

SeerSense™ DS80 Module

Edge computing VSLAM, AI, and CV engines

Package







SDK

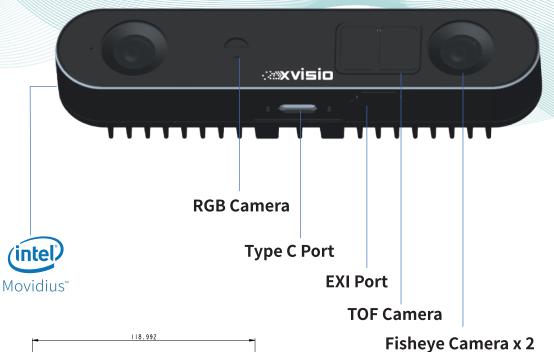


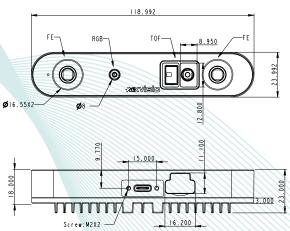
Tool Chain

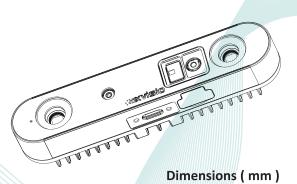
System Spec

| Item | Spec | Remark |
|---------------------|---|--|
| Processor | Myriad X | Intel Movidius VPU |
| Cameras | | |
| -Stereo | 1280x800/640x400,60fps DFOV150°/ HFOV130°/VFOV74° | Mono, Global shutter 80mm baseline |
| -RGB | 8MP (4192x3104), 30fps DFOV79.9/HFOV68°/VFOV53° | Photo: 8.2MP/13MP (MAX) Video: VGA/720P/1080P @ 30fps |
| -TOF | 640x480/320x240, 30fps DFOV78°/ HFOV64°/ VFOV50° | 0.5-5m =<1% depth error 940nm, Class 1 laser eye safety compliant |
| IMU | 9 Axis | 1000Hz fusion for VSLAM |
| CNN Engine | Dual engine | Parallel processing |
| Stereo Depth Engine | VGA/720P SGBM (Semi-Global Block Match) | 50/60fps, 6.5 meter |
| 6DoF SLAM Engine | 500-1000Hz mm accuracy | On board processing Multiple working mode |
| Power Consumption | Avg 2.8W | // |
| Supply Voltage | 5V 3A | |
| Port | USB Type C | Camera Stream, Depth, Al image, 6DoF Output |
| | Debug Port | UART, Sync Pin |
| Weight Size | 93g 119Lx23Dx24H | LxDxH (mm) |
| SDK | VIO, CSLAM, 3D reconstruction, Depth/Point Cloud (SGBM/TOF) Object detection, Gesture, Plane detection, RGBD camera | |
| Tool Chain | Open VINO, Open CV, Xvsdk-viewer Demo Tool | |









Key Benefits

- One-stop solution for VSLAM, depth, vision AI, CV edge computing
- Multiple OS support for wide range of deployment
- Both passive (SGBM) and active (TOF) depth engine on one device
- Edge computing to offload host resource loading
- Feature-rich SDKs and tool kit for fast development
- Compact, portable, and low power consumption

| CE CB FG | RoHS |
|------------------------|-----------------------|
| Laser module class | Class 1 laser product |
| Standard | IEC 60825-1:2014 |
| Laser modile Vf(V) Max | 2.3 |
| Optical power(W) Max | 2.6 |
| Wavelength(nm) | 940 |

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