SIEMENS

Data sheet

3RW5534-2HF14



SIRIUS soft starter 200-480 V 113 A, 110-250 V AC, spring-type terminals Failsafe

Figure similar

product brand name	SIRIUS
product category	Hybrid switching devices
product designation	Failsafe soft starters
product type designation	3RW55
manufacturer's article number	
 of high feature HMI module usable 	<u>3RW5980-0HF00</u>
 of communication module PROFINET standard usable 	<u>3RW5980-0CS00</u>
 of communication module PROFINET high-feature usable 	<u>3RW5950-0CH00</u>
 of communication module PROFIBUS usable 	<u>3RW5980-0CP00</u>
 of communication module Modbus TCP usable 	<u>3RW5980-0CT00</u>
 of communication module Modbus RTU usable 	<u>3RW5980-0CR00</u>
 of communication module Ethernet/IP 	<u>3RW5980-0CE00</u>
 of circuit breaker usable at 400 V 	3VA2216-7MN32-0AA0; Type of coordination 1, Iq = 65 kA, CLASS 10
 of circuit breaker usable at 400 V at inside-delta circuit 	3VA2220-7MN32-0AA0; Type of coordination 1, Iq = 65 kA, CLASS 10
 of the gG fuse usable up to 690 V 	<u>3NA3244-6; Type of coordination 1, Iq = 65 kA</u>
 of the gG fuse usable at inside-delta circuit up to 500 V 	<u>3NA3244-6; Type of coordination 1, Iq = 65 kA</u>
 of full range R fuse link for semiconductor protection usable up to 690 V 	<u>3NE1225-0; Type of coordination 2, Iq = 65 kA</u>
 of back-up R fuse link for semiconductor protection usable up to 690 V 	<u>3NE3231: Type of coordination 2. Iq = 65 kA</u>
 of the redundant contactor for applications > SIL 1 according to EN 62061 	<u>3RT1056</u>
 of the redundant contactor for applications > SIL 1 at inside-delta circuit according to EN 62061 	<u>3RT1056</u>
 of the redundant contactor for applications > SIL 1 according to EN ISO 13849-1 	<u>3RT1065</u>
 of the redundant contactor for applications > SIL 1 at inside-delta circuit according to EN ISO 13849-1 	<u>3RT1065</u>
General technical data	
starting voltage [%]	20 100 %
stopping voltage [%]	50 %; non-adjustable
start-up ramp time of soft starter	0 360 s
ramp-down time of soft starter	0 360 s
start torque [%]	10 100 %
stopping torque [%]	10 100 %
torque limitation [%]	20 200 %
current limiting value [%] adjustable	125 800 %
breakaway voltage [%] adjustable	40 100 %
breakaway time adjustable	0 2 s
number of parameter sets	3
accuracy class	5 (based on IEC 61557-12)

contificate of quitability	
certificate of suitability	Vec
CE marking	Yes
UL approval	Yes
CSA approval	Yes
product component	
HMI-High Feature	Yes
is supported HMI-High Feature	Yes
product feature integrated bypass contact system	Yes
number of controlled phases	3
trip class	CLASS 10A / 10E (default) / 20E / 30E; acc. to IEC 60947-4-2
current unbalance limiting value [%]	10 60 %
ground-fault monitoring limiting value [%]	10 95 %
buffering time in the event of power failure	400 mg
for main current circuit	100 ms
for control circuit	100 ms
idle time adjustable	0 255 s
insulation voltage rated value	480 V
degree of pollution	3, acc. to IEC 60947-4-2
impulse voltage rated value	6 kV
blocking voltage of the thyristor maximum	1 400 V
service factor	1.15
surge voltage resistance rated value	6 kV
maximum permissible voltage for protective separation	400 V/ doop not apply for the minister comparison
between main and auxiliary circuit	480 V; does not apply for thermistor connection
shock resistance	15 g / 11 ms, from 6 g / 11 ms with potential contact lifting
vibration resistance	15 mm up to 6 Hz; 2 g up to 500 Hz 60 1 800 s
recovery time after overload trip adjustable utilization category according to IEC 60947-4-2	AC 53a
reference code according to IEC 81346-2	Q
Substance Prohibitance (Date)	11/22/2019
product function	11/22/2013
ramp-up (soft starting)	Yes
 ramp-down (soft stop) 	Yes
breakaway pulse	Yes
adjustable current limitation	Yes
 creep speed in both directions of rotation 	Yes
• pump ramp down	Yes
• DC braking	Yes
motor heating	Yes
slave pointer function	Yes
trace function	Yes
 intrinsic device protection 	Yes
 motor overload protection 	Yes; Full motor protection (thermistor motor protection and electronic motor overload protection) / When using the motor overload protection according to ATEX, an upstream contactor is required in inside-delta circuit.
 evaluation of thermistor motor protection 	Yes; Type A PTC or Klixon / Thermoclick
inside-delta circuit	Yes
auto-RESET	Yes
manual RESET	Yes
remote reset	Yes
 communication function 	Yes
 operating measured value display 	Yes
event list	Yes
error logbook	Yes
 via software parameterizable 	Yes
 via software configurable 	Yes
screw terminal	No
 spring-loaded terminal 	Yes
PROFlenergy	Yes; in connection with the PROFINET Standard and PROFINET High-Feature communication modules
• firmware update	Yes
 removable terminal for control circuit 	Yes

voltage ramp	Yes
torque control	Yes
 combined braking 	Yes
 analog output 	Yes; 4 20 mA (default) / 0 10 V
 programmable control inputs/outputs 	Yes
 condition monitoring 	Yes
 automatic parameterisation 	Yes
 application wizards 	Yes
 alternative run-down 	Yes
 emergency operation mode 	Yes
 reversing operation 	Yes
 soft starting at heavy starting conditions 	Yes
Power Electronics	
operational current	
• at 40 °C rated value	113 A
• at 40 °C rated value minimum	23 A
• at 50 °C rated value	101 A
• at 60 °C rated value	89 A
operational current at inside-delta circuit	
• at 40 °C rated value	196 A
● at 50 °C rated value	175 A
• at 60 °C rated value	154 A
operating voltage	
rated value	200 480 V
 at inside-delta circuit rated value 	200 480 V
relative negative tolerance of the operating voltage	-15 %
relative positive tolerance of the operating voltage	10 %
relative negative tolerance of the operating voltage at inside-delta circuit	-15 %
relative positive tolerance of the operating voltage at inside-delta circuit	10 %
operating power for 3-phase motors	
• at 230 V at 40 °C rated value	30 kW
 at 230 V at inside-delta circuit at 40 °C rated value 	55 kW
	55 kW
 at 400 V at 40 °C rated value 	
 at 400 V at 40 °C rated value at 400 V at inside-delta circuit at 40 °C rated value 	110 kW
	110 kW 50 Hz
• at 400 V at inside-delta circuit at 40 °C rated value	
at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value	50 Hz
at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value	50 Hz 60 Hz
• at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency	50 Hz 60 Hz -10 %
at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency	50 Hz 60 Hz -10 % 10 %
• at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%]	50 Hz 60 Hz -10 % 10 %
• at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC	50 Hz 60 Hz -10 % 10 % Relative to set le
• at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup	50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le 34 W
• at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup	50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le 34 W 30 W
• at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup	50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le 34 W 30 W
• at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup power loss [W] at AC at current limitation 350 %	50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le 34 W 30 W 27 W
• at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup power loss [W] at AC at current limitation 350 % • at 40 °C during startup	50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le 34 W 30 W 27 W 1 500 W
 at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC at 40 °C after startup at 60 °C after startup at 60 °C after startup at 40 °C during startup at 40 °C during startup at 50 °C during startup 	50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le 34 W 30 W 27 W 1 500 W 1 279 W
 at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC at 40 °C after startup at 50 °C after startup at 60 °C after startup at 40 °C during startup at 50 °C during startup at 50 °C during startup at 60 °C during startup at 60 °C during startup at 60 °C during startup 	50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le 34 W 30 W 27 W 1 500 W 1 279 W 1 074 W
 at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC at 40 °C after startup at 50 °C after startup at 60 °C after startup at 40 °C during startup at 50 °C during startup at 60 °C during startup at 60 °C during startup at 60 °C during startup ot 60 °C during startup 	50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le 34 W 30 W 27 W 1 500 W 1 279 W 1 074 W
 at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC at 40 °C after startup at 50 °C after startup at 60 °C after startup at 60 °C during startup at 50 °C during startup at 60 °C during st	50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le 34 W 30 W 27 W 1 500 W 1 279 W 1 074 W Electronic, tripping in the event of thermal overload of the motor
 at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC at 40 °C after startup at 50 °C after startup at 60 °C after startup at 40 °C during startup at 40 °C during startup at 60 °C during startup by e of the motor protection Control circuit/ Control type of voltage of the control supply voltage 	50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le 34 W 30 W 27 W 1 500 W 1 279 W 1 074 W Electronic, tripping in the event of thermal overload of the motor
• at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 60 °C after startup • at 60 °C after startup • at 40 °C during startup • at 40 °C during startup • at 50 °C during startup • at 60 °	50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le 34 W 30 W 27 W 1 500 W 1 279 W 1 074 W Electronic, tripping in the event of thermal overload of the motor AC
• at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup • at 60 °C during startup • at 50 °C during startup • at 60 °C during startup	50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le 34 W 30 W 27 W 1 500 W 1 279 W 1 074 W Electronic, tripping in the event of thermal overload of the motor AC 110 250 V
 at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC at 40 °C after startup at 50 °C after startup at 60 °C after startup at 40 °C during startup at 50 °C during startup at 60 °C during startup at 50 Hz at 50 Hz at 60 Hz relative negative tolerance of the control supply voltage at at 60 Hz relative negative tolerance of the control supply voltage at at 60 Hz at 60	50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le 34 W 30 W 27 W 1 500 W 1 279 W 1 074 W Electronic, tripping in the event of thermal overload of the motor AC 110 250 V 110 250 V
 at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC at 40 °C after startup at 50 °C after startup at 60 °C after startup at 60 °C during startup at 50 °C during startup at 50 °C during startup at 50 °C during startup at 60 °C during startup at 50 °C during startup at 60 °C during startup at 60 °C during startup at 60 °C during startup	50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le 34 W 30 W 27 W 1 500 W 1 279 W 1 074 W Electronic, tripping in the event of thermal overload of the motor AC 110 250 V 110 250 V -15 %
 at 400 V at inside-delta circuit at 40 °C rated value Operating frequency 1 rated value Operating frequency 2 rated value relative negative tolerance of the operating frequency relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC at 40 °C after startup at 60 °C after startup at 60 °C after startup at 60 °C during startup at 50 °C during startup at 60 °C during	50 Hz 60 Hz -10 % 10 % 10 %; Relative to set le 34 W 30 W 27 W 1 500 W 1 279 W 1 074 W Electronic, tripping in the event of thermal overload of the motor AC 110 250 V -15 % 10 %

AC at 60 Hz control supply voltage frequency	50 60 Hz
relative negative tolerance of the control supply voltage frequency	-10 %
relative positive tolerance of the control supply voltage frequency	10 %
control supply current in standby mode rated value	100 mA
holding current in bypass operation rated value	180 mA
inrush current by closing the bypass contacts maximum	0.8 A
inrush current peak at application of control supply voltage maximum	43 A
duration of inrush current peak at application of control supply voltage	1.6 ms
design of the overvoltage protection	Varistor
design of short-circuit protection for control circuit	4 A gG fuse (Icu=1 kA), 6 A quick-acting fuse (Icu=1 kA), C1 miniature circuit breaker (Icu= 600 A), C6 miniature circuit breaker (Icu= 300 A); Is not part of scope of supply
Inputs/ Outputs	
number of digital inputs	4
with fail-safe	1
parameterizable	4
 number of digital outputs 	3
 Number of digital outputs with fail-safe 	1
 number of digital outputs parameterizable 	2
 number of digital outputs not parameterizable 	1
digital output version	2 normally-open contacts (NO) / 1 normally-closed contact (NC) / 1 changeover contact (CO)
number of analog outputs	1
switching capacity current of the relay outputs	
• at AC-15 at 250 V rated value	3 A
 at DC-13 at 24 V rated value 	1 A
Response times	
Response times OFF-delay time with safety-related request when switched off via control inputs maximum	100 ms
OFF-delay time with safety-related request when switched off	100 ms
OFF-delay time with safety-related request when switched off via control inputs maximum	100 ms Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°)
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions	
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°)
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm 0 mm
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm 0 mm 100 mm
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • at the side weight without packaging	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm 0 mm 100 mm 75 mm
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • at the side	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm 0 mm 100 mm 75 mm 5 mm
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • at the side weight without packaging	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm 0 mm 100 mm 75 mm 5 mm
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • at the side weight without packaging Connections/ Terminals	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm 0 mm 100 mm 75 mm 5 mm
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • at the side weight without packaging Connections/ Terminals type of electrical connection	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm 0 mm 100 mm 75 mm 5 mm 6.85 kg
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • at the side weight without packaging Connections/ Terminals type of electrical connection • for control circuit • for control circuit	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm 0 mm 100 mm 75 mm 5 mm 6.85 kg busbar connection
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • downwards • at the side weight without packaging Connections/ Terminals type of electrical connection • for control circuit width of connection bar maximum wire length for thermistor connection	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm 0 mm 100 mm 75 mm 5 mm 6.85 kg busbar connection spring-loaded terminals
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • downwards • at the side weight without packaging Connections/ Terminals type of electrical connection • for control circuit width of connection bar maximum wire length for thermistor connection • with conductor cross-section = 0.5 mm ² maximum	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm 0 mm 100 mm 100 mm 75 mm 5 mm 6.85 kg busbar connection spring-loaded terminals 25 mm
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • downwards • at the side weight without packaging Connections/ Terminals type of electrical connection • for control circuit width of connection bar maximum wire length for thermistor connection	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm 0 mm 100 mm 75 mm 5 mm 6.85 kg busbar connection spring-loaded terminals 25 mm
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • downwards • at the side weight without packaging Connections/ Terminals type of electrical connection • for control circuit width of connection bar maximum wire length for thermistor connection • with conductor cross-section = 0.5 mm ² maximum	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm 0 mm 100 mm 100 mm 75 mm 5 mm 6.85 kg busbar connection spring-loaded terminals 25 mm
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • downwards • at the side weight without packaging Connections/ Terminals type of electrical connection • for main current circuit • for control circuit width of connection bar maximum wire length for thermistor connection • with conductor cross-section = 0.5 mm² maximum • with conductor cross-section = 1.5 mm² maximum	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm 0 mm 10 mm 0 mm 100 mm 5 mm 6.85 kg busbar connection spring-loaded terminals 25 mm 50 m 150 m 250 m
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • downwards • at the side weight without packaging Connections/ Terminals type of electrical connection • for control circuit width of connection bar maximum with conductor cross-section = 0.5 mm² maximum • with conductor cross-section = 2.5 mm² maximum	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm 0 mm 10 mm 0 mm 100 mm 75 mm 5 mm 6.85 kg busbar connection spring-loaded terminals 25 mm 50 m 150 m 250 m
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • downwards • at the side weight without packaging Connections/ Terminals type of electrical connection • for control circuit width of connection bar maximum with conductor cross-section = 0.5 mm² maximum • with conductor cross-section = 2.5 mm² maximum • with conductor cross-section = 2.5 mm² maximum	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm 0 mm 10 mm 0 mm 100 mm 5 mm 6.85 kg busbar connection spring-loaded terminals 25 mm 50 m 150 m 250 m
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • downwards • at the side weight without packaging Connections/ Terminals type of electrical connection • for control circuit • for control circuit width of connection bar maximum with conductor cross-section = 0.5 mm² maximum • with conductor cross-section = 1.5 mm² maximum • with conductor cross-section = 2.5 mm² maximum • with conductor cross-section = 2.5 mm² maximum • for DIN cable lug for main contacts stranded	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm 0 mm 10 mm 0 mm 100 mm 75 mm 5 mm 6.85 kg busbar connection spring-loaded terminals 25 mm 50 m 150 m 250 m
OFF-delay time with safety-related request when switched off via control inputs maximum Installation/ mounting/ dimensions mounting position fastening method height width depth required spacing with side-by-side mounting • forwards • backwards • upwards • downwards • at the side weight without packaging Connections/ Terminals type of electrical connection • for control circuit • for control circuit width of connection bar maximum with conductor cross-section = 0.5 mm² maximum • with conductor cross-section = 1.5 mm² maximum • with conductor cross-section = 2.5 mm² maximum • with conductor cross-sections • for DIN cable lug for main contacts stranded • for DIN cable lug for main contacts finely stranded	Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) screw fixing 306 mm 185 mm 203 mm 10 mm 0 mm 10 mm 0 mm 100 mm 75 mm 5 mm 6.85 kg busbar connection spring-loaded terminals 25 mm 50 m 150 m 250 m

- for AWO ophics for control size it colid	0
for AWG cables for control circuit solid	2x (24 16)
 for AWG cables for control circuit finely stranded with core end processing 	2x (24 16)
wire length	
between soft starter and motor maximum	800 m
at the digital inputs at DC maximum	1 000 m
tightening torque	
 for main contacts with screw-type terminals 	10 14 N·m
 for auxiliary and control contacts with screw-type terminals 	0.8 1.2 N·m
tightening torque [lbf·in]	
 for main contacts with screw-type terminals 	89 124 lbf·in
 for auxiliary and control contacts with screw-type terminals 	7 10.3 lbf-in
Ambient conditions	
installation altitude at height above sea level maximum	2 000 m; Derating as of 1000 m, see catalog
ambient temperature	
during operation	-25 +60 °C; Please observe derating at temperatures of 40 °C or above
	, , , , , , , , , , , , , , , , , , ,
during storage and transport	-40 +80 °C
environmental category	
 during operation according to IEC 60721 	3K6 (no ice formation, only occasional condensation), 3C3 (no salt mist), 3S2 (sand must not get into the devices), 3M6
during storage according to IEC 60721	1K6 (only occasional condensation), 1C2 (no salt mist), 1S2 (sand must not get inside the devices), 1M4
 during transport according to IEC 60721 	2K2, 2C1, 2S1, 2M2 (max. fall height 0.3 m)
EMC emitted interference	acc. to IEC 60947-4-2: Class A
Communication/ Protocol	
communication module is supported	
PROFINET standard	Yes
PROFINET high-feature	Yes
EtherNet/IP	Yes
Modbus RTU	Yes
Modbus TCP	Yes
PROFIBUS	Yes
UL/CSA ratings	
manufacturer's article number	
 of circuit breaker 	
 — usable for Standard Faults at 460/480 V according to UL 	Siemens type: 3VA52, max. 250 A; Iq = 10 kA
 — usable for High Faults at 460/480 V according to UL 	Siemens type: 3VA52, max. 250 A; lq max = 65 kA
 — usable for Standard Faults at 460/480 V at inside- delta circuit according to UL 	Siemens type: 3VA52, max. 250 A; Iq = 10 kA
	Siemens type: 3VA52, max. 250 A; Iq max = 65 kA
— usable for Standard Faults at 575/600 V according to UL	Siemens type: 3VA52, max. 250 A; Iq = 10 kA
usable for High Faults at 575/600 V at inside-delta circuit according to UL	Siemens type: 3VA52, max. 250 A; lq max = 65 kA
— usable for Standard Faults at 575/600 V at inside- delta circuit according to UL	Siemens type: 3VA52, max. 250 A; Iq = 10 kA
• of the fuse	
 usable for Standard Faults up to 575/600 V according to UL 	Type: Class RK5 / K5, max. 350 A; lq = 10 kA
— usable for High Faults up to 575/600 V according to UL	Type: Class J / L, max. 350 A; lq = 100 kA
UL — usable for Standard Faults at inside-delta circuit up to 575/600 V according to UL	Type: Class RK5 / K5, max. 350 A; lq = 10 kA
— usable for High Faults at inside-delta circuit up to 575/600 V according to UL	Type: Class J / L, max. 350 A; lq = 100 kA
operating power [hp] for 3-phase motors	
	30 hp
• at 200/208 V at 50 °C rated value	30 hp
• at 220/230 V at 50 °C rated value	30 hp
• at 460/480 V at 50 °C rated value	75 hp
	50 h m
 at 200/208 V at inside-delta circuit at 50 °C rated value at 220/230 V at inside-delta circuit at 50 °C rated value 	50 hp 60 hp

• at 460/480 V at inside-delta circuit at 50 °C rated value	125 hp
contact rating of auxiliary contacts according to UL	R300-B300
Safety related data	
safety device type according to IEC 61508-2	Туре В
B10d value	500 000
Safety Integrity Level (SIL)	
according to IEC 61508	SIL1
SIL Claim Limit (subsystem) according to EN 62061	SIL 1
performance level (PL) according to EN ISO 13849-1	C
category according to EN ISO 13849-1	2
stop category according to EN 60204-1	0
Safe failure fraction (SFF)	60 %
average diagnostic coverage level (DCavg)	90 %
diagnostics test interval by internal test function maximum	1 000 s
PFHD with high demand rate according to EN 62061	1E-6 1/h
PFDavg with low demand rate according to IEC 61508	0.09
hardware fault tolerance according to IEC 61508	0
T1 value for proof test interval or service life according to IEC 61508	20 a
safe state	Open load circuit
protection class IP on the front according to IEC 60529	IP00; IP20 with cover
touch protection on the front according to IEC 60529	finger-safe, for vertical contact from the front with cover
electromagnetic compatibility	acc. to IEC 60947-4-2
ATEX	
certificate of suitability	
• ATEX	Yes
• IECEx	Yes
 according to ATEX directive 2014/34/EU 	BVS 18 ATEX F 003 X
type of protection according to ATEX directive 2014/34/EU	II (2)G [Ex eb Gb] [Ex db Gb] [Ex pxb Gb], II (2)D [Ex tb Db] [Ex pxb Db], I (M2) [Ex db Mb]
hardware fault tolerance according to IEC 61508 relating to ATEX	0
PFDavg with low demand rate according to IEC 61508 relating to ATEX	0.008
PFHD with high demand rate according to EN 62061 relating to ATEX	5E-7 1/h
Safety Integrity Level (SIL) according to IEC 61508 relating to ATEX	SIL1
T1 value for proof test interval or service life according to IEC 61508 relating to ATEX	3 a
Certificates/ approvals	
General Product Approval	
Confirmation CCC	
EMC For use in hazardous locations	Declaration of Con- formity Test Certificates Marine / Shipping

2



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<u>Ty</u> at

<u>Type Test Certific-</u> ates/Test Report



Marine / Shipping other

 Marine / Shipping
 other

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Further information

Siemens has decided to exit the Russian market (see here).

https://press.siemens.com/global/en/pressrelease/siemens-wind-down-russian-business

Siemens is working on the renewal of the current EAC certificates.

Please contact your local Siemens office on the status of validity of the EAC certification if you intend to import or offer to supply these products to an EAC relevant market (other than the sanctioned EAEU member states Russia or Belarus).

Information on the packaging

https://support.industry.siemens.com/cs/ww/en/view/109813875

Information- and Downloadcenter (Catalogs, Brochures,...)

https://www.siemens.com/ic10

Industry Mall (Online ordering system)

https://mall.industry.siemens.com/mall/en/en/Catalog/product?mlfb=3RW5534-2HF14

Cax online generator

http://support.automation.siemens.com/WW/CAXorder/default.aspx?lang=en&mlfb=3RW5534-2HF14

Service&Support (Manuals, Certificates, Characteristics, FAQs,...)

https://support.industry.siemens.com/cs/ww/en/ps/3RW5534-2HF14

Image database (product images, 2D dimension drawings, 3D models, device circuit diagrams, EPLAN macros, ...)

http://www.automation.siemens.com/bilddb/cax_de.aspx?mlfb=3RW5534-2HF14&lang=en

Characteristic: Tripping characteristics, I²t, Let-through current

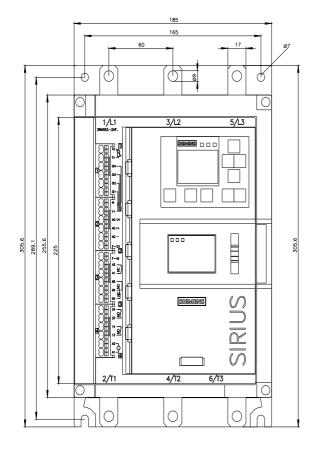
https://support.industry.siemens.com/cs/ww/en/ps/3RW5534-2HF14/char

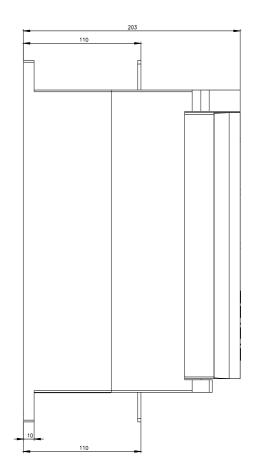
Characteristic: Installation altitude

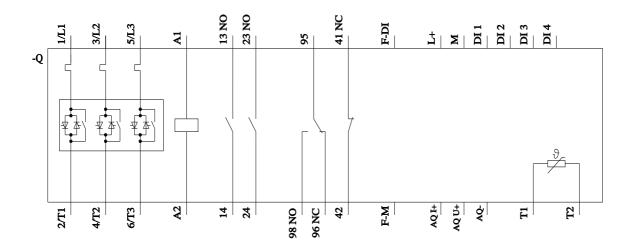
http://www.automation.siemens.com/bilddb/index.aspx?view=Search&mlfb=3RW5534-2HF14&objecttype=14&gridview=view1

Simulation Tool for Soft Starters (STS)

https://support.industry.siemens.com/cs/ww/en/view/101494917







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