

GP30

Standard Board

GP30-EVA-KIT

ams Eval Kit Manual [v1-02] 2017-Oct-25 Page 1 Document Feedback

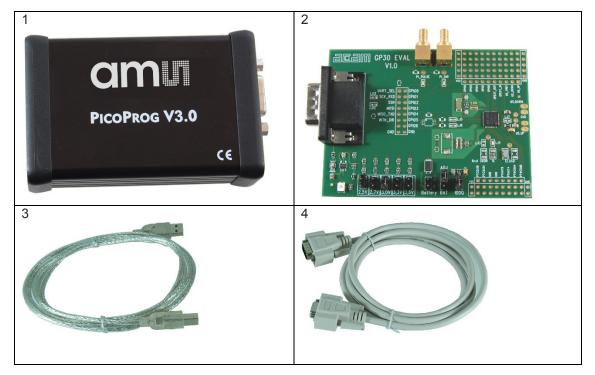
Content Guide

1	Introduction	3
2	Quick Start Guide	4
2.1	Install the Software	4
2.2	Install the Hardware:	4
2.3	Quick Start for Initial Measurements	4
3	Hardware Description	6
3.1	Introduction	6
3.2	Communication Interface	6
3.3	External amplifier	7
4	Software Description	8
4.1	Measurement	8
4.1.1	First step with measurement control elements	8
4.1.2	Time of Flight Measurement Results	9
4.1.3	2-Wire Temperature Measurement Results	. 10
4.2	Ultrasonic Measurement Control	. 11
4.3	Temperature Measurement Control	. 12
4.4	General Control	. 13
4.5	Interfaces	. 14
4.6	Interrupt & Error Handling	. 15
4.7	acam	. 15
4.8	Firmware Parameters and Firmware Error Counters	. 15
5	Software Menu	. 17
5.1	File	. 17
5.2	Tools	. 17
5.3	Firmware	. 20
5.4	Help	. 23
6	Schematics, Layers and BOM	. 25
7		~~
	Ordering & Contact Information	. 30
8	Copyrights & Disclaimer	

1 Introduction

The GP30-EVA-KIT is a platform for a quick and easy start-up and evaluation of the TDC-GP30 ultrasonic flow converter (UFC). It supports the QFN40 package, which makes available the full functionality of TDC-GP30. The development kit offers user-friendly configuration and extensive testing of the TDC-GP30, but also the complete assembler environment for programming the device. For a proper use of the evaluation system, we strongly recommend to refer to the latest TDC-GP30 datasheets.





Pos.	Item	Comment
1	PICOPROG V3.0	Programmer and interface
2	GP30-EVA-BOARD	Based on TDC-GP30 in QFN40 package
3	High density DSUB15 cable	Connecting Evaluation board to programmer
4	USB cable	Connects PicoProg V3.0 to PC

The board shows a patch field close to the GPIO pins where an external amplifier as well as analog switches for gas meter operation can be connected.

Please download the latest software for the kit from

http://www.acam.de/download-center/ultrasonicflowconverter/

2 Quick Start Guide

This section describes how to quickly set up the GP30-EVA-KIT, establish basic operation and make measurements.

2.1 Install the Software

It is crucial to install the software before connecting the evaluation kit to your computer. A default driver loading of your OS may interfere with correct installation.

- Download the latest zipped software installation package to the desired directory.
- Unzip the package to the desired directory.
- Open "setup.exe" from the unzipped directory.
- Follow the instructions on the screen.

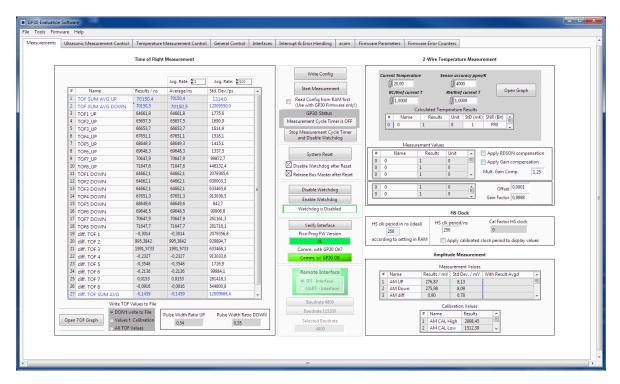
2.2 Install the Hardware:

- Make sure software is installed correctly before proceeding with this step!
- Connect your computer with the PicoProg V3.0 using USB cable.
- Connect PicoProg V3.0 and the evaluation kit motherboard using the DB15 interfaces
- The green LED on the evaluation kit should be on.
- Connect your spool piece to US_UP and US_DOWN

2.3 Quick Start for Initial Measurements

From the "Start" menu, go to "All Programs" and then to the "acam" directory. Double click the "GP30_v1_5_3" icon (or newer versions, if available) to begin execution of the evaluation software. The following screen should appear:

Figure 2: Measurement Page





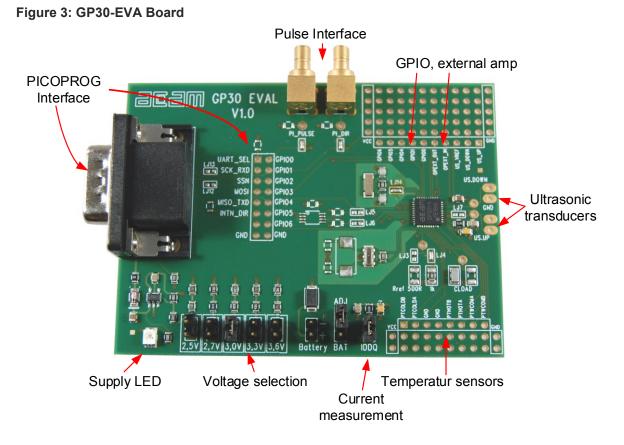
- 1. Click the "Verify Interface" button to confirm communication between PicoProg V3.0 and TDC-GP30 is working. Both fields, "Pico Prog FW version " and "Comm. With GP30 OK?" should become green.
- 2. Next, open our configuration GP30Y_config_default_A1.A2.11.03 and download it into the chip, pressing "Write Config".
- 3. Connect your spool piece to pins US_UP and US_DOWN.
- 4. Press "Start Measurement" to begin measuring.

At this point, after successful completion of the above steps, a basic operation of the EVA kit should be possible. The following sections provide a detailed description of the hardware and software for advanced operation.

3 Hardware Description

3.1 Introduction

The GP30-EVA-BOARD, shown in figure 3, s the front-end for a water or heat meter. The transducers and temperature sensors can be connected directly to this board. It comes with a 32,768 kHz quartz (X2) and a 4 MHz ceramic oscillator (X1). All ports of TDC-GP30 are available. Additional patch fields allow an easy extension with additional circuits. Those can be amplifiers or analog switches for operation in gas meter mode.



3.2 Communication Interface

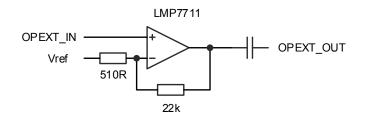
The PICOPROG device is a USB-to-SPI converter box that interfaces all UFC evaluation systems. With version 3.0, the PICOPROG also supports the USB-to-UART conversion of TDC-GP30. The PICOPROG is registered by the operating system initially as "picoprog v3.0 unprogrammed". As soon as the GP30 evaluation software starts, a special firmware is written into the PICOPROG to handle the SPI or UART communication with the TDC-GP30. The PICOPROG is now listed as "UNIPRO" in the device manager. For SPI communication only, PICOPROG version 2.0 is sufficient.



3.3 External amplifier

A typical circuit for an external amplifier at high frequencies (1 to 4 MHz) could be this one:

Figure 4: External amplifier example



4 Software Description

4.1 Measurement

When started, the software comes up with the main window, showing the "Measurements" tab.

Figure 5 Main window

Itrasonic Measurement Control		Measurement Contro	ol General Control		Interrupt & Error Handling acam Fi	imware Parameters Firmware Error Counters
	Time of Flight	t Measurement				2-Wire Temperature Measurement
					Write Config	Current Temperature Sensor accuracy ppm/K
		Avg. Rate: 📲	Avg. Rate: \$100		Start Measurement	() 20,00 () 4000
# Name	Results / ns	Average/ns	Std. Dev./ps			RC/Rref current T RH/Rref current T Open Graph
1 TOF SUM AVG UP	70150,4	70150,4	1314,0		Read Config from RAM first	1,0000
2 TOF SUM AVG DOWN	70150,5	70150,5	12009550,0		(Use with GP30 Firmware only!)	Calculated Temperature Results
3 TOF1 UP	64661,8	64661,8	1775,6		GP30 Status	# Name Results Unit StD (mK) SNR (Bit)
4 TOF2_UP	65657,5	65657,5	1690,9		Measurement Cycle Timer is OFF	0 0 1 0 1 FR0
5 TOF3_UP	66653,7	66653,7	1614,9		Stop Measurement Cycle Timer	· · · · · · · · · · · · · · · · · · ·
6 TOF4_UP	67651,1	67651,1	1518,1		and Disable Watchdog	
7 TOF5_UP	68649,3	68649,3	1415,1			Measurement Values
8 TOF6_UP	69648,3	69648,3	1337,5		System Reset	# Name Results Unit Apply RDSON compensation
9 TOF7_UP	70647,9	70647,9	99872,7	-	Maria	0 0 1 0 E Apply Gain compensation
10 TOF8_UP	71647,6	71647,6	446132,4	-	Disable Watchdog after Reset	0 0 1 0 Mult. Gain Comp. 1,25
11 TOF1 DOWN	64662,1	64662,1	2079365,6	-	Release Bus Master after Reset	0 0 1 0 + Mult. Gain Comp. 1,25
12 TOF2 DOWN	64662,1	64662,1	930003,3	- 1		0 0 1 0 Offset 0,0001
13 TOF3 DOWN	64662,1	64662,1	633465,6	=	Disable Watchdog	
14 TOF4 DOWN	67651,3	67651,3	913036,5	- 11	Enable Watchdog	Gain Factor 0,9998
15 TOF5 DOWN	68649,6	68649,6	842,7	- 11	Watchdog is Disabled	<u>u</u>
16 TOF6 DOWN	69648,5	69648,5	99906,8		Trateina og is ofsatorea	HS Clock
17 TOF7 DOWN	70647,9	70647,9	261161,3 281718 1		Verify Interface	HS clk period in ns (ideal) HS clk period/ns Cal Factor HS clock
18 TOFS DOWN	71647,7	71647,7	2079356.8			250 250 0
19 diff. TOF 1	995,3842	995.3842	929894,7	- 11	Pico Prog FW Version	according to setting in RAM Apply calibrated clock period to display values
20 diff. TOF 2 21 diff. TOF 3	1995,5842 1991,5733	1991,5733	633468.1		21	Apply calibrated clock period to display values
	-0.2327	-0.2327	913033.6		Comm. with GP30 OK?	Amplitude Measurement
22 diff. TOF 4 23 diff. TOF 5	-0,2327	-0,2327	913033,6		Comm. w/ GP30 OK	
24 diff. TOF 5	-0,3548	-0,3548	99984.1	- 11		Measurement Values
24 diff. TOF 6 25 diff. TOF 7	-0,2136	-0,2136	281418.1	-	Remote Interface	# Name Results / mV Std Dev. / mV With Result Avgd
25 diff. TOF 8	-0.0916	-0.0916	544800.8	_	SPI - Interface	1 AM UP 276,87 8,13
27 diff. TOF SUM AVG	-0.1459	-0.1459	12009668.4	-	O UART - Interface	2 AM Down 275,98 8,09
	1.1	0,1109	200000,4		Baudrate 4800	3 AM diff 0,90 0,78 +
	Values to File					Calibration Values
		Pulse Width Ratio UP	Pulse Width Ratio	DOWN	Baudrate 115200	# Name Results
	f. Calibration	0,54	0,55		Selected Baudrate	1 AM CAL High 2898,45
C All TOP	Values				4800	2 AM CAL Low 1512,39 +

4.1.1 First step with measurement control elements

A good first step is to load a working configuration and make measurements in frontend mode (without using the internal 32-Bit μ P). ams provides a sample configuration file named GP30Y_config_default_A1.A2.11.03 which typically works well with DN20 spool pieces.

Load configuration file: File menu \rightarrow Open Config \rightarrow choose appropriate configuration file

- **Next step:** Press "System Reset" button. Now the PICOPROG FW version field should get green and the appropriate version should be displayed (20 or higher). Further, "Comm GP30 OK?" should get green to show that communication with TDC-GP30 works.
- Next step: If watchdog is not disabled by "System Reset" button → press "Disable Watchdog" button.
- Next step: Press "Write Config" button to download the configuration settings into TDCX-GP30.
- **Next step:** Press "Start measurement" button. Now the chip starts to measure and the software displays the results in the table "Time of Flight Measurements".

The user can now modify the configuration to fit it to his needs. Having done this, the user can store his own configuration files.

4.1.2 Time of Flight Measurement Results

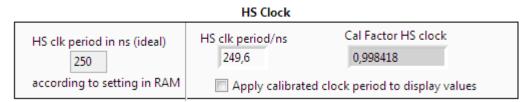
GP30 stores the first 8 hits of every TOF direction separately and also the sum of all measured hits. These 9 results are displayed for both directions, as we call them up and down. The evaluation software additionally calculates the difference between up and down stream, DIFF-TOF. In total, all 27 results are displayed in the "Results" column.

In the "Average" column the user can set the sample size for the averaging (<1000). The software calculates the rolling average of the results accordingly. In "Std. Dev." column the standard deviation, calculated over a variable sample size, is displayed. The number of samples can be chosen (e.g. 100).

The same is done with the amplitude values of the receiving signals and the pulse width ratio between first hit and start hit. The values for both directions are displayed.

Note: The high speed calibration is by default off. This is more convenient when comparing measurement data. But when collecting data for calibration it is strongly recommended to have this active.

Figure 6 HS Clock calibration



A graph to display TOF measurement results opens in a separate window by pressing "TOF Graph" button

It is possible to activate up to four plots. Each plot has various selections, e.g. TOF1UP, TOF2UP etc.. Always averaged values are displayed.

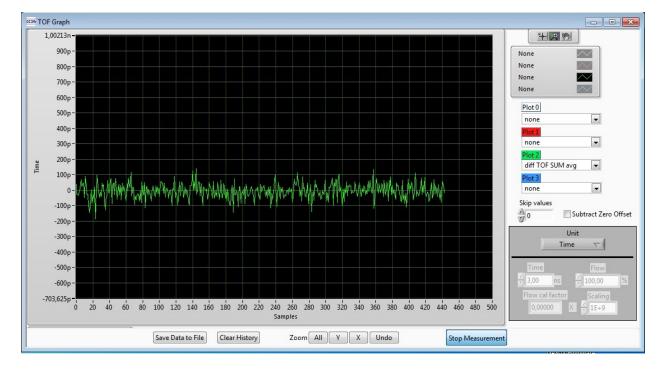


Figure 7 TOF Graph

ams Eval Kit Manual [v1-02] 2017-Oct-25

 \sim

-

-

•

-

The measurement data can be exported into text files, either the main values for calibration only, or the full data.

Figure 8 Data export for calibration

	А	В	С	D	E	F	G	Н	Ι	J	К	L
1	08.08.2016 16:18	s Elapsed	diffTOFSu	sumTOFS	diffTOF1	sumTOF1	PW UP	PW DOW	AM UP	AM DOW	Status Re	gister
2	16:18:50	0	0,000000	0,000000	0,000000	0,000000	1,992,187	1,992,187	7,168,211	6,991,830		FFFFFFF
З	16:19:03	13,69	0,000000	0,000000	0,000000	0,000000	1,992,187	1,992,187	7,152,268	7,215,327		FFFFFFF
4	16:19:04	14,03	0,000000	0,000000	0,000000	0,000000	1,992,187	1,992,187	7,152,268	7,215,327		FFFFFFF
5	16:19:04	14,49	0,000000	0,000000	0,000000	0,000000	1,992,187	1,992,187	8,988,957	9,103,998		FFFFFFF
6	16:19:05	15,02	0,000000	0,000000	0,000000	0,000000	1,992,187	1,992,187	9,177,363	9,125,247		FFFFFFF

Figure 9 Dat export complete

	A	в	C	D	E	F	G	н	1	J	K	L	M	N	0	P	Q	B	S	т	U	V	V	×	Y	Z	AA	AB	AC	AD	AE	AF	AG	AH	AL
1	******	s Elapse	TOFSun	TOFSur	TOF1up	TOF2 up	TOF3 up	TOF4 up	TOF5 up	TOF6 up	TOF7 up	TOF8 up	TOF1dov	TOF2 do	TOF3 do	TOF4 do	TOF5 do	TOF6 do	TOF7 do	TOF8 do	diff. TOF	diff. TOF	diff. TOF	diff. TOF4	diff. TOF	PW UP	PW DOW	AMUP	AMDOW	Status P	legister				
2	16:19:10	0	0,00	0,00	0,00	0.00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	1,99	1,99	8,89	9,10		FFFFFFFF
3	16:19:22	12,05	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00												0,000000					1,99	9,26	8,81		FFFFFFFF
4	16:19:22	12,30	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	1,99	1,99	9,26	8,81		FFFFFFFF
5	16:19:23	12,75	0,00	0,00	0,00	0.00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	1,99	1,99	8,81	8,46		FFFFFFFF
6	16:19:23	13,30	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	1,99	1,99	8,18	8,41		FFFFFFFF
7	16:19:24	13,79	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	0,00000	1,99	1,99	6,81	6,91		FFFFFFFF

4.1.3 2-Wire Temperature Measurement Results

A graph to display temperature measurement results opens in a separate window by "Temperature Graph" button, similar to TOF graph.



Figure 10

abu

Amplit

4.2 Ultrasonic Measurement Control

In this tab the user makes all settings for an appropriate ultrasonic measurement. They group as follows:

- Time of Flight Sequence Control
- Time of Flight Hit Control
- Amplitude Measurement Control
- Transducer Interface Options

Figure 11

GP30 Evaluation Software								_ - ×
File Tools Firmware Help								
Measurements Ultrasonic Measurement Control Temperature Mea	asurement Control General Control	Interfaces Interrupt & E	rror Handling acam Fin	rmware Parameters F	Firmware Error Cou	unters		^
		т	ime of Flight: Sequence Con	trol				
			Ultrasonic Pause	-			Direction Mode	
	25	Pause 1,0 * T(BF_SEL) in m		ause between TOF Up a 20,00 m		Toggle Directio	n with every Measurement	2
Fire Pulse Clock Divider Ze	ero Cross Calibration Rate						Time Of Flight Edge Mode	
Register Setting HS Clock Divisor 3 1 4	equence Cycle Trigger 🗾 👩	Noise Mas		Timeout TOF 128 µs	• 0	Positive Edge of	of TOF Hit	• 0
		Time Of Flig	ht: Hit Control					
TOF Hits	Stored in Front End data Buffer	Start H	it Mode					
No. of TOF Hits 12 Hits 12	DF and first 8 TOF values	Start Hit by First Hit Dete	ction 🔹 0	Firs 85	t Hit Level Up 74,8	mV	First Hit Polarity Positive 0	
		Selected Start Hit aft	er First Hit Detection					
No. of ignored Hits Si 0 Hits 0	itart Hit Delay Window	9. Hit	8	First 85	Hit Level Down	mV	Enable Pulse Width Detection	1
		A	mplitude Measurement Con	trol				
	Amplitude Measurement Ra	te Amp	litude Measurement Calibrati	on Rate A	Amplitude Measur	ement Peak Detect	ion End	
	Every TOF Measurement	Every 20t	h Amplitude Measurement	• 5	After 8 Hits		8	
			Transducer Interface Option	ns				
Transducer Interface 5		Enable Gas Meter Mode	Enable Analog Switt Enable Precharge Tr Enable Pull-Down T Enable Both Receive Enable Both Fire But	ransistors in both US But ransistors in both US Bu t Path Transistors		🛄 Enable E	ixternal Receive Amplifier (QFN 40 c	unly)
<[III					

The meanings of the various settings are displayed in clear text. For more details about the register settings please refer to the GP30 manual.

4.3 Temperature Measurement Control

All settings for an appropriate temperature measurement are done in this tab, which are grouped as follows:

- Sequence Control
- Measurement Control
- Temperature Measurement Cycle Time

Figure 12

GP30 Evaluation Software				- • ×
File Tools Firmware Help				
Measurements Ultrasonic Measurement Control Temperature	e Measurement Control General Control Interfaces Interrup	ot & Error Handling acam Firmware Parameters	Firmware Error Counters	
		Sequence Control		
	Measurement Repetition Ra	te		
	Temperature Measurement every: 0	Sequence Cycle Triggers	Measurement Subtask Handling (Pause Time) 5 * T(BF_SEL) in ms	
	Port Measurement Order 1. Default Order -> 2. Reversed	Pause I	between Temperature Measurements 30,00 ms	
		Measurement Control		
	Wire Mode *			
		Port Control		
		Number of Ports 3 Ports 1	Number of Fake Measurements	=
	Measurement Mode	s Ports	2 Fake Measurements	
	Internal Resistor	Inactive Ports during Measurement Pulled to GND		
* Curren	nt Software Release supports only 2-wire Temperature Mode			
		Temperature Measurement Cycle Time		
	Į	Discharge Select		
				-
•		m		► a

The meanings of the various settings are displayed in clear text. For more details about the register settings please refer to the GP30 manual.

4.4 General Control

The "General Control" tab covers configuration settings for

- Task sequencing
- High speed clock control
- Voltage measurement
- CPU handling
- Timer Settings

Figure 13

GP30 Evaluation Software		
File Tools Firmware Help		
Measurements Ultrasonic Measurement Control Temperature Measurement Control General Control Interfaces	Interrupt & Error Handling acam Firmware Parameters Firmware E	rror Counters
	Task Sequencing	
Set Cycle Time of Task Sequencer Select Base Frequency for Pause Times	V Enable Task Sequencer Restart	Bandgap Pulse Mode
Cycle Time Task Sequencer Base Frequency Select	Task Sequencer Start Mode	Synchronized with task sequencer
128 m 125 ms BF_SEL = 50 Hz 💌 0 T	Task Sequencing Starts: Independent of Remote Interface State 💌 1	
	High Speed Clock Control	
Settling Time	High Speed Clock Select	HS_CLK Calibration Rate
135 µs 💌 2	4MHz 💌 0	Every 20th Sequence Cycle 💌 5
	Voltage Measurement	
Vcc Measurement Rate	Low Battery Detection Threshold	Vcc Measured
Every 50th Sequence Cycle 🔹 6	14 🚖 2,48 Volt	0,00 Read Measured Vcc
	CPU Handling	
VEnable Post Processing VCPU Request Enable V Post Processing Enable		
Post Processing Mode	Enable General Purpose Timer Request	Checksum Execution after Bootloader
Post Precessing only after TOF, AM, AMC, TM or HCC Measurement		
	Timer	
Update Mode for Time Stamp Value	General Purpose Timer	Checksum Timer
Updated Automatically every second	1 hour 💌 D	Checksum Every hour
	General Purpose Handling with HS Clock	
4	111	•
٠		• at

The meanings of the various settings are displayed in clear text. For more details about the register settings please refer to the GP30 manual.

Firmware

In case the TDC-GP30 has firmware, setting flag "Enable post processing" turns on the CPU (flow meter mode). Having this not set, the GP30 runs as front-end in time conversion mode.

4.5 Interfaces

The "Interfaces" tab covers configuration settings for

- Pulse interface including test option
- EEPROM interface
- GPIO Control
- UART remote interface.

Figure 14

ents Ultrasonic Measurement Control Temperature Measureme	ent Control General Control	Interfaces	Interrupt & Error Handling ad	am Firmware Parameters	Firmware Error Counters
Pulse Interface			GPIOs		UART Interface Control *
Pulse Interface Control					CRC Control
Finable Pulse Interface		Configuratio	n SCK (SPI) or RxD (UART) Port		UART CRC Polynomial
General Update Mode				J	1021
Update by PI_UPD only	GPIO)	GF	10 1	UART CRC Reversed Order
Output Mode	Configuration GPIO 0		Configuration GPIO 1		UART CRC in Unreversed Order
Forward and Backward Pulses on 1 Line	Output		0 Output	• 0	UART Initial CRC Value
Pulse Width	Select GPIO 0		Select GPIO 1		Initial CRC Value 0x1111
32 🚖 31,25 ms	Pulse Interface->Pulse		1 Pulse Interface->Direct	ion 🔹 1	UART CRC Mode
Pulse Interface Test					Default Settings
ruse interrace l'est	GPIO 2	2	GF	10 3	
Update Pulse Interface	Configuration GPIO 2		Configuration GPIO 3		UART Wake Up Command Enable
No. of Pulses	Input Pull Up		1 Input Pull Up	• 1	Wake Up Command Enabled
0,00000	Select GPIO 2		Select GPIO 3		Baud rate
	General Purpose Out [2]		0 General Purpose Out [3] 🔹 0	UART High Baud Rate
Minimum Distance 2 Pulses					19200 Baud 💌 0
32,227 ms	GPIO 4 (QFN	40 only)		FN 40 only)	High Baud Rate Timeout
Time Between Internal Updates	Configuration GPIO 4	-	Configuration GPIO 5	_	120 ms 💌 7
3 🔅 2,93 ms	Input Pull Up		1 Input Pull Up	• 1	UART High Baud Mode
No. of Internal Upd. between General Upd.	Select GPIO 4		Select GPIO 5		High Baud rate controlled by remote controller 💌 👔
	General Purpose Out [4]		0 General Purpose Out [] • 0	
	GPIO 6 (QFN	40 only)			Clear Mode for UART IRQ UART INT cleared by remote controller
External EEPROM Interface	·				OAKTINT cleared by remote controller
	Configuration GPIO 6 Input Pull Up	-	-		UART Data Message
ROM Interface Mode			1		Address Length
ROM Disabled 💽 0	Select GPIO 6		1		0 0
ROM Pull Up Enable	General Purpose Out [6]		0		* Current Software Release supports only SPI Interface
erface Pull Ups Disabled 🔹 💿					
ROM Slave Address					
•					

The meanings of the various settings are displayed in clear text. For more details about the register settings please refer to the GP30 manual.

Pulse Interface

The pulse interface needs an appropriate firmware in the chip. The settings in the evaluation software only generate an artificial pulse to test the general functionality. The output is not related to any measurement.

UART

The UART is not supported in this software version.

4.6 Interrupt & Error Handling

On this tab error indicators and interrupt sources for remote interface can be selected.

Figure 15

The meanings of the various settings are displayed in clear text. For more details about the register settings please refer to the GP30 manual.

4.7 acam

On this tab specific parameters are displayed, but for ams internal use and analysis only.

4.8 Firmware Parameters and Firmware Error Counters

Those two tabs display and allow editing of parameters related to the ams flow firmware. They are of use only for TDC-GP30-F01. For details please refer to the datasheet TDC-GP30 Vol.4 Firmware Overview.

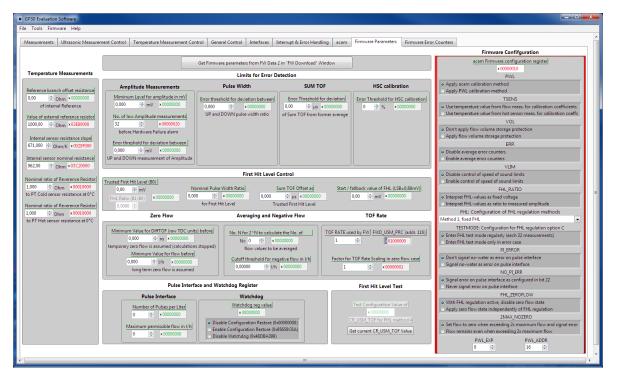
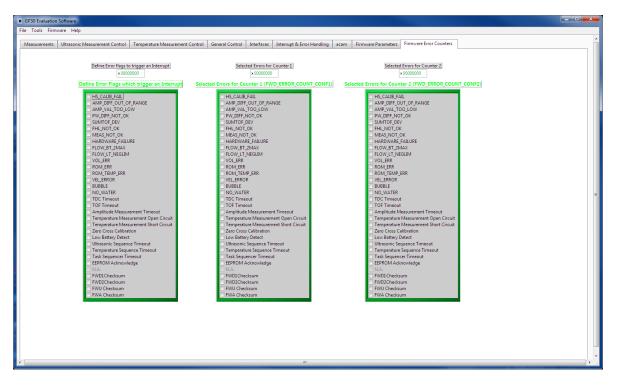


Figure 16



5 Software Menu

Beside main window, the software menu allows the opening of other windows. There are some menu items which are redundant to available buttons of main window.

5.1 File

• Open Config

This dialog box allows the path selection of a configuration file, covering the register settings, necessary for a proper configuration of the GP30. After opening this file, the control settings are updated in the GUI.

• Save Config

This menu item allows the saving of the current GUI control settings into a configuration file

Close

Close all open windows of the GP30 Evaluation software.

5.2 Tools

Run Measurement

Same function as "Start/Stop Measurement" button in "Measurement" tab of main window.

• TOF Graph

Same function as "Open TOF Graph" button in "Measurement" tab of main window.

• Temperature Graph

Same function as "Open Graph" button for temperature measurement in "Measurement" tab of main window.

RAM Memory

Figure 17

RAM Memory			
		lues in RAM Memory	
	A M V	ddress EC	
	Write Value	Read Data	
	1556	00 00 09 40	
	Write RAM	Read RAM	

Opens a window which allows single write and read accesses to random access area for addresses 0x000 – 0x0FF.

The random access area from 0x100 – 0x17F, containing the firmware data, can be accessed separately by "Firmware Download" window.

• Registers

ers						
	-	User Interfac	e	-		GP30 RAM
	Configuratio	n Register UI		Config	uration Regi	ster GP30
0xCB	x 00230806 x 00230806 x 00230808 x 00230808	CR_PI_E2P CR_GP_CTRL CR_UART CR_JEH CR_CPM CR_MRG_TS CR_TM CR_USM_PRC CR_USM_PRC CR_USM_TOF CR_USM_AM	Read Settings from GP30 RAM and Transfer to GUI Read and Transfer <	0xC9 0xCA 0xCB	x 0034010A x 00000044 x 00003000 x 001F03FF x 00680AE8 x 00012100 x 00380004 x 0002824 x 03E68C83	CR_WD_DIS CR_PIE2P CR_GP_CTRL CR_UART CR_JEH CR_CPM CR_MRG_TS CR_TM CR_USM_PRC CR_USM_FRC CR_USM_TOF CR_USM_AM CR_TRIMI
0xCD	× 00230808 × 00230808 SHR Regis	CR_TRIM2 CR_TRIM3		0xCD 0xCE	× C03765CF × 00230808	CR_TRIM2 CR_TRIM3
	TOF Rate 1 Start Hit Dela 0 First Wave Le 40 First Wave Le 40	y Window vel Up			TOF Rate 1 Start Hit Delay 1 0 First Wave Leve 40 First Wave Leve 40	Nindow I Up
				Read	I GP30 Register	Settings

Opens a window which shows the registers important for a proper configuration setting of the GP30. In the left column, the register contents correspond to the settings done in tabs of GUI main window. If the button "Read GP30 Register Settings" is pressed, the configuration settings located in GP30 registers are displayed in the right column,. By pressing "Read and Transfer" button, the register settings in the tabs of main window and in the left column of this window are updated with the register settings from right column.

Remote Commands

This window summarizes some additional commands which can be executed via remote interface.

- System Reset: Executes a complete system reset of GP30. Same function as "System Reset" button in "Measurement" tab of main window.
- System Init: Same function as "System Reset" without clearing the configuration (CR_...) and the system handling (SHR_...) register.

am

Figure 19

Remote Commands	
System Reset Recall FW Code System Init CPU Init SV Init FEP Init	
Request Bus Master Release Bus Master	
Measure Cycle Timer Off Measure Cycle Timer On	
Clear Interrupt Flags	
Communication Request General Purpose Request	
Tag Measure Cycle Timer Off	

- CPU Init: Clears the CPU block in GP30
- SV Init: Clears the supervisor block in GP30
- FEP Init: Clears the frontend processing block in GP30
- Request/Release Bus Master: Allows the request of the bus master in GP30, e.g. if the random access bus is blocked by a deadlock, caused by an improper firmware download.
- Measure Cycle Timer Off/On: Stop & start of the measure cycle timer.
- Clear Interrupt Flags: Clears all bits in SRR_IRQ_FLAG register
- Communication Request: Allows an asynchronous demand by remote controller to get an interrupt by GP30, signalizing the time for remote communication
- General Purpose Request: Allows an asynchronous request by remote controller to initiate a general purpose handling in in firmware of integrated GP30 CPU.



5.3 Firmware

Assembler

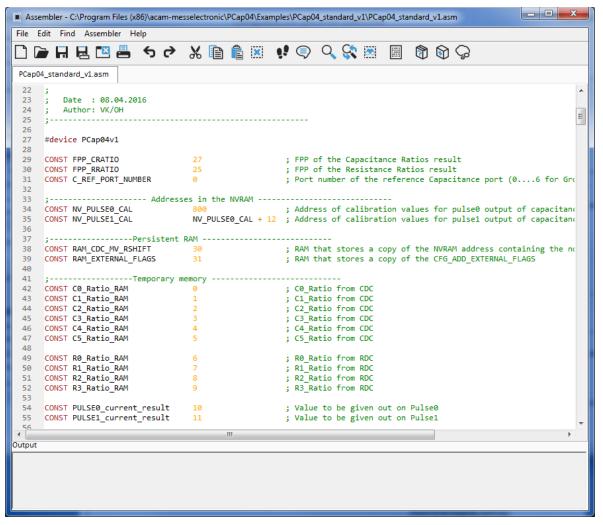
The TDC-GP30 assembler is integrated into the GP30 evaluation software. It is opened in the Firmware menu of the main program:

Figure 20

a	ican	mai	in.	vi						
ſ	File	File Tools		Firmware	Calibration	Н	elp	_		
	Measureme		Assem	oler	Ct	rl+A	trol	Temp		
					Debugging		Ctr	rl+D		
	# 1 TOF		Firmwa	re Download			ic Mea esults	Table		
			CPU Va	lues	Ctr	rl+V	esuits			
			INdiffie		_	resuit	s / ns	Avera		
			SUM AVG	UP		64558	,4	64558		
		2	2	TOF	SUM AVG	DOWN		64558	,4	64558

The following window comes up:

Figure 21



This is a comfortable editor with syntax highlighting, search and replace, copy and paste functions.

Figure 22



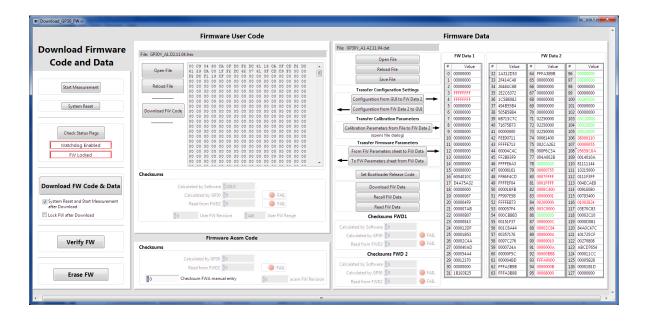
Under menu item "Assembler" the user finds the compile and download options. The download option effects, that "Firmware Download" window is opened (see also below).

Whether the call of these functions was successful or not is indicated by the messages at the bottom of the assembler window.

• Firmware Download

This window allows the download of the user code and firmware data, including the configuration, to the non-volatile memory. In case the bootlaoder release code is set, the configuration from the FW Data 2 section is copied into the configuration registers.

"Firmware User Code" is either one of ams firmware examples, either the customers code or in case of chips with ams firmware (TDC-GP30-F01) the open source part. The FW Data 1 and 2 include firmware relevant coefficients and the configuration. The figure below shows an example for anTDC-GP30-F01 application. As free part of the user code firmware GP30Y_A1.D2.11.04.hex is loaded. For the configuration and flow calculation data file GP30Y_A1.A2.11.04.dat is loaded.

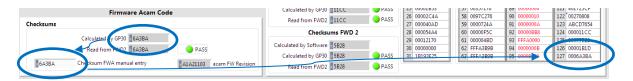


- With "Check Status Flag", the watchdog and the lock state of the GP30 can be checked.
 Please make sure that the watchdog is disabled before starting a download or other transactions in this window.
- In the "Firmware User Code" section, a firmware user code file (*.hex), which is typically generated by the assembler tool and intended for the user part of 4kx8 Program NVRAM, can be loaded by pressing "Open File".
- In the "Firmware Data" section, a firmware data file (*.dat), which is intended for the 128x32 Data NVRAM, can be loaded by pressing "Open File". This section also contains some additional transfer options from GUI to FW Data 2 fields and from GP30 back to FW Data 2 fields. The configuration can exchanged between the GUI of the evaluation file and the data file. Calibration can also be exchanged between GUI and data file.

- By pressing "Download FW Code & Data" both files are stored in the corresponding NVRAMs. This action takes a few seconds. After the download, both files are located in the volatile as well in the non-volatile part of the appropriate NVRAMs. The download can be combined with a lock option of the firmware.
- When pressing "Download FW Code & Data" any running firmware program is stopped. If a new proper auto running firmware program is downloaded, this firmware can be started again by performing a system reset. A select box allows to reset and restart measurement automatically after download.
- The last four addresses of the FW Data 2 section contain the checksums which are stored to GP30 when downloading firmware to GP30. These fields are directly updated, when firmware files are loaded or content of firmware data fields are changed.
- Pressing the "Verify FW" button after downloading compares the content of the NVRAMs with the given files by their checksums. The software calculates the checksum of the given files and reads the calculated checksums of GP30 as well as the stored checksums at the end of FWD2 section. Note: The firmware data file word 127 is by default empty, not knowing the checksum of the on-chip ams firmware.

Firmware Acam Code	,	Calculated by GP30	PASS	25 00001B53 26 00002C4A	57 00357176 58 0097C276	89 00000004 90 00000010	121 401725CF 122 00270808
Checksums		Read from FWD2 11CC	PASS	27 000040AD	59 0000724A	91 0000000A	123 ABCD7654
		Checksums FWD 2		28 000054A4	60 00000F5C	92 00000BB8	124 000011CC
Calculated by GP30			r.	29 00012170	61 000004BD 93 FFFA0000 125 00005B28		125 00005B28
Read from FWD2	G FAIL	Calculated by Software 5B28		30 00000000	62 FFFA3B9B	94 000000B	126 00001B1D
		Calculated by GP30 5B28	PASS	31 1B193E25	63 FFFA3B9B	95 00008000	127 00000000
0 Checksum FWA manual entry	A1A21103 acam FW Revision	Read from FWD2 5B28	PASS				

SO copy manually the calculated checksum for the ams code into the field "Checksum FWY manual entry". Word 127 in the data will be updated and after downloading again the verification will pass for all.



- In the "Firmware Acam Code" section, the checksums for the ams firmware code are also checked and displayed after a "Verify FW". The ams firmware code cannot be modified by user. Therefore a checksum calculated by software filed is missing in this section.
- A lock state of GP30 or a hang-up, caused by a faulty firmware user code can be dissolved by pressing "Erase FW" button. After that, a new firmware (user code & data) need to be downloaded again.



• CPU Values

This tab is only for customer who uses the ams firmware for flow calculation. It reads out some important CPU values like water temperature, flow, velocity, etc. To enable the readout the "Read calculated values" checkbox has to be set.

The lower sections allows to read from any RAM addresses.

Figure 23

CPU Temperature Results from Flow CPU Results # Name Results Unit 1 Temperature 30,28 °C 2 Sound Velocity 1510,36 us # Name Results Unit 2 Sound Velocity 1510,36 us # Name Results Unit 1 Temperature Cold 0,00 °C 2 Temperature Cold 0,00 °C 3 Volume Flow 0,000 m/s 4 Volume Flow 0,000 m/s 5 Temperature Cold Sensor 0,00 Ohm 4 Resistance Cold Sensor 0,00 Ohm 5 Temperature Internal 0,00 °C # Name Results Unit 1 TOF sum 141777,25 ns 2 TOF diff -0,0648 ns			leasurement	25		Open CPL	Graph]		
1 Temperature 30,28 *C 2 Sound Velocity 1510,36 µs CPU Results with ext. Temperature Sensors # Name Results Unit 1 Temperature Cold 0,00 *C 3 Resistance Cold Sensor 0,00 O/O 4 Resistance Cold Sensor 0,00 O/O 5 Temperature Internal 0,00 *C CPU Results at self-defined RAM Adresses CPU Results at self-defined RAM Adresses CPU Results at self-defined RAM Adresses			rom Flow							
2 Sound Velocity 1510,36 µs CPU Results with ext. Temperature Sensors # Name Results Unit 1 Temperature Cold 0,00 *C 2 Temperature Cold Sensor 0,00 *C 3 Volume Flow 0,00000 m/3 4 Volume Flow 0,000 Liter 5 Temperature Cold Sensor 0,00 Ohm 5 Temperature Internal 0,00 *C # Name Results Unit 1 TOF sum 141777,25 ns 2 TOF diff -0,0648 ns	#									
CPU Results with ext. Temperature Sensors 3 Volume Flow 0,000000 m^33 # Name Results Unit 1 Temperature Cold 0,00 *C 2 Temperature Hot 0,00 *C 3 Resistance Cold Sensor 0,00 m/s CPU TOF Values # Volume Flow 0,000 4 Volume Flow 0,000 m/s CPU TOF Values # Volume Flow 0,000 4 Volume Flow 0,000 m/s 5 Temperature Hot 0,00 *C # Name Results Unit 1 TOF sum 141777,25 ns 2 TOF diff -0,0648 ns CPU Results at self-defined RAM Adresses Mult. Factor 1 Calculated Result 1 0 * # 0 = 0 Address 2 Mult. Factor 2 Calculated Result 2 0 0 * # 0 = 0				°C						
CPU Results with ext. Temperature Sensors I Temperature Cold 0,00 * 1 Temperature Cold 0,00 * 2 Temperature Hot 0,00 * 3 Resistance Cold Sensor 0,00 Ohn 4 Resistance Hot Sensor 0,00 Ohn 5 Temperature Internal 0,00 * 7 Top sum 141777,25 ns 2 TOF diff -0,0648 ns 2 TOF diff -0,0648 ns	2	Sound Velocity	1510,36	μs						
# Name Results Unit 1 Temperature Cold 0,00 *C 2 Temperature Hot 0,00 *C 3 Resistance Cold Sensor 0,00 Ohm 4 Volume Flow 0,00 m/s 5 Flow Speed -0,00 m/s 6 Flow Speed -0,00 m/s 7 Resistance Cold Sensor 0,00 Ohm 5 Temperature Internal 0,00 *C 7 Temperature Internal 0,00 *C 8 CPU Results at self-defined RAM Adresses Address 1 Mult. Factor 1 Calculated Result 1 7 0 = 0 Address 2 Mult. Factor 2 Calculated Result 2 10 * 0 = 0		CPU Results with ext. Ten	perature Sens	ors	1.0			1.555.67		
1 Temperature Cold 0,00 *C 2 Temperature Hot 0,00 *C 3 Resistance Cold Sensor 0,00 Ohm 4 Resistance Hot Sensor 0,00 Ohm 5 Temperature Internal 0,00 *C 2 TOF sum 143777,25 ns 2 TOF diff -0,0648 ns CPU Results at self-defined RAM Adresses Address 1 * * 0 = 0 Address 2 Mult. Factor 1 Calculated Result 1 Calculated Result 2 0 * 0 = 0	#		and the second se		10.00		100 C 100 C 100			
2 Temperature Hot 0.00 *C 3 Resistance Cold Sensor 0.00 Ohm 4 Resistance Hot Sensor 0.00 Ohm 5 Temperature Internal 0.00 *C CPU Results at self-defined RAM Adresses CPU Results at self-defined RAM Adresses Address 1 Mult. Factor 1 Calculated Result 1 0 * 0 = 0 Address 2 Mult. Factor 2 Calculated Result 2 Calculated Result 2					5	Flow Speed	-0,00 m/s			
3 Resistance Cold Sensor 0,00 Ohm 4 Resistance Hot Sensor 0,00 Ohm 5 Temperature Internal 0,00 °C CPU Results at self-defined RAM Adresses CPU Results at self-defined RAM Adresses Address 1 Mult. Factor 1 Calculated Result 1 Address 2 Mult. Factor 2 Calculated Result 2 0 * 0 = 0				CPU TOF Values						
4 Resistance Hot Sensor 0,00 Ohm 1 TOF sum 141777,25 ns 5 Temperature Internal 0,00 "C 1 TOF sum 141777,25 ns CPU Results at self-defined RAM Adresses Address 1 Calculated Result 1 0 * 0 = 0 Address 2 Mult. Factor 1 Calculated Result 2 Calculated Result 2 0 * 0 = 0					#	Name		Results	Unit	
$CPU \text{ Results at self-defined RAM Addresses}$ $Address 1 \qquad Mult. Factor 1 \qquad Calculated Result 1$ $Address 2 \qquad Mult. Factor 2 \qquad Calculated Result 2$ $Address 4 \qquad 0 \qquad * \qquad 0 \qquad = 0$					1	TOF sum	141	777,25	ns	
Address 1Mult. Factor 1Calculated Result 1 0 $*$ 0 $=$ 0 Address 2Mult. Factor 2Calculated Result 2 0 $*$ 0 $=$ 0	5	Temperature Internal	0,00	°C	2	TOF diff	-0	0648	ns	
$\begin{array}{c} \\ \\ \hline \\ \\ \hline \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ $			CPU Results	at self-defir	ned R	AM Adresses				
Address 2 Mult. Factor 2 Calculated Result 2				Mult. Facto	r 1	Calculated	Result 1			
$\frac{\lambda}{2} = 0 \qquad \qquad \star \frac{\lambda}{2} = 0$		0	* 7	0		= 0				
				Mult. Facto	r2	Calculated	Result 2			
			*	0		= 0				
		Address 3	4	Mult Easte	. 2	Caladatad	D			
Address Multi-ractors Calculated Result s					15		Kesult 3			

5.4 Help

When moving the cursor over the values in tabs of main window, the parameter name (used in the GP30 manual) is displayed. By right-click and selection of "Description and Tip", a window is opened showing additional description of the value.

Pause 1,0 * T(BF_SEL) in ms	▼ 4

Description and Tip	×
"Ultrasonic Pause Handling" Description	
USM_PAUSE> CR_USM_PRC (0x0C8)	*
Selects pause time between 2 ultrasonic measurements	
	-
"Ultrasonic Pause Handling" Tip	
USM_PAUSE	
ОК	Help

Help Contents

Not supported in this software revision

USB Communication

ams Eval Kit Manual [v1-02] 2017-Oct-25

PicoProg Settings
Disable USB Handle
PicoProg FW Path
R C:\Program Files (x86)\aca\data\PicoProgFW_GP30_v21.hex Change
GP30 Communication
Last_Com_Action Read_Res
stop_meas Comm w/ GP30 OK USB Error

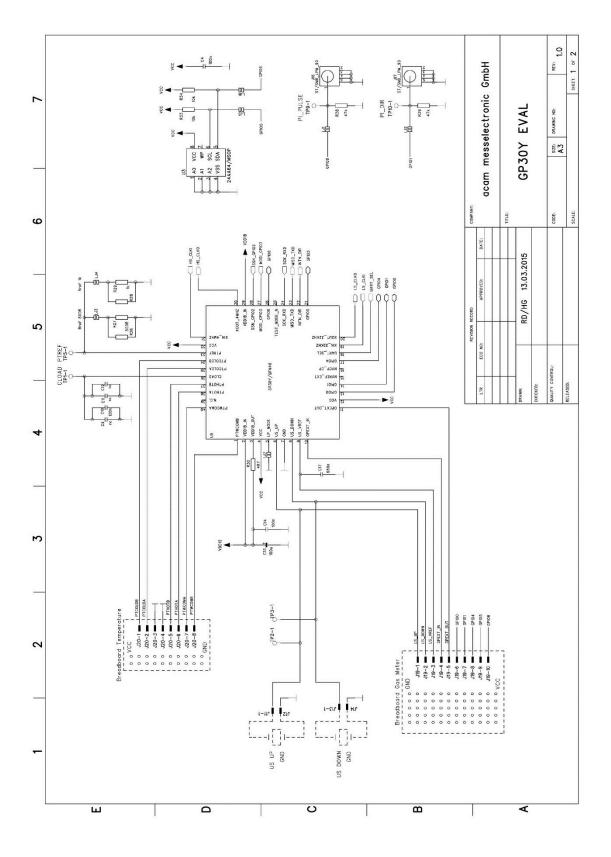
As described in chapter "Software Installation".

About

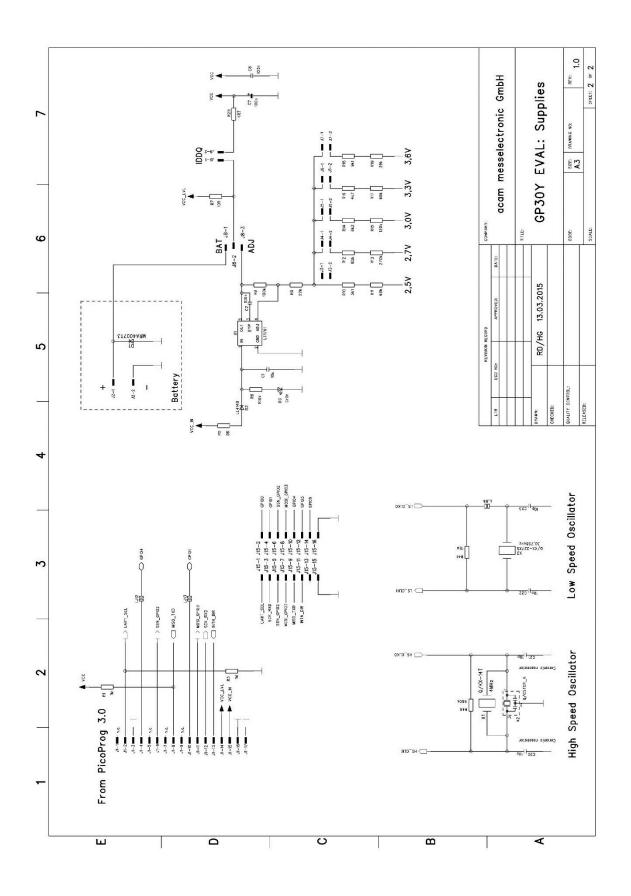
Displays software version number together with general information about software and ams.

6 Schematics, Layers and BOM

Figure 24: GP30-EVA-BOARD Schematics



ams Eval Kit Manual [v1-02] 2017-Oct-25



ams Eval Kit Manual [v1-02] 2017-Oct-25 Page 26 Document Feedback



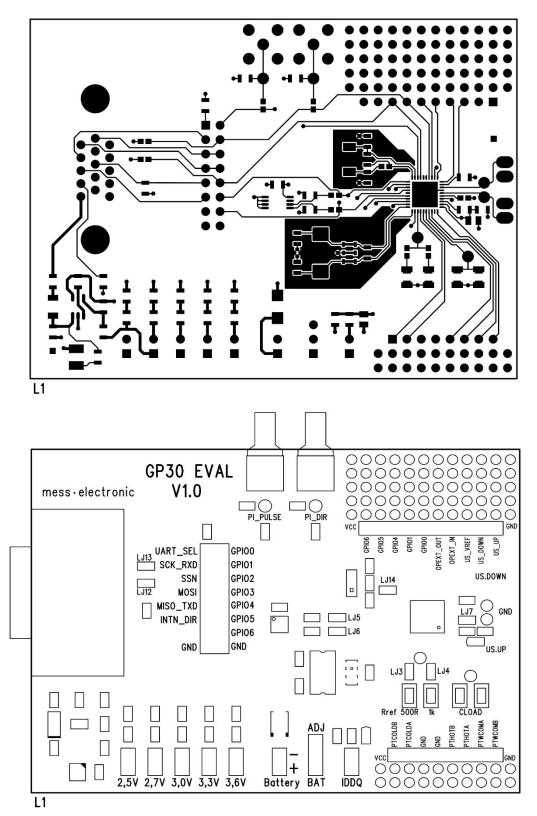


Figure 26: Bill of Materials for GP30-EVA-BOARD

Item	Qty	Reference	Part Name	PART DESC	ТҮРЕ
1	3	C2 C8 C14	C805,100n	CHIP-CAPACITOR	
2	2	C22 C23	C805,10p	CHIP-CAPACITOR	
3	1	C1	C805,10u	CHIP-CAPACITOR	
4	1	C17	C805,680n	CHIP-CAPACITOR	
5	1	C10	C1206,100n	CHIP-CAPACITOR	GRM31C5C1E104JA01L
6	2	C7 C13	F95_P,100u	TANTAL	F950J107MPAAQ2
7	-	U5	GP30Y/QFN40	TDC GP30Y	
8	1	D3	LED/HSMX-	SURFACE	
U	·	20	PLCC2,Grün	MOUNT LED	
9	1	D2	LL4148	DIODE	
10	1	U1	LT1761	LOW NOISE LDO	LT1761ES5-BYP
11	4	LJ1 LJ2 LJ4 LJ14	L_JUMPER	SOLDER BRIDGE	
12	1	D1	MRA4007T3	DIODE	
13	1	X2	Q/CSTCR_G,4MHz	CERAMIC RESONATOR	CSTCR4M00G53-R0
14	1	X3	Q/KX- 327XS,32,768kHz	CRYSTAL QUARTZ	KX-327XS
15	1	R5	R805,0R	CHIP-RESISTOR	
16	2	R25 R30	R805,4R7	CHIP-RESISTOR	
17	1	R7	R805,10R	CHIP-RESISTOR	
18	1	R29	R805,1k	CHIP-RESISTOR	
19	1	R16	R805,4k7	CHIP-RESISTOR	
20	1	R10	R805,5k1	CHIP-RESISTOR	
21	1	R14	R805,8k2	CHIP-RESISTOR	
22	1	R18	R805,9k1	CHIP-RESISTOR	
23	1	R9	R805,22k	CHIP-RESISTOR	
24	1	R19	R805,39k	CHIP-RESISTOR	
25	2	R11 R17	R805,68k	CHIP-RESISTOR	
26	1	R12	R805,82k	CHIP-RESISTOR	
27	2	R6 R8	R805,100k	CHIP-RESISTOR	
28	1	R15	R805,120k	CHIP-RESISTOR	
29	1	R13	R805,270k	CHIP-RESISTOR	
30	1	R40	R805,560k	CHIP-RESISTOR	
31	1	R41	R805,10M	CHIP-RESISTOR	
32	7	J2 J3 J4 J5 J6 7 J9	ST/254_2	STIFTLEISTE 2POL.	

ltem	Qty	Reference	Part Name	PART DESC	ТҮРЕ
33	1	J8	ST/254_3_1R	STIFTLEISTE 3POL.	
34	1	J1	ST/DSUB15HD_ABG	MALE CONNECTOR DSUB15 ABG	
35	2	J16 J17	ST/SMB_LPM_90	SMB CONNECTOR ABG	R114.665.000

7 Ordering & Contact Information

Ordering Code	Part Number	Description
GP30-EVA-KIT	220260004	GP30 Eval Kit for QFN40 version including PICOPROG and cables
GP30-EVA-BOARD	220260008	GP30 evaluation board for QFN40 version

Buy our products or get free samples online at:

www.ams.com/ICdirect

Technical Support is available at:

www.ams.com/Technical-Support

Provide feedback about this document at:

www.ams.com/Document-Feedback

For further information and requests, e-mail us at:

ams_sales@ams.com

For sales offices, distributors and representatives, please visit:

www.ams.com/contact

Headquarters

ams AG Tobelbaderstrasse 30 8141 Premstaetten Austria, Europe

Tel: +43 (0) 3136 500 0 Website: www.ams.com

8 Copyrights & Disclaimer

Copyright ams AG, Tobelbader Strasse 30, 8141 Premstaetten, Austria-Europe. Trademarks Registered. All rights reserved. The material herein may not be reproduced, adapted, merged, translated, stored, or used without the prior written consent of the copyright owner.

Demo Kits, Evaluation Kits and Reference Designs are provided to recipient on an "as is" basis for demonstration and evaluation purposes only and are not considered to be finished end-products intended and fit for general consumer use, commercial applications and applications with special requirements such as but not limited to medical equipment or automotive applications. Demo Kits, Evaluation Kits and Reference Designs have not been tested for compliance with electromagnetic compatibility (EMC) standards and directives, unless otherwise specified. Demo Kits, Evaluation Kits and Reference Designs shall be used by qualified personnel only.

ams AG reserves the right to change functionality and price of Demo Kits, Evaluation Kits and Reference Designs at any time and without notice.

Any express or implied warranties, including, but not limited to the implied warranties of merchantability and fitness for a particular purpose are disclaimed. Any claims and demands and any direct, indirect, incidental, special, exemplary or consequential damages arising from the inadequacy of the provided Demo Kits, Evaluation Kits and Reference Designs or incurred losses of any kind (e.g. loss of use, data or profits or business interruption however caused) as a consequence of their use are excluded.

ams AG shall not be liable to recipient or any third party for any damages, including but not limited to personal injury, property damage, loss of profits, loss of use, interruption of business or indirect, special, incidental or consequential damages, of any kind, in connection with or arising out of the furnishing, performance or use of the technical data herein. No obligation or liability to recipient or any third party shall arise or flow out of ams AG rendering of technical or other services.

9 Revision Information

Changes from previous version to current revision 1-02 (2017-Oct-25)

Page

Updated screenshots software

Note: Page numbers for the previous version may differ from page numbers in the current revision. Correction of typographical errors is not explicitly mentioned.

Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

ScioSense:

GP30-EVA-KIT GP30-EVA-KIT-F01 GP30-EVA-BOARD GP30-EVA-F01-BOARD