

Data sheet for SINAMICS G120X

Article No.: 6SL3230-1YE24-0AF0

Client order no. : Order no.: Offer no. : Remarks:

Rated data				
Input				
	Number of phases	3 AC		
	Line voltage	380 480 V +10 %	-20 %	
	Line frequency	47 63 Hz		
	Rated voltage	400V IEC	480V NEC	
	Rated current (LO)	17.00 A	14.30 A	
	Rated current (HO)	13.25 A	10.60 A	
Output				
	Number of phases	3 AC		
	Rated voltage	400V IEC	480V NEC 1)	
	Rated power (LO)	7.50 kW	10.00 hp	
	Rated power (HO)	5.50 kW	7.50 hp	
	Rated current (LO)	18.00 A	14.00 A	
	Rated current (HO)	13.20 A	11.00 A	
	Rated current (IN)	18.50 A		
	Max. output current	24.00 A		
Pulse frequency		4 kHz		
Output frequency for vector control		0 200 Hz		
Output frequency for V/f control		0 550 Hz		
Overload capability				
П	Low Overload (LO)			

Overload	capability
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Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time

0.70 0.85
0.96
0.97
63 dB
0.259 kW
RFI suppression filter for Category C2
Category C2
without SIRIUS device (e.g. via S7- 1500F)

Communication

Communication PROFINET, EtherNet/IP



Item no.: Consignment no. : Project :

Inputs / outputs				
Standard digital inputs				
Number	6			
Switching level: $0 \rightarrow 1$	11 V			
Switching level: $1 \rightarrow 0$	5 V			
Max. inrush current	15 mA			
Fail-safe digital inputs				
Number	1			
Digital outputs				
Number as relay changeover contact	2			
Output (resistive load)	DC 30 V, 5.0 A			
Number as transistor	0			
Analog / digital inputs				
Number	2 (Differential input)			
Resolution	10 bit			
Switching threshold as digital input				
0 → 1	4 V			
1 → 0	1.6 V			
Analog outputs				
Number	1 (Non-isolated output)			

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	



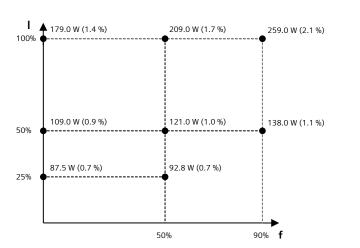
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Ambient conditions			
Standard board coating type	Class 3C3, according to IEC 60721-3-3: 2002		
Cooling	Air cooling using an integrated fan		
Cooling air requirement	0.009 m³/s (0.325 ft³/s)		
Installation altitude	1,000 m (3,280.84 ft)		
Ambient temperature			
Operation	-20 45 °C (-4 113 °F)		
Transport	-40 70 °C (-40 158 °F)		
Storage	-25 55 °C (-13 131 °F)		
Relative humidity			
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible		
Connections			
Signal cable			
Conductor cross-section	0.15 1.50 mm ² (AWG 24 AWG 16)		
Line side			
Version	screw-type terminal		
Conductor cross-section	1.50 6.00 mm ² (AWG 16 AWG 10)		
Motor end			
wotor enu			
Version	Screw-type terminals		
	Screw-type terminals 1.50 6.00 mm² (AWG 16 AWG 10)		
Version	1.50 6.00 mm²		
Version Conductor cross-section	1.50 6.00 mm²		
Version Conductor cross-section DC link (for braking resistor)	1.50 6.00 mm² (AWG 16 AWG 10)		

Mechanical data				
Degree of protection		IP20 / UL open type		
Frame size		FSB		
Net weight		6.16 kg (13.58 lb)		
Dimensions				
	Width	100 mm (3.94 in)		
	Height	275 mm (10.83 in)		
	Depth	218 mm (8.58 in)		
Standards				
Compliance with standards		UL, cUL, CE, C-Tick (RCM), EAC, KCC, SEMI F47, REACH		
CE marking		EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC		





The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

*converted values

¹⁾ The output current and HP ratings are valid for the voltage range 440V-480V

³⁾Typical value. More information can be found in the element group "Converter losses to IEC 61800-9-2" in this datasheet.

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