

Prodigy[®]/CME Machine Controller Board



Prodigy[®]/CME Machine Controller Boards

provide high performance motion control for medical, scientific, automation, industrial, and robotic applications. Available in 1, 2, 3, and 4-axis configurations, these boards support DC Brush, Brushless DC, and step motors and allow user-written C-language code to be downloaded and run directly on the board. The Prodigy/CME Machine Controller has on-board Atlas[®] amplifiers that eliminate the need for external amplifiers. To build a fully functioning system only a power supply, motors, and cabling are needed.

Built on the Magellan Motion Control IC

Based on PMD's industry-leading Magellan® Motion Processor, the Prodigy/CME Machine Controller boards provide user-selectable profile modes including S-curve, trapezoidal, velocity contouring, and electronic gearing with on-the-fly parameter change. Servo loop compensation utilizes a full 32-bit position error, PID with velocity and acceleration feedforward, integration limit and dual biquad filters for sophisticated control of complex loads.

On-Board Amplifiers

Up to four on-board Atlas amplifiers provide high performance amplification for even the most demanding applications. These compact and powerful units provide field oriented control, safety monitoring, and industry-leading drive efficiencies.

Easy to Use and Program

The Pro-Motion[®] GUI makes it easy to set-up and analyze system parameters and motion performance. PMD's C-Motion and VB-Motion[®] libraries simplify the program development process and allow the use of industry standard C/C++ or Visual Basic programming languages.

FEATURES

- Complete all-in-one machine controller
- Available in 1, 2, 3, and 4-axis configurations
- Uses PMD's advanced Magellan[®] Motion Processor
- Supports DC Brush, Brushless DC, and step motors
- On-board high performance Atlas[®] amplifiers
- S-curve, trapezoidal, electronic gearing, and velocity-contouring
- Ethernet, CANbus and serial communications
- Board-level execution of user application code at 96 MIPs
- High speed loop rate: 50 μsec/axis
- Up to 256 microsteps per full step resolution
- Up to 1KW peak output power per axis
- Extensive fault detection including over and undervoltage, motor short, and overtemp
- Single voltage supply drives motors and board logic

CONFIGURATION

- Incremental quadrature and Absolute SSI encoder support
- 6-step commutation and field oriented control modes
- Profile and servo changes on-the-fly
- Advanced PID filter with feedforward and dual biguad filters
- High-speed hardware performance trace (up to 468 KB)
- 8 channels of high precision 16-bit analog input and output
- 12+ channels of general purpose digital I/O
- Two directional limit switches, high speed index, and home inputs per axis
- C-Motion Engine development tools
- Support for external amplifiers via +/- 10V analog output
- Includes Pro-Motion[®], C-Motion[®] and VB-Motion[®] development software



Technical Overview



SPECIFICATIONS

	Machine Controller			
Number of axes supported	1, 2, 3 or 4 axes			
Supported motor types	DC Brush, Brushless DC, Step motor			
Servo loop rates	51.2 µsec to 1.6 sec. Minimum depends upon number of enabled axes and use of trace			
Encoder formats supported	Quadrature, Absolute SSI			
Quadrature decode rate	40 Mcounts/sec			
Capability for onboard amplifier	Yes, Atlas Digital Amplifier			
Motor output signals	Analog ± 10V			
General purpose digital I/O	8 bi-directional, 4 input, 4 output			
General purpose analog input	8 16-bit channels (± 10V)			
General purpose analog outputs	8 16-bit channels (± 10V)			
Limit switches	2 per axis: one for each direction of travel			
User program memory	256 KB Flash / 8 KB RAM			
User program stack memory	8 KB RAM			
Dual ported RAM	128 KB or 468 KB (enhanced memory option)			
Communication modes	Serial, CANbus, Ethernet			
Dimensions	7.80'' x 4.88'' x .78" (19.8cm x 12.4cm x 1.98cm)			
On-board amplifier voltage range	12 - 56V			
On-board amplifier continuous current output	DC Brush Motor: 14 ADC Brushless DC Motor: 10 Arms Step motor: 9Arms			

ATLAS[®] Digital Amplifiers

ATLAS[®] Digital amplifiers are compact single-axis amplifiers that provide high performance torque control of DC brush, brushless DC, and step motors. They are packaged in a Compact or Ultra Compact solderable module and utilize standard through-hole pins for all connections.

Voltage Input	12-56 VDC						
Microstepping resolution	256						
PWM frequency	20, 40, 80 kHz						
Current Loop rate	20 kHz						
Power rating options	75W, 250W, 500W						
Mechanical Dimensions	Ultra Compact size: 1.05" x 1.05" x .53" (27mm x 27mm x 13mm)						
	Compact size: 1.52" x 1.52" x .60" (39mm x 39mm x 15mm)						
Profile modes							
S-curve point-to-point:	Position, velocity, acceleration, deceleration, jerk						
Trapezoidal point-to-point:	Position, velocity, acceleration, deceleration						
Velocity-contouring:	Velocity, acceleration, deceleration						
Electronic gearing:	Encoder trajectory position of one axis used to drive a second axis. Master and slave axes and gear ratio parameters						

Filter modes

Scalable PID with Velocity, Acceleration feedforward, Integration limit, Offset bias, Dual biquad filter, Settable derivative sampling time, Output motor command limiting.

Development Tools



EASY START-UP Developers Kit

INCLUDES

- Prodigy Machine Controller Developer Kit
- Pro-Motion software
- Software Development Kit (SDK) with C-Motion
- Complete manual set
- Complete cable and prototyping connector set





TUNE & OPTIMIZE Pro-Motion® GUI

Pro-Motion is a sophisticated, easy-to-use Windows-based exerciser program for use with PMD motion control ICs, modules, and boards.

FEATURES

- Motion oscilloscope graphically displays processor parameters in real-time
- Autotuning
- Ability to save and load settings
- Axis wizard
- Distance and time units conversion

- Motor-specific parameter setup
- Axis shuttle performs programmable motion between two positions
- Communications monitor echoes all commands sent by Pro-Motion to the board
- Advanced Bode analysis for frequency machine response



C-Motion is a complete, easy-to-use, motion programming language that includes a source library containing all the code required for communicating with PMD motion ICs, board, and modules.

C-MOTION FEATURES INCLUDE:

- Extensive library of commands for virtually all motion design needs
- Develop embeddable C/C++ applications
- Complete, functional examples
- Supports PC/104, serial, CAN, Ethernet, and SPI communications

code for executing a profile and track btured in this example could e used fo

race buffer wrap mode to a one time trace aceMode(hAxis1, PMDTraceOneTime);

It the processor variables that we want to capture

tTraceVariable(hAxis1, PMDTraceVariable1, PMDAxis1) etTraceVariable(hAxis1, PMDTraceVariable2, PMDAxis1, setTraceVariable(hAxis1, PMDTraceVariable3, PMDAxis1,

// set the trace to begin when we issue the next update command SetTraceStart(hAxis1, PMDTraceConditionNextUpdate)

// set the trace to stop when the MotionComplete event occurs

SetTraceStop(hAxis1, PMDTraceConditionEventStatus, PMDEventMotionCompleteBit, PMDTraceStateHigh); SetProfileMode(hAxis1, PMDTrapezoidalProfile);

set the profile parameters

tion V:

tPosition(hAxis1, 200000); (elocity(hAxis1, 0x200000);

celeration(hAxis1, 0x1000); leration(hAxis1, 0x1000);

PMD PRODUCT FAMILY OVERVIEW

	# Axes	Motor Types	Format	Voltage	Communication	Features
JUNO® VELOCITY & TORQUE CONTROL ICS	1	Brushless DCDC BrushStep Motor	64-pin TQFP56-pin VQFN	3.3 V	RS232/485CANbusSPI	Velocity controlCurrent controlField oriented control
MAGELLAN® MOTION CONTROL ICS	1,2,3,4	Brushless DCDC BrushStep Motor	144-pin TQFP100-pin TQF	3.3 V	RS232/485CANbusSPIParallel	 Position control Torque/current control Field oriented control Profile generation
ATLAS® DIGITAL AMPLIFIERS	1	Brushless DCDC BrushStep Motor	• 20-pin solderable module	12-56 V	 SPI Pulse and direction 	Torque/current controlField oriented controlMOSFET amplifier
ION®/CME N-SERIES DIGITAL DRIVES	1	Brushless DCDC BrushStep Motor	Fully enclosed PCB-mounted module	12-56 V	EthernetRS232/485CAN FDSPI	 Position control Torque/current control Field oriented control Profile generation MOSFET amplifier Downloadable user code
ION® 500 & 3000 DIGITAL DRIVES	1	Brushless DCDC BrushStep Motor	Fully enclosed cable-connected module	12-56 V 20-195 V	EthernetRS232/485CANbus	 Position control Torque/current control Field oriented control Profile generation MOSFET amplifier Downloadable user code
PRODIGY® MOTION BOARDS	1,2,3,4	Brushless DCDC BrushStep Motor	 Machine Controller PC/104 Standalone 	 5 V: PC/104 and Standalone 12-56 V: Machine Controller 	 Ethernet RS232/485 CANbus PC/104 bus 	 Position control Torque/current control Field oriented control Profile generation Downloadable user code

C-Motion® is the common motion language for all Performance Motion Devices products.

FOR ORDERING PRODIGY MACHINE CONTROLLERS



To place an order email purchaseorders@pmdcorp.com. For questions email support@pmdcorp.com



About Performance Motion Devices

Performance Motion Devices (PMD) is a worldwide leader in motion control ICs, boards and modules. Dedicated to providing cost-effective, high performance motion systems to OEM customers, PMD utilizes extensive in-house expertise to minimize time-tomarket and maximize customer satisfaction.

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