MicroStrain Product Datasheet

3DM-CX5-IMU **Inertial Measurement Unit**

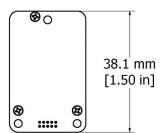


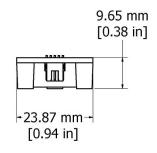
The MicroStrain Sensing 3DM-CX5 family of highperformance, industrial-grade, board-level inertial sensors provides a wide range of triaxial inertial measurements, computed attitude, and navigation solutions.

In all models, the Inertial Measurement Unit (IMU) includes direct measurement of acceleration and angular rate, and is fully temperature-compensated and calibrated over the operating temperature range. The use of Micro-Electro-Mechanical System (MEMS) technology allows for highly accurate, small, lightweight devices.

SensorConnect software is a user friendly program for device configuration. MIP Monitor (MicroStrain Internet Protocol) can also be used. Both packages provide for device configuration, live data monitoring, and recording. Alternatively, the MIP Data Communications Protocol is available for development of custom interfaces and easy OEM integration.

The sensor operates independent of computer platform, operating system, or coding language.





PRODUCT HIGHLIGHTS

- Triaxial accelerometer, gyroscope, temperature sensors achieve the optimal combination of measurement qualities
- Smallest, lightest, highest performance IMU in its class

FEATURES AND BENEFITS BEST IN CLASS PERFORMANCE

- · Fully calibrated, temperature-compensated, and mathematically-aligned to an orthogonal coordinate system for highly accurate outputs
- High-performance, low-drift gyros with low noise density and vibration rectification error.
- Accelerometer noise as low as 20 ug/√Hz

EASE OF USE

- SensorConnect enables simple device configuration, live data monitoring and recording.
- Optional hardware communications-development kit available.
- The MSCL API allows easy integration with C++, Python, .NET, C#, Visual Basic, LabVIEW and MATLAB environments.
- MIP open byte level communication protocol

COST EFFECTIVE

- · Out-of-the box solution reduces development time
- · Volume discounts

APPLICATIONS

- Unmanned vehicles
- Robotics
- · Platform stabilization, artificial horizon
- · Health and usage monitoring of vehicles





Inertial Measurement Unit

Specifications

| General | | |
|--|--|--|
| Integrated sensors | Triaxial accelerometer, triaxial gyroscope, and temperature sensors | |
| Data outputs | Inertial Measurement Unit (IMU) outputs: acceleration, angular rate, delta theta, delta velocity | |
| Inertial Measurement Unit (IMU) Sensor Outputs | | |
| | Accelerometer | Gyroscope |
| Measurement range | ±8 g (standard) ±2 g, ±4 g, ±20 g, ±40 g (optional) | 300°/sec (standard) ±75, ±150, ±900°/sec (optional) |
| Non-linearity | ±0.02% fs | ±0.02% fs |
| Resolution | 0.02 mg (+/- 8 g) | <0.003°/sec (300 degrees/second) |
| Bias instability | ±0.04 mg | 8°/hr |
| Initial bias error | ±0.002 g | ±0.04°/sec |
| Scale factor stability | ±0.03% | ±0.05% |
| Noise density | 20 μg/√Hz (2 g) | 0.005°/sec/√Hz (300°/sec) |
| Alignment error | ±0.05° | ±0.05° |
| Adjustable bandwidth | 225 Hz (max) | 250 Hz (max) |
| Offset error over temperature | 0.06% (typ) | 0.04% (typ) |
| Gain error over temperature | 0.03% (typ) | 0.03% (typ) |
| Scale factor non- linearity (@ 25°C) | 0.02% (typ) 0.06% (max) | 0.02% (typ) 0.06% (max) |
| Vibration induced noise | | 0.072°/s RMS/g RMS |
| (VRE) Vibration rectification error | 0.03% | 0.001°/s/g2 RMS |
| IMU filtering | Digital sigma-delta wide band anti-aliasing filter to digital averaging filter (user adjustable) scaled into physical units. | |
| Sampling rate | 1 kHz | 4 kHz |
| IMU data output rate | 1 Hz to 1000 Hz | |

| Operating Parameters | | |
|------------------------------------|---|--|
| Communication | TTL serial (3.0 V dc, 9,600 bps to 921,600 bps, default 115,200) | |
| Power source | + 3.2 to 5.2 V dc | |
| Power consumption | 300 mW (typ) | |
| Operating temperature | -40°C to +85°C | |
| Mechanical shock limit | 500g/1ms absolute maximum survivability.* | |
| Physical Specifications | | |
| Dimensions | 38 mm x 24 mm x 9.7 mm | |
| Weight | 8 grams | |
| Enclosure material | Aluminum | |
| MTBF | 400,094 hours (Telcordia method, GM/35C) | |
| Regulatory compliance | CE, REACH, ROHS | |
| Integration | | |
| Connectors | Data/power: FTSH Series Connectivity kit: Micro-D9 | |
| Software | SensorConnect and MIP Monitor software included; Windows XP/Vista/7/8/10 compatible | |
| Data Communications Protocol (DCP) | Protocol compatibility across GX3, GX4, RQ1, GQ4, GX5 CX5 and CV5 product families | |
| Software development kit | MicroStrain Communication Library (MSCL) open source license includes full documentation and sample code. | |
| Hardware development kit | Available option | |

*Prolonged exposure to >2x full scale range can result in permanent damage. See manual for details







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MicroStrain by HBK: 3DM-CX5-I0 3DM-CX5-IMU