permitted in bit5 or bit7 1 - Disables all writes except for the WRITE_PROTECT and OPERATION commands (bit5 and bit7 must be 0) Bit7: 0 - Enables all writes as permitted in bit5 or bit6 1 - Disables all writes except for the WRITE_PROTECT command (bit5 and bit6 must be 0) 										
11	STORE_DEFAULT_ALL	Copies all current re the module. Takes of							e mem	ory (EEPI	ROM) on		
12	RESTORE_DEFAULT_ALL	Restores all current memory (EEPROM)							n the m	odule no	on-volatile		
		Copies the current value in the data by									es the		
13	STORE_DEFAULT_CODE	Bit Position	7	6	5	4	3	2	1	0			
		Access	w	W	W	W	w	W	W	W			
		Function				Comma	nd code))					
		Restores the currer value in the data by			ue in th								
14	RESTORE_DEFAULT_CODE	Bit Position	7	6	5	4	3	2	1	0			
		Access	w	W	w	w	W	W	W	W			
		Function				Comma	nd code	è					
		The module has MC changed)DE set	to Linec	ir and E	xponen	t set to	-13. The	ese valu	ues cann	iot be		
20	VOUT_MODE	Bit Position	7	6	5	4	3	2	1	0			
20	VOUT_MODE	Access	r	r	r	r	r	r	r	r			
		Function		Mode				xponer	nt				
		Default Value	0	0	0	1	0	0	1	1			

*NOTE: The EEPROM memory can be completely written in entirety (for example, using STORE_DEFAULT_ALL command) only four times. During the situation of partial rewrites, numerous writes are available within the confines of the available memory (for example, using STORE_DEFAULT_CODE command).

Hex Code	Command				Brie	ef Desc	ription					Non-Volatile Memory Storage
		Apply a fixed offset	voltaae	to the	output	voltage	commo	and valu	e. Expo	nent is f	ixed at -13.	
		Format						ent binar				
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
22		Function				High	Byte					NEC.
22	VOUT_TRIM	Default Value	0	0	0	0	0	0	0	0		YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Low	Byte					
		Default Value	0	0	0	0	0	0	0	0		
		Sets the target volt	age for	margini	ng the o	output	high. Ex	ponent	is fixed	at -13.		
		Format	J					nt binar				
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
25		Function				High	Byte				1	YES
25	VOUT_MARGIN_HIGH	Default Value	0	0	0	1	0	1	0	1		TES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Low	Byte					
		Default Value	0	0	0	1	1	1	1	1		
		Sets the target volt	age for	margini	ng the o	output l	ow. Exp	onent is	s fixed a	t -13		
		Format						ent binar				
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
26		Function				High	Byte					1/50
26	VOUT_MARGIN_LOW	Default Value	0	0	0	1	0	0	0	1		YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Low	Byte					
		Default Value	0	1	0	0	1	0	0	0		
		Sets the scaling of t Output voltage. Th scaled by the value	e intern	al refere	ence is f	qual to t fixed at	he ratio 0.6V. Th	of inter ne outpu	nal refe It voltag	rence V je read	ref to the back gets	
		Format		L	inear, tv	vo's cor	npleme	ent binar	ту —			
		Bit Position	7	6	5	4	3	2	1	0		
2A	VOUT_SCALE_MONITOR	Access	r	r	r	r	r	r	r/w	r/w	l	YES
		Function			xponer		•		Mantiss		l	
		Default Value	1	0	1	1	1	0	1	0	l	
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					tissa			-		
		Default Value	0	0	0	0	0	0	0	0		
		Sets the value of in	put volte							s fixed o	pt -6	
		Format			1		· ·	ent binai	ŕ –		ļ	
		Bit Position	7	6	5	4	3	2	1	0	ļ	
		Access	r	r	r	r	r	r	r	r	ł	
35	VIN_ON	Function			xponer				Mantiss		ł	YES
		Default Value	1	1	0	0	1	0	1	0	ł	
		Bit Position	7	6	5	4	3	2	1	0	ł	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	ł	
		Function		_	1		itissa		1	1	ł	
		Default Value	0	0	1	1	0	0	1	1		

Code					Non-Volatile							
		Coto the university	المريقين وال			Descrip		off 5		a fi!		Memory Storage
		Sets the value of in	out volte							s fixed o	dt -6	
		Format				vo's con						
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
36	VIN_OFF	Function			xponen				1antisso			YES
50		Default Value	1	1	0	0	1	0	1	0		123
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Mant	tissa					
		Default Value	0	0	0	1	0	0	1	1		
		Returns the value o	f the ga	in corre	ection te	rm used	d to corr	ect the	measu	red out	out current	
		Format				vo's con						
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r/w		
		Function			xponen				1antisso			
38	IOUT_CAL_GAIN	Default Value				ased or	n factory					YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	1/ 00	1/ 🗸	17 00	Mant		17 00	17 00	17 00		
		Default Value		V· Vo	riahla h			, calibra	ntion			
	Default Value V: Variable based on factory calibration Returns the value of the offset correction term used to correct the measured output											
		current									itput	1
		Format		Li	inear, tv	vo's con	nplemer	nt binar	Ϋ́			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r/w	r	r		
39		Function Exponent Mantissa										YES
		Default Value				ased or	n factor	/ calibro	ation			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Mant		.,	.,			
		Default Value		V· Vo	iriable b	ased or		/ calibro	ntion			
		Sets the voltage lev	el for a							nt -13		
		Format				wo's col				10.	7	
		Bit Position	7	6	5	4	3	2	y 1	0	+	
			-		-		-	_			-	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
10		Function				High	Byte					1/50
40	VOUT_OV_FAULT_LIMIT	Default Value	0	0	0	1	0	1	1	0		YES
		Bit Position	7	6	5	4	3	2	1	0	1	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
		Function	17 VV	17 00	17 VV			17 W	17 VV	17 VV	-	
			-				Byte					
		Default Value	0	1	1	0	0	1	1	0		
		Instructs the modul	e on the	e action	to take	in respo	onse to	an outr	out over	rvoltaae	e fault	
		Format				Jnsigne					1	
		Bit Position	7	6	5	4	3	2	1	0	1	
41	VOUT_OV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r	1	YES
			RSP	RSP							×	0
		Function	[1]	[0]	RS[2]	RS[1]	RS[0]	Х	Х	Х		
		Default Value				1	1	0	0	0		

Hex Code	Command				Brief	Descri	ption					Non-Volatile
Code		Sets the value of ou	utput va	ltaae a	t which	the mod	dule aer	nerates	warning	for ove	er-voltaae.	Memory Storage
		Exponent is fixed at		Je ge e			g			,		
		Format		L	inear, t	vo's cor	npleme	nt bina	ry			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
42	VOUT_OV_WARN_LIMIT	Function			Exponer	nt			Mantiss	a		YES
		Default Value	0	0	0	1	0	1	0	1		-
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function		.,	.,		tissa	.,	.,	.,		
		Default Value	0	0	1	0	0	0	0	1		
		Sets the value of ou	utput vo	ltage a	t which	the mod	dule ger	nerates	warning	g for un	der-voltage.	
		Exponent is fixed at	t -13								_	
		Format		L	inear, t	vo's cor	npleme	nt bina	ry			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r/w		
43	VOUT_UV_WARN_LIMIT	Function		E	Exponer	nt		I	Mantiss	c		YES
		Default Value	0	0	0	1	0	0	0	1		
1		Bit Position	7	6	5	4	3	2	1	0	1	
1		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
1		Function					tissa				1	
		Default Value	0	1	0	0	1	0	0	0]	
		Sets the voltage lev	el for a	n outpu	it under	voltage	fault. E	xponen	ıt is fixed	d at -13.		
		Format				wo's cor						
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r/w	r	r		
		Function			Exponer				Mantiss			
44	VOUT_UV_FAULT_LIMIT	Default Value	0	0	0	1	0	0	0	0		YES
		Bit Position	7	6	5	4	3	2	1	0		
			r	r	r/w	r/w	r/w	r/w	r/w	r/w		
		Function			17 00		tissa	17 00	1/ 00	17 00		
		Default Value	0	1	0	1	0	0	0	0		
			Ţ	-		-	Ţ					
		Instructs the modu										
		Format				Unsigne	d Binar	У				
		Bit Position	7	6	5	4	3	2	1	0		
45	VOUT_UV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES
		Function	RSP	RSP	RS[2]	RS[1]	RS[0]	Х	Х	Х		
			[1]	[0]								
		Default Value Sets the current lev	1 el for a		1 t overcu	1 Irrent fo	1 Tuilt (car	0 Inot be	0 change	-1) 0]	
									-	J	1	
		Format	_	1		vo's cor	· · · · · · · · · · · · · · · · · · ·		í –	^		
1		Bit Position	7	6	5	4	3	2	1	0		
1		Access	r	r	r	r	r	r/w	r	r		
46	IOUT_OC_FAULT_LIMIT	Function			Exponer	1	1		Mantiss			YES
		Default Value	1	1	1	0	0	0	1	1		
1		Bit Position	7	6	5	4	3	2	1	0		
1		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w		
1		Function				Man	tissa					
		Default Value	0	0	0	0	1	1	1	1		
		Sets the value of cu	irrent le				0		0	or over	current.	
1		Format				vo's cor	-		1	-		
1		Bit Position	7	6	5	4	3	2	1	0		
1		Access	r	r	r	r	r	r	r	r/w		
4A	IOUT OC WARN LIMIT	Function		. 6	Exponer	1			Mantiss			YES
44	ICOT_CC_WARN_LIMIT	Default Value	1	1	1	0	0	0	1	0		IE3
1		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
1		Function				Man	tissa					
1		Default Value	1	1	1	1	1	1	1	1		
L		P	•					•	•			

Hex	Command				Briof	Descri	ntion					Non-Volatile
Code	Communu				Brief	Descri	ption					Memory Storage
		Sets the temperatu	re level	above	which o	ver-tem	peratur	e fault (occurs.			
		Format		L	inear, tv	vo's cor	npleme	nt binaı	гy			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r/w	r	r		
		Function		E	Exponer	nt		1	Mantiss	a		
4F	OT_FAULT_LIMIT	Default Value	1	1	1	0	1	0	1	1		YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w		
		Function		-			tissa					
		Default Value	1	1	1	0	0	1	1	1		
		Configures the over	r tempe	rature f	ault rea	sponse						
		Format	lempe	. atore I		Insigne	d Binary	/				
		Bit Position	7	6	5	4	3	2	1	0		
50	OT_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES
		Function	RSP	RSP	RS[2]	RS[1]	RS[0]	X	X	X		
			[1]	[0]								
		Default Value	1	0	1	1	1	0	0	0		
		Sets the over temp	erature	warning	g level ir	∩ °C						
		Format	Format Linear, two's complement binary									
		Bit Position	7	6	5	4	3	2	Í 1	0	ĺ	
		Access	r	r	r	r	r	r	r	r	1	
51	51 OT_WARN_LIMIT	Function		. 6	Exponer	nt		1	Mantiss	a		YES
51		Default Value	1	1	1	0	1	0	1	1		163
		Bit Position	7	6	5	4	3	2	1	0]	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w]	
		Function		-	-	-	itissa	-		-		
		Default Value	1	0	0	1	0	1	1	0		
		Configures the VIN	overvol	tage fai	ult respo	onse.						
		Format			l		ed Binary					
		Bit Position	7	6	5	4	3	2	1	0		
056	VIN_OV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES
		Function	RSP	RSP	RS[2]	RS[1]	RS[0]	Х	х	х		
		Default Value	[1]	[0] 0	0	0	0	0	0	0		
		ļ					-	÷			nont fixed	
		Sets the value of th at -6	emput	voitage	that ca	uses IN	put voito	ige iow	wurnin	y. Expoi	IETIL TIXEO	
1		Format	1	1	inear tv	NO'S CO	mpleme	nt bina	rv.		1	
1		Bit Position	7	6	5	4	3	2	1	0	ł	
		Access	r	r	r	r	r	r	r	r	1	
57	VIN OV WARN LIMIT	Function		. 6	Exponer				Mantiss	a	ĺ	YES
		Default Value	1	1	0	1	0	0	1	1	1	
1		Bit Position	7	6	5	4	3	2	1	0	1	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function		·	·	Mar	itissa	·	·	· _	1	
		Default Value	1	0	0	1	0	0	1	1]	
L											-	

Hex	Command				Brief D	escripti	on					Non-Volatile Memory
Code		Sets the value of th		voltago	that co	usos in			warnin	a Evpop	ont	Storage
		fixed at -6	emput	voitage		uses in	JUL VOIL	ige iow	warnin	у. Ехроп	ent	
		Format		1	inear t	wo's cor	nnleme	nt hina	rv.			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
58	VIN_UV_WARN_LIMIT	Function		 F	Exponer		·		Mantiss			YES
00		Default Value	1	1	0	0	1	0	1	0		120
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Man	itissa					
		Default Value	0	1	0	0	0	0	0	0		
		Sets the value of th fixed at -6.	nent									
		Format		L	inear, t	wo's cor	mpleme	nt binaı	ry			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
59	VIN_UV_FAULT_LIMIT	Function		1	xponer	1			Mantiss			YES
		Default Value	1	1	0	0	1	0	1	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access Function	r	r/w	r/w	r/w	r/w tissa	r/w	r/w	r/w		
		Default Value	0	0	0	0	1	1	0	1		
		Instructs the modul		-		-		_		ervoltag	e	
		fault.										
		Format				Unsigne						
5A	VIN UV FAULT RESPONSE	Bit Position	7	6	5	4	3	2	1	0		YES
-		Access	r/w	r/w	r/w	r/w	r/w	r	r	r		
		Function	RSP [1]	RSP [0]	RS[2]	RS[1]	RS[0]	X	X	X		
		Default Value	1	0	1	1	1	0	0	0		
		Sets the output voltage level at which the PGOOD pin is asserted high. Exponent is fixed at -13.										
		Format				wo's cor				-		
		Bit Position	7	6	5	4	3	2	1	0		
		Access Function	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
5E	POWER_GOOD_ON	Default Value	0	0	0	High 1	Byte 0	0	1	0		YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	· · · · ·				Byte					
		Default Value	0	0	1	1	1	1	1	1		
		Sets the output volt	aae lev	el at wh	nich the	PGOOD	pin is d	e-asser	ted low	. Expone	ent is	
		fixed at -13.				2000						
		Format			Linear,	two's co	mplem	ent bind	ary			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
5F	POWER_GOOD_OFF	Function					h Byte					YES
		Default Value	0	0	0	1	0	0	0	1		
		Bit Position	7	6	5	4	3	2	1	0	_	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	-	
		Function	0	1	0		v Byte	0	0	^	_	
		Default Value	0	1	0	0	1	0	0	0		

Tab	le 6	(contir	nued)
		(00	

Hex												Non-Volatile Memory	
Code	Command						ription					Storage	
		Sets the delay time	in ms c										
		Format			Linear,	two's d	compler	nent bind	ary				
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r	r	r	r	r	r	r/w			
60	TON_DELAY	Function		E	Exponer	nt			Mantis	sa		YES	
00	TON_DELAT	Default Value	1	1	1	1	1	0	0	0		fES	
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r/w	r/w	r/w	r/w		r/w	r/w	r/w			
		Function				-	antissa						
		Default Value	0	0	0	0	0	0	0	0			
		Sets the rise time in	n ms of t	he outp		<u> </u>	0				-		
		Format				-	compler	nent bind					
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r	R	r	r	r	r	r/w			
61	61 TON_RISE	Function			xponer				Mantis			YES	
<u> </u>		Default Value	1	0	1	1	1	0	1	1	4	. 25	
			Bit Position	7	6	5	4	3	2	1	0	4	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	-		
		Function				1	antissa			-	4		
		Default Value	1	1	1	1	1	1	1	1			
		Sets the delay time	in ms o								-		
		Format						nent bind					
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r	R	r	r	r	r	r/w			
64	TOFF_DELAY	Function		1	xponer			_	Mantis			YES	
• ·		Default Value	1	1	1	1	1	0	0	0	_		
		Bit Position	7	6	5	4	3	2	1	0	_		
		Access	r/w	r/w	r/w	r/w		r/w	r/w	r/w	_		
		Function Default Value	0	0	0	0	antissa 0	0	0	0	-		
			-	-	-		-	-	0	0			
		Sets the fall time in	ms of 1	ne outp							7		
		Format Bit Position	7	C				nent bind	· ·	0	-		
		Access	7	6	5 R	4	3	2	1	0 r/w	-		
		Function	r	r		r	r	r	r		-		
65	TOFF_FALL	Default Value	1	0	Exponer 1	1	1	0	Mantis: 1	1	-	YES	
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r/w	r/w	r/w	r/w		r/w	r/w	r/w	-		
		Function	17 VV	17 VV	17 VV		antissa	1/ VV	17 VV	17 VV	-		
		Default Value	1	1	1	1	1	1	1	1	1		
		Returns one byte o	finform			mmar	v of the	-		dulo fault			
		Format		GLIOTTW	nur u SU		signed E						
		Bit Position	7	6	5		4	3	2	1	0		
78	STATUS_BYTE	Access	r	r	R	+	r r	r	r	r	r	NO	
		Flag	X					VIN_UV		CML O			
		Default Value	0	0	0		01_00	0	0		0		
			÷	ÿ	v	10000	•		÷	-	•		
		Returns two bytes of Format	JI IIIIOff I	nuuon	with a S		nsigned		s iuui(/	warning	CONDICIONS		
		Bit Position	7	6		5	nsignea 4		2	1	0		
		Access	r	r b		s R	4 r	3 r	2 r	r	r		
		Flag		IOUT_0		X	X	PGOO		X	X		
79	STATUS_WORD	Default Value	0	0001_0		0	0	0		0	0	NO	
		Bit Position	7	6		5	4	3	2	1	0		
		Access	r	r		R	r r	r	r	r			
		Flag	X	OFF			IOUT O						
		Default Value	0	0		0	0	0	0	0	0		
		Benault Vulue	5	v	1	~	U	U	U	0	v		

Hex	Command				Brief De	esc <u>rip</u>	tio <u>n</u> _						Non-Volatile
Code		Returns one byte of	informat	ion				0.000	dulo's	outout	voltage		Memory Storage
		related faults	mormat	.1011 \	with the	status	SOLU	emo	uule s	ουιρυι	voltage		
		Format	Unsigned Binary										
7A	STATUS_VOUT	Bit Position	7		6 5 4						. 0		NO
		Access	r		r		r r						
		Flag	VOUT_0	OV									
		Default Value	0		0 ()	0		0	0 0	0		
		Returns one byte of information with the status of the module's output current related faults Format Unsigned Binary											
		Format					gned I		y				
7B	STATUS_IOUT	Bit Position	7		6 5	4		3		2	1 0		NO
		Access	r		r r	r		r		r	r r		
		Flag	IOUT_O)C	XX		1001		WARN		XX		
		Default Value	0		0 0	0		0		0	0 0		
		Returns one byte of	finformat	ion v	with the	status	s of th	e mo	dule's	input r	elated fa	ults	
		Format				Uns	igned	Bino	ry				
		Bit Position	7		6		5		4	3	2 1	0	
7C	STATUS_INPUT	Access	r		r		r		r	r	r r	r	NO
		Flag	VIN_OV_	_FAU	JLT _WA	RNI	VIN_L WARN		VIN_ _FAU		x x	х	
		Default Value	0		C		0		0	0	0 0	0	
		faults											
		Format	_			Unsig				_			
7D	STATUS_TEMPERATURE	Bit Position	7		6		5	4	3		1 0		
		Access Flag	r OT_FAL	ΠТ	r OT W	ARN	r X	r X	r X		r r X X	-	
		Default Value	01_1A0		01_00		0	0	0		0 0		
		Returns one byte of information with the status of the module's communication related faults											
		Format				Unsia	ned B	inarv	,			1	
		Bit Position	7		6	5	4	3	2	1	0		
7E	STATUS_CML	Access	r		r	r	r	r	r	r	r		
		Flag	Invalio Comma		Invalid Data	PEC Fail	х	Х	х	Othe Comr	n X		
		Default Value	0		0	0	0	0	0	Faul ⁻ 0	0	1	
							<u> </u>		النا	-		1 -+ C	
		Returns the value of Format	t the inpu								is fixed (at -6 1	
		Bit Position	7	6	Linear, t	wosc 4		emer 3	1t bind 2	ry 1	0	1	
		Access	r	r	r	4 r		r	r	r	r	1	
		Function			Expone					Mantis		1	
88	READ_VIN	Default Value	1	1	0	1		0	V	V	V	1	
		Bit Position	7	6	5	4		3	2	1	0]	
		Access	r	r	r	r		r	r	r	r		
		Function	L		.		antiss				1 .		
		Default Value	V	V	V	V		V	V	V	V		
		Returns the value of Format	f the outp		oltage o Linear, t						d at -13	1	
		Bit Position	7	6	5	4		3	2	1	0	1	
		Access	r	r	r	r		r	r	r	r	1	
8B	READ_VOUT	Function			·	M	antiss	a]	
00		Default Value	V	V	V	V		V	V	V	V	l	
		Bit Position	7	6	5	4		3	2	1	0	ł	
		Access	r	r	r	r		r a	r	r	R		
		Function Default Value	V	V	V	M V	antiss	a V	V	V	V	ł	
			V	V	V	V		v	V	V	V	J	

Hex Code	Command				Brief De	escriptio	on					Non-Volatile Memory Storage
		Returns the value o	f the e	itout cu	rrent of	the mo	dule					
		Format	i the ot		inear, ti			nt hina	n.			
		Bit Position	7	6	5	4	3	2	y 1	0		
		Access	r	r	r	r	r	r	r	r		
		Function			Exponer				Mantiss			
8C	READ_IOUT	Default Value	1	1	1	0	0	V	V	u V		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	R		
		Function					tissa		'			
		Default Value	V	V	V	V	V	V	V	V		
		Returns the module	induc	tor tom	poratur	o in °C						
		Format	muuc		inear, t		mnleme	nt hina	rv.			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
		Function			Exponer				Mantiss			
8D	READ_TEMPERATURE_1	Default Value	1	1	1	0	1	V	V	V		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
		Function	1	'	1 1		tissa	1 '				
		Default Value	V	V	V	V	V	V	V	V		
		Returns the module	PWM	controlle	er temp	erature	in °C					
		Format			inear, tv			ent bina	ry			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
		Function			xponer		·		Mantiss			
8E	READ_TEMPERATURE_2	Default Value	1	1	1	0	1	V	V	V		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
		Function			. ·		tissa		·			
		Default Value	V	V	V	V	V	V	V	V		
			eturns the switching Frequency of the converter. The Frequency is in Kilohertz and s read only, consisting of two bytes. Format Linear, two's complement binary								and	
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
95	READ_FREQUENCY	Function			xponer				Mantiss			
,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		Default Value	0	0	0	0	0	0	0	1		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
		Function				Mar	itissa					
		Default Value	1	0	0	1	0	0	0	0		
		Returns one byte in	dicatin	g the m					pec. 1.1	(read or	nly)	
		Format				Unsigne	ed Binar	у				
98	PMBUS_REVISION	Bit Position	7	6	5	4	3	2	1	0		YES
		Access	r	r	r	r	r	r	r	r		
		Default Value	0	0	1	0	0	0	1	0		
		Returns the minimu Format Bit Position Access	im inpu 7 r		ie the m inear, tu 5 r					t (read o 0 r	inly)	
		Function			Exponer		•		Mantiss			1150
AO	MFR_VIN_MIN	Default Value	1	1	0	0	0	0	1	0		YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
		Function		•		Mar	itissa	•	•	-		
		Default Value	0	1	1	0	0	1	1	0		

Hex Code	Command	Brief Description										Non-Volatile Memory Storage
-coue		Returns the minimu				ihle fr	om th	e mod	uletree	nd only)		Fiemory Storuge
		Format	μιιουιμ		inear, tv	NO'S CO	mnlei	ment k	ne net			
		Bit Position	7	6	5	4	3		2	1	0	
		Access	r	r	r	r	r		r	r	r	
		Function	'				ntissa					
A4	MFR_VOUT_MIN	Default Value	1	0	1	0	0		0	1	1	YES
		Bit Position	7	6	5	4	3		2	1	0	
		Access	r	r	r	r	r		r	r	r	
		Function					ntissa					
		Default Value	1	1	0	1	0		1	1	0	
			_		Ţ						-	
		Returns module na	me info	rmation	(read o	nlv)						
		Format		mation		Jnsign	od Rir	narv				
		Bit Position	7	6	5	4	3		2	1	0	
		Access	r	r	r	r	r		r	r	r	
		Function	1	I	I		served		1	1	1	
D0	MFR_SPECIFIC_00	Default Value	0	0	0	0	0		0	0	0	YES
		Bit Position	7	6	5	4	3		2	1	0	
		Access										
			r	r	r	r	r		r	r Decer	r	
		Function	0		Module				_	Reserve		
		Default Value	0	0	1	0	1		0	0	0	
		Poturne module inf	ormatio	n /read	only							
		Returns module inf Format	ormatio	iii (read	uniy)	line	2004 0	liner			1	
			7	6			gned E		2	1	0	
		Bit Position	7	6	5		4	3	2	1	0	
		Access	r	r	r		r Iula Ni	r	r	r	r	
		Function	0	1		-	dule No		0	1	0	
		Default Value	0	1	0		1	0	0	1	0	
		Bit Position	7	6	5		4	3	2	1	0	
		Access	r	r	r		r	r	r	r	r	
		Function	-				dule No			1 -	-	
		Default Value	0	0	1		1	1	1	0	0	
		Bit Position	7	6	5		4	3	2	1	0	
		Access	r	r	r		r	r	r	r	r	
		Function					dule N					
		Default Value	0	0	C		0	0	1	1	0	
		Bit Position	7	6	5	,	4	3	2	1	0	
		Access	r	r	r		r	r	r	r	r	
		Function					dule N	ame		-		
		Bit Position	7	6	5		4	3	2	1	0	
D1	MFR_SPECIFIC_01	Access	r	r	r		r	r	r	r	r	YES
		Function				Mod	dule N	ame		-		
		Default Value	0	0	1		0	0	0	1	0	
		Bit Position	7	6	5	,	4	3	2	1	0	
		Access	r	r	r		r	r	r	r	r	
		Function				Mod	dule N	ame				
		Default Value	0	0	1		1	0	0	1	0	
		Bit Position	7	6	5		4	3	2	1	0	
		Access	r	r	r		r	r	r	r	r	
		Function				Mod	dule N	ame				
		Default Value	0	0	C)	1	0	0	0	0	
		Bit Position	7	6	5	5	4	3	2	1	0	
		Access	r	r	r		r	r	r	r	r	
		Function				Mod	dule N	ame				
		Default Value	0	0	C)	0	0	1	1	0	
		Bit Position	7	6	5		4	3	2	1	0	
			1	1						-		
		Access	r	r	r		r	r	r	r	r	

		Tab	ole 6 (c	contin	ued)							
Hex Code	Command				Brief	Descrip	otion					Non-Volatile Memory Storage
DB	MFR_VOUT_MARGIN_HIGH	Returns the target	voltage	e for ma	rgining	the out	out hig	h. Expor	ient is fi	xed at	-13.	YES
		Format			Linear, t	wo's co	mplem	ent bina	ry			
1		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
		Function			Expone	nt			Mantiss	a		
		Default Value	V	V	V	V	V	V	V	V		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	R		
		Function		-			ntissa					
		Default Value	V	V	V	V	V	V	V	V		
		Returns the target v	voltage							d at -1	3	
		Format					npleme	nt binar	У			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
DC	MFR_VOUT_MARGIN_LOW	Function				Man						YES
DC		Default Value	V	V	V	V	V	V	V	V		125
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
		Function				Man						
		Default Value	V	V	V	V	V	V	V	V		
		Returns the index d	erived f	rom the		r strapp Jnsigne			E pin of	the mo	odule.	
		Bit Position	7	C					1	0		
DD	MFR_RTUNE_INDEX	Access	7 r	6 r	5 r	4 r	3 r	2 r	1 r	0 r		YES
		Function	1	I	I			I	I	1		
		Default Value	V	V	V	Rese V	V	V	V	V		
		Corresponding PME Format Bit Position Access Function	7 r	6 r	5 r	Jnsigne 4 r Rese	d Binar 3 r rved	y 2 r	1 r	0 r		
		Default Value	0	0	0	0	0	0	0	1		
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r	r		
DF	MFR_WRITE_PROTECT	Function	-		Descrip			-	1	4		YES
UF	MIN_WINTE_FRUIEU	Default Value	1	1	1	1	1	1	1	1	l	163
		Bit 0: ON_OFF_CON Bit 1: IOUT_CAL con Bit 2: IOUT_OC_FAL Bit 3: IOUT_OC_FAL Bit 4: OT_FAULT_LIN Bit 5: OT_FAULT_RE Bit 6: TOFF_MAX_W Bit 7: MFR_EXT_TEM Bit 8: MFR_PHASE_(Bit 9: MFR_SPECIFIC	nmand JLT_LIM JLT_RES MIT SPONSE (ARN_LI 1P_CAL_ CONTRC	IT PONSE E MIT _OFFSET	J	h IOUT_	CAL_G	AIN and	IOUT_C	AL_OFF	SET	
		Gets or sets the tar						f the dev	ice, in v	olts. Se	tting a	
		non-zero value here	e will en					nt hin			1	
		Format Bit Position	7					nt binar		0		
			7 r	6 r	5 r	4 r	3 r	2 r/w	1 r	0 r		
50		Access	r	r		r +	r		r 1anticco			YES
EO	MFR_VOUT_OFF	Function Default Value	1	1	xponer 0	0	0	0	1antisso 0	ı V		TES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r r	r/w	r/w	r/w	r/w	r/w		
		Function	1	l í	l '	Man		17 VV	1/ VV	1 / VV		
		Default Value	V	V	V	V	V	V	V	V		
			v	v	v	v	v	v	v	v	1	

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Table 6 (continued)

Hex Code	Command	Brief Description										Non-Volatile Memory Storage
E7	MFR_FEATURES_CONTROL	Allows user to enab Format Bit Position Access Function Default Value Bit Position Access Function Default Value Bit 0: VTRACK ENAB Bit 1: SYNC ENABLE Bit 2: SYNC IN/OUT, Bit 3: SYNC Edae, 0	7 r 0 15 r 0 8LE, 0 = 1 c, 0 = Dis 0 = Syn	6 r 0 14 r See 0 Disabler; sabled; c signa	5 r 13 r e Descrij 0 d; 1 = Er 1 = Endt	Unsigne 4 r Rese 0 12 r otion Be 0 nabled oled	d Binar 3 r/w erved 0 11 r elow 0	2 r/w 0 10 r	1 r/w 9 r	0 r/w 0 8 r		YES

Digital Power Insight (DPI)

GE offers a software tool that set helps users evaluate and simulate the PMBus performance of the GDT080 modules without the need to write software.

The software can be downloaded for free at <u>http://go.ge-energy.com/DigitalPowerInsight.html</u>. A GE USB to I2C adapter and associated cable set are required for proper functioning of the software suite. For first time users, the GE DPI Evaluation Kit can be purchased from leading distributors at a nominal price and can be used across the entire range of GE Digital POL Module.

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Thermal Considerations

Power modules operate in a variety of thermal environments; however, sufficient cooling should always be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test set-up is shown in Figure 38. The preferred airflow direction for the module is shown in Figure 39.

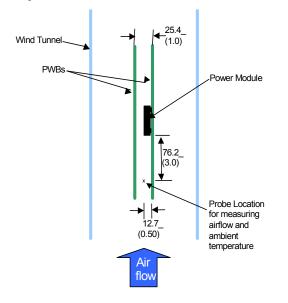


Figure 38. Thermal Test Setup.

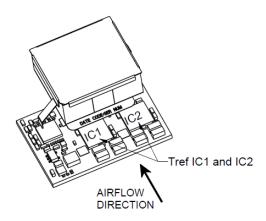


Figure 39. Preferred airflow direction and location of hotspot of the module (Tref).

The thermal reference points, T_{ref} used in the specifications are also shown in Figure 39. For reliable operation the temperatures at these points should not exceed 120°C. The output power of the module should not exceed the rated power of the module (Vo,set x lo,max).

Please refer to the Application Note "Thermal Characterization Process For Open-Frame Board-Mounted Power Modules" for a detailed discussion of thermal aspects including maximum device temperatures.

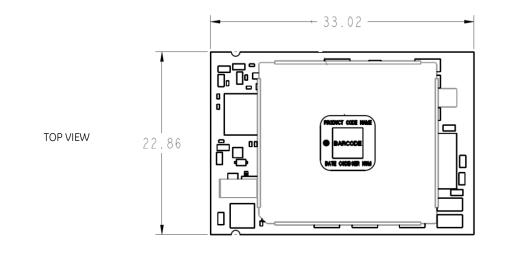
Example Ap <u>Requirement</u> Vin: Vout: Iout: ΔVout: Vin, ripple	pplication Circuit ts: 12V 1.2V 80A max., worst case load transient is from 20A to 60A 1.5% of Vout (18mV) for worst case load transient 2% of Vin (220mV p-p)	
Vin+ CI3	VIN VOUT VS+ PGOOD MODULE CLK CLK DATA ADDR0 SMBALRT# ADDR1 SIG_GND SYNC GND VS+	Vout+
GND CI1 CI2 CI3 CO1 CO2 CO3 RTune RTrim	Decoupling cap - 1x0.1µF/16V ceramic capacitor (e.g. Murata LLA215R71A224MA14) 6x22µF/16V ceramic capacitor (e.g. Murata GRM32ER61C226KE20) 470µF/16V bulk electrolytic Decoupling cap - 1x0.047µF/16V ceramic capacitor (e.g. Murata LLA215R71A224MA14) 6 x 47µF/6.3V ceramic capacitor (e.g. Murata GRM31CR60J476ME19) 5 x 1000µF/2.5V Polymer (e.g. Sanyo Poscap) 4.22kohms SMT resistor (can be 1206, 0805 or 0603 size) 2kΩ SMT resistor (can be 1206, 0805 or 0603 size, recommended tolerance of 0.1%)	GND

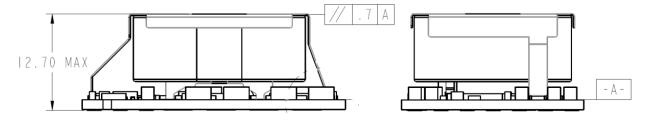
GE

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Mechanical Outline

Dimensions are in millimeters and (inches). Tolerances: x.x mm \pm 0.5 mm (x.xx in. \pm 0.02 in.) [unless otherwise indicated] x.xx mm \pm 0.25 mm (x.xxx in \pm 0.010 in.)



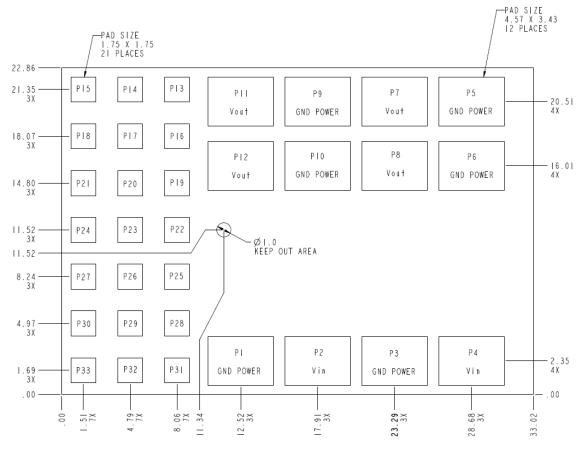


SIDE VIEWS

80A GigaDLynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Recommended Pad Layout



Pinout Details

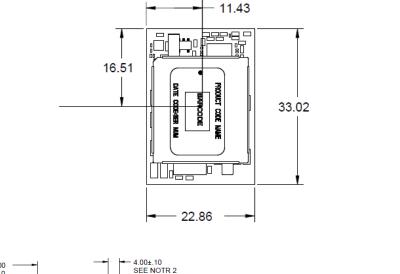
PIN	FUNCTION	PIN	FUNCTION	PIN	FUNCTION
1	GND	15	SEQ	29	SMBALERT#
2	VIN	16	VS+	30	NC
3	GND	17	SIG_GND	31	NC
4	VIN	18	NC	32	NC
5	GND	19	PGOOD	33	NC
6	GND	20	ADDR0		
7	VOUT	21	NC		
8	VOUT	22	SYNC		
9	GND	23	ADDR1		
10	GND	24	RTUNE		
11	VOUT	25	ON/OFF		
12	VOUT	26	CLK		
13	VS-	27	NC		
14	TRIM	28	DATA		

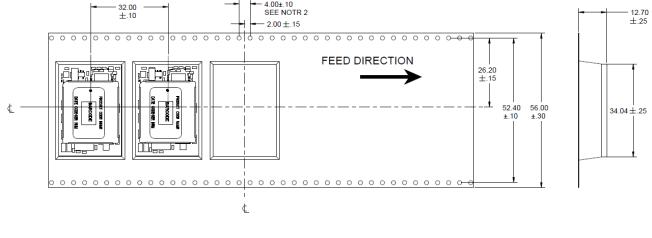
4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

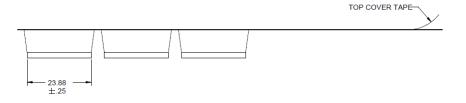
Packaging Details

The 80A GigaDLynx™ 80A modules are supplied in tape & reel as standard. Modules are shipped in quantities of 80 modules per reel.

All Dimensions are in millimeters and (in inches).







Reel Dimensions :

Outside Dimensions :	330.2 mm (13.00)
Inside Dimensions :	177.8 mm (7.00")
Tape Width:	56.00 mm (2.205")

Surface Mount Information

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Pick and Place

GE

The 80A GigaDLynx[™] modules use an open frame construction and are designed for a fully automated assembly process. The modules are fitted with a label designed to provide a large surface area for pick and place operations. The label meets all the requirements for surface mount processing, as well as safety standards, and is able to withstand reflow temperatures of up to 300°C. The label also carries product information such as product code, serial number and the location of manufacture.

Nozzle Recommendations

The module weight has been kept to a minimum by using open frame construction. Variables such as nozzle size, tip style, vacuum pressure and placement speed should be considered to optimize this process. The minimum recommended inside nozzle diameter for reliable operation is 10mm. The maximum nozzle outer diameter, which will safely fit within the allowable component spacing, is 17 mm.

Bottom Side / First Side Assembly

This module is not recommended for assembly on the bottom side of a customer board. If such an assembly is attempted, components may fall off the module during the second reflow process.

Lead Free Soldering

The modules are lead-free (Pb-free) and RoHS compliant and fully compatible in a Pb-free soldering process. Failure to observe the instructions below may result in the failure of or cause damage to the modules and can adversely affect long-term reliability.

Pb-free Reflow Profile

Power Systems will comply with J-STD-020 Rev. C (Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices) for both Pb-free solder profiles and MSL classification procedures. This standard provides a recommended forced-air-convection reflow profile based on the volume and thickness of the package (table 4-2). The suggested Pb-free solder paste is Sn/Ag/Cu (SAC). The recommended linear reflow profile using Sn/Ag/Cu solder is shown in Fig. 40. Soldering outside of the recommended profile requires testing to verify results and performance.

MSL Rating

The 80A GigaDLynx[™] modules have a MSL rating of 3.

Storage and Handling

The recommended storage environment and handling procedures for moisture-sensitive surface mount packages is detailed in J-STD-033 Rev. A (Handling, Packing, Shipping and Use of Moisture/Reflow Sensitive Surface Mount Devices). Moisture barrier bags (MBB) with desiccant are required for MSL ratings of 2 or greater. These sealed packages should not be broken until time of use. Once the original package is broken, the floor life of the product at conditions of \leq 30°C and 60% relative humidity varies

according to the MSL rating (see J-STD-033A). The shelf life for dry packed SMT packages will be a minimum of 12 months from the bag seal date, when stored at the following conditions: < 40° C, < 90% relative humidity.

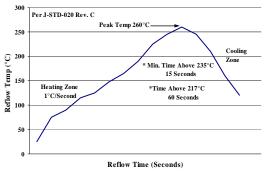


Figure 40. Recommended linear reflow profile using Sn/Ag/Cu solder.

Post Solder Cleaning and Drying Considerations

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to *Board Mounted Power Modules: Soldering and Cleaning* Application Note (AN04-001).

80A GigaDLynx™: Non-Isolated DC-DC Power Modules

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

Ordering Information

Please contact your GE Sales Representative for pricing, availability and optional features.

Table 7. Device Codes

Device Code	Input Voltage Range	Output Voltage	Output Current	On/Off Logic	Sequencing	Comcodes
GDT080A0X3-SRZ	4.5 – 14Vdc	0.6 – 2.0 Vdc	80A	Negative	Yes	150037110
GDT080A0X43-SRZ	4.5 – 14Vdc	0.6 – 2.0 Vdc	80A	Positive	Yes	150044134

-Z refers to RoHS compliant parts

Table 8. Coding Scheme

Package Identifier	Family	Sequencing Option	Output current	Output voltage	On/Off logic	Remote Sense	Options		ROHS Compliance
G	D	Т	080A0	х		3	-SR	-H	Z
P=Pico U=Micro M=Mega G=Giga	D=Dlynx Digital V = DLynx Analog.	T=with EZ Sequence X=without sequencing	80A	programm	4 = positive No entry = negative	3 = Remote Sense	S = Surface Mount R = Tape & Reel	Extra Ground Pins	Z = ROHS6

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