## CP2000AC48TEZ-FB2 Compact Power Line High Efficiency Rectifier

Input: 100-120/220-240 Vac; Output: 2250W @ 48Vdc; 5 Vdc @ 4W



### **Applications**

Description

• Wide band power amplifiers

### **Features**

- Efficiency 95%
- Compact 1RU form factor providing 30 W/in3
- 2250W @ 52V from nominal 220 240Vac
- 1200W from nominal 100 − 120Vac (for V<sub>o</sub> > 30Vdc)
- Output voltage programmable from 18V 58Vdc
- PMBus compliant dual I<sup>2</sup>C and RS485 serial busses
- Power factor correction (meets EN/IEC 61000-3-2 and EN 60555-2 requirements)
- Output overvoltage and overload protection
- AC Input overvoltage and undervoltage protection
- Over-temperature warning and protection
- Redundant, parallel operation with active load sharing
- Redundant +5V Aux power
- Remote ON/OFF
- Hot insertion/removal (hot plug)
- Four front panel LED indicators
- UL\* Recognized to UL60950-1, CAN/ CSA<sup>†</sup> C22.2 No. 60950-1, and VDE<sup>‡</sup> 0805-1 Licensed to IEC60950-1
- CE mark meets 2006/95/EC directive§
- Internally controlled Variable-speed fan
- RoHS Directive 2011/65/EU and amended Directive (EU) 2015/863
- Special Foldback Curve

The CP2000AC48TEZ-FB Rectifier has an extremely wide programmable output voltage capability and fold-back current limiting features. High-density front-to-back airflow is designed for minimal space utilization and is highly expandable for future growth. This custom rectifier incorporates both RS485 and dual-redundant I<sup>2</sup>C communications busses that allow it to be used in a broad range of applications. Feature set flexibility makes this rectifier an excellent choice for a set of applications requiring operation over a wide output voltage range.

- \* UL is a registered trademark of Underwriters Laboratories, Inc.
- + CSA is a registered trademark of Canadian Standards Association.
- **‡** VDE is a trademark of Verband Deutscher Elektrotechniker e.V.
- S This product is intended for integration into end-user equipment. All the required procedures for CE marking of end-user equipment should be followed. (The CE mark is placed on selected products.)
- $^{**}$  ISO is a registered trademark of the International Organization of Standards.



# GE

## CP2000AC48TEZ-FB Rectifier

Input: 100-120/220-240 Vac; Output: 2250W @ 48Vdc; 5 Vdc @ 4W

### **Electrical Specifications**

Input		_				
Pa	rameter	Min	Тур	Max	Units	Notes
Startup Input Vo Low-line Op High-line Op	eration			90 200		
Operating Voltage Range Low-line Configuration High-line Configuration		90 200	100, 110, 120 220 - 240	140 265	Vac	
Surges (no dam	age)	305				
Input Frequency		47		66	Hz	
Input Current	Input Current			12 13.5	А	At 110 Vac At 240 Vac
Inrush Transient	t		25	30	Apk	Measured at 25°C for all line conditions; does not include X-Capacitors charging.
Input Leakage C	urrent		2.5	3.5	mA	Measured at 265Vac, 60Hz
Power Factor		0.96	0.98			From 50% to 100% (2250W @ HL, 1200W @ LL). load
Ffficience 1	30 – 90% of FL	93	95		%	With or'ing function, aux 5V output, dual/redundant I²C and RS485 communications and POE isolation
Efficiency <sup>1</sup>	>38V	85			%	>30% load Test condition: input; 240Vac, 60hz, output; 52Vdc
Holdup			20 30		ms	48Vdc, Measurement starts at zero crossing of the ac voltage, and voltage decayed to 40V. ← For loads below 1200W.
Ride thru		1/2	1		cycle	Tested at nominal 115V and 230V . Complies to CISPR24 standards
Power Fail Warr	ning <sup>2</sup>	3	5		ms	Alarm issued via PFW signal going LO 5 ms prior to the main output decaying below 40Vdc.

Main Output					
Parameter	Min	Тур	Max	Units	Notes
Output Power	1200 2250			w	Above 30Vdc from nominal 90-120Vac upto 55°C. Above 48Vdc from nominal 200-265Vac upto 55°C
Default Set point		48		Vdc	Output floats with respect to frame ground.
Overall Regulation <sup>3</sup>	-1 -2		+1 +2	%	0 – 45C, minimum load 2.5A > 45C
Output Voltage Set Range	18		58	Vdc	Analog margining and RS485
	18		58	Vdc	Set by I <sup>2</sup> C
Output current	1 1		23 43.3	А	1200W @ 52V @ 90-120Vac. 2250W @ 52V @ 200-240Vac.

<sup>&</sup>lt;sup>1</sup> At 52Vdc, 240Vrms and 25°C.

<sup>&</sup>lt;sup>2</sup> Internal protection circuits may override the PFW signal and may trigger an immediate shutdown.

<sup>&</sup>lt;sup>3</sup> Includes all variations due to specified load range, drift, and environmental conditions.

Input: 100-120/220-240 Vac; Output: 2250W @ 48Vdc; 5 Vdc @ 4W

### Electrical Specifications (continued)

Main Output	Parar				Min	Тур	Max	Units				Note	20		
Current Share	Falai	leter		> 42V	-5	TYP	5	Onits		ompared to	the aver			dolivorod	by a
Current Share				> 42 V < 42 V	-5 -10		5 10	%FL		ompared to et of Rectifie			current	uenvered	uyd
Output Ripple										-					
RMS (5Hz t						60	100	mVrms		leasured wit			th under	any condi	tion of
Peak-to-Pe	ak (5Hz to 20	)MHz)					500	mVp-p	mVp-p loading. Minimum load		d is 1A.				
External Bulk L	oad Capacita	ince			0		5,000	μF	w	xternal capa vill not meet	its turn-(	ON rise tir	ne requir	ement.	
Turn-On						_		_		Aonotonic Tu					
Delay Rise Time - S	andard (PM	Bus)				5 100		s ms		°C operatior nom below			On from	60% to 10	JU% OT
	-Telecom (					5		S			o o ope.	utioni			
Overshoot							2	%							
Load Step Res	oonse						50	%FL	$\Delta$	$1/\Delta t$ slew rate the set the set the set of the set o	te 1A/µs.	rogulatia	n roquire	monte	
$\Delta I$ $\Delta V$						2.0	50	%FL Vdc		ettiing time ' Ainimum loa				ments.	
	Response Time					2		ms				P	1		
		Power	r Limit – hig	gh line	2250			W							
		Powe	er limit – lo	ow line	1200			W							
	The over					sot ~ 5%	ahovo +	he load on	/elone	shown horo					
	ine overn	The overload current limit threshold should be set $\cong$ 5% above the load envelope shown here													
								Hine Line	e						
	Vo(V)	18	20	23	25	28	32	36	38	48	50	53	56	58	1
	Io(A)	20.7	24.3	23	33.3	38.6	43.4	45.8	46.9		45	42.5	40.2	38.8	
			Vo(V)												
		60													
			<u> </u>		-										
			55 -												
			50 -			<b>.</b>					$\searrow$				
Permissible			48				un								
Load			45 -				C AOWE								
Boundary			40				- China - Chin	<u>*</u>							
			38 – –									250			
			35								//-	1-10			
			30 – –							<u> </u>		•			
									and the second		St North				
			25 -					-104	=30V)	<sub>107</sub> 0	2				
			20			San Street St	1794*Vo-11	1.595[1.8v<=Vo<							
			<u>–</u>			10=	441 T								
			15 – 15		20	25			- <b></b> - 5	40	 45	5	<b>Io(A)</b>		
	1				-				v Line						
								LOV							
	Vo(V)	18	2.0	23	25	28	32	36	38	48	50	53	56	58	1
	Vo(V) Io(A)	18 20.7	20 24.3	23 29.7	25 33.3	28 38.6	32 37.5	36 33.3	38 31.6	48 25	50 24	53 22.6	56 21.4	58 20.7	

<sup>4</sup> Below -5°C, the rise time is approximately 5 minutes to protect the bulk capacitors.

Input: 100-120/220-240 Vac; Output: 2250W @ 48Vdc; 5 Vdc @ 4W

	Contract terms are for supporting all loads inside the load map. The customer will develop a control interface which maintains the operating voltage and current so as to not exceed the load map.
,	Units should be able to be plugged in one at a time and guarantee system start up. Units should stay in current limit for approximately 20 seconds to guarantee restart.

### Electrical Specifications (continued)

Main Output (continued)								
Over-voltage								
Delayed			60	Vdc	200msec delayed shutdown to be implemented.			
Immediate Latchoff			65	Vdc	Instantaneous shutdown above this point.			
	Three restart attempts may be implemented within a one minute window prior to a latched shutdown							
Over-temperature								
Warning		5		°C	Implemented prior to commencement of an OT shutdown			
Shutdown		20		°C	Below the maximum rating of the device being protected			
Auto-recoverable	Tempera	ture hyste	eresis of	approximately	10°C provided between shutdown and restart.			
Overcurrent events that exceed the envelope by 5% v	vill hiccup	continuou	Isly at a	frequency of ap	proximately once every 20 seconds. For voltage set- points			
below 42V, a tracking Under Voltage shutdown occu	rs at 2 volt	s below s	et-point.	UV must exhib	it for more than 1 second before shutdown. UV shutdown			
will exhibit the same 20 second hiccup behavior.								

Electrical Specifications (continued)									
Auxiliary Output									
Parameter	Min	Тур	Max	Units	Notes				
Output Voltage Setpoint		5		Vdc					
Output Current	0.005		0.75	А					
Overall Regulation	-10		+5	%	Within ±5% when load is < 0.5A.				
Ripple and Noise		50	100	mVpk-pk	20MHz bandwidth				
Over-voltage Clamp			7	Vdc					
Over-current Limit	110		175	%FL					

Input: 100-120/220-240 Vac; Output: 2250W @ 48Vdc; 5 Vdc @ 4W

Environmental, EMC, Re	<u> </u>	-						
Environmental		[						
Parameter	Min	Тур	Max	Units	Notes			
Ambient Temperature								
Operating	-405		55	°C	Air inlet from sea level to 5,000 feet.			
Derating		1	2	°C	Per 1,000 feet above 5,000 feet.			
Storage Temperature	-40		85	°C				
Humidity	5		95	%	Relative humidity, non-condensing			
Altitude	-60		4000	m	For operation above 2500m (5000 ft.), maximum operating			
Altitude	-200		13000	ft	temperature is derated by 2°C per 305m (1000 ft.).			
Shock and Vibration					IPC9592 sections 5.2.8 – 5.2.13			
Earthquake Rating	4			Zone	Per Telcordia GR-63-CORE, all floors, when installed in CP Shelf.			
Acoustic Noise	Noise is proportional to fan speed, load and ambient temperature.							
Harmonic Emissions	Per EN/IEC61000-3-2							
Radiated Emissions <sup>6</sup>	Exceeds FCC and CISPR22 (EN55022) - Class A by a 6dB margin							
Conducted Emissions - ac	Exceeds FCC and CISPR22 (EN55022) Class A Telcordia GR-1089-CORE - Class A by a 6dB margin							
ESD	Error free	per EN/IEC 610	00-4-2 Level	3 (6 kV con	tact discharge, 8 kV air discharge).			
Radiated Immunity	Error free	per EN/IEC 610	00-4-3 Level	3 (10 V/m)				
Electrical Fast Transient Burst	Error free	per EN/IEC 610	00-4-4 Level	3 (2 kV, 5 k	Hz repetition rate)			
Lightning Surge, Error Free Damage Free		)00-4-5 Level 4 41 Level A3 (6 k	•	,	kV differential mode). tial mode)			
Line sags and interruptions					n or 25% sag (115V, 230V – nominal for UUT) for 2 seconds the An input sag below 80V may cause an immediate shutdown.]			
Conducted Immunity	Error free	per EN/IEC 610	00-4-6 Level	3 (10Vrms)				
Reliability (calculated)		450,000		Hours	At ambient of 25°C at full load per Telcordia SR-332, issue 2, Reliability Prediction for Electronic Equipment, Method I Case III.			
Isolation								
Input-Chassis/Signals	1500			Vrms	Per EN60950.			
Input - Output	3000			Vrms	Consult factory for testing to this requirement			
Output-Chassis	500			Vdc	Internal Lineage standard, GR_947			
Output-Chassis/Signals	2250			Vdc	POE compliant Rectifier, Per IEEE802.3.			
Service Life		10		Years	25°C ambient, full load excluding fans.			

<sup>&</sup>lt;sup>5</sup> Designed to start and work at an ambient as low as -40°C, but may not meet operational limits until above -5°C

<sup>&</sup>lt;sup>6</sup> Radiated emissions compliance was met using a Lineage Power shelf. This shelf includes output common and differential mode capacitors that assist in meeting compliance.

Input: 100-120/220-240 Vac; Output: 2250W @ 48Vdc; 5 Vdc @ 4W

#### **Control and Status**

GF

The Rectifier provides three means for monitor/control: analog, PMBus™, or the GE Galaxy-based RS485 protocol.

Details of analog control and the PMBus<sup>™</sup> based protocol are provided in this data sheet. GE will provide separate application notes on the Galaxy RS485 based protocol for users to interface to the rectifier. Contact your local GE representative for details.

#### **Signal Reference**

Unless otherwise noted, all signals are referenced to

Logic\_GRD. See the Signal Definitions Table at the end of this

document for further description of all the signals.

Logic\_GRD is isolated from the main output of the power supply for PMBus communications. Communications and the 5V standby output are not connected to main power return (Vout(-)) and can be tied to the system digital ground point selected by the user. (Note that RS485 communications is referenced to Vout(-), main power return of the power supply).

Logic\_GRD is capacitively coupled to Frame\_GRD inside the power supply. The maximum voltage differential between Logic\_GRD and Frame\_GRD should be less than 100V<sub>DC</sub>.

#### **Control Signals**

**Enable:** Controls the main  $48V_{DC}$  output when either analog control or PMBus protocols are selected, as configured by the Protocol pin. This pin must be pulled low to turn **ON** the rectifier. The rectifier will turn **OFF** if either the **Enable** or the **ON/OFF** pin is released. This signal is referenced to Logic\_GRD. In RS485 mode this pin is ignored.

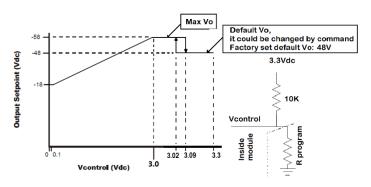
**ON/OFF:** This is a shorter pin utilized for hot-plug applications to ensure that the rectifier turns **OFF** before the power pins are disengaged. It also ensures that the rectifier turns **ON** only after the power pins have been engaged. Must be connected to  $V_OUT(-)$  for the rectifier to be ON.

**Margining:** The  $48V_{DC}$  output can be adjusted between  $18 - 58V_{DC}$  by a control voltage on the Margin pin. This control voltage can be generated either from an external voltage source, or by forming a voltage divider between 3.3V and Logic\_GRD, as shown in Fig. 13. The power supply includes the high side pull-up  $10k\Omega$  resistor to  $3.3V_{DC}$ . Connecting a resistor between the margin pin and Logic\_GRD will complete the divider.

An open circuit, or a voltage level >  $3.0V_{DC}$ , on this pin sets the main output to the factory default setting of  $48V_{DC}$ .

Hardware margining is only effective until software commanded output voltage changes are not executed. Software commanded output voltage settings permanently override the hardware margin setting until power to the internal controller is interrupted, for example if input power or bias power is recycled.

The controller always restarts into its default configuration, programmed to set the output as instructed by the margin pin. Subsequent software commanded settings permanently override the margin pin. Adding a resistor between margin and Vout(-) is an ideal way of changing the factory set point of the rectifier to whatever voltage level is desired by the user.



## Figure 13. Diagram showing how output can be margined using Vcontrol adjustment.

**Module Present Signal:** This signal has dual functionality. It can be used to alert the system when a rectifier is inserted. A  $500\Omega$  resistor is present in series between this signal and Logic\_GRD. An external pull-up should not raise the voltage on the pin above  $0.25V_{DC}$ . When the voltage on this pin exceeds  $1V_{DC}$ , the write\_protect feature of the EEPROM is enabled.

**8V\_INT:** Single wire connection between modules, Provides bias to the DSP of an unpowered module.

**Reset:** This is a PCA9541 multiplexer function utilized during PMBus communications. If momentarily grounded (Logic\_GRD), the multiplexer would reset itself.

**Protocol:** Establishes the communications mode of the rectifier, between analog/PMBus and RS485 modes. For RS485, connect a  $10k\Omega$  pull-down resistor from this pin to V\_OUT( - ). For analog/PMBus leave the pin open. Do not tie this signal pin to V\_OUT( - ) because that connection configures the internal DSP into a reprogrammed state.

Unit Address: Each module has an internal  $10k\Omega$  resistor pulled up between unit\_address and  $3.3V_{DC}$ . A resistor between unit\_address and Vout(-) sets the appropriate unit address.

			I <sup>2</sup> C ad	dress
Rectifier	<b>Resistor Value</b>	Nominal voltage	A1	A0
1	30K	2.477	0	0
2	14K	1.925	0	1
3	6K	1.243	1	0
4	2.5K	0.654	1	1

Shelf Address: By applying the required voltage between the shelf address pin and Vout(-), up to 8 different shelves and so up to 32 different modules can be addressed using either the PMBus or GE Galaxy based RS485 protocol.

PMBus addressing is limited to a maximum of 8 modules and so the software decodes the shelf address setting into either shelf 0 or shelf 1 in PMBus applications. If more than two shelves are paralleled, the user must separate the I<sup>2</sup>C lines so that address conflicts do not occur.

Shelf_address	1	2	3	4
Maximum voltage	3.45	2.97	2.56	2.14
Nominal voltage	3.30	2.86	2.4	1.96
Minimum voltage	3.00	2.60	2.18	1.73
Address bit- A2	0	1	0	1

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100-120/200-277VAc input; Output: 2725W @ 52Vdc, 5VDC @ 4W

Shelf_address	5	6	7	8
Maximum voltage	1.70	1.25	0.80	0.25
Nominal voltage	1.50	1.10	0.60	0.01
Minimum voltage	1.29	0.84	0.30	0
Address bit- A2	0	1	0	1

#### **Status Signals**

Power Capacity: A HI on this pin indicates that the rectifier delivers high line rated output power; a LO indicates that the rectifier is connected to low line configured for 1200W operation.

**Power Fail Warning:** This signal is HI when the main output is being delivered and goes LO for the duration listed in this data sheet prior to the output decaying below the listed voltage level.

Fault: This signal goes LO for any failure that requires rectifier replacement. These faults may be due to:

- Fan failure
- Over-temperature warning
- Over-temperature shutdown
- Over-voltage shutdown
- Internal Rectifier Fault

### **Digital Feature Descriptions**

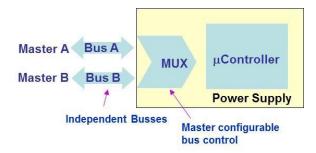
**PMBus™ compliance:** The power supply is fully compliant to the Power Management Bus (PMBus™) rev1.2 requirements with the following exceptions:

The power supply continuously updates its STATUS and ALARM registers to the latest state in order to capture the 'present' state of the power supply. There are a number of indicators, such as those indicating a communications fault (PEC error, data error) that do not get cleared until specifically instructed by the host controller sending a clear\_faults command. A 'bit' indicator notifies the user if the STATUS and ALARM registers changed since the last 'read' by the host controller.

For example, if a voltage surge causes a momentary shutdown for over voltage the power supply will automatically restart if the 'auto\_restart' feature is invoked. During the momentary shutdown the power supply issues an Alert# indicating to the system controller that a status change has occurred. If the system controller reads back the STATUS and ALARM registers while the power supply is shut down it will get the correct fault condition. However, inquiry of the state of the power supply after the restart event would indicate that the power supply is functioning correctly. The STATUS and ALARM indicators did not freeze at the original shutdown state and so the reason for the original Alert# is erased. The restart 'bit' would be set to indicate that an event has occurred.

The power supply also clears the STATUS and ALARM registers after a successful read back of the information in these registers, with the exception of communications error alarms. This automated process improves communications efficiency since the host controller does not have to issue another clear\_faults command to clear these registers. **Dual, redundant buses:** Two independent I<sup>2</sup>C lines provide true communications bus redundancy and allow two independent controllers to sequentially control the power supply. For example, a short or an open connection in one of the I<sup>2</sup>C lines does not affect communications capability on the other I<sup>2</sup>C line. Failure of a 'master' controller does not affect the power supplies and the second 'master' can take over control at any time.

Using the PCA9541 multiplexer: Transition between the two I<sup>2</sup>C lines is provided by the industry standard PCA9541 I<sup>2</sup>C master selector multiplexer. Option 01 of the device code is supplied which, upon start-up, connects channel 0 to the power supply. In this fashion applications using only a single I<sup>2</sup>C line can immediately start talking across the bus without first requiring to reconfigure the multiplexer.



# Figure 14. Diagram showing conceptual representation of the dual ${\rm I}^2 C$ bus system.

Control can be taken over at any time by a specific 'master' even during data transmission to the other 'master'. The 'master' needs to be able to handle incomplete transmissions in the multi-master environment in case switching should commence in the middle of data transmission.

Master/Slave: The 'host controller' is always the MASTER. Power supplies are always SLAVES. SLAVES cannot initiate communications or toggle the Clock. SLAVES also must respond expeditiously at the command of the MASTER as required by the clock pulses generated by the MASTER.

**Clock stretching:** The power supply may initiate clock stretching if it is busy. The 'slave' may keep the clock LO until it is ready to receive instructions. The maximum clock stretch interval is 25ms.

The host needs to refrain from issuing the next clock signal until the clock is released, or it needs to delay the next clock pulse beyond the clock stretch interval of the power supply.

Note that clock stretching occurs after the 9<sup>th</sup> (ACK) bit, the exception being the START command.

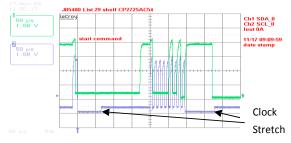


Figure 14. Example waveforms showing clock stretching.

### GE

## CP2725AC54TE CPL High Efficiency Rectifier

100-120/200-277VAc input; Output: 2725W @ 52Vdc, 5VDC @ 4W

**Communications speed:** Both 100kHz and 400kHz clock rates are supported. The power supplies default to the 100kHz clock rate.

Packet Error Checking: The power supply will not respond to commands without the trailing PEC. The integrity of communications is compromised if packet error correction is not employed. There are many functional features, including turning OFF the main output, that require validation to ensure that the correct command is executed.

PEC is a CRC-8 error-checking byte, based on the polynomial  $C(x) = x^8 + x^2 + x + 1$ , in compliance with PMBus<sup>TM</sup> requirements. The calculation is based in all message bytes, including the originating write address and command bytes preceding read instructions. The PEC is appended to the message by the device that supplied the last byte.

**SMBusAlert#:** The power supply can issue SMBAlert# driven from either its internal micro controller ( $\mu$ C) or from the PCA9541 I<sup>2</sup>C bus master selector. That is, the SMBAlert# signal of the internal  $\mu$ C funnels through the PCA9541 master selector that buffers the SMBAlert# signal and splits the signal to the two SMBAlert# signal pins exiting the power supply. In addition, the PCA9541 signals its own SMBAlert# request to either of the two SMBAlert# signals when required.

Non-supported commands: Non supported commands are flagged by setting the appropriate STATUS bit and issuing an SMBAlert# to the 'host' controller.

**Data out-of-range:** The power supply validates data settings and sets the data out-of-range bit and SMBAlert# if the data is not within acceptable range.

SMBAlert# triggered by the  $\mu$ C: The  $\mu$ C driven SMBAlert# signal informs the 'master/host' controller that either a STATE or ALARM change has occurred. Normally this signal is HI. The signal will change to its LO level if the power supply has changed states and the signal will be latched LO until the power supply receives a 'clear' instruction as outlined below. If the alarm state is still present after the 'clear\_faults' command has been received, then the signal will revert back into its LO level again and will latch until a subsequent 'clear' signal is received from the host controller.

The signal will be triggered for any state change, including the following conditions;

- VIN under or over voltage
- Vout under or over voltage
- IOUT over current
- Over Temperature warning or fault
- Fan Failure
- Communication error
- PEC error
- Invalid command
- Internal faults

The power supply will clear the SMBusAlert# signal (release the signal to its HI state) upon the following events:

- Completion of a 'read\_status' instruction
- Receiving a CLEAR\_FAULTS command
- The main output recycled (turned OFF and then ON) via the ENABLE signal pin
- The main output recycled (turned OFF and then ON) by the OPERATION command

SMBAlert# triggered by the PCA9541: If clearing the Alert# signal via the clear\_faults or read back fails, then reading back the Alert# status of the PCA9541 will be necessary followed by clearing of the PCA9541 Alert#.

The PCA9541 can issue an Alert# even when single bus operation is selected where the bus master selector has not been used or addressed. This may occur because the default state of the PCA9541/01 integrated circuit issues Alert# to both i<sup>2</sup>C lines for all possible transitioning states of the device. For example, a RESET caused by a glitch would cause the Alert# to be active.

If the PCA9541 is not going to be used in a specific application (such as when only a single I<sup>2</sup>C line is utilized), it is imperative that interrupts from the PCA9541 are de-activated by the host controller. To de-activate the interrupt registers the PCA9541 the 'master' needs to address the PCA9541 in the 'write' mode, the interrupt enable (IE) register needs to be accessed and the interrupt masks have to be set to HI '1'. (Note: do not mask bit 0 which transmits Alert# from the power supply). This command setting the interrupt enable register of the PCA9541 is shown below;

Start		Unit Address									
1	7	6	5	4	3	2	1	0	1		
S	1	1	1	0	A2	A1	A0	0	А		

Command Code	ACK	IE Register	Stop
8	1	8	
0x00	A	0x0E	Р

There are two independent interrupt enable (IE) registers, one for each controller channel (I<sup>2</sup>C-0 and I<sup>2</sup>C-1). The interrupt register of each channel needs to be configured independently. That is, channel I<sup>2</sup>C-0 cannot configure the IE register of I<sup>2</sup>C-1 or vise-versa.

This command has to be initiated to the PC9541 only once after application of power to the device. However, every time a restart occurs the PCA9541 has to be reconfigured since its default state is to issue Alert# for changes to its internal status.

If the application did not configure the interrupt enable register the Alert# line can be cleared (de-activated), if it has been activated by the PCA9541, by reading back the data from the interrupt status registers (Istat).

Refer to the PCA9541 data sheet for further information on how to communicate to the PCA9541 multiplexer.

Please note that the PCA9541 does not support Packet Error Checking (PEC).

**Re-initialization:** The I<sup>2</sup>C code is programmed to re-initialize if no activity is detected on the bus for 5 seconds. Re- initialization is designed to guarantee that the I<sup>2</sup>C  $\mu$ Controller does not hang up the bus. Although this rate is longer than the timing requirements specified in the SMBus specification, it

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had to be extended in order to ensure that a re-initialization would not occur under normal transmission rates. During the few µseconds required to accomplish re-initialization the  $I^2C$  µController may not recognize a command sent to it. (i.e. a start condition).

Global broadcast: This is a powerful command because it can instruct all power supplies to respond simultaneously in one command. But it does have a serious disadvantage. Only a single power supply needs to pull down the ninth *acknowledge* bit. To be certain that each power supply responded to the global instruction, a *READ* instruction should be executed to each power supply to verify that the command properly executed. The GLOBAL BROADCAST command should only be executed for write instructions to slave devices.

Note: The PCA9541 i2c master selector does not respond to the GLOBAL BROADCAST command.

**Read back delay:** The power supply issues the SMBAlert # notification as soon as the first state change occurred. During an event a number of different states can be transitioned to before the final event occurs. If a read back is implemented rapidly by the host a successive SMBAlert# could be triggered by the transitioning state of the power supply. In order to avoid successive SMBAlert# s and read back and also to avoid reading a transitioning state, it is prudent to wait more than 2 seconds after the receipt of an SMBAlert# before executing a read back. This delay will ensure that only the final state of the power supply is captured.

Successive read backs: Successive read backs to the power supply should not be attempted at intervals faster than every one second. This time interval is sufficient for the internal processors to update their data base so that successive reads provide fresh data.

Device ID: Address bits A2, A1, A0 set the specific address of the power supply. The least significant bit x (LSB) of the address byte configures write [0] or read [1] events. In a *write* command the system instructs the power supply. In a *read* command information is being accessed from the power supply.

		Address Bit							
	7	6	5	4	3	2	1	0	
PCA9541	1	1	1	0	A2	A1	A0	R/W	
Micro controller	1	0	0	0	A2	A1	A0	R/W	
External EEPROM	1	0	1	0	A2	A1	A0	R/W	
Global Broadcast	0	0	0	0	0	0	0	0	
MSB									

The **Global Broadcast** instruction executes a simultaneous *write* instruction to all power supplies. A *read* instruction cannot be accessed globally. The three programmable address bits are the same for all I<sup>2</sup>C accessible devices within the power supply.

#### PMBus<sup>™</sup> Commands

Standard instruction: Up to two bytes of data may follow an instruction depending on the required data content. Analog data is always transmitted as LSB followed by MSB. PEC is mandatory and includes the address and data fields.

8	1	8	1	8	1	1
Low data byte	А	High data byte	А	PEC	А	Р

#### Master to Slave Slave to Master

SMBUS annotations; S – Start , Wr – Write, Sr – re-Start, Rd – Read, A – Acknowledge, NA – not-acknowledged, P – Stop

**Direct mode data format:** The Direct Mode data format is supported, where  $y = [mX + b] \times 10^{R}$ . In the equation, y is the data value from the controller and x is the 'real' value either being set or returned. except for V<sub>IN</sub> and Fan speed, x is the data value from the controller and y is the 'real' value.

For example, to set the output voltage to  $50.45V_{DC}$ , Multiply the desired set point by the m constant,  $50.45 \times 400 = 20,180$ . Convert this binary number to its hex equivalent: 20,180b = 0x4ED4. The result is sent LSB=0xD4 first, then MSB=0x4E.

#### The constants are

FUNCTION	Operation	m	b	R
Output voltage	Write / read	400	0	0
Output voltage shutdown				
Output Current	read	5	0	0
Temperature	read	1	0	0
Input Voltage	read	1	75	0
Input Power	read	1	0	0
Fan Speed setting (%)	read	1	0	0
Fan speed in RPM	read	100	0	0

#### PMBus<sup>™</sup> Command set:

Command	Hex Code	Data Field	Function
Operation	01	1	Output ON/OFF
Clear_Faults	03	0	Clear Status
Vout_command	21	2	Set Vout
Vout_OV_fault_limit	40	2	Set OV fault limit
Read_status	D0	10	Read Status, Vout, Iout, T
LEDs test ON	D2	0	Test LEDs
LEDs test OFF	D3	0	
Service_LED_ON	D4	0	Service LED
Service_LED_OFF	D5	0	
Enable_write	D6	0	Enable EEPROM write
Disable_write	D7	0	Disable EEPROM write
Inhibit_restart	D8	0	Latch upon failure
Auto_restart	D9	0	Hiccup
Isolation_test	DA	0	Perform isolation test
Read_input_string	DC	2	Read Vin and Pin
Read_firmware_rev	DD	3	Firmware revisions
Read_run_timer	DE	3	Accumulated ON state
Fan_speed_set	DF	3	Fan speed control
Fan_normal_speed	EO	0	Stop fan control
Read_fan_speed	E1	4	Fan control & speed
Stretch_LO_25ms	E2	0	Production test feature

#### **Command Descriptions**

**Operation (01h) :** By default the Power supply is turned **ON** at power up as long as *ENABLE* is active LO. The Operation command is used to turn the Power Supply ON or OFF via the PMBus. The data byte below follows the OPERATION command.

FUNCTION	DATA BYTE
Unit ON	0x80
Unit OFF	0x00

1	8		1	8 @ 201		ral Electric Company. All rights reserved.
S	Slave address	Wr	Α	Command Code	Α	a Liectric Company. All rights reserved.

100-120/200-277VAc input; Output: 2725W @ 52Vdc, 5VDC @ 4W

To **RESET** the power supply cycle the power supply OFF, wait at least 2 seconds, and then turn back ON. All alarms and shutdowns are cleared during a restart.

Clear\_faults (03h): This command clears information bits in the STATUS registers, these include:

- Isolation OK
- Isolation test failed
- Restarted OK
- Invalid command
- Invalid data
- PEC error

Vout\_Command (21h) : This command is used to change the output voltage of the power supply. Changing the output voltage should be performed simultaneously to all power supplies operating in parallel using the Global Address (Broadcast) feature. If only a single power supply is instructed to change its output, it may attempt to source all the required power which can cause either a power limit or shutdown condition.

Software programming of output voltage overrides the set point voltage configured during power\_up. The program no longer looks at the 'margin pin' and will not respond to any hardware voltage setting. The default state cannot be accessed any longer unless power is removed from the DSP.

To properly hot-plug a power supply into a live backplane, the system generated voltage should get re-configured into either the factory adjusted firmware level or the voltage level reconfigured by the margin pin. Otherwise, the voltage state of the plugged in power supply could be significantly different than the powered system.

Voltage margin range: 42V<sub>DC</sub> – 58 V<sub>DC</sub>.

A voltage programming example: The task: set the output voltage to  $50.45V_{\text{DC}}$ 

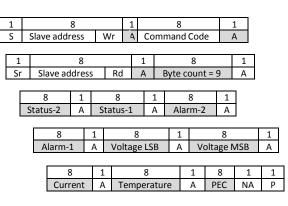
The constants for voltage programming are: m = 400, b and R = 0. Multiply the desired set point by the m constant, 50.45 x 400 = 20,180. Convert this binary number to its hex equivalent: 20,180b = 4ED4h. Transmit the data LSB first, followed by MSB, 0 x D44Eh.

Vout\_OV\_fault\_limit (40h) : This command sets the Output Overvoltage Shutdown level.

#### Manufacturer-Specific PMBus<sup>™</sup> Commands

Many of the manufacturer-specific commands read back more than two bytes. If more than two bytes of data are returned, the standard SMBus<sup>™</sup> Block read is utilized. In this process, the Master issues a Write command followed by the data transfer from the power supply. The first byte of the Block Read data field sends back in hex format the number of data bytes, exclusive of the PEC number, that follows. Analog data is always transmitted LSB followed by MSB. A No-ack following the PEC byte signifies that the transmission is complete and is being terminated by the 'host'.

Read\_status (D0h) : This 'manufacturer specific' command is the basic read back returning STATUS and ALARM register data, output voltage, output current, and internal temperature data in a single read.



#### Status and alarm registers

The content and partitioning of these registers is significantly different than the standard register set in the PMBus<sup>™</sup> specification. More information is provided by these registers and they are accessed rapidly, at once, using the 'multi parameter' read back scheme of this document. There are a total of four registers. All errors, 0 – normal, 1 – alarm.

#### Status-2

Bit	Title	Description
7	PEC Error	Mismatch between computed and transmitted PEC. The instruction has not been executed. Clear_Flags resets this register.
6	Will Restart	Restart after a shutdown = 1
5	Invalid Instruction	The instruction is not supported. An ALERT# will be issued. Clear_Flags resets this register.
4	Power Capacity	High line power capacity = 1
3	Isolation test failed	Information only to system controller
2	Restarted ok	Informs HOST that a successful RESTART occurred clearing the status and alarm registers
1	Data out of range	Flag appears until the data value is within range. A clear_flags command does not reset this register until the data is within normal range.
0	Enable pin HI	State of the ENABLE pin, HI = 1 = OFF

**Isolation test failed:** The 'system controller' has to determine that sufficient capacity exists in the system to take a power supply 'off line' in order to test its isolation capability. Since the power supply cannot determine whether sufficient redundancy is available, the results of this test are provided, but the 'internal fault' flag is not set.

#### Status-1

Bit	Title	Description
7	spare	
6	Isolation test OK	Isolation test completed successfully.
5	Internal fault	The power supply is faulty
4	Shutdown	
3	Service LED ON	ON = 1
2	External fault	the power supply is functioning OK
1	LEDs flashing	LEDs tested test ON = 1
0	Output ON	ON = 1

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#### Alarm-2

Bit	Title	Description
7	Fan Fault	
6	No primary	No primary detected
5	Primary OT	Primary section OT
4	DC/DC OT	DC/DC section OT
3	Output voltage lower than bus	Internal regulation failure
2	Thermal sensor failed	Internal failure of a temperature sensing circuit
1	5V out_of_limits	Either OVP or OCP occurred
0	Power delivery	a power delivery fault occurred

**Power Delivery:** The power supply compares its internal sourced current to the current requested by the current share pin. If the difference is > 10A, a fault is issued.

#### Alarm-1

Bit	Title	Description
7	Unit in power limit	An overload condition that results in
		constant power
6	Primary fault	Indicates either primary failure or
		INPUT not present. Used in
		conjunction with bit-0 and Status_1
		bits 2 and 5 to assess the fault.
5	Over temp.	One of the over_temperature
	shutdown	sensors tripped the supply
4	Over temp warning	Temperature is too high, close to
		shutdown
3	In over current	Shutdown is triggered by low
		output voltage < 39V <sub>DC</sub> .
2	Over voltage	
	shutdown	
1	Vout out_of_limits	Indication the output is not within
		design limits. This condition may or
		may not cause an output shutdown.
0	Vin out_of_limits	The input voltage is outside design
		limits

LEDS test ON (D2h): Will turn-ON simultaneously the four front panel LEDs of the Power supply sequentially 7 seconds ON and 2 seconds OFF until instructed to turn OFF. The intent of this function is to provide visual identification of the power supply being talked to and also to visually verify that the LEDs operate and driven properly by the micro controller.

**LEDS test OFF (D3h)**: Will turn-OFF simultaneously the four front panel LEDs of the Power supply.

Service LED ON (D4h): Requests the power supply to *flash*-ON the Service (ok-to-remove) LED. The *flash* sequence is approximately 0.5 seconds ON and 0.5 seconds OFF.

Service LED OFF (D5h) : Requests the power supply to turn OFF the Service (ok-to-remove) LED.

**Enable write (D6h) :** This command enables write permissions into the upper ¼ of memory locations for the external EEPROM. A write into these locations is normally disabled until commanded through I<sup>2</sup>C to permit writing into the protected area. A delay of about 10ms is required from the time the instruction is requested to the time that the power supply actually completes the instruction.

See the FRU-ID section for further information of content written into the EEPROM at the factory.

**Disable write (D7h)**: This command disables write permissions into the upper ¼ of memory locations for the external EEPROM.

Unit in Power Limit or in Current Limit: When output voltage is > 36V<sub>DC</sub> the Output LED will continue blinking. When output voltage is < 36V<sub>DC</sub>, if the unit is in the RESTART mode, it goes into a hiccup. When the unit is ON the output

LED is ON, when the unit is OFF the output LED is OFF. When the unit is in latched shutdown the output LED is OFF.

Inhibit\_restart (D8h) : The Inhibit-restart command directs the power supply to remain latched off for over\_voltage, over\_temperature and over\_current. The command needs to be sent to the power supply only once. The power supply will remember the INHIBIT instruction as long as internal bias is active.

**Restart after a lachoff:** To restart after a latch\_off either of four restart mechanisms are available. The hardware pin **Enable** may be turned OFF and then ON. The unit may be commanded to restart via i2c through the *Operation* command by first turning OFF then turning ON. The third way to restart is to remove and reinsert the unit. The fourth way is to turn OFF and then turn ON ac power to the unit. The fifth

way is by changing firmware from **latch off** to **restart**. Each of these commands must keep the power supply in the OFF state for at least 2 seconds, with the exception of changing to **restart**.

A successful restart shall clear all alarm registers, set the **restarted successful** bit of the **Status\_2** register.

A power system that is comprised of a number of power supplies could have difficulty restarting after a shutdown event because of the non-synchronized behavior of the individual power supplies. Implementing the latch-off mechanism

permits a synchronized restart that guarantees the simultaneous restart of the entire system.

A synchronous restart can be implemented by;

1. Issuing a GLOBAL OFF and then ON command to all power supplies,

2. Toggling Off and then ON the ENABLE signal

3. Removing and reapplying input commercial power to the entire system.

The power supplies should be turned OFF for at least 20 - 30 seconds in order to discharge all internal bias supplies and reset the soft start circuitry of the individual power supplies.

Auto\_restart (D9h) : Auto-restart is the default configuration for overvoltage, overcurrent and overtemperature shutdowns.

However, overvoltage has a unique limitation. An overvoltage shutdown is followed by three attempted restarts, each restart delayed 1 second, within a 1 minute window. If within the 1 minute window three attempted restarts failed, the unit will latch OFF. If within the 1 minute less than 3 shutdowns occurred then the count for latch OFF resets and the 1 minute window starts all over again.

This command resets the power supply into the default autorestart configuration.

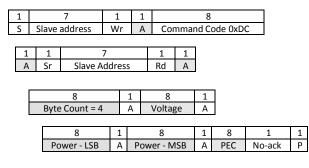
Isolation test (DAh): This command verifies functioning of output OR'ing. At least two paralleled power supplies are required. The host should verify that N+1 redundancy is established. If N+1 redundancy is not established the test can fail. Only one power supply should be tested at a time.

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Verifying test completion should be delayed for approximately 30 seconds to allow the power supply sufficient time to properly execute the test.

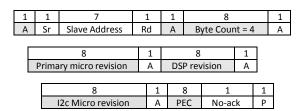
Failure of the isolation test is not considered a power supply FAULT because the N+1 redundancy requirement cannot be verified. The user must determine whether a true isolation fault indeed exists.

**Read input string (DCh)**: Reads back the input voltage and input power consumed by the power supply. In order to improve the resolution of the input voltage reading the data is shifted by 75V.



**Read\_firmware\_rev [0 x DD]:** Reads back the firmware revision of all three  $\mu$ C in the power supply.

1	7	1	1	8	1
S	Slave address	Wr	Α	Command Code 0xDD	Α



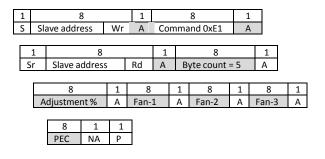
For example; the read returns one byte for each device (i.e.  $0 \times 002114h$ ). The sequence is primary micro, DSP, and I<sup>2</sup>C micro. 0x00 in the first byte indicates that revision information for the primary micro is not supported. The number 21 for the DSP indicates revision 2.1, and the number 14 for the i2c micro indicates revision 1.4.

Read\_run\_timer [0 x DE]: This command reads back the operational ON state in hours. The operational ON state is accumulated from the time the power supply is initially programmed at the factory. The operational ON state includes standby and delivery of main output power. Recorded capacity is approximately 10 years.

-	1		7			1	1		8		
	S	Sla	Slave address Wr					Com	mand Code 0xDE		A
							1	1	0		1
	S	ir Slave Address				Rd	A Byte count = 4			A	
		·	Slaven	uure			na		Byte count 4		
		8			1		8	1	8	1	
		Т	Time 8 LSB /		A1	Ti	neı	А	Time - MSB	Α	
			PEC	No-ack			Р				

Fan\_speed\_set (DFh) : This command instructs the power supply to increase the speed of the fan. The transmitted data byte represents the hex equivalent of the duty cycle in percentage, i.e.  $100\% = 0 \times 64h$ . The command can only increase fan speed, it cannot instruct the power supply to reduce the fan speed below what the power supply requires for internal control.

Fan\_normal\_speed (E0h): This command returns fan control to the power supply. It does not require a trailing data byte. Read\_Fan\_speed (E1h) : Returns the commanded fan speed in percent and the measured fan speed in RPM from the individual fans. Up to 3 fans are supported. If a fan does not exist (units may contain from 1 to 3 fans), or if the command is not supported the unit return 0x00.



Stretch\_LO\_25ms (E2h) : Command used for production test of the clock stretch feature.

None supported commands or invalid data: The power supply notifies the MASTER if a non-supported command has been sent or invalid data has been received. Notification is implemented by setting the appropriate STATUS and ALARM registers and setting the SMBAlert# flag.

#### Fault Management

The power supply records faults in the STATUS and ALARM registers above and notifies the *MASTER* controller as described in the **Alarm Notification** section of the non-conforming event.

The STATUS and ALARM registers are continuously updated with the latest event registered by the rectifier monitoring circuits. A *host* responding to an SMBusALERT# signal may receive a different state of the rectifier if the state has changed from the time the SMBusALERT# has been triggered by the rectifier.

The power supply differentiates between **internal faults** that are within the power supply and **external faults** that the power supply protects itself from, such as overload or input voltage out of limits. The FAULT LED, FAULT PIN or i2c alarm is not asserted for EXTERNAL FAULTS. Every attempt is made to annunciate External Faults. Some of these annunciations can be observed by looking at the input LEDs. These fault categorizations are predictive in nature and therefore there is a likelihood that a categorization may not have been made correctly.

Input voltage out of range: The Input LED will continue blinking as long as sufficient power is available to power the

## GE

## CP2725AC54TE CPL High Efficiency Rectifier

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LED. If the input voltage is completely gone the Input LED is OFF.

#### **State Change Definition**

A **state\_change** is an indication that an event has occurred that the MASTER should be aware of. The following events shall trigger a **state\_change**;

- Initial power-up of the system when AC gets turned ON. This is the indication from the rectifier that it has been turned ON. Note that the master needs to read the status of each power supply to reset the system\_interrupt. If the power supply is back-biased through the 8V\_INT or the 5VSTB it will not issue an SMBALERT# when AC power is turned back ON.
- Whenever the power supply gets hot-plugged into a working system. This is the indicator to the system (MASTER) that a new power supply is on line.
- Any changes in the bit patterns of the STATUS and ALARM registers are a STATUS change which triggers the SMBALERT# flag. Note that a host-issued command such as CLEAR\_FAULTS will not trigger an SMB

#### Hot plug procedures

Careful system control is recommended when hot plugging a power supply into a live system. It takes about 15 seconds for a power supply to configure its address on the bus based on the analog voltage levels present on the backplane. If communications are not stopped during this interval, multiple power supplies may respond to specific instructions because the address of the hot plugged power supply always defaults to xxxx000 (depending on which device is being addressed within the power supply) until the power supply configures its address.

The recommended procedure for hot plug is the following: The system controller should be told which power supply is to be removed. The controller turns the service LED ON, thus informing the installer that the identified power supply can be removed from the system. The system controller should then poll the module\_present signal to verify when the power supply is re-inserted. It should time out for 15 seconds after this signal is verified. At the end of the time out all communications can resume.

#### **Predictive Failures**

Alarm warnings that do not cause a shutdown are indicators of potential future failures of the power supply. For example, if a thermal sensor failed, a warning is issued but an immediate shutdown of the power supply is not warranted.

Another example of potential predictive failure mechanisms can be derived from information such as fan speed when multiple fans are used in the same power supply. If the speed of the fans varies by more than 20% from each other, this is an indication of an impending fan wear out.

The goal is to identify problems early before a protective shutdown would occur that would take the power supply out of service.

#### External EEPROM

A 64k-bit EEPROM is provided across the  $I^2C$  bus. This EEPROM is used for both storing FRU\_ID information and for providing a scratchpad memory function for customer use.

Functionally the EEPROM is equivalent to the ST M34D64 part that has its memory partitioned into a *write protected* upper ¼ of memory space and the lower ¾ section that cannot be protected. FRU ID is written into the *write protected* portion of memory.

Write protect feature: Writing into the upper 1/4 of memory can be accomplished either by hardware or software.

The power supply pulls down the write\_protect (Wp) pin to ground via a  $500\Omega$  resistor between the 'module\_present' signal pin and Logic\_GRD (see the Module Present Signal section of Input Signals). Writing into the upper ¼ of memory can be accomplished by pulling HI the module\_present pin.

An alternative, and the recommended approach, is to issue the Enable\_write command via software.

Page implementation: The external EEPROM is partitioned into 32 byte pages. For a write operation only the starting address is required. The device automatically increments the memory address for each byte of additional data it receives. However, if the 32 byte limit is exceeded the device executes a wrap- around that will start rewriting from the first address specified. Thus byte 33 will replace the first byte written, byte 34 the second byte and so on. One needs to be careful therefore not to exceed the 32 byte page limitation of the device.

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#### Table 1: FRU\_ID

#### The upper quarter of memory starting from address 6144 shall be reserved for factory ID and factory data.

		Length	Format	Static	Description	Notes/Example
1		(bytes)		Value		
	•		1	Туре		
6144d	0x1800	12	ASCII	Fixed	GE-energy - Product ID	CP2725AC54TE
6156d	0x180C	10	ASCII	Fixed	GE-energy – Part Number	123456789x or C123456789
6166d	0x1816	6	ASCII	Variable	GE-energy - Hardware revision	x:xxxx controlled by PDI series #
6172d	0x181C	6	ASCII	Variable	spare	
6178d	0x1822	14	ASCII	Variable	GE-energy - Serial_No	01KZ51018193 <u>xx</u>
						01 Year of manufacture - 2001
						KZ factory, in this case Matamoros
						51 week of manufacture
						018193xx serial # mfg choice
6192d	0x1830	40	ASCII	Variable	GE- Manufacturing location	"Matamoros, Tamps, Mexico"
6232d	0x1858	8	ASCII	Fixed	spare	
6240d	0x1860	2	HEX	Fixed	spare	
6242d	0x1862	158	ASCII	Fixed	Customer Information	These fields are reserved for use by the customer.
6400d	0x1900	5	HEX	Fixed	M, B, & R for voltage read	M & B are 2 bytes each sent as MSB and then
6405d	0x1905	5	HEX	Fixed	M, B, & R for current read	LSB. R is one byte. These are stored as two's
6410d	0x1903	5	HEX	Fixed	M, B, & R temp read	complement.
6415d	0x190F	5	HEX	Fixed	spare	
6420d	0x1914	5	HEX	Fixed	M, B, & R for voltage set	See the section on Direct Mode Constants
6425d	0x1919	5	HEX	Fixed	M, B, & R for input voltage read	Stored in the EEPROM for the constants stored
6430d	0x191E	1	HEX	Variable	Validation CHKSUM	in these fields
6431d	9x191F	5	HEX	Fixed	M, B, & R for input power read	]
6436d	0x1924	5	HEX	Fixed	M, B, & R for fan percent adjust	]
6441d	0x1929	5	HEX	Fixed	M, B, & R for fan RPM read	]
6446d	0 x 192E	5	HEX	Fixed	M, B, & R for converter input voltage read	

Notes:

Memory locations 0x00 to 0x17FF and 0x1A00 to 0x2000 are blank (0xFF). Locations 0x1800 to 0x19FF contain FRUID, locations not specified are filled with 0's. Checksum is the complement of the sum of locations 0x1800 to 0x19FF (chksum = 0xFF – sum(0x1800-0x19FF)), excluding serial number field (checksum will always be the same since all fields are fixed except serial number).

### Table 2: Alarm and LED state summary

		Power Supply LED State				Monitoring Signals			
Condition	AC OK Green	DC OK Green	Service Amber	Fault Red		Fault	отw	PFW	Module Present
ОК	1	1	0	0		н	н	н	LO
Thermal Alarm (5C before shutdown)	1	1	1	0		н	LO	HI	LO
Thermal Shutdown	1	0	1	1		LO	LO	LO	LO
Defective Fan	1	0	0	1		LO	HI	LO	LO
Blown AC Fuse in Unit	1	0	0	1		LO	н	LO	LO
AC Present but not within limits	Blinks	0	0	0		н	HI	- <sup>4</sup>	LO
AC not present <sup>1</sup>	0	0	0	0		н	HI	LO	LO
Boost Stage Failure	1	0	0	1		LO	HI	LO	LO
Over Voltage Latched Shutdown	1	0	0	1		LO	н	LO	LO
Over Current	1	Blinks	0	0		н	HI	LO	LO
Non-catastrophic Internal Failure <sup>2</sup>	1	1	0	1		LO	н	HI	LO
Missing Module									н
Standby (remote)	1	0	0	0		н	HI	LO	LO
Service Request (PMBus mode)	1	1	Blinks	0		н	HI	HI	LO
Communications Fault (RS485 mode)	1	1	0	Blinks		н	HI	HI	LO

 $^{\scriptscriptstyle 1}$  This signal is correct if the rectifier is back biased from other rectifiers in the shelf .

<sup>2</sup> Any detectable fault condition that does not cause a shutting down. For example, ORing FET failure, boost section out of regulation, etc.

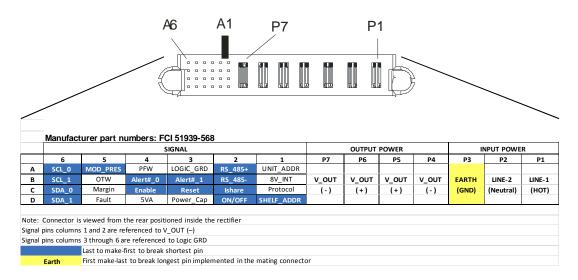
<sup>3</sup> Signal transition from HI to LO is output load dependent

<sup>4</sup> The PFW signal changes states when the boost voltage decays and not when the AC is out of regulation.

100-120/200-277VAC input; Output: 2725W @ 52Vdc, 5VDC @ 4W

### **Output Connector**

Mating Connector: right angle PWB mate - all pins: AMP 1450572-1, right angle PWB mate except pass-thru input power: AMP 6450378-1



100-120/200-277VAC input; Output: 2725W @ 52Vdc, 5VDC @ 4W

### **Signal Definitions**

All hardware alarm signals (Fault, PFW, OTW, Power Capacity) are open drain FETs. These signals should be pulled HI to either 3.3V or 5V. Maximum sink current 5mA. An active LO signal (< 0.4Vdc) state. All signals are referenced to Logic GRD unless otherwise stated. Contact your Lineage Power representative for more details.

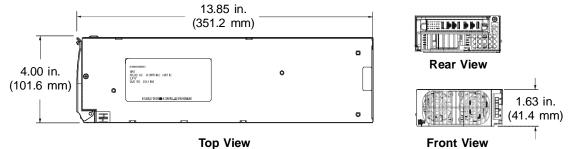
Function	Label	Туре	Description
Output Enable	Enable	Input	If shorted to LOGIC_GRD, the Rectifier output is enabled when using I <sup>2</sup> C mode of operation. May also be toggled to reset a latched OFF Rectifier. Function not available in RS485 mode.
Power Fail Warning	PFW	Output	An open drain FET; normally HI, indicating output power is present. Changes to LO at least 5msec before the output voltage decays below 40Vdc.
I <sup>2</sup> C Interrupt	Alert#_0 Alert#_1	Output	Interrupt signal via I <sup>2</sup> C lines indicating that service is requested from the host controller. This signal pin is pulled up to 3.3V via a $10k\Omega$ resistor and switches to active LO when an interrupt occurs.
Rectifier Fault	Fault	Output	Indicates that an internal fault exists. An open drain FET; normally HI, changes to LO.
Module Present	MOD_PRES	Output	Short pin, see Status and Control description for further information on this signal.
ON/OFF	ON/OFF	Input	Short pin, connects last and breaks first; used to activate and deactivate output during hot-insertion and extraction, respectively. Ref: Vout ( - )
Protocol select	Protocol	Input	See Status and Control description for further information on this signal. Ref: Vout ( - ).
Margining	Margin	Input	Allows changing of output voltage through an analog voltage input or via resistor divider.
Over-Temperature Warning	OTW	Output	An open drain FET; normally HI, changes to LO approximately 5°C prior to thermal shutdown.
Power Capacity	POWER_CAP	Output	Open drain FET; Used to indicate Rectifier operation mode; HI indicates 2250W operation and LO indicates 1200W operation.
Rectifier address	Unit_addr	Input	Voltage level addressing of Rectifiers within a single shelf. Ref: Vout ( - ).
Shelf Address	Shelf_addr	Input	Voltage level addressing of Rectifiers within multiple shelves. Ref: Vout ( - ).
Back bias	8V_INT	Bi-direct	Diode OR'ed 8Vdc drain; used to back bias microprocessors and DSP of failed Rectifier from operating Rectifiers. Ref: Vout ( - ).
Mux Reset	Reset	Input	Resets the I <sup>2</sup> C lines to I <sup>2</sup> C line 0.
Standby power	5VA	Output	5V at 0.75A provided for external use by either adjacent power supplies or the using system.
Current Share	Ishare	Bi-direct	A single wire interface between each of the power unit forces them to share the load current. Ref: Vout ( - ).
I <sup>2</sup> C Line 0	SCL_0, SDA_0	Input	I <sup>2</sup> C line 0.
I <sup>2</sup> C Line 1	SCL_1, SDA_1	Input	I <sup>2</sup> C line 1.
I <sup>2</sup> C Interrupt	Alert#_0, Alert#_1	Output	Goes active LO
RS485 Line	RS_485+ RS_485-	Bi-direct	RS485 line.

Input: 100-120/220-240 Vac; Output: 2250W @ 48Vdc; 5 Vdc @ 4W

### Front Panel LEDs

	Analog Mode	I <sup>2</sup> C Mode	RS485 Mode		
□~	<	ON: Input ok Blinking: Input out of limits			
□=	<	ON: Output ok Blinking: Overload			
*	<b>ON:</b> Over-temperature Warning	ON: Over-temperature Warning Blinking: Service	<b>ON:</b> Over-temperature Warning		
□!	← OI	N: Fault	ON: Fault Blinking: Not communicating		

### **Dimensions**



Faceplate color shall be dark grey with a green hinge.

### **Physical**

Packaged weight	5.4/2.45 lbs/kgs
Unpacked weight	4.8/2.18 lbs/kgs
Heat release	100 Watts or 341 BTUs @ 80% load, 153 Watts or 522 BTUs @ 100% load

### **Ordering Information**

Item	Description	Comcode
CP2000AC48TEZ-FB2	52Vdc @ 43.3A, 5Vdc @ 0.75A, RoHS Complaint, conformal coated	1600158237A

### **Contact Us**

For more information, call us at

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