

## Revision History AS4C16M16D1A - 66-pin TSOPII PACKAGE

Revision	Details	Date
Rev 1.1	Preliminary datasheet	July 2015
Rev 1.2	Production Released	Aug 2015

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### Features

- Fast clock rate: 200MHz
- Differential Clock CK & CK
- Bi-directional DQS
- DLL enable/disable by EMRS
- Fully synchronous operation
- Internal pipeline architecture
- Four internal banks, 4M x 16-bit for each bank
- Programmable Mode and Extended Mode registers - CAS Latency: 2, 2.5, 3
  - Burst length: 2, 4, 8
  - Burst Type: Sequential & Interleaved
- Individual byte write mask control
- DM Write Latency = 0
- Auto Refresh and Self Refresh
- 8192 refresh cycles / 64ms
- Precharge & active power down
- Power supplies: VDD & VDDQ =  $2.5V \pm 0.2V$
- Interface: SSTL\_2 I/O Interface
- Operating Temperature:
  - Commercial (0°C~70°C)
  - Industrial (-40°C~85°C)
- Package: 66 Pin TSOP II, 0.65mm pin pitch
- Pb free and Halogen free

#### Overview

The AS4C16M16D1 SDRAM is a high-speed CMOS double data rate synchronous DRAM containing 256 Mbits. It is internally configured as a quad 4M x 16 DRAM with a synchronous interface (all signals are registered on the positive edge of the clock signal, CK). Data outputs occur

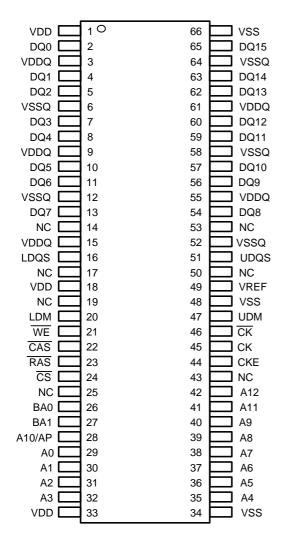
at both rising edges of CK and CK d Read and write accesses to the SDRAM are burst oriented; accesses start at a selected location and continue for a programmed number of locations in a programmed sequence. Accesses begin with the registration of a BankActivate command which is then followed by a Read or Write command. The AS4C16M16D1 provides programmable Read or Write burst lengths of 2, 4, or 8. An auto precharge function may be enabled to provide a self-timed row precharge that is initiated at the end of the burst sequence. The refresh functions, either Auto or Self Refresh are easy to use. In addition, AS4C16M16D1 features programmable DLL option. By having a programmable mode register and extended mode register, the system can choose the most suitable modes to maximize its performance. These devices are well suited for applications requiring high memory band-width, result in a device particularly well suited to high performance main memory and graphics applications.

Product part No	Clock	Temperature	Data Rate	Package				
AS4C16M16D1A-5TCN	200MHz	Commercial 0°C to 70°C	400Mbps/pin	66pin TSOPII				
AS4C16M16D1A-5TIN	200MHz	Industrial -40°C to 85°C	400Mbps/pin	66pin TSOPII				

### Table 1. Ordering Information

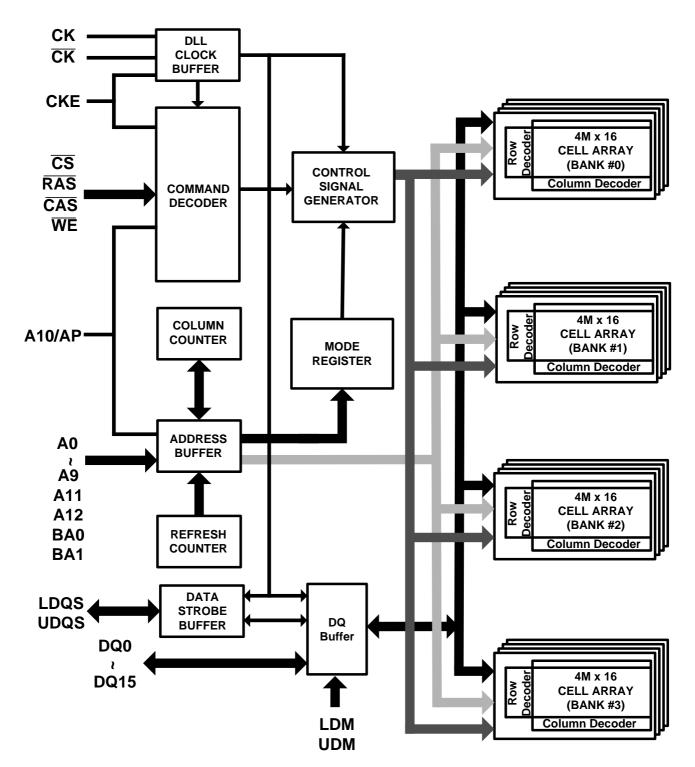


### Figure 1. Pin Assignment (Top View)





### Figure 2. Block Diagram





## **Pin Descriptions**

### Table 2. Pin Details

Symbol	Туре	Description
CK, <del>CK</del>	Input	<b>Differential Clock:</b> CK, $\overline{CK}$ are driven by the system clock. All SDRAM input signals are sampled on the positive edge of CK. Both CK and $\overline{CK}$ increment the internal burst counter and controls the output registers.
СКЕ	Input	<b>Clock Enable:</b> CKE activates (HIGH) and deactivates (LOW) the CK signal. If CKE goes low synchronously with clock, the internal clock is suspended from the next clock cycle and the state of output and burst address is frozen as long as the CKE remains low. When all banks are in the idle state, deactivating the clock controls the entry to the Power Down and Self Refresh modes.
BA0, BA1	Input	<b>Bank Activate:</b> BA0 and BA1 define to which bank the BankActivate, Read, Write, or BankPrecharge command is being applied.
A0-A12	Input	<b>Address Inputs:</b> A0-A12 are sampled during the BankActivate command (row address A0-A12) and Read/Write command (column address A0-A8 with A10 defining Auto Precharge).
CS	Input	<b>Chip Select:</b> $\overline{CS}$ enables (sampled LOW) and disables (sampled HIGH) the command decoder. All commands are masked when $\overline{CS}$ is sampled HIGH. $\overline{CS}$ provides for external bank selection on systems with multiple banks. It is considered part of the command code.
RAS	Input	<b>Row Address Strobe:</b> The $\overrightarrow{RAS}$ signal defines the operation commands in conjunction with the $\overrightarrow{CAS}$ and $\overrightarrow{WE}$ signals and is latched at the positive edges of CK. When $\overrightarrow{RAS}$ and $\overrightarrow{CS}$ are asserted "LOW" and $\overrightarrow{CAS}$ is asserted "HIGH," either the BankActivate command or the Precharge command is selected by the $\overrightarrow{WE}$ signal. When the $\overrightarrow{WE}$ is asserted "HIGH," the BankActivate command is selected and the bank designated by BA is turned on to the active state. When the $\overrightarrow{WE}$ is asserted "LOW," the Precharge command is selected and the bank designated by BA is turned on to the active state. When the $\overrightarrow{WE}$ is asserted "LOW," the Precharge command is selected and the bank designated by BA is selected and the bank designated by BA is selected.
CAS	Input	<b>Column Address Strobe:</b> The $\overline{CAS}$ signal defines the operation commands in conjunction with the $\overline{RAS}$ and $\overline{WE}$ signals and is latched at the positive edges of CK. When $\overline{RAS}$ is held "HIGH" and $\overline{CS}$ is asserted "LOW," the column access is started by asserting $\overline{CAS}$ "LOW." Then, the Read or Write command is selected by asserting $\overline{WE}$ "HIGH" or "LOW".
WE	Input	Write Enable: The $\overline{WE}$ signal defines the operation commands in conjunction with the $\overline{RAS}$ and $\overline{CAS}$ signals and is latched at the positive edges of CK. The $\overline{WE}$ input is used to select the BankActivate or Precharge command and Read or Write command.
LDQS,	Input /	Bidirectional Data Strobe: Specifies timing for Input and Output data. Read Data
UDQS	Output	Strobe is edge triggered. Write Data Strobe provides a setup and hold time for data and DQM. LDQS is for DQ0~7, UDQS is for DQ8~15.
LDM,	Input	Data Input Mask: Input data is masked when DM is sampled HIGH during a write
UDM		cycle. LDM masks DQ0-DQ7, UDM masks DQ8-DQ15.
DQ0 - DQ15	Input /	<b>Data I/O:</b> The DQ0-DQ15 input and output data are synchronized with positive and
	Output	negative edges of LDQS and UDQS. The I/Os are byte-maskable during Writes.



Vdd	Supply	Power Supply: $2.5V \pm 0.2V$ .
Vss	Supply	Ground
Vddq	Supply	<b>DQ Power:</b> 2.5V $\pm$ 0.2V. Provide isolated power to DQs for improved noise immunity.
Vssq	Supply	DQ Ground: Provide isolated ground to DQs for improved noise immunity.
Vref	Supply	Reference Voltage for Inputs: +0.5*VDDQ
NC	-	No Connect: These pins should be left unconnected.



### **Operation Mode**

Fully synchronous operations are performed to latch the commands at the positive edges of CK. Table 3 shows the truth table for the operation commands.

Command	State	CKEn-1	CKEn	DM	BA0,1	A10	A0-9, 11-12	CS	RAS		WE
BankActivate	Idle <sup>(3)</sup>	Н	Х	Х	V	Ro	w address	L	L	Н	Н
BankPrecharge	Any	Н	Х	Х	V	L	Х	L	L	Н	L
PrechargeAll	Any	Н	Х	Х	Х	Н	Х	L	L	Н	L
Write	Active <sup>(3)</sup>	Н	Х	Х	V	L	Column	L	Н	L	L
Write and AutoPrecharge	Active <sup>(3)</sup>	н	Х	Х	V	н	address (A0 ~ A8)	L	н	L	L
Read	Active <sup>(3)</sup>	н	Х	Х	V	L	Column	L	Н	L	Н
Read and Autoprecharge	Active <sup>(3)</sup>	Н	Х	Х	V	Н	address (A0 ~ A8)	L	н	L	Н
Mode Register Set	Idle	Н	Х	Х		OP (	code	L	L	L	L
Extended MRS	Idle	Н	Х	Х		OP (	code	L	L	L	L
No-Operation	Any	Н	Х	Х	Х	Х	Х	L	Н	Н	Н
Burst Stop	Active <sup>(4)</sup>	н	Х	Х	Х	Х	Х	L	Н	Н	L
Device Deselect	Any	н	Х	Х	Х	Х	Х	Н	Х	Х	Х
AutoRefresh	Idle	Н	н	Х	Х	Х	Х	L	L	L	Н
SelfRefresh Entry	Idle	н	L	Х	Х	Х	Х	L	L	L	Н
SelfRefresh Exit	Idle	L	н	Х	Х	Х	Х	Н	Х	Х	Х
	(SelfRefresh)							L	Н	Н	Н
Precharge Power Down	Idle	Н	L	Х	Х	Х	Х	Н	Х	Х	Х
Mode Entry								L	Н	Н	Н
Precharge Power Down	Any	L	н	Х	Х	Х	Х	Н	Х	Х	Х
Mode Exit	(PowerDown)							L	Н	Н	Н
Active Power Down Mode Entry	Active	Н	L	х	х	Х	х	Н	Х	Х	Х
								L	V	V	V
Active Power Down Mode	Any	L	н	Х	Х	Х	Х	H	X	Х	Х
	(PowerDown)							L	Н	Н	Н
Data Input Mask Disable	Active	Н	Х	L	Х	Х	Х	Х	Х	Х	Х
Data Input Mask Enable(5)	Active	Н	X	Н	Х	Х	Х	Х	Х	Х	Х

Table 3. Truth Table (Note (1), (2))

**Note:** 1. V=Valid data, X=Don't Care, L=Low level, H=High level

2. CKEn signal is input level when commands are provided.

CKEn-1 signal is input level one clock cycle before the commands are provided.

3. These are states of bank designated by BA signal.

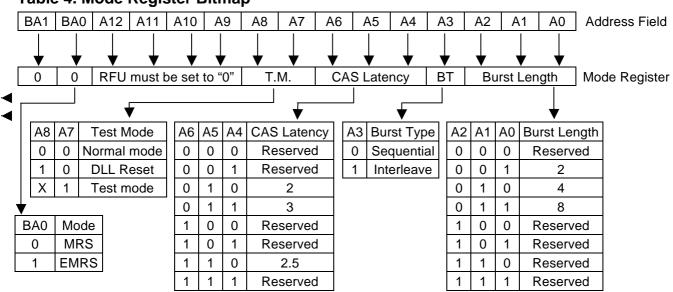
4. Device state is 2, 4, and 8 burst operation.

5. LDM and UDM can be enabled respectively.



#### Mode Register Set (MRS)

The Mode Register stores the data for controlling various operating modes of a DDR SDRAM. It programs CAS Latency, Burst Type, and Burst Length to make the DDR SDRAM useful for a variety of applications. The default value of the Mode Register is not defined; therefore the Mode Register must be written by the user. Values stored in the register will be retained until the register is reprogrammed. The Mode Register is written by asserting Low on  $\overline{CS}$ ,  $\overline{RAS}$ ,  $\overline{CAS}$ ,  $\overline{WE}$ , BA1 and BA0 (the device should have all banks idle with no bursts in progress prior to writing into the mode register, and CKE should be High). The state of address pins A0~A12 and BA0, BA1 in the same cycle in which  $\overline{CS}$ ,  $\overline{RAS}$ ,  $\overline{CAS}$  and  $\overline{WE}$  are asserted Low is written into the Mode Register. A minimum of two clock cycles, tMRD, are required to complete the write operation in the Mode Register. The Mode Register is divided into various fields depending on functionality. The Burst Length uses A0~A2, Burst Type uses A3, and CAS Latency (read latency from column address) uses A4~A6. A logic 0 should be programmed to all the undefined addresses to ensure future compatibility. Reserved states should not be used to avoid unknown device operation or incompatibility with future versions. Refer to the table for specific codes for various burst lengths, burst types and CAS latencies.



#### Table 4. Mode Register Bitmap

#### • Burst Length Field (A2~A0)

This field specifies the data length of column access using the A2 $\sim$ A0 pins and selects the Burst Length to be 2, 4, 8.

#### Table 5. Burst Length

	5		
A2	A1	A0	Burst Length
0	0	0	Reserved
0	0	1	2
0	1	0	4
0	1	1	8
1	0	0	Reserved
1	0	1	Reserved
1	1	0	Reserved
1	1	1	Reserved



Addressing Mode Select Field (A3)

The Addressing Mode can be one of two modes, either Interleave Mode or Sequential Mode. Both Sequential Mode and Interleave Mode support burst length of 2, 4 and 8.

#### Table 6. Addressing Mode

A3	Addressing Mode	
0	Sequential	
1	Interleave	

• Burst Definition, Addressing Sequence of Sequential and Interleave Mode

#### Table 7. Burst Address ordering

Durat Langth	S	tart Addres	s	Cogneptial	Interlegive	
Burst Length	A2	A1	A0	Sequential	Interleave	
2	Х	Х	0	0, 1	0, 1	
2	Х	Х	1	1, 0	1, 0	
	Х	0	0	0, 1, 2, 3	0, 1, 2, 3	
4	Х	0	1	1, 2, 3, 0	1, 0, 3, 2	
4	Х	1	0	2, 3, 0, 1	2, 3, 0, 1	
	Х	1	1	3, 0, 1, 2	3, 2, 1, 0	
	0	0	0	0, 1, 2, 3, 4, 5, 6, 7	0, 1, 2, 3, 4, 5, 6, 7	
	0	0	1	1, 2, 3, 4, 5, 6, 7, 0	1, 0, 3, 2, 5, 4, 7, 6	
	0	1	0	2, 3, 4, 5, 6, 7, 0, 1	2, 3, 0, 1, 6, 7, 4, 5	
8	0	1	1	3, 4, 5, 6, 7, 0, 1, 2	3, 2, 1, 0, 7, 6, 5, 4	
0	1	0	0	4, 5, 6, 7, 0, 1, 2, 3	4, 5, 6, 7, 0, 1, 2, 3	
	1	0	1	5, 6, 7, 0, 1, 2, 3, 4	5, 4, 7, 6, 1, 0, 3, 2	
	1	1	0	6, 7, 0, 1, 2, 3, 4, 5	6, 7, 4, 5, 2, 3, 0, 1	
	1	1	1	7, 0, 1, 2, 3, 4, 5, 6	7, 6, 5, 4, 3, 2, 1, 0	

#### • CAS Latency Field (A6~A4)

This field specifies the number of clock cycles from the assertion of the Read command to the first read data. The minimum whole value of CAS Latency depends on the frequency of CK. The minimum whole value satisfying the following formula must be programmed into this field.  $t_{CAC}(min) \leq CAS$  Latency X tck

#### Table 8. CAS Latency

A6	A5	A4	CAS Latency
0	0	0	Reserved
0	0	1	Reserved
0	1	0	2 clocks
0	1	1	3 clocks
1	0	0	Reserved
1	0	1	Reserved
1	1	0	2.5 clocks
1	1	1	Reserved



#### • Test Mode field (A8~A7)

These two bits are used to enter the test mode and must be programmed to "00" in normal operation.

#### Table 9. Test Mode

A8	A7	Test Mode
0	0	Normal mode
1	0	DLL Reset

• (BA0, BA1)

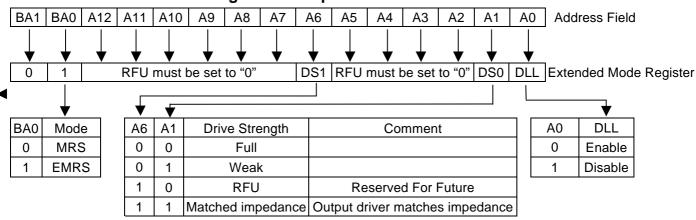
#### Table 10. MRS/EMRS

BA1	BA0	A12 ~ A0
RFU	0	MRS Cycle
RFU	1	Extended Functions (EMRS)



#### Extended Mode Register Set (EMRS)

The Extended Mode Register Set stores the data for enabling or disabling DLL and selecting output driver strength. The default value of the extended mode register is not defined, therefore must be written after power up for proper operation. The extended mode register is written by asserting low on  $\overline{CS}$ ,  $\overline{RAS}$ ,  $\overline{CAS}$ , and  $\overline{WE}$ . The state of A0 ~ A12, BA0 and BA1 is written in the mode register in the same cycle as  $\overline{CS}$ ,  $\overline{RAS}$ ,  $\overline{CAS}$ , and  $\overline{WE}$  going low. (the device should have all banks idle with no bursts in progress prior to writing into the mode register, and CKE should be High). A1 is used for setting driver strength to normal, or weak. Two clock cycles are required to complete the write operation in the extended mode register. The mode register contents can be changed using the same command and clock cycle requirements during operation as long as all banks are in the idle state. A0 is used for DLL enable or disable. "High" on BA0 is used for EMRS. Refer to the table for specific codes.



### Table 11. Extended Mode Register Bitmap



#### Table 12. Absolute Maximum Rating

Symbol	ltem	Rating	Unit	
VIN, VOUT	Input, Output Voltag	ge	- 0.5~ Vddq + 0.5	V
Vdd, Vddq	Power Supply Volta	ge	- 1~3.6	V
_	Ambient Temperature	Commercial	0~70	°C
TA		Industrial	-40~85	°C
Tstg	Storage Temperatu	re	-55~150	°C
TSOLDER	Soldering Temperat	Soldering Temperature		°C
PD	Power Dissipation		1	W
los	Short Circuit Output Co	urrent	50	mA

Note1: Stress greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device.

Note2: These voltages are relative to Vss

### Table 13. Recommended D.C. Operating Conditions (VDD = 2.5V ± 0.2V, TA = -40~85 °C)

				-
Parameter	Min.	Max.	Unit	Note
Power Supply Voltage	2.3	2.7	V	
Power Supply Voltage (for I/O Buffer)	2.3	2.7	V	
Input Reference Voltage	0.49*Vddq	0.51* Vddq	V	
Input High Voltage (DC)	Vref + 0.15	V <sub>DDQ</sub> + 0.3	V	
Input Low Voltage (DC)	-0.3	Vref – 0.15	V	
Termination Voltage	Vref - 0.04	Vref + 0.04	V	
Input Voltage Level, CK and $\overline{CK}$ inputs	-0.3	Vddq + 0.3	V	
Input Different Voltage, CK and $\overline{CK}$ inputs	0.36	Vddq + 0.6	V	
Input leakage current	-2	2	μA	
Output leakage current	-5	5	μA	
Output High Current	-16.2	-	mA	Vон = 1.95V
Output Low Current	16.2	-	mA	Vol = 0.35V
	Power Supply Voltage Power Supply Voltage (for I/O Buffer) Input Reference Voltage Input High Voltage (DC) Input Low Voltage (DC) Termination Voltage Input Voltage Level, CK and $\overline{CK}$ inputs Input Different Voltage, CK and $\overline{CK}$ inputs Input leakage current Output leakage current Output High Current	Power Supply Voltage2.3Power Supply Voltage (for I/O Buffer)2.3Input Reference Voltage $0.49^*V_{DDQ}$ Input High Voltage (DC) $V_{REF} + 0.15$ Input Low Voltage (DC)-0.3Termination Voltage $V_{REF} - 0.04$ Input Voltage Level, CK and $\overline{CK}$ inputs-0.3Input Different Voltage, CK and $\overline{CK}$ inputs0.36Input leakage current-2Output leakage current-5Output High Current-16.2	Power Supply Voltage2.32.7Power Supply Voltage (for I/O Buffer)2.32.7Input Reference Voltage $0.49^*V_{DDQ}$ $0.51^*V_{DDQ}$ Input High Voltage (DC) $V_{REF} + 0.15$ $V_{DDQ} + 0.3$ Input Low Voltage (DC) $-0.3$ $V_{REF} - 0.15$ Termination Voltage $V_{REF} - 0.04$ $V_{REF} + 0.04$ Input Voltage Level, CK and $\overline{CK}$ inputs $-0.3$ $V_{DDQ} + 0.3$ Input Different Voltage, CK and $\overline{CK}$ inputs $0.36$ $V_{DDQ} + 0.6$ Input leakage current $-2$ 2Output leakage current $-5$ 5Output High Current $-16.2$ $-$	Power Supply Voltage2.32.7VPower Supply Voltage (for I/O Buffer)2.32.7VInput Reference Voltage $0.49^*V_{DDQ}$ $0.51^*V_{DDQ}$ VInput High Voltage (DC) $V_{REF} + 0.15$ $V_{DDQ} + 0.3$ VInput Low Voltage (DC) $-0.3$ $V_{REF} - 0.15$ VTermination Voltage $V_{REF} - 0.04$ $V_{REF} + 0.04$ VInput Voltage Level, CK and $\overline{CK}$ inputs $-0.3$ $V_{DDQ} + 0.3$ VInput Different Voltage, CK and $\overline{CK}$ inputs $0.36$ $V_{DDQ} + 0.6$ VInput leakage current $-2$ $2$ $\mu A$ Output leakage current $-5$ $5$ $\mu A$

Note: All voltages are referenced to Vss.

Symbol	Parameter	Min.	Max.	Unit
CIN1	Input Capacitance (CK, $\overline{CK}$ )	2	3	pF
CIN2	Input Capacitance (All other input-only pins)	2	3	pF
Cı/o	DQ, DQS, DM Input/Output Capacitance	4	5	pF

Note: These parameters are guaranteed by design, periodically sampled and are not 100% tested



### Table 15. D.C. Characteristics ( $V_{DD} = 2.5V \pm 0.2V$ , $T_A = -40 \sim 85 \circ C$ )

		-5		
Parameter & Test Condition	Symbol	Max.	Unit	Note
<b>OPERATING CURRENT:</b> One bank; Active-Precharge; tRC=tRC(min); tCK=tCK(min); DQ,DM and DQS inputs changing once per clock cycle; Address and control inputs changing once every two clock cycles.	IDD0	65	mA	
<b>OPERATING CURRENT :</b> One bank; Active-Read- Precharge; BL=4; tRC=tRC(min); tCK=tCK(min); lout=0mA; Address and control inputs changing once per clock cycle	IDD1	70	mA	
PRECHARGE POWER-DOWN STANDBY CURRENT: All banks idle; power-down mode; tCK=tCK(min); CKE=LOW	IDD2P	5	mA	
<b>PRECHARGE FLOATING STANDBY CURRENT:</b> CKE = HIGH; CS =HIGH(DESELECT); All banks idle; tck=tck(min); Address and control inputs changing once per clock cycle; VIN=VREF for DQ, DQS and DM	IDD2F	30	mA	
<b>PRECHARGE QUIET STANDBY CURRENT:</b> CKE = HIGH; CS =HIGH(DESELECT); All banks idle; tcκ=tcκ(min); Address and other control input stadle at HIGH or LOW; VIN=VREF for DQ, DQS and DM	IDD2Q	20	mA	
ACTIVE POWER-DOWN STANDBY CURRENT : one bank active; power-down mode; CKE=LOW; tck=tck(min)	IDD3P	20	mA	
<b>ACTIVE STANDBY CURRENT</b> : CS =HIGH;CKE=HIGH; one bank active ; tRC=tRC(max);tCK=tCK(min);Address and control inputs changing once per clock cycle; DQ,DQS,and DM inputs changing twice per clock cycle	IDD3N	55	mA	
<b>OPERATING CURRENT BURST READ :</b> BL=2; READS; Continuous burst; one bank active; Address and control inputs changing once per clock cycle; tck=tck(min); lout=0mA;50% of data changing on every transfer	IDD4R	100	mA	
<b>OPERATING CURRENT BURST Write :</b> BL=2; WRITES; Continuous Burst ;one bank active; address and control inputs changing once per clock cycle; tCK=tCK(min); DQ,DQS,and DM changing twice per clock cycle; 50% of data changing on every transfer	IDD4W	100	mA	
AUTO REFRESH CURRENT : tRC=tRFC(min); tCK=tCK(min)	IDD5	100	mA	
SELF REFRESH CURRENT: Sell Refresh Mode ; CKE≦ 0.2V;tcκ=tcκ(min)	IDD6	2	mA	1
BURST OPERATING CURRENT 4 bank operation: Four bank interleaving READs; BL=4;with Auto Precharge; tRC=tRC(min); tCK=tCK(min); Address and control inputs change only during Active, READ, or WRITE command	IDD7	140	mA	



## Table 16. Electrical Characteristics and Recommended A.C.Operating Condition

 $(V_{DD} = 2.5V \pm 0.2V, T_A = -40 \sim 85 °C)$ 

Symbol	Parameter		-5			Note
Symbol			Min.	Max.	Unit	Note
	С	L = 2	7.5	12	ns	
tск	Clock cycle time	L = 2.5	6	12	ns	
	С	L = 3	5	10	ns	
tсн	Clock high level width		0.45	0.55	tск	
tc∟	Clock low level width		0.45	0.55	tск	
thp	Clock half period		t <sub>CLMIN</sub> or t <sub>CHMIN</sub>	-	ns	2
tнz	Data-out-high impedance time from CK,	CK	-	0.7	ns	3
t∟z	Data-out-low impedance time from CK,	CK	-0.7	0.7	ns	3
<b>t</b> DQSCK	DQS-out access time from CK, $\overline{CK}$		-0.6	0.6	ns	
tac	Output access time from CK, $\overline{CK}$		-0.7	0.7	ns	
tDQSQ	DQS-DQ Skew		-	0.4	ns	
<b>t</b> RPRE	Read preamble		0.9	1.1	tск	
<b>t</b> RPST	Read postamble		0.4	0.6	tск	
tDQSS	CK to valid DQS-in		0.72	1.25	tск	
twpres	DQS-in setup time		0	-	ns	4
twpre	DQS write preamble		0.25	-	tск	
twpst	DQS write postamble		0.4	0.6	tск	5
<b>t</b> DQSH	DQS in high level pulse width		0.35	-	tск	
<b>t</b> DQSL	DQS in low level pulse width		0.35	-	tск	
tıs	Address and Control input setup time		0.7	-	ns	6
tıн	Address and Control input hold time		0.7	-	ns	6
tos	DQ & DM setup time to DQS		0.4	-	ns	
tрн	DQ & DM hold time to DQS		0.4	-	ns	
tqн	DQ/DQS output hold time from DQS		thp - t <sub>QHS</sub>	-	ns	
trc	Row cycle time		55	-	ns	
<b>t</b> RFC	Refresh row cycle time		70	-	ns	
tras	Row active time		40	70k	ns	
trcd	Active to Read or Write delay		15	-	ns	
<b>t</b> RP	Row precharge time		15	-	ns	
trrd	Row active to Row active delay		10	-	ns	
twr	Write recovery time		15	-	ns	
<b>t</b> wtr	Internal Write to Read Command Delay		2	-	tск	
<b>t</b> MRD	Mode register set cycle time		10	-	ns	
trefi	Average Periodic Refresh interval		-	7.8	μS	7
txsrd	Self refresh exit to read command delay	/	200	-	tск	
<b>t</b> XSNR	Self refresh exit to non-read command of		75	-	ns	
<b>t</b> DAL	Auto Precharge write recovery + precharg		twr + trp	-	ns	
<b>t</b> DIPW	DQ and DM input puls width		1.75	-	ns	
tipw	Control and Address input pulse width		2.2	-	ns	1
t <sub>QHS</sub>	Data Hold Skew Factor		-	0.5	ns	
t <sub>DSS</sub>	DQS falling edge to CK setup time		0.2	-	tск	<u> </u>
t <sub>DSH</sub>	DQS falling edge hold time from CK		0.2	-	tск	

#### Table 17. Recommended A.C. Operating Conditions (VDD = 2.5V ± 0.2V, TA = -40~85 °C)

Symbol	Parameter	Min.	Max.	Unit
VIH (AC)	Input High Voltage (AC)	Vref + 0.31	-	V
Vı∟(AC)	Input Low Voltage (AC)	-	Vref – 0.31	V
VID (AC)	Input Different Voltage, CK and $\overline{CK}$ inputs	0.7	Vddq + 0.6	V
Vix (AC)	Input Crossing Point Voltage, CK and $\overline{CK}$ inputs	0.5*Vddq-0.2	0.5*Vddq+0.2	V

#### Note:

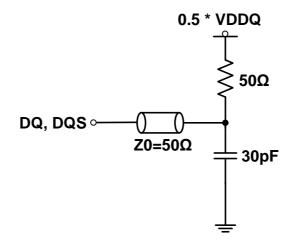
- 1) Enables on-chip refresh and address counters.
- 2) Min(t<sub>CL</sub>, t<sub>CH</sub>) refers to the smaller of the actual clock low time and actual clock high time as provided to the device.
- tHz and tLz transitions occur in the same access time windows as valid data transitions. These parameters are not referenced to a specific voltage level, but specify when the device output is no longer driving(HZ), or begins driving(LZ).
- 4) The specific requirement is that DQS be valid (High, Low, or at some point on a valid transition) on or before this CK edge. A valid transition is defined as monotonic, and meeting the input slew rate specifications of the device. When no writes were previously in progress on the bus, DQS will be transitioning from High-Z to logic LOW. If a previous write was in progress, DQS could be HIGH, LOW, or transitioning from HIGH to LOW at this time, depending on tDQSS.
- 5) The maximum limit for this parameter is not a device limit. The device will operate with a greater value for this parameter, but system performance (bus turnaround) will degrade accordingly.
- 6) For command/address slew rate  $\geq$  0.5V/ns and <1.0V/ns. For CK & CK slew rate  $\geq$  1.0V/ns.
- 7) A maximum of eight AUTO REFRESH commands can be posted to any given DDR SDRAM device.
- 8) Power-up sequence is described in Note 10
- 9) A.C. Test Conditions

#### Table 18. SSTL \_2 Interface

Reference Level of Output Signals (VREF)	0.5 * VDDQ
Output Load	Reference to the Test Load
Input Signal Levels	Vref+0.31 V / Vref-0.31 V
Input Signals Slew Rate	1 V/ns
Reference Level of Input Signals	0.5 * Vddq



### Figure 3. SSTL\_2 A.C. Test Load



#### 10) Power up Sequence

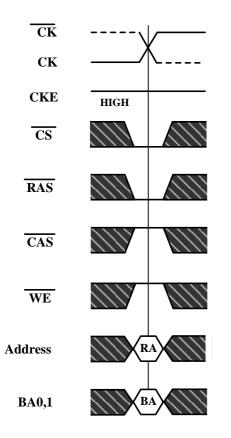
Power up must be performed in the following sequence.

- 1) Apply power to VDD before or at the same time as VDDQ, VTT and VREF when all input signals are held "NOP" state and maintain CKE "LOW".
- 2) Start clock and maintain stable condition for minimum 200µs.
- 3) Issue a "NOP" command and keep CKE "HIGH"
- 4) Issue a "Precharge All" command.
- 5) Issue EMRS enable DLL.
- 6) Issue MRS reset DLL. (An additional 200 clock cycles are required to lock the DLL).
- 7) Precharge all banks of the device.
- 8) Issue two or more Auto Refresh commands.
- 9) Issue MRS with A8 to low to initialize the mode register.



## **Timing Waveforms**

### Figure 4. Activating a Specific Row in a Specific Bank

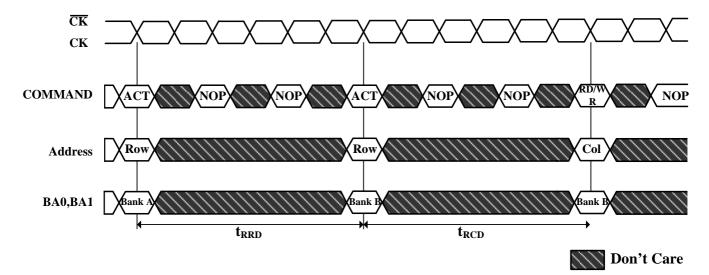


RA=Row Address BA=Bank Address

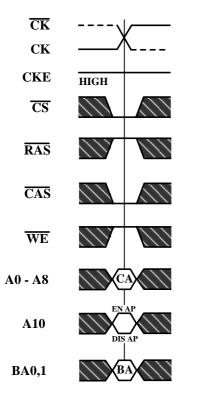




### Figure 5. tRCD and tRRD Definition



### Figure 6. READ Command

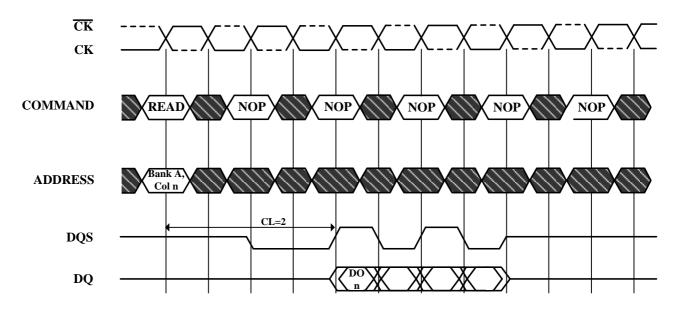


CA=Column Address BA=Bank Address EN AP=Enable Autoprecharge DIS AP=Disable Autoprecharge



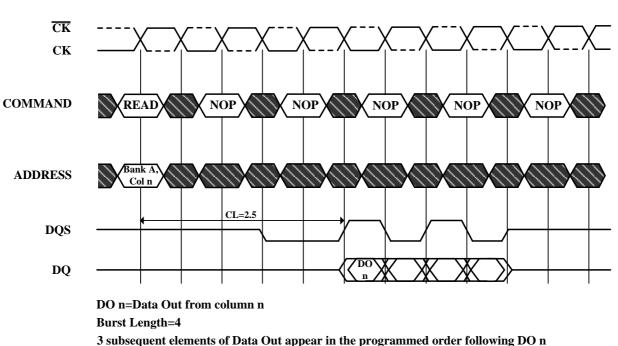


### Figure 7. Read Burst Required CAS Latencies (CL=2)



DO n=Data Out from column n Burst Length=4 3 subsequent elements of Data Out appear in the programmed order following DO n



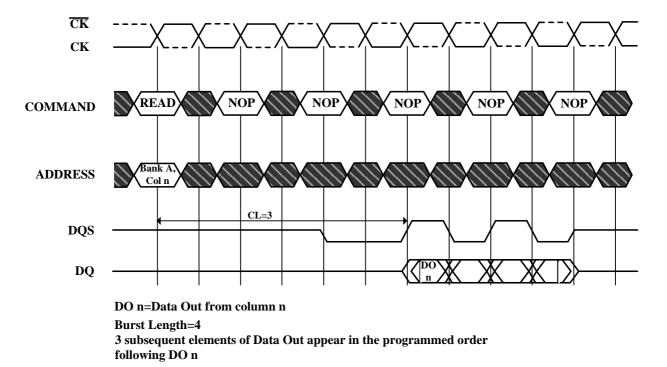


# Read Burst Required CAS Latencies (CL=2.5)





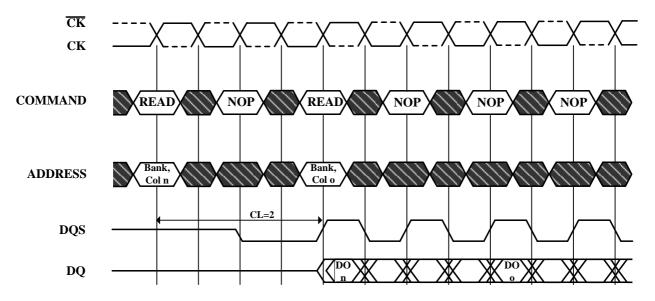
### Read Burst Required CAS Latencies (CL=3)







### Figure 8. Consecutive Read Bursts Required CAS Latencies (CL=2)

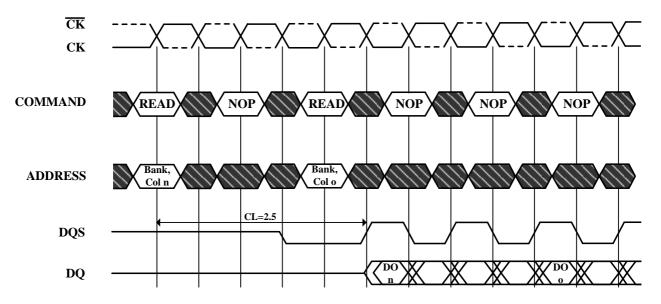


DO n (or o)=Data Out from column n (or column o) Burst Length=4 or 8 (if 4, the bursts are concatenated; if 8, the second burst interrupts the first) 3 subsequent elements of Data Out appear in the programmed order following DO n 3 (or 7) subsequent elements of Data Out appear in the programmed order following DO o Read commands shown must be to the same device





### Consecutive Read Bursts Required CAS Latencies (CL=2.5)

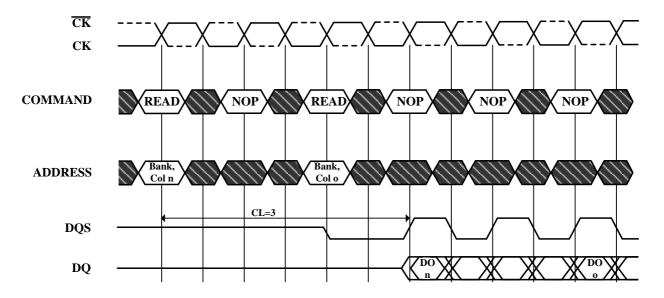


DO n (or o)=Data Out from column n (or column o) Burst Length=4 or 8 (if 4, the bursts are concatenated; if 8, the second burst interrupts the first) 3 subsequent elements of Data Out appear in the programmed order following DO n 3 (or 7) subsequent elements of Data Out appear in the programmed order following DO o Read commands shown must be to the same device





### Consecutive Read Bursts Required CAS Latencies (CL=3)

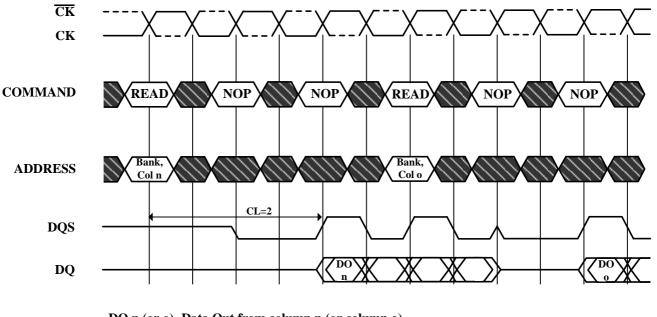


DO n (or o)=Data Out from column n (or column o) Burst Length=4 or 8 (if 4, the bursts are concatenated; if 8, the second burst interrupts the first) 3 subsequent elements of Data Out appear in the programmed order following DO n 3 (or 7) subsequent elements of Data Out appear in the programmed order following DO o Read commands shown must be to the same device



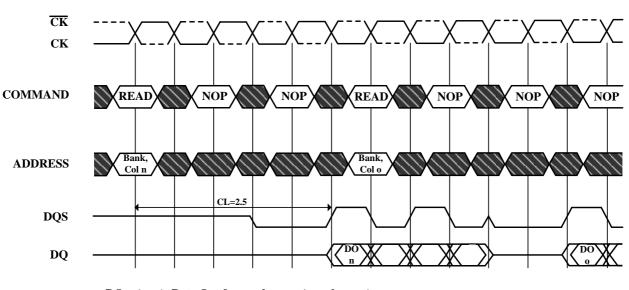


### Figure 9. Non-Consecutive Read Bursts Required CAS Latencies (CL=2)



DO n (or o)=Data Out from column n (or column o) Burst Length=4 3 subsequent elements of Data Out appear in the programmed order following DO n (and following DO o)





### Non-Consecutive Read Bursts Required CAS Latencies (CL=2.5)

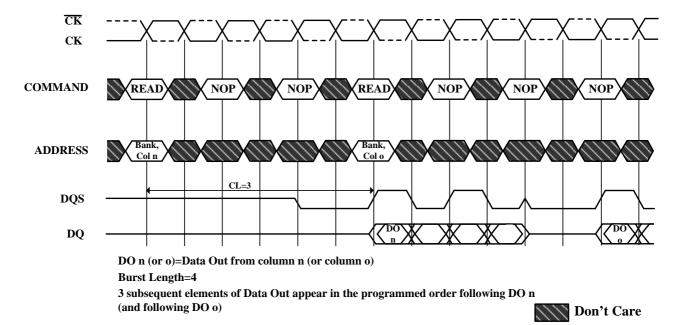
DO n (or o)=Data Out from column n (or column o) Burst Length=4

3 subsequent elements of Data Out appear in the programmed order following DO n (and following DO o)



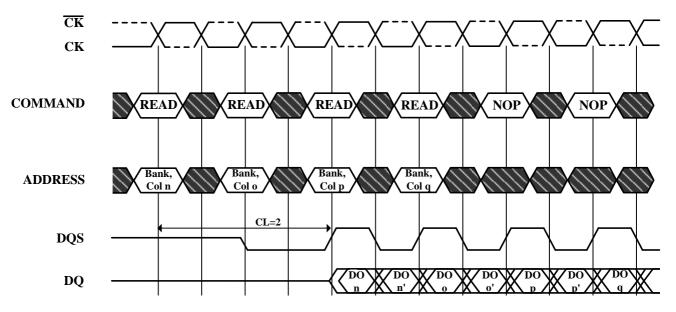


### Non-Consecutive Read Bursts Required CAS Latencies (CL=3)



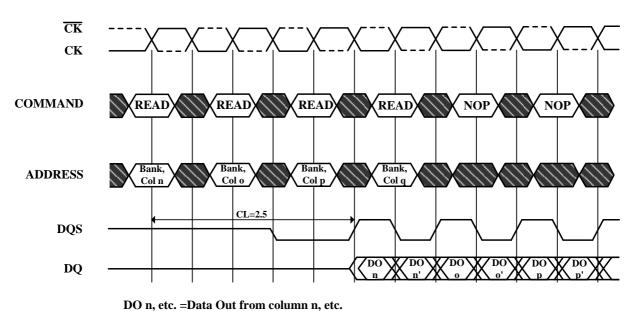


### Figure 10. Random Read Accesses Required CAS Latencies (CL=2)



DO n, etc. =Data Out from column n, etc. n', etc. =the next Data Out following DO n, etc. according to the programmed burst order Burst Length=2,4 or 8 in cases shown. If burst of 4 or 8, the burst is interrupted Reads are to active rows in any banks





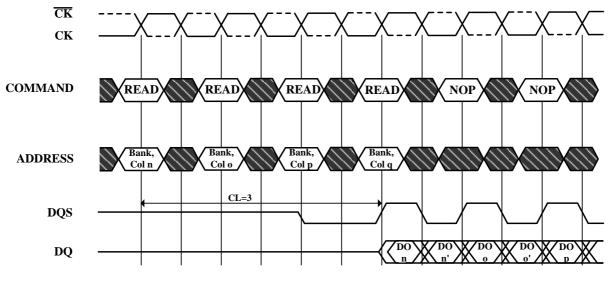
### Random Read Accesses Required CAS Latencies (CL=2.5)

n', etc. =the next Data Out following DO n, etc. according to the programmed burst order Burst Length=2,4 or 8 in cases shown. If burst of 4 or 8, the burst is interrupted Reads are to active rows in any banks





### Random Read Accesses Required CAS Latencies (CL=3)



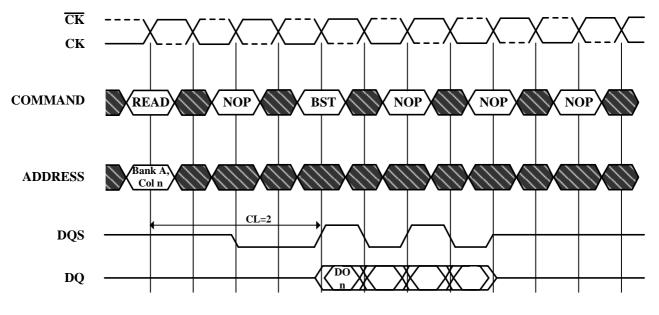
DO n, etc. =Data Out from column n, etc.

n', etc. =the next Data Out following DO n, etc. according to the programmed burst order Burst Length=2,4 or 8 in cases shown. If burst of 4 or 8, the burst is interrupted Reads are to active rows in any banks





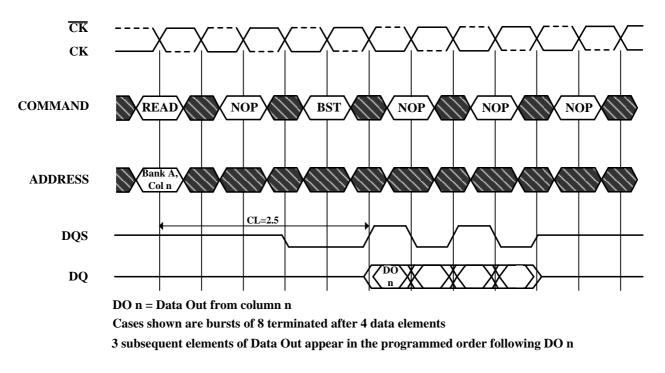
### Figure 11. Terminating a Read Burst Required CAS Latencies (CL=2)



DO n = Data Out from column n Cases shown are bursts of 8 terminated after 4 data elements 3 subsequent elements of Data Out appear in the programmed order following DO n



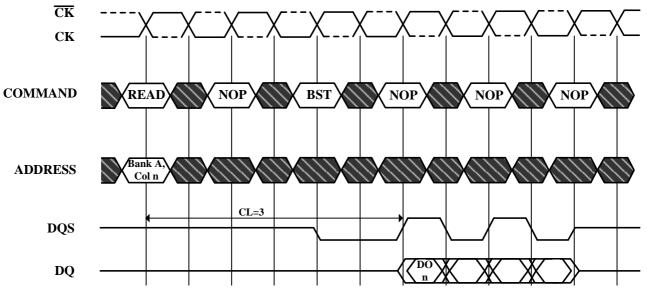
# Terminating a Read Burst Required CAS Latencies (CL=2.5)







### Terminating a Read Burst Required CAS Latencies (CL=3)



DO n = Data Out from column n

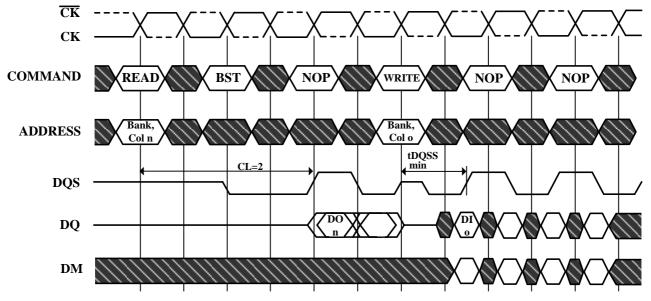
Cases shown are bursts of 8 terminated after 4 data elements

3 subsequent elements of Data Out appear in the programmed order following DO n





### Figure 12. Read to Write Required CAS Latencies (CL=2)



DO n (or o)= Data Out from column n (or column o)

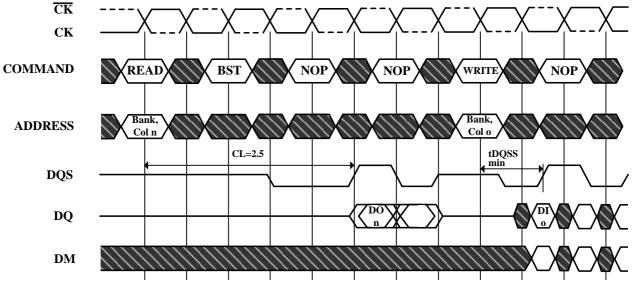
Burst Length= 4 in the cases shown (applies for bursts of 8 as well; if burst length is 2, the BST command shown can be NOP)

1 subsequent element of Data Out appears in the programmed order following DO n Data in elements are applied following DI o in the programmed order





## Read to Write Required CAS Latencies (CL=2.5)



DO n (or o)= Data Out from column n (or column o)

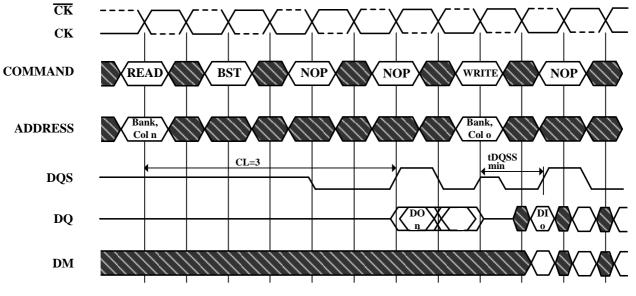
Burst Length= 4 in the cases shown (applies for bursts of 8 as well; if burst length is 2, the BST command shown can be NOP)

1 subsequent element of Data Out appears in the programmed order following DO n Data in elements are applied following DI o in the programmed order





## Read to Write Required CAS Latencies (CL=3)



DO n (or o)= Data Out from column n (or column o)

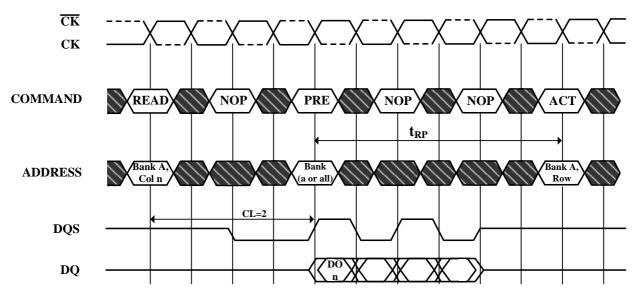
Burst Length= 4 in the cases shown (applies for bursts of 8 as well; if burst length is 2, the BST command shown can be NOP)

1 subsequent element of Data Out appears in the programmed order following DO n Data in elements are applied following DI o in the programmed order





### Figure 13. Read to Precharge Required CAS Latencies (CL=2)



**DO n = Data Out from column n** 

Cases shown are either uninterrupted bursts of 4, or interrupted bursts of 8 3 subsequent elements of Data Out appear in the programmed order following DO n

Precharge may be applied at (BL/2) tCK after the READ command

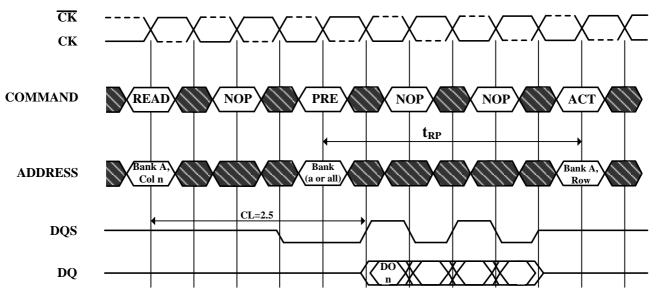
Note that Precharge may not be issued before tRAS ns after the ACTIVE command for applicable banks

The Active command may be applied if tRC has been met





#### Read to Precharge Required CAS Latencies (CL=2.5)



DO n = Data Out from column n

Cases shown are either uninterrupted bursts of 4, or interrupted bursts of 8 3 subsequent elements of Data Out appear in the programmed order following DO n

Precharge may be applied at (BL/2) tCK after the READ command

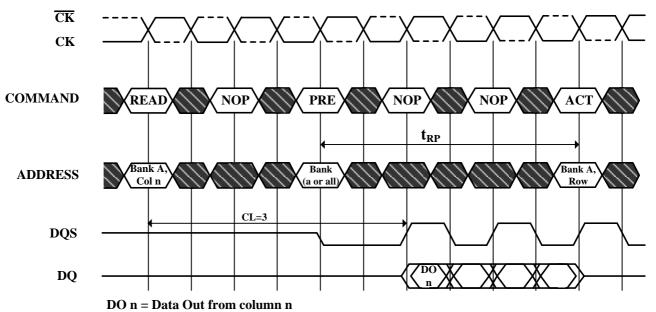
Note that Precharge may not be issued before tRAS ns after the ACTIVE command for applicable banks

The Active command may be applied if tRC has been met





#### Read to Precharge Required CAS Latencies (CL=3)



Cases shown are either uninterrupted bursts of 4, or interrupted bursts of 8 3 subsequent elements of Data Out appear in the programmed order following DO n

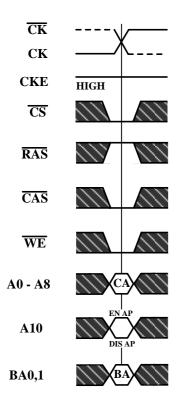
Precharge may be applied at (BL/2) tCK after the READ command Note that Precharge may not be issued before tRAS ns after the ACTIVE command for applicable banks

The Active command may be applied if tRC has been met





### Figure 14. Write Command

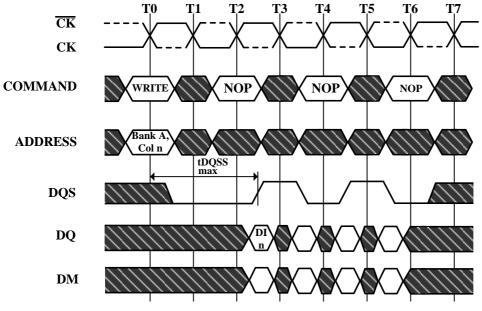


CA=Column Address BA=Bank Address EN AP=Enable Autoprecharge DIS AP=Disable Autoprecharge





# Figure 15. Write Max DQSS



DI n = Data In for column n

**3** subsequent elements of Data In are applied in the programmed order following DI n

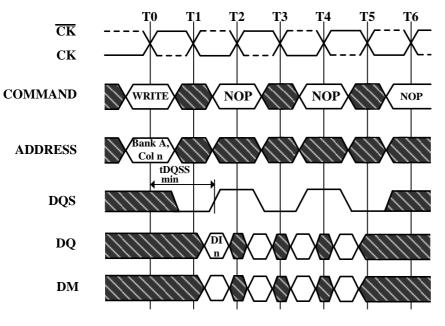
A non-interrupted burst of 4 is shown

A10 is LOW with the WRITE command (AUTO PRECHARGE disabled)





# Figure 16. Write Min DQSS

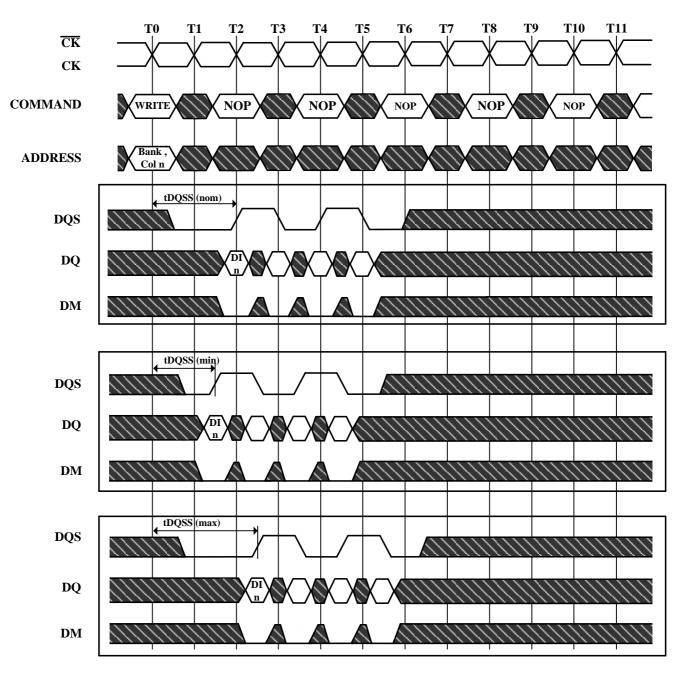


DI n = Data In for column n 3 subsequent elements of Data In are applied in the programmed order following DI n A non-interrupted burst of 4 is shown A10 is LOW with the WRITE command (AUTO PRECHARGE disabled)





# Figure 17. Write Burst Nom, Min, and Max tDQSS



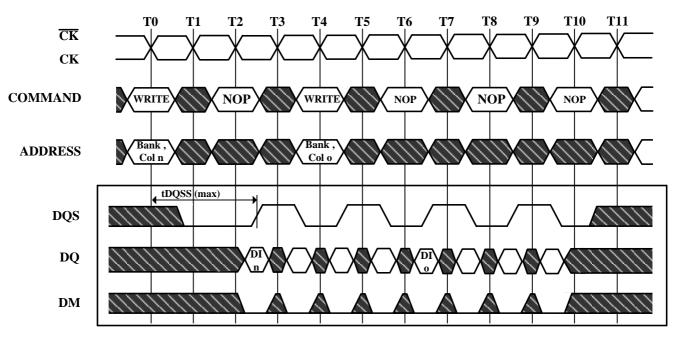
**DI** n = **Data** In for column n

3 subsequent elements of Data are applied in the programmed order following DI n A non-interrupted burst of 4 is shown A10 is LOW with the WRITE command (AUTO PRECHARGE disabled) DM=UDM & LDM





#### Figure 18. Write to Write Max tDQSS



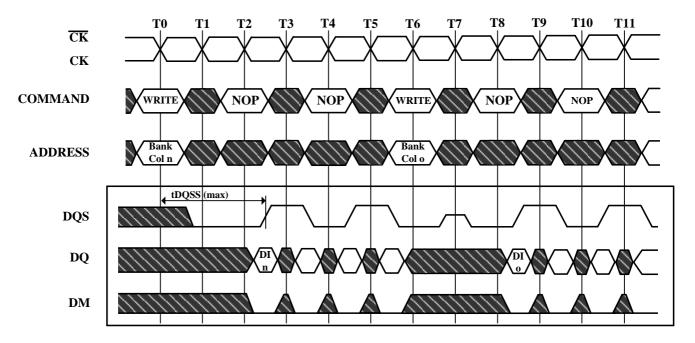
DI n , etc. = Data In for column n,etc.

3 subsequent elements of Data In are applied in the programmed order following DI n 3 subsequent elements of Data In are applied in the programmed order following DI o Non-interrupted bursts of 4 are shown DM= UDM & LDM





# Figure 19. Write to Write Max tDQSS, Non Consecutive



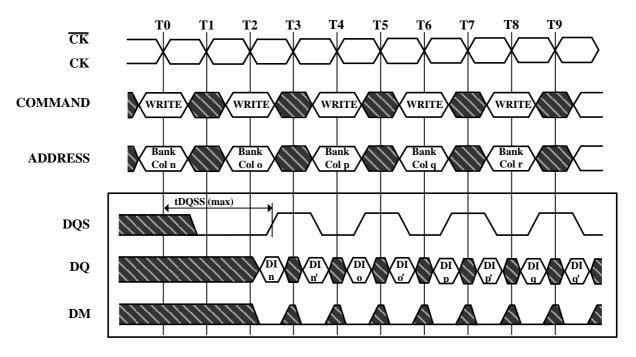
DI n, etc. = Data In for column n, etc. 3 subsequent elements of Data In are applied in the programmed order following DI n

3 subsequent elements of Data In are applied in the programmed order following DI o Non-interrupted bursts of 4 are shown DM= UDM & LDM





# Figure 20. Random Write Cycles Max tDQSS



DI n, etc. = Data In for column n, etc.

n', etc. = the next Data In following DI n, etc. according to the programmed burst order Programmed Burst Length 2, 4, or 8 in cases shown

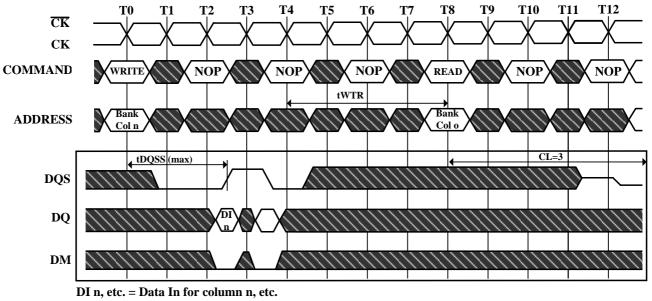
If burst of 4 or 8, the burst would be truncated

Each WRITE command may be to any bank and may be to the same or different devices DM= UDM & LDM





# Figure 21. Write to Read Max tDQSS Non Interrupting



1 subsequent elements of Data In are applied in the programmed order following DI n A non-interrupted burst of 2 is shown

tWTR is referenced from the first positive CK edge after the last Data In Pair

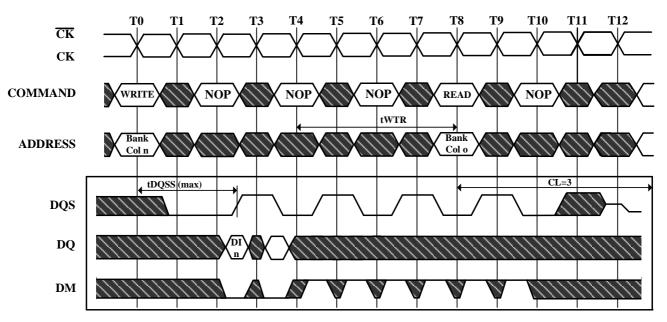
A10 is LOW with the WRITE command (AUTO PRECHARGE is disabled)

The READ and WRITE commands are to the same devices but not necessarily to the same bank DM= UDM & LDM





# Figure 22. Write to Read Max tDQSS Interrupting



DI n, etc. = Data In for column n, etc.

1 subsequent elements of Data In are applied in the programmed order following DI n An interrupted burst of 8 is shown, 2 data elements are written

tWTR is referenced from the first positive CK edge after the last Data In Pair

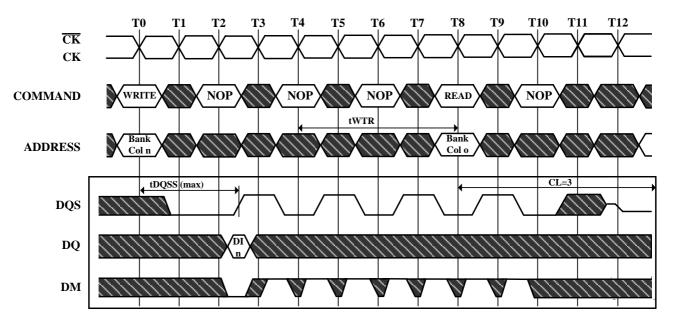
A10 is LOW with the WRITE command (AUTO PRECHARGE is disabled)

The READ and WRITE commands are to the same devices but not necessarily to the same bank DM= UDM & LDM





# Figure 23. Write to Read Max tDQSS, ODD Number of Data, Interrupting



DI n = Data In for column n

An interrupted burst of 8 is shown, 1 data elements are written

tWTR is referenced from the first positive CK edge after the last Data In Pair (not the last desired Data In element)

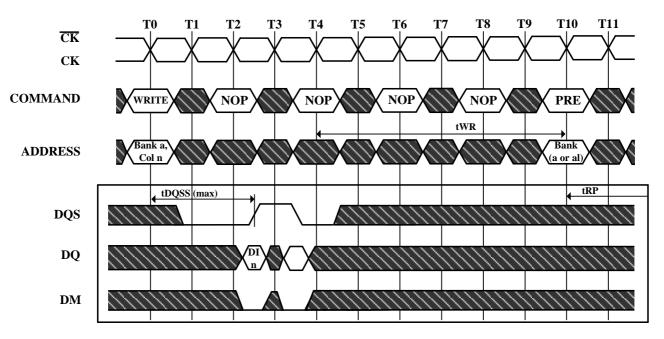
A10 is LOW with the WRITE command (AUTO PRECHARGE is disabled)

The READ and WRITE commands are to the same devices but not necessarily to the same bank DM= LDM & UDM





# Figure 24. Write to Precharge Max tDQSS, NON- Interrupting



DI n = Data In for column n

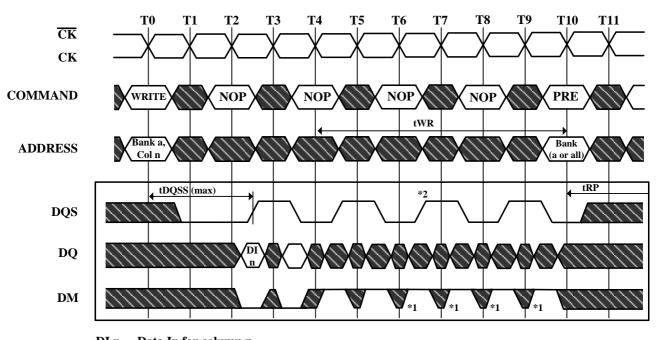
1 subsequent elements of Data In are applied in the programmed order following DI n A non-interrupted burst of 2 is shown

tWR is referenced from the first positive CK edge after the last Data In Pair A10 is LOW with the WRITE command (AUTO PRECHARGE is disabled) DM= UDM & LDM





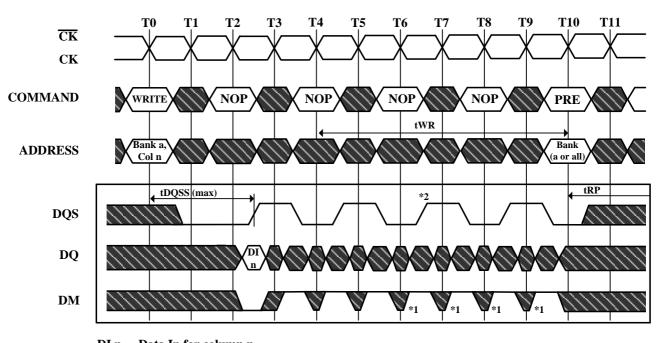
# Figure 25. Write to Precharge Max tDQSS, Interrupting



DI n = Data In for column n An interrupted burst of 4 or 8 is shown, 2 data elements are written tWR is referenced from the first positive CK edge after the last Data In Pair A10 is LOW with the WRITE command (AUTO PRECHARGE is disabled) \*1 = can be don't care for programmed burst length of 4 \*2 = for programmed burst length of 4, DQS becomes don't care at this point DM= UDM & LDM



# Figure 26. Write to Precharge Max tDQSS ODD Number of Data Interrupting



DI n = Data In for column n An interrupted burst of 4 or 8 is shown, 1 data element is written tWR is referenced from the first positive CK edge after the last Data In Pair A10 is LOW with the WRITE command (AUTO PRECHARGE is disabled)

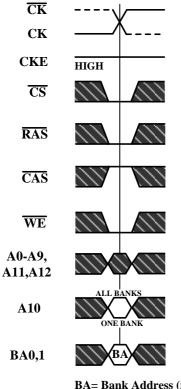
\*1 = can be don't care for programmed burst length of 4

\*2 = for programmed burst length of 4, DQS becomes don't care at this point DM= UDM & LDM





#### Figure 27. Precharge Command

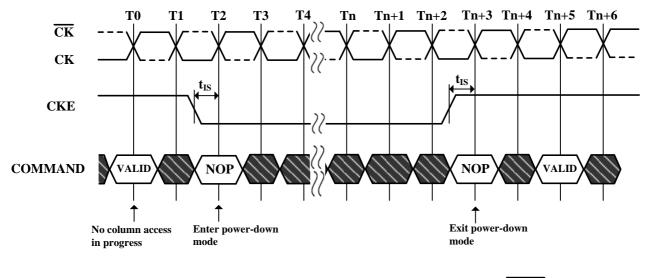


BA= Bank Address (if A10 is LOW, otherwise don't care)



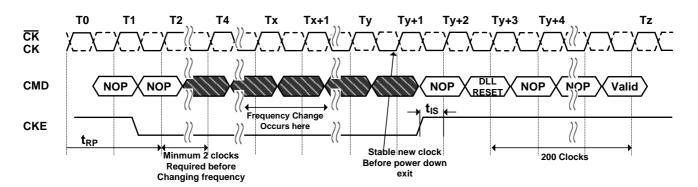


#### Figure 28. Power-Down



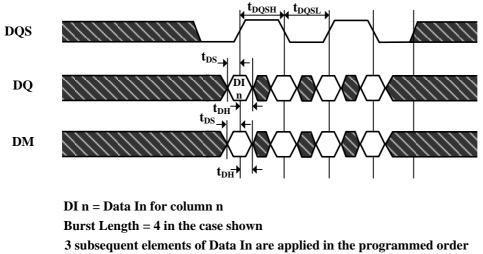


# Figure 29. Clock Frequency Change in Precharge





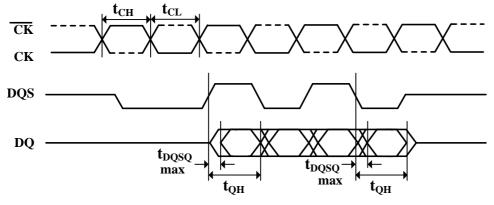
# Figure 30. Data input (Write) Timing



following DI n



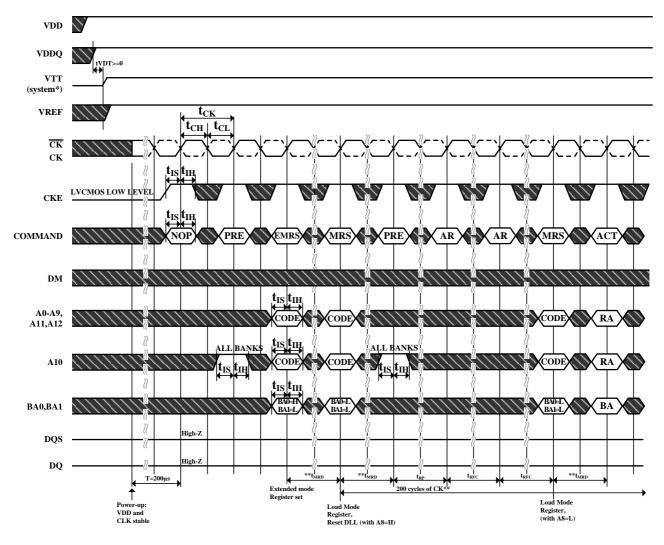
# Figure 31. Data Output (Read) Timing



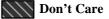
**Burst Length = 4 in the case shown** 



#### Figure 32. Initialize and Mode Register Sets

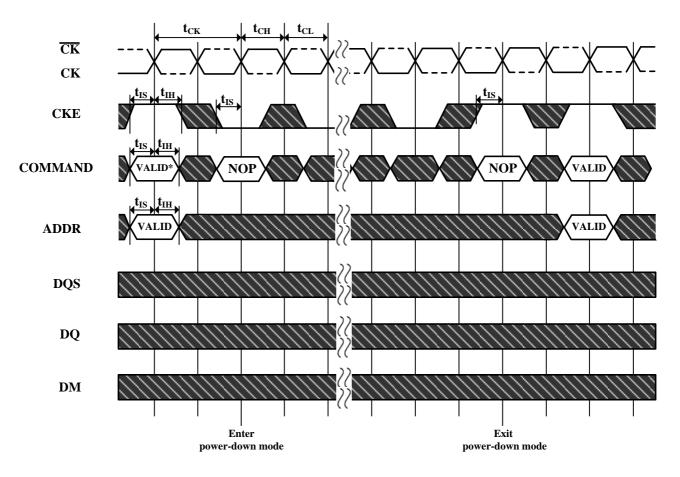


\*=VTT is not applied directly to the device, however tVTD must be greater than or equal to zero to avoid device latch-up. \*\* = tMRD is required before any command can be applied, and 200 cycles of CK are required before any executable command can be applied the two auto Refresh commands may be moved to follow the first MRS but precede the second PRECHARGE ALL command.





# Figure 33. Power Down Mode

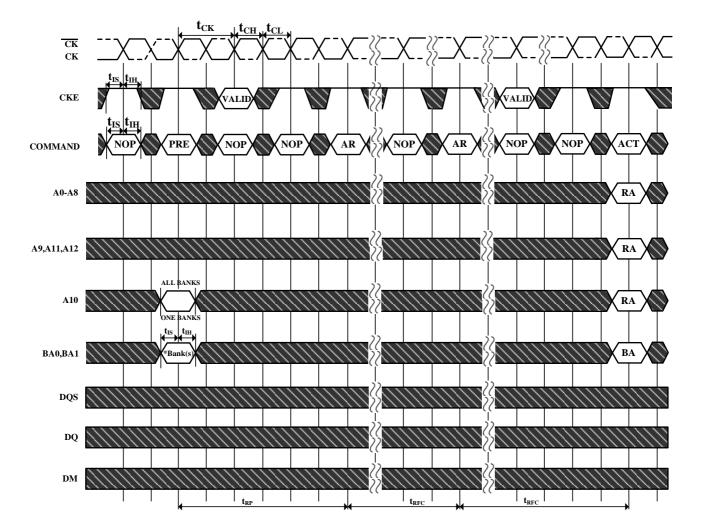


No column accesses are allowed to be in progress at the time Power-Down is entered \*=If this command is a PRECHARGE ALL (or if the device is already in the idle state) then the Power-Down mode shown is Precharge Power Down. If this command is an ACTIVE (or if at least one row is already active) then the Power-Down mode shown is active Power Down.

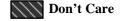




# Figure 34. Auto Refresh Mode

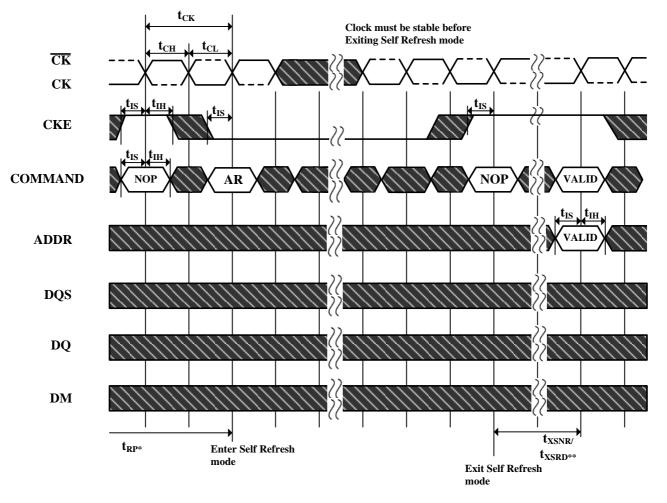


\* = " Don't Care", if A10 is HIGH at this point; A10 must be HIGH if more than one bank is active (i.e., must precharge all active banks) PRE = PRECHARGE, ACT = ACTIVE, RA = Row Address, BA = Bank Address, AR = AUTOREFRESH NOP commands are shown for ease of illustration; other valid commands may be possible after tRFC DM, DQ and DQS signals are all " Don't Care" /High-Z for operations shown





# Figure 35. Self Refresh Mode

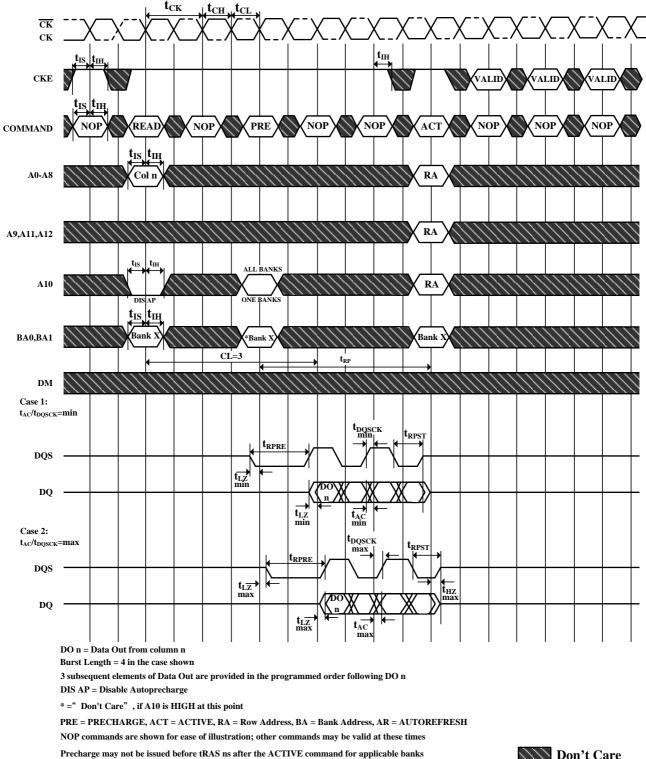


\* = Device must be in the "All banks idle" state prior to entering Self Refresh mode \*\* = tXSNR is required before any non-READ command can be applied, and tXSRD (200 cycles of CK) is required before a READ command can be applied.





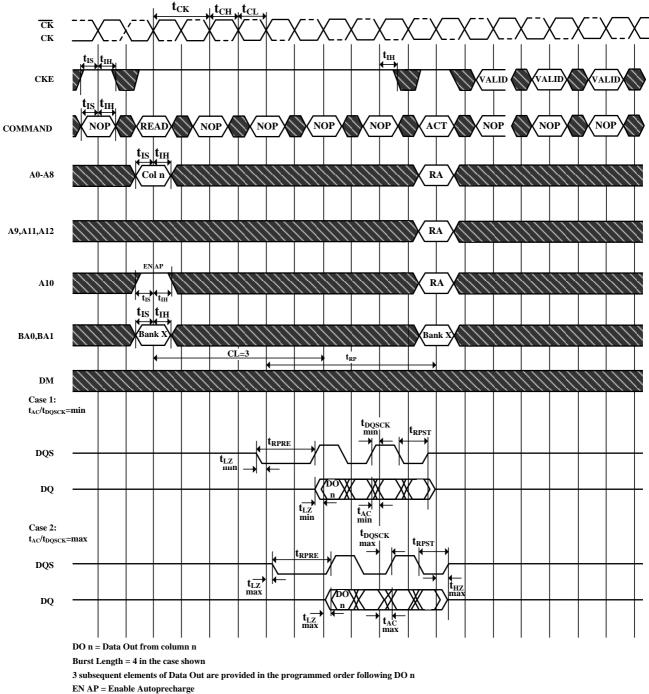
# Figure 36. Read without Auto Precharge







# Figure 37. Read with Auto Precharge



ACT = ACTIVE, RA = Row Address

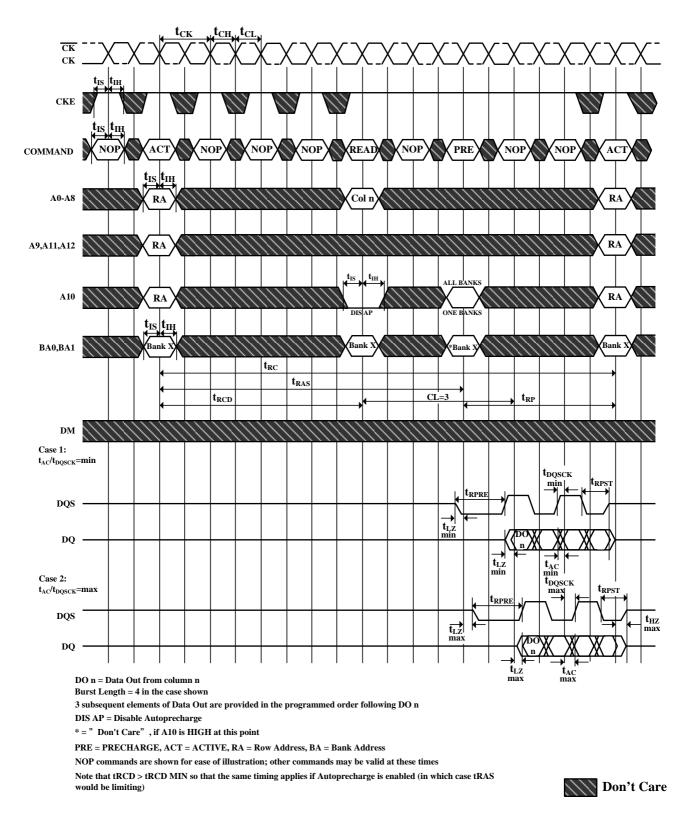
NOP commands are shown for ease of illustration; other commands may be valid at these times

The READ command may not be issued until tRAP has been satisfied. If Fast Autoprecharge is supported, tRAP = tRCD, else the READ may not be issued prior to tRASmin - (BL\*tCK/2)



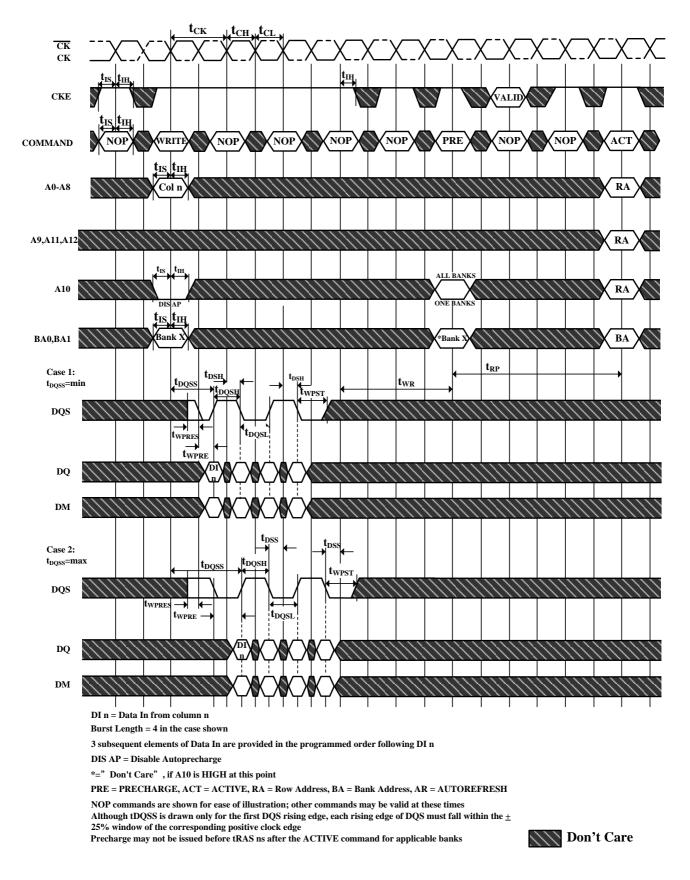


#### Figure 38. Bank Read Access



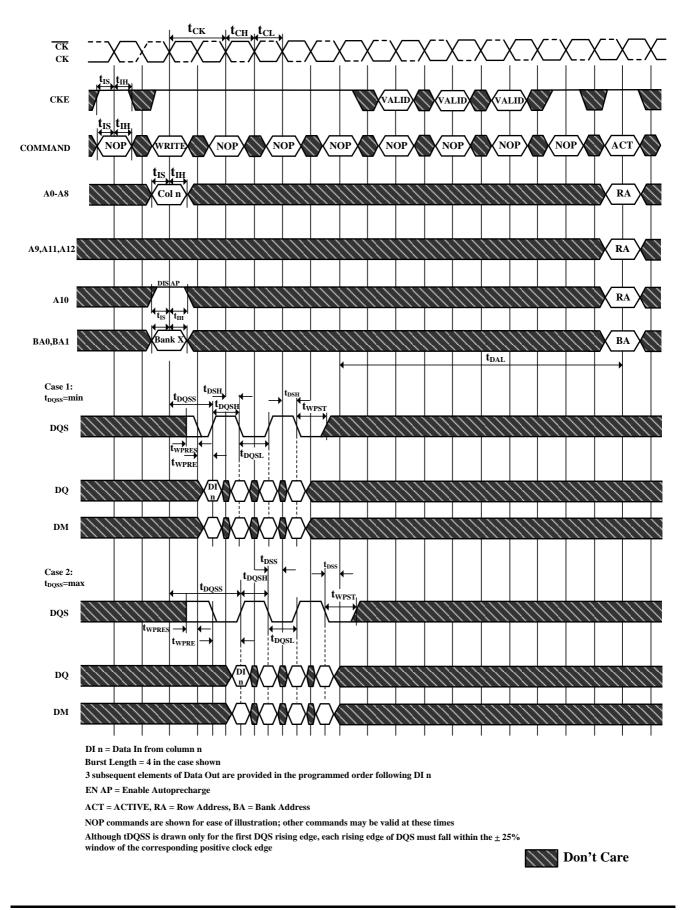


#### Figure 39. Write without Auto Precharge



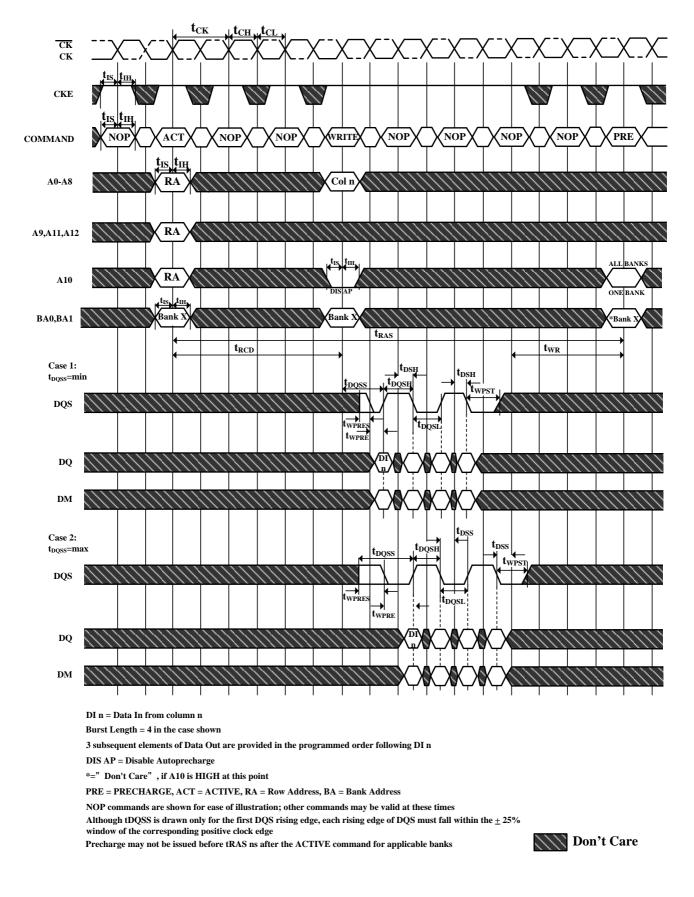


## Figure 40. Write with Auto Precharge





#### Figure 41. Bank Write Access





#### Figure 42. Write DM Operation

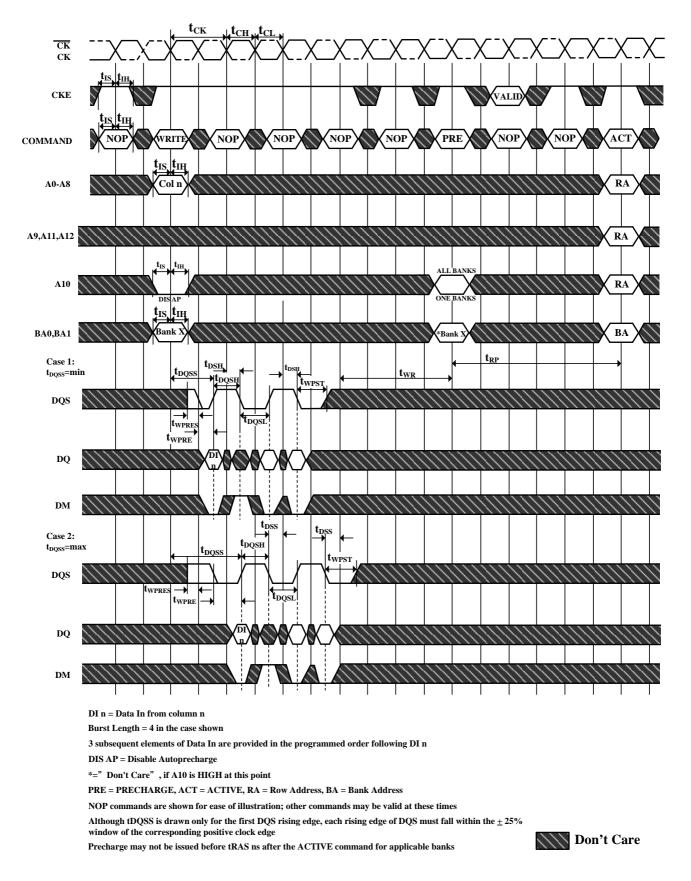
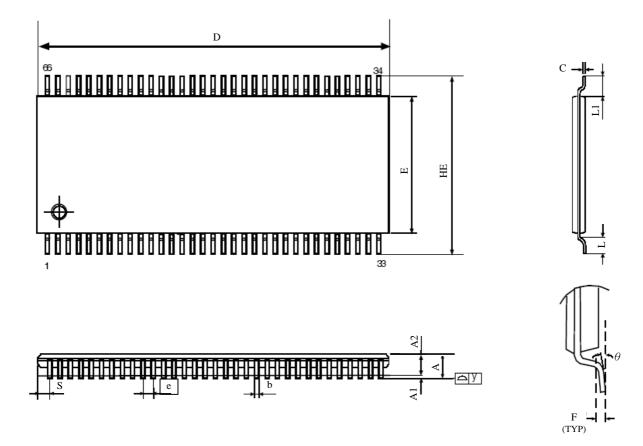




Figure 43. 66 Pin TSOP II Package Outline Drawing Information Units: mm



Symbol	Dimension in mm			Dimension in inch		
	Min	Nom	Max	Min	Nom	Max
А			1.2			0.047
A1	0.05		0.2	0.002		0.008
A2	0.9	1.0	1.1	0.035	0.039	0.043
b	0.22		0.45	0.009		0.018
е		0.65			0.026	
С	0.095	0.125	0.21	0.004	0.005	0.008
D	22.09	22.22	22.35	0.87	0.875	0.88
E	10.03	10.16	10.29	0.395	0.4	0.405
HE	11.56	11.76	11.96	0.455	0.463	0.471
L	0.40	0.5	0.6	0.016	0.02	0.024
L1		0.8			0.032	
F		0.25			0.01	
$\theta$	0 °		8°	0 °		8°
S		0.71			0.028	
Ωy			0.10			0.004



#### PART NUMBERING SYSTEM

AS4C	16M16D1A	5	Т	C/I	Ν
DRAM	16M16=16Mx16 D1A=DDR1 (A version)	5=200MHz	T = TSOPII	C=Commercial (0° C∼70° C) I=Industrial (- 40° C∼85° C)	Indicates Pb and Halogen Free



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Alliance Memory:

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