

MOS DIGITAL INTEGRATED CIRCUIT SILICON GATE CMOS

4 GBIT (512M × 8 BIT) CMOS NAND E²PROM

DESCRIPTION

The TC58BYG2S0HBAl6 is a single 1.8V 4Gbit (4,429,185,024 bits) NAND Electrically Erasable and Programmable Read-Only Memory (NAND E²PROM) organized as (4096 + 128) bytes \times 64 pages \times 2048 blocks. The device has a 4224-byte static register which allows program and read data to be transferred between the register and the memory cell array in 4224-bytes increments. The Erase operation is implemented in a single block unit (256 Kbytes + 8 Kbytes: 4224 bytes \times 64 pages).

The TC58BYG2S0HBAl6 is a serial-type memory device which utilizes the I/O pins for both address and data input/output as well as for command inputs. The Erase and Program operations are automatically executed making the device most suitable for applications such as solid-state file storage, voice recording, image file memory for still cameras and other systems which require high-density non-volatile memory data storage.

The TC58BYG2S0HBAl6 has ECC logic on the chip and 8bit read errors for each 528Bytes can be corrected internally.

FEATURES

Organization

х8

Memory cell array 422 Register 422

 $\begin{array}{l} 4224\times128K\times8\\ 4224\times8 \end{array}$

Page size
Block size

4224 bytes (256K + 8K) bytes

Modes

Read, Reset, Auto Page Program, Auto Block Erase, Status Read, Page Copy, Multi Page Read, Multi Page Program, Multi Block Erase, ECC Status Read

Mode control

Serial input/output

Command control

Number of valid blocks

Min 2008 blocks Max 2048 blocks

Power supply

 $V_{CC} = 1.7V$ to 1.95V

Access time

Cell array to register 55 μs typ. (Single Page Read) / 90 μs typ. (Multi Page Read)

Read Cycle Time 25 ns min (C_L=30pF)

Program/Erase time

Auto Page Program 340 μs/page typ. Auto Block Erase 3.5 ms/block typ.

Operating current

Read (25 ns cycle) 30 mA max Program (avg.) 30 mA max Erase (avg.) 30 mA max Standby 50 μA max

Package

P-VFBGA67-0608-0.80-001 (Weight: 0.095 g typ.)

8bit ECC for each 528Byte is implemented on the chip.



PIN ASSIGNMENT (TOP VIEW)

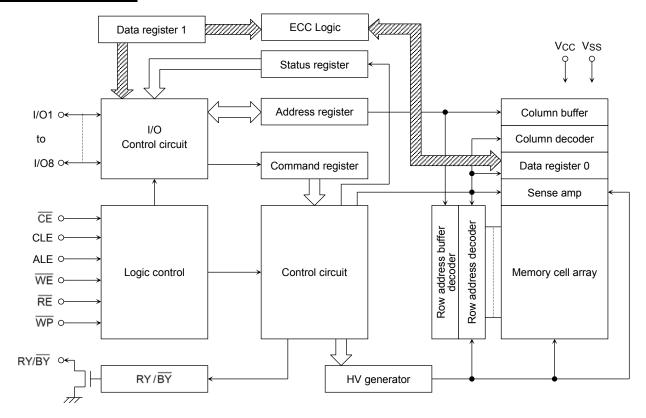
	1	2	3	4	5	6	7	8
Α	7	NC	NC			NC	NC	NC
В	NC	$\overline{\text{WP}}$	ALE	Vss	CE	$\overline{\text{WE}}$	RY/BY	NC
С	NC	NC	RE	CLE	NC	NC	NC	NC
D		NC	NC	NC	NC	NC	NC	
Е		NC	NC	NC	NC	NC	NC	
F		NC	NC	NC	NC	NC	NC	
G		NC	I/O1	NC	NC	NC	Vcc	
Н	NC	NC	I/O2	NC	Vcc	I/O6	I/O8	NC
J	NC	Vss	I/O3	I/O4	1/05	I/O7	Vss	NC
K	NC	NC	NC			NC	NC	NC

PIN NAMES

I/O1 to I/O8	I/O port
CE	Chip enable
WE	Write enable
RE	Read enable
CLE	Command latch enable
ALE	Address latch enable
WP	Write protect
RY/BY	Ready/Busy
Vcc	Power supply
V _{SS}	Ground
NC	No Connection



BLOCK DIAGRAM



ABSOLUTE MAXIMUM RATINGS

SYMBOL	RATING	VALUE	UNIT
Vcc	Power Supply Voltage	-0.6 to 2.5	V
VIN	Input Voltage	-0.6 to 2.5	V
V _{I/O}	Input /Output Voltage	$-0.6 \text{ to V}_{CC} + 0.3 (\le 2.5 \text{ V})$	V
P _D	Power Dissipation	0.3	W
TSOLDER	Soldering Temperature (10 s)	260	°C
TSTG	Storage Temperature	–55 to 125	°C
TOPR	Operating Temperature	-40 to 85	°C

CAPACITANCE *(Ta = 25°C, f = 1 MHz)

SYMBOL	PARAMETER	CONDITION	MIN	MAX	UNIT
CIN	Input	VIN = 0 V	_	10	pF
Cout	Output	V _{OUT} = 0 V	_	10	pF

^{*} This parameter is periodically sampled and is not tested for every device.



VALID BLOCKS

SYMBOL	PARAMETER	MIN	TYP.	MAX	UNIT
NvB	VB Number of Valid Blocks		_	2048	Blocks

NOTE: The device occasionally contains unusable blocks. Refer to Application Note (13) toward the end of this document.

The first block (Block 0) is guaranteed to be a valid block at the time of shipment.

The specification for the minimum number of valid blocks is applicable over lifetime.

RECOMMENDED DC OPERATING CONDITIONS

SYMBOL	PARAMETER	MIN	TYP.	MAX	UNIT
Vcc	Power Supply Voltage	1.7	_	1.95	٧
VIH	High Level Input Voltage	V _{CC} x 0.8	_	V _{CC} + 0.3	V
VIL	Low Level Input Voltage	-0.3*	_	V _{CC} x 0.2	V

^{* -2} V (pulse width lower than 20 ns)

DC CHARACTERISTICS (Ta = -40 to 85°C, V_{CC} = 1.7 to 1.95V)

SYMBOL	PARAMETER	CONDITION	MIN	TYP.	MAX	UNIT
I _{IL}	Input Leakage Current	V _{IN} = 0 V to V _{CC}	_	_	±10	μΑ
ILO	Output Leakage Current	Vout = 0 V to Vcc	_	_	±10	μΑ
ICCO1	Serial Read Current	$\overline{CE} = V_{IL}$, $I_{OUT} = 0$ mA, $t_{RC} = 25$ ns	_	_	30	mA
ICCO2	Programming Current	_	_	_	30	mA
Іссоз	Erasing Current	_	_	_	30	mA
Iccs	Standby Current	$\overline{CE} = V_{CC} - 0.2 \text{ V}, \overline{WP} = 0 \text{ V/V}_{CC}$	_	_	50	μΑ
VoH	High Level Output Voltage	I _{OH} = -0.1 mA	V _{CC} – 0.2	_	_	V
VoL	Low Level Output Voltage	I _{OL} = 0.1 mA	_	_	0.2	V
I _{OL} (RY/BY)	Output Current of RY/BY pin	V _{OL} = 0.2 V	_	4	_	mA



AC CHARACTERISTICS AND RECOMMENDED OPERATING CONDITIONS (Ta = -40 to 85°C, V_{CC} = 1.7 to 1.95V)

tCLH CLE Hold Time 5 — ns tCS CE Setup Time 20 — ns tCH CE Hold Time 5 — ns tWP Write Pulse Width 12 — ns tWP Write Pulse Width 12 — ns tALE. ALE Setup Time 12 — ns tALH. ALE Hold Time 5 — ns tDD Data Hold Time 12 — ns tDH Data Hold Time 5 — ns tWC Write Cycle Time 25 — ns tWC Write Cycle Time 10 — ns tWW William Hold Time 10 — ns tWW William Hold Time 10 — ns tRR Ready to WE Falling Edge 20 — ns tRR Ready to WE Falling Edge 20 — ns tRR Read	SYMBOL	PARAMETER	MIN	MAX	UNIT
CCS CE Setup Time 20	tcls	CLE Setup Time	12	_	ns
tich CE Hold Time 5 — ns twp Write Pulse Width 12 — ns tALS ALE Setup Time 12 — ns tALH ALE Hold Time 5 — ns tDs Data Setup Time 12 — ns tDh Data Hold Time 5 — ns tDh Wife Cycle Time 25 — ns tWW Write Cycle Time 10 — ns tWW Will High Hold Time 10 — ns tww Will High Time town 100 — ns tRR Ready to RE Falling Edge 20 — ns tRR Ready to RE Falling Edge 20 — ns tRR Ready to RE Falling Edge 20 — ns tRR Read Pulse Width 12 — ns tRR Read You William 12 — ns tRR	tclh	CLE Hold Time	5	_	ns
twp Write Pulse Width 12 — ns tals ALE Setup Time 12 — ns tal.H ALE Hold Time 5 — ns tbp Data Setup Time 12 — ns tbp Data Hold Time 12 — ns tbp Write Cycle Time 25 — ns tww Wild High Hold Time 10 — ns trex Ready to RE Falling Edge 20 — ns trex Ready to RE Falling Edge 20 — ns trex Read Pulse Width 12 — ns trex Read Cycle Time 25 — ns trex Read Cycle Time 25 — ns tr	tcs	CE Setup Time	20	_	ns
Talls ALE Setup Time 12 — ns Tall ALE Hold Time 5 — ns tos Data Setup Time 12 — ns toh Data Hold Time 12 — ns tw Write Cycle Time 25 — ns tw We High Hold Time 10 — ns tw We High to WE Low 100 — ns tre Ready to RE Falling Edge 20 — ns tre Ready to WE Falling Edge 20 — ns tre Read Pulse Width 12 — ns tre Read Pulse Width 12 — ns tre Read Cycle Time 25 — ns tre R	tсн	CE Hold Time	5	_	ns
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toth Data Hold Time 5 — ns twc Write Cycle Time 25 — ns tww WE High Hold Time 10 — ns tww WP High to WE Low 100 — ns trans Ready to Ready to RE Falling Edge 20 — ns trans Ready to WE Falling Edge 20 — ns trans Read Pulse Width 12 — ns trace Read Pulse Width 12 — ns trace Read Cycle Time 25 — ns trace Ready to Microson 10 — ns <	talh	ALE Hold Time	5	_	ns
Moc Write Cycle Time 25 — ns MWH WE High Hold Time 10 — ns MWH WE High Hold Time 10 — ns MWW WP High to WE Low 100 — ns MWW WP High to WE Low 100 — ns MRR Ready to WE Falling Edge 20 — ns MRW Read Pulse Width 12 — ns MRP Read Pulse Width 12 — ns MRC Read Pulse Width 12 — ns MRE	t _{DS}	Data Setup Time	12	_	ns
tww WE High Hold Time 10 — ns tww WP High to WE Low 100 — ns trex Ready to RE Falling Edge 20 — ns trew Ready to WE Falling Edge 20 — ns trep Read Pulse Width 12 — ns trep Read Cycle Time 25 — ns trec Read Cycle Time 25 — ns tree RE Access Time — 20 ns tceA CE Access Time — 25 ns tceA CE Low to RE Low 10 — ns trep RE High to Output Hold Time 25 — ns	t _{DH}	Data Hold Time	5	_	ns
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ttrR Ready to RE Falling Edge 20 — ns trw Ready to WE Falling Edge 20 — ns trep Read Pulse Width 12 — ns trep Read Pulse Width 12 — ns trec Read Cycle Time 25 — ns trec Read Cycle Time 25 — ns trea RE Access Time — 20 ns tceA CE Access Time — 25 ns tcLA CE Low to RE Low 10 — ns tcLA CE Low to RE Low 10 — ns treb Text RE Low to Output Hold Time 25 — ns treb Tight to Output Hold Time 5 — ns ns tcHZ RE High to Output High Impedance — 60 ns tcHZ Tigh	twH	WE High Hold Time	10	_	ns
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trea RE Access Time — 20 ns tceA CE Access Time — 25 ns tcLR CLE Low to RE Low 10 — ns tar ALE Low to RE Low 10 — ns tar RE High to Output Hold Time 25 — ns treHOH RE Low to Output Hold Time 5 — ns treHZ RE High to Output High Impedance — 60 ns tcHZ OE High to Output High Impedance — ns tcSD CE High to ALE or CLE Don't Care 0 — ns treH RE High Hold Time 10 — ns treH RE High Hold Time 10 — ns treH RE High to WE Low 30 — ns twHC WE High to RE Low 60 — ns twHR WE High to RE Low 60 — ns twWB WE High to Busy — 100 n	tRP	Read Pulse Width	12	_	ns
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tar ALE Low to RE Low 10 — ns trandh RE High to Output Hold Time 25 — ns trandh RE Low to Output Hold Time 5 — ns trandh RE High to Output High Impedance — 60 ns trandh CE High to Output High Impedance — 0 — ns trandh RE High Hold Time 10 — ns trandh RE High Hold Time 10 — ns trandh RE High Hold Time 0 — ns trandh RE High Time High Time 0 — ns trandh RE High Time Ne Ne Ne Ne Ne Ne twh RE High Time High Time Ne	tcea	CE Access Time	_	25	ns
tRHOH RE High to Output Hold Time 25 — ns tRLOH RE Low to Output Hold Time 5 — ns tRHZ RE High to Output High Impedance — 60 ns tCHZ CE High to Output High Impedance — 20 ns tCSD CE High to ALE or CLE Don't Care 0 — ns tREH RE High Hold Time 10 — ns tIR Output-High-Impedance-to-RE Falling Edge 0 — ns tRHW RE High to WE Low 30 — ns tWHC WE High to RE Low 60 — ns tWB WE High to Busy — 100 ns	tclr	CLE Low to RE Low	10	_	ns
tRLOH RE Low to Output Hold Time 5 — ns tRHZ RE High to Output High Impedance — 60 ns tCHZ CE High to Output High Impedance — 20 ns tCSD CE High to ALE or CLE Don't Care 0 — ns tREH RE High Hold Time 10 — ns tIR Output-High-Impedance-to-RE Falling Edge 0 — ns tRHW RE High to WE Low 30 — ns tWHC WE High to CE Low 30 — ns tWHR WE High to RE Low 60 — ns tWB WE High to Busy — 100 ns	tar	ALE Low to RE Low	10	_	ns
TRHZ RE High to Output High Impedance — 60 ns TCHZ CE High to Output High Impedance — 20 ns TCSD CE High to ALE or CLE Don't Care 0 — ns TREH RE High Hold Time 10 — ns TIR Output-High-Impedance-to-RE Falling Edge 0 — ns TREHW RE High to WE Low 30 — ns TWHC WE High to CE Low 30 — ns TWHR WE High to RE Low 60 — ns TWHR WE High to Busy — 100 ns	trнон	RE High to Output Hold Time	25	_	ns
tCHZ CE High to Output High Impedance — 20 ns tCSD CE High to ALE or CLE Don't Care 0 — ns tREH RE High Hold Time 10 — ns tIR Output-High-Impedance-to-RE Falling Edge 0 — ns tRHW RE High to WE Low 30 — ns tWHC WE High to CE Low 30 — ns tWHR WE High to RE Low 60 — ns tWB WE High to Busy — 100 ns	trloh	RE Low to Output Hold Time	5	_	ns
tCSD CE High to ALE or CLE Don't Care 0 — ns tREH RE High Hold Time 10 — ns tIR Output-High-Impedance-to-RE Falling Edge 0 — ns tRHW RE High to WE Low 30 — ns tWHC WE High to CE Low 30 — ns tWHR WE High to RE Low 60 — ns tWB WE High to Busy — 100 ns	trhz	RE High to Output High Impedance	_	60	ns
tree RE High Hold Time 10 — ns trink Output-High-Impedance-to-RE Falling Edge 0 — ns tree RE High to WE Low 30 — ns twhc WE High to CE Low 30 — ns twhr WE High to RE Low 60 — ns tws WE High to Busy — 100 ns	tcHZ	CE High to Output High Impedance	_	20	ns
tIR Output-High-Impedance-to-RE Falling Edge 0 — ns tRHW RE High to WE Low 30 — ns tWHC WE High to CE Low 30 — ns tWHR WE High to RE Low 60 — ns tWB WE High to Busy — 100 ns	tcsp	CE High to ALE or CLE Don't Care	0	_	ns
tRHW RE High to WE Low 30 — ns twHC WE High to CE Low 30 — ns twHR WE High to RE Low 60 — ns twB WE High to Busy — 100 ns	tREH	RE High Hold Time	10	_	ns
twhc WE High to CE Low 30 — ns twhr WE High to RE Low 60 — ns twb WE High to Busy — 100 ns	tıR	Output-High-Impedance-to- RE Falling Edge	0	_	ns
twhr WE High to RE Low 60 — ns twB WE High to Busy — 100 ns	t _{RHW}	RE High to WE Low	30	_	ns
twB WE High to Busy — 100 ns	twnc	WE High to CE Low	30	_	ns
	twhr	WE High to RE Low	60	_	ns
t _{RST} Device Reset Time (Ready/Read/Program/Erase) — 5/5/10/500 μs	t _{WB}	WE High to Busy	_	100	ns
	t _{RST}	Device Reset Time (Ready/Read/Program/Erase)	_	5/5/10/500	μS

^{*1:} tCLS and tALS can not be shorter than tWP.

^{*2:} tCS should be longer than tWP + 8ns.



AC TEST CONDITIONS

PARAMETER	CONDITION			
PARAWETER	V _{CC} : 1.7 to 1.95V			
Input level	V _{CC} -0.2V, 0.2V			
Input pulse rise and fall time	3 ns			
Input comparison level	Vcc / 2			
Output data comparison level	V _{CC} / 2			
Output load	C _L (30 pF) + 1 TTL			

Note: Busy to ready time depends on the pull-up resistor tied to the RY/BY pin. (Refer to Application Note (9) toward the end of this document)

PROGRAMMING / ERASING / READING CHARACTERISTICS

 $(Ta = -40 \text{ to } 85^{\circ}\text{C}, V_{CC} = 1.7 \text{ to } 1.95\text{V})$

SYMBOL	PARAMETER		TYP.	MAX	UNIT	NOTES
Average Programming Time (Single Page)		_	340	700	μS	
tPROG	Average Programming Time (Multi Page)	_	370	700	μS	
tDCBSYW1	Busy Time in Multi Page Program(following 11h)	_	0.5	1	μs	
N	Number of Partial Program Cycles in the Same Page	_	_	4		(1)
t _{BERASE}	Block Erasing Time	_	3.5	10	ms	
	Memory Cell Array to Starting Address (Single Page)	_	55	220	_	
t _R	Memory Cell Array to Starting Address (Multi Page)	_	90	420	μS	

⁽¹⁾ Refer to Application Note (12) toward the end of this document.

Data Output

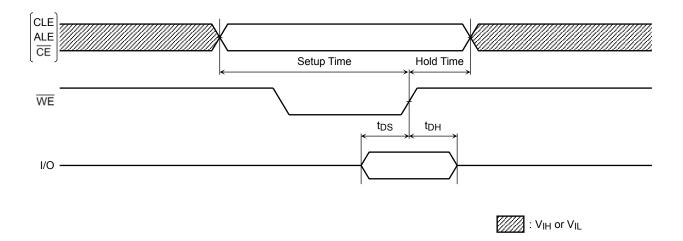
When tREH is long, output buffers are disabled by /RE=High, and the hold time of data output depend on tRHOH (25ns MIN). On this condition, waveforms look like normal serial read mode.

When tREH is short, output buffers are not disabled by /RE=High, and the hold time of data output depend on tRLOH (5ns MIN). On this condition, output buffers are disabled by the rising edge of CLE, ALE, /CE or falling edge of /WE, and waveforms look like Extended Data Output Mode.

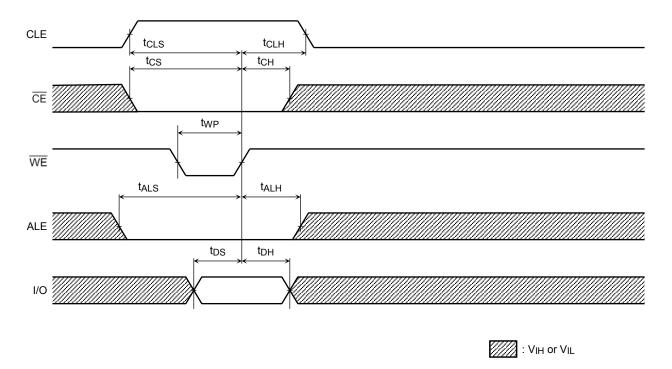


TIMING DIAGRAMS

Latch Timing Diagram for Command/Address/Data

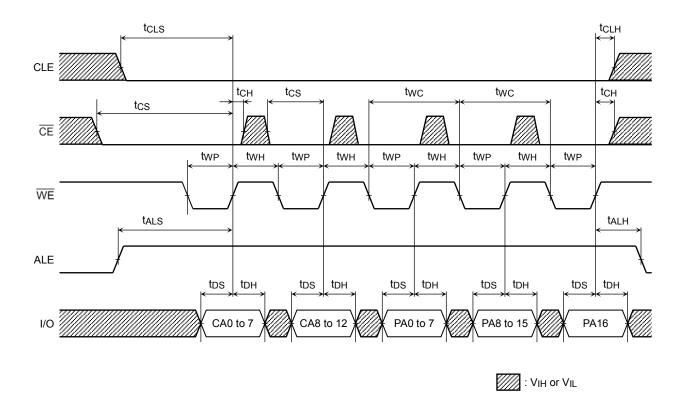


Command Input Cycle Timing Diagram

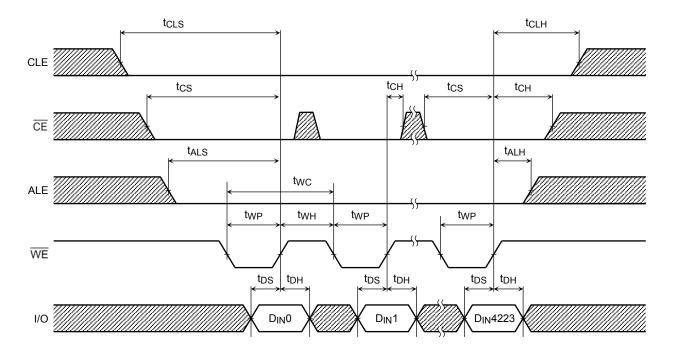




Address Input Cycle Timing Diagram

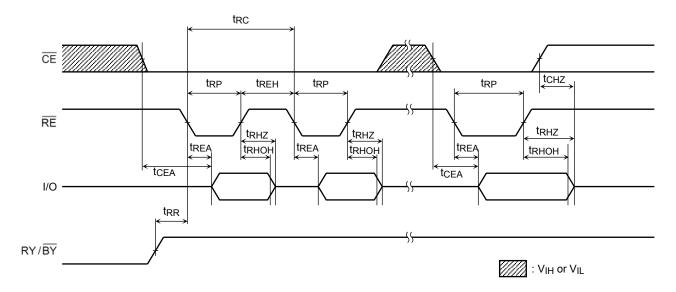


Data Input Cycle Timing Diagram

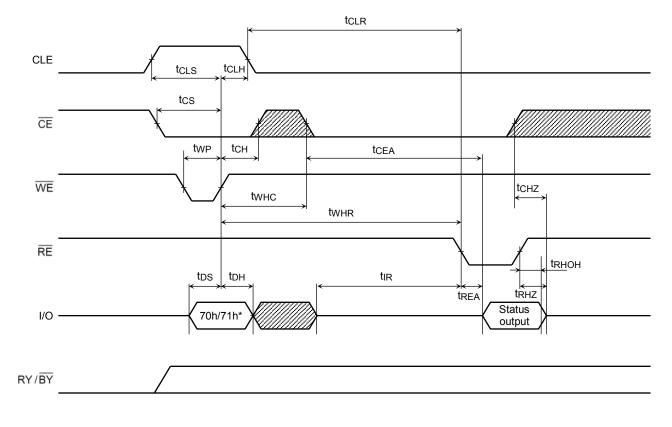




Serial Read Cycle Timing Diagram



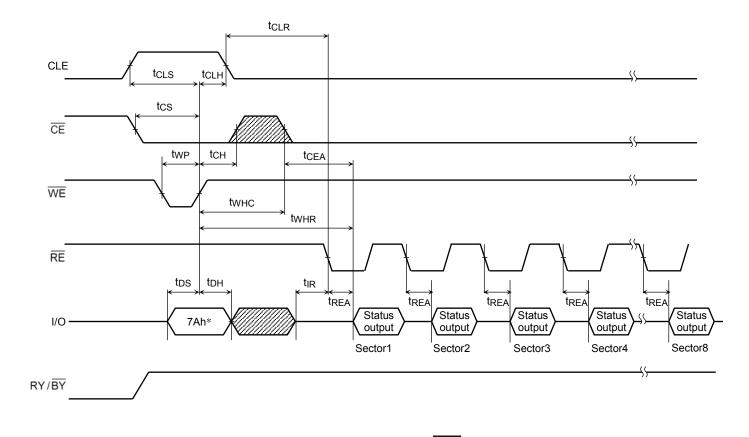
Status Read Cycle Timing Diagram



^{*: 70}h/71h represents the hexadecimal number



ECC Status Read Cycle Timing Diagram



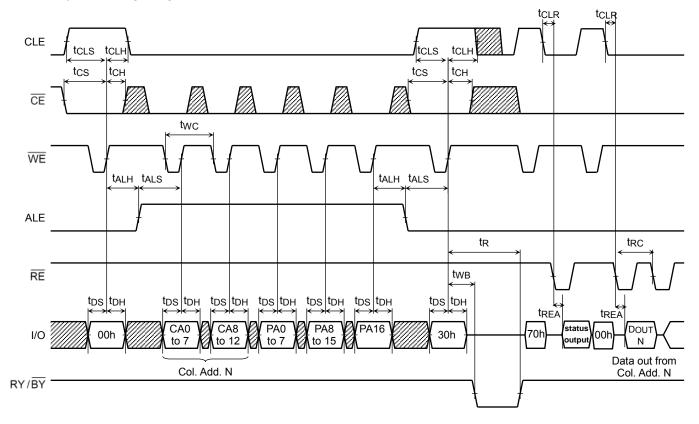
[:] V_{IH} or V_{IL}

^{*:} ECC Status output should be read for all 8 sector information.

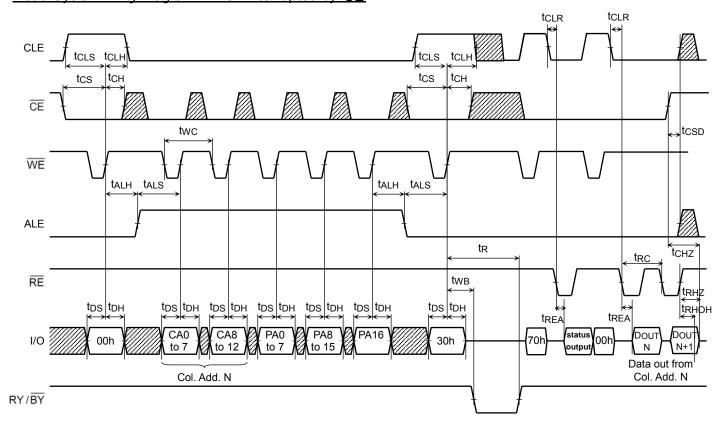
^{**: 7}Ah command can be input to the device from [after RY/BY returns to High] to [before Dout or Next command input].



Read Cycle Timing Diagram

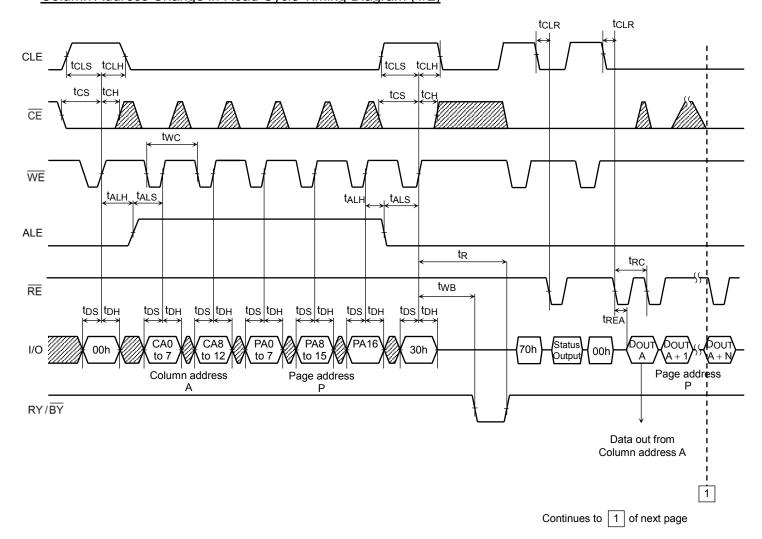


Read Cycle Timing Diagram: When Interrupted by $\overline{\mathsf{CE}}$



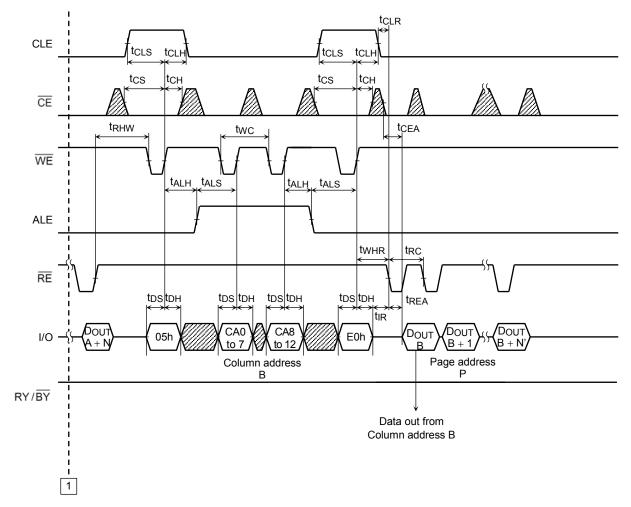


Column Address Change in Read Cycle Timing Diagram (1/2)





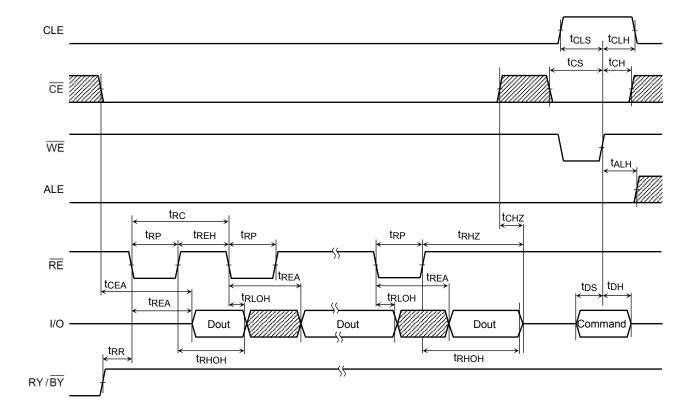
Column Address Change in Read Cycle Timing Diagram (2/2)



Continues from 1 of previous page

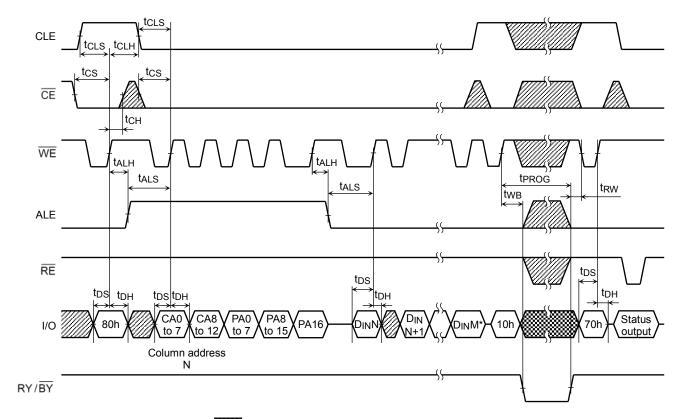


Data Output Timing Diagram





Auto-Program Operation Timing Diagram



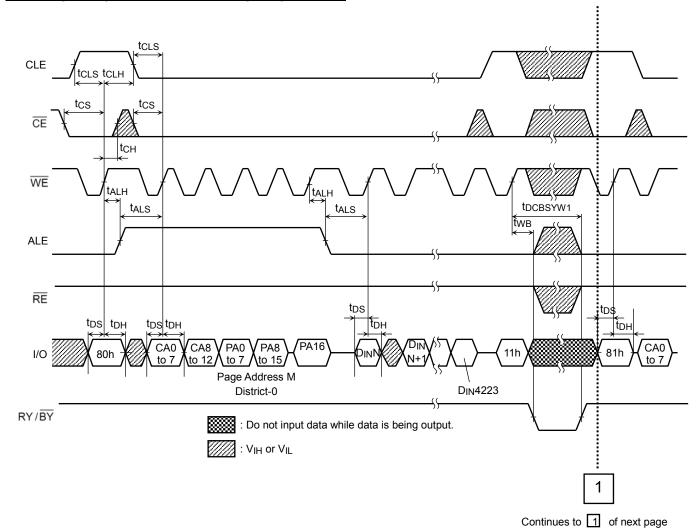
: Do not input data while data is being output.

: VIH or VIL

*) M: up to 4223

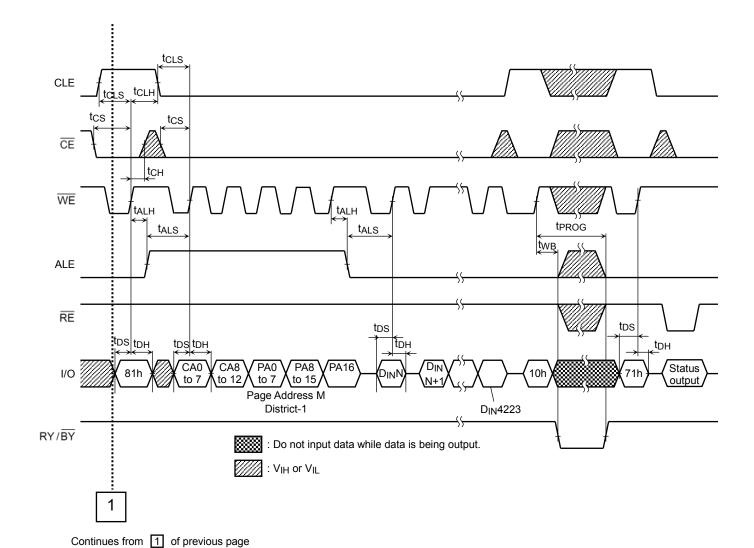


Multi-Page Program Operation Timing Diagram (1/2)



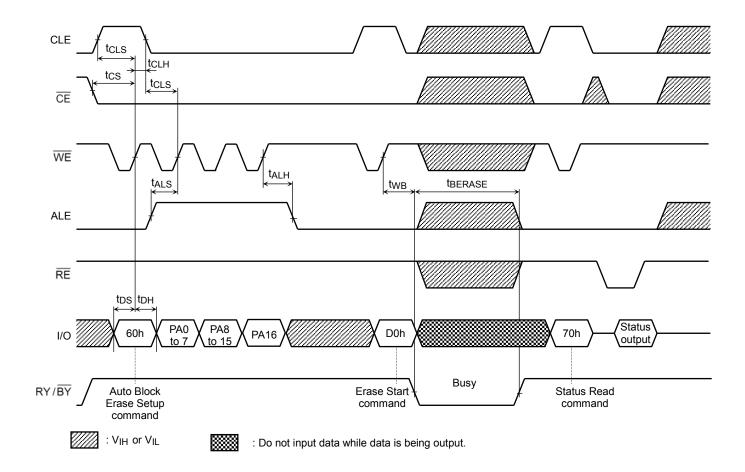


Multi-Page Program Operation Timing Diagram (2/2)



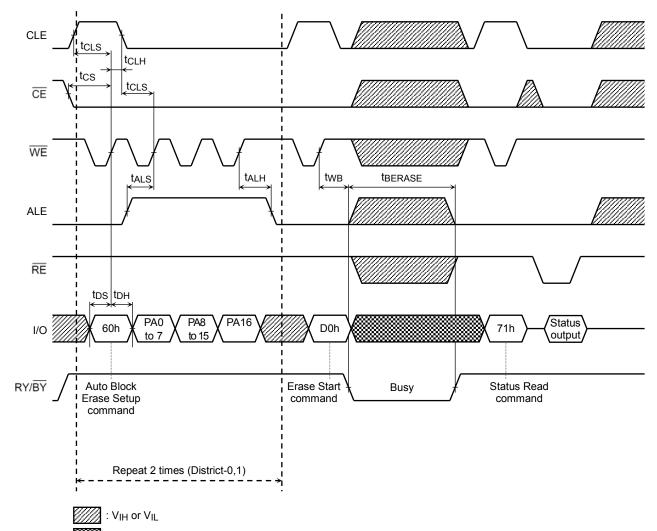


Auto Block Erase Timing Diagram



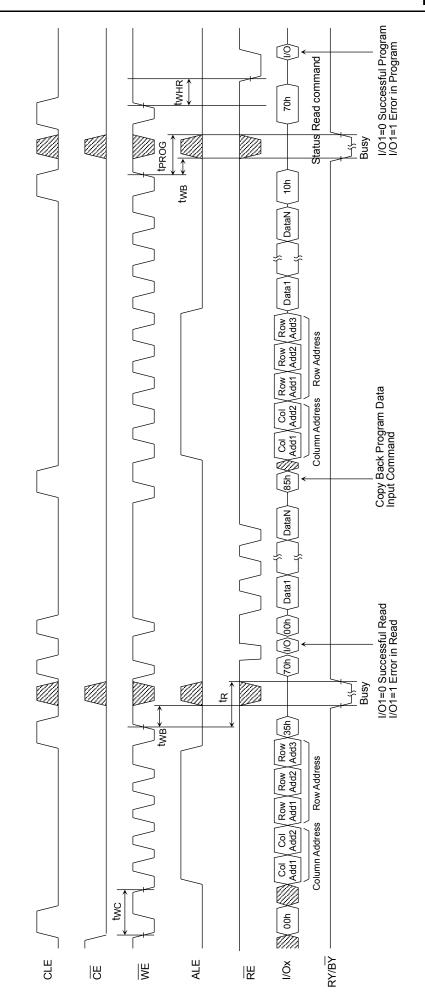


Multi Block Erase Timing Diagram



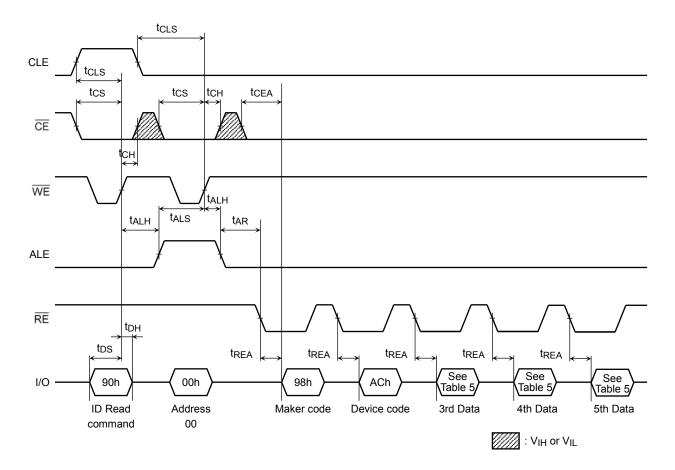
: Do not input data while data is being output.







ID Read Operation Timing Diagram





PIN FUNCTIONS

The device is a serial access memory which utilizes time-sharing input of address information.

Command Latch Enable: CLE

The CLE input signal is used to control loading of the operation mode command into the internal command register. The command is latched into the command register from the I/O port on the rising edge of the $\overline{\rm WE}$ signal while CLE is High.

Address Latch Enable: ALE

The ALE signal is used to control loading address information into the internal address register. Address information is latched into the address register from the I/O port on the rising edge of $\overline{\text{WE}}$ while ALE is High.

Chip Enable: CE

The device goes into a low-power Standby mode when \overline{CE} goes High during the device is in Ready state. The \overline{CE} signal is ignored when device is in Busy state (RY/ \overline{BY} = L), such as during a Program, Erase or Read operation, and will not enter Standby mode even if the \overline{CE} input goes High.

Write Enable: WE

The WE signal is used to control the acquisition of data from the I/O port.

Read Enable: RE

The \overline{RE} signal controls serial data output. Data is available trea after the falling edge of \overline{RE} . The internal column address counter is also incremented (Address = Address + 1) on this falling edge.

I/O Port: I/O1 to 8

The I/O1 to 8 pins are used as a port for transferring address, command and input/output data to and from the device.

Write Protect: WP

The $\overline{\mathrm{WP}}$ signal is used to protect the device from accidental programming or erasing. The internal voltage regulator is reset when $\overline{\mathrm{WP}}$ is Low. This signal is usually used for protecting the data during the power-on/off sequence when input signals are invalid.

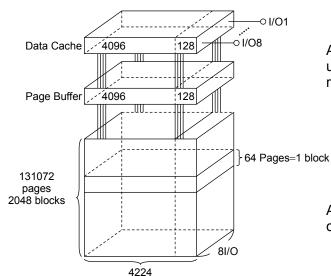
Ready/Busy: RY/BY

The RY/\overline{BY} output signal is used to indicate the operating condition of the device. The RY/\overline{BY} signal is in Busy state (RY/\overline{BY} = L) during the Program, Erase and Read operations and will return to Ready state (RY/\overline{BY} = H) after completion of the operation. The output buffer for this signal is an open drain and has to be pulled-up to V_{CC} with an appropriate resistor.



Schematic Cell Layout and Address Assignment

The Program operation works on page units while the Erase operation works on block units.



A page consists of 4224 bytes in which 4096 bytes are used for main memory storage and 128 bytes are for redundancy or for other uses.

1 page = 4224 bytes

1 block = 4224 bytes × 64 pages = (256K + 8K) bytes

Capacity = 4224 bytes \times 64 pages \times 2048 blocks

An address is read in via the I/O port over five consecutive clock cycles, as shown in Table 1.

Table 1. Addressing

	I/O8	1/07	I/O6	I/O5	I/O4	I/O3	I/O2	I/O1
First cycle	CA7	CA6	CA5	CA4	CA3	CA2	CA1	CA0
Second cycle	L	L	L	CA12	CA11	CA10	CA9	CA8
Third cycle	PA7	PA6	PA5	PA4	PA3	PA2	PA1	PA0
Fourth cycle	PA15	PA14	PA13	PA12	PA11	PA10	PA9	PA8
Fifth cycle	L	L	L	L	L	L	L	PA16

CA0 to CA12: Column address PA0 to PA5: Page address in block PA6 to PA16: Block address



Operation Mode: Logic and Command Tables

The operation modes such as Program, Erase, Read and Reset are controlled by command operations shown in Table 3. Address input, command input and data input/output are controlled by the CLE, ALE, $\overline{\text{CE}}$, $\overline{\text{WE}}$, $\overline{\text{RE}}$ and $\overline{\text{WP}}$ signals, as shown in Table 2.

Table 2. Logic Table

	CLE	ALE	CE	WE	RE	WP *1
Command Input	Н	L	L	7	Н	*
Data Input	L	L	L	F	Н	Н
Address Input	L	Н	L	7	Н	*
Serial Data Output	L	L	L	Н	7	*
During Program (Busy)	*	*	*	*	*	Н
During Erase (Busy)	*	*	*	*	*	Н
During Daniel (Duran)	*	*	Н	*	*	*
During Read (Busy)	*	*	L	H (*2)	H (*2)	*
Program, Erase Inhibit	*	*	*	*	*	L,
Standby	*	*	Н	*	*	0 V/Vcc

H: VIH, L: VIL, *: VIH or VIL

^{*1:} Refer to Application Note (10) toward the end of this document regarding the WP signal when Program or Erase Inhibit.

^{*2:} If $\overline{\sf CE}$ is low during read busy, $\overline{\sf WE}$ and $\overline{\sf RE}$ must be held High to avoid unintended command/address input to the device or read to device. Reset or Status Read command can be input during Read Busy.



Table 3. Command table (HEX)

	First Set	Second Set	Acceptable while Busy
Serial Data Input	80	_	
Read	00	30	
Column Address Change in Serial Data Output	05	E0	
Auto Page Program	80	10	
Column Address Change in Serial Data Input	85	_	
	80	11	
Multi Page Program	81	10	
Read for Copy-Back	00	35	
Copy-Back Program	85	10	
Auto Block Erase	60	D0	
ID Read	90	_	
Status Read	70	_	0
Status Read for Multi-Page Program or Multi Block Erase	71	_	0
ECC Status Read	7A	_	
Reset	FF	_	0

HEX data bit assignment

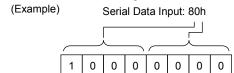


Table 4. Read mode operation states

	CLE	ALE	CE	WE	RE	I/O1 to I/O8	Power
Output select	L	L	L	Н	L	Data output	Active
Output Deselect	L	L	L	Н	Н	High impedance	Active

H: V_{IH}, L: V_{IL}

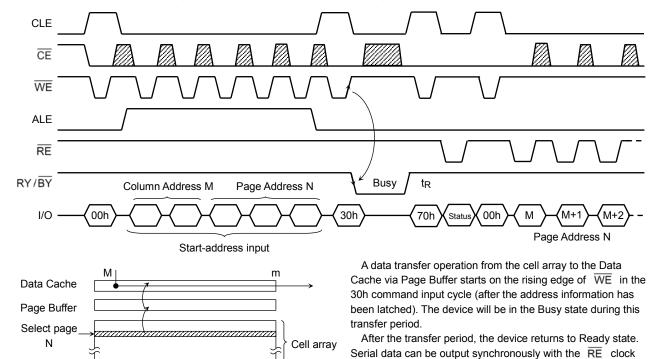
from the start address designated in the address input cycle.



DEVICE OPERATION

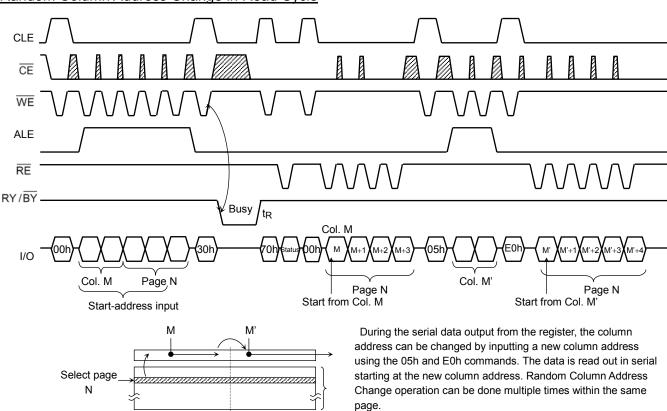
Read Mode

Read mode is set when the "00h" and "30h" commands are issued to the Command register. Between the two commands, a start address for the Read mode needs to be issued. After initial power on sequence, "00h" command is latched into the internal command register. Therefore read operation after power on sequence is executed by the setting of only five address cycles and "30h" command. Refer to the figures below for the sequence and the block diagram (Refer to the detailed timing chart).



Random Column Address Change in Read Cycle

I/O1 to 8: m = 4223



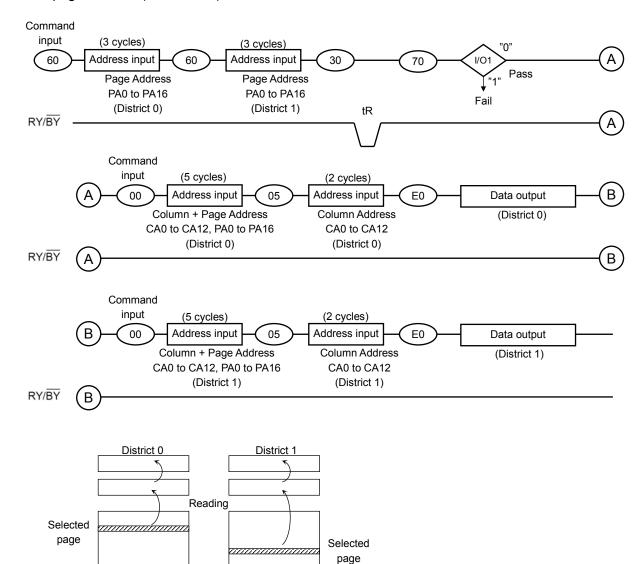


Multi Page Read Operation

The device has a Multi Page Read operation.

The sequence of command and address input is shown below.

Same page address (PA0 to PA5) within each district has to be selected.



The data transfer operation from the cell array to the Data Cache via Page Buffer starts on the rising edge of \overline{WE} in the 30h command input cycle (after the 2 Districts address information has been latched). The device will be in the Busy state during this transfer period.

After the transfer period, the device returns to Ready state. Serial data can be output synchronously with the $\overline{\text{RE}}$ clock from the start address designated in the address input cycle.

ECC Status command <7Ah> can be used only for Single Page Read. It is not supported for Multi Page Read operation.



Internal addressing in relation with the Districts

To use Multi Page Read operation, the internal addressing should be considered in relation with the District.

- The device consists of 2 Districts.
- Each District consists of 1024 erase blocks.
- The allocation rule is follows.

District 0: Block 0, Block 2, Block 4, Block 6,..., Block 2046 District 1: Block 1, Block 3, Block 5, Block 7,..., Block 2047

Address input restriction for the Multi Page Read operation

There are following restrictions in using Multi Page Read;

(Restriction)

Maximum one block should be selected from each District.

Same page address (PA0 to PA5) within two districts has to be selected.

For example:

(60) [District 0, Page Address 0x00000] (60) [District 1, Page Address 0x00040] (30)

(60) [District 0, Page Address 0x00001] (60) [District 1, Page Address 0x00041] (30)

(Acceptance)

There is no order limitation of the District for the address input.

For example, following operation is accepted;

(60) [District 0] (60) [District 1] (30)

(60) [District 1] (60) [District 0] (30)

It requires no mutual address relation between the selected blocks from each District.

Operating restriction during the Multi Page Read operation

Make sure WP is held to High level when Multi Page Read operation is performed.



ECC & Sector definition for ECC

Internal ECC logic generates Error Correction Code during busy time in program operation. The ECC logic manages 9bit error detection and 8bit error correction in each 528Bytes of main data and spare data. A section of main field (512Bytes) and spare field (16Bytes) are paired for ECC. During read, the device executes ECC of itself. Once read operation is executed, Status Read Command (70h) can be issued to check the read status. The read status remains until other valid commands are executed.

To use ECC function, below limitation must be considered.

- A sector is the minimum unit for program operation and the number of program per page must not exceed 4.

4KByte Page Assignment

1st	2nd	3rd	4th	5th	6th	7th	8th	1st	2nd	3rd	4th	5th	6th	7th	8th
Main	Spare														
512B	16B														

Note) The Internal ECC manages all data of Main area and Spare area.

Definition of 528Byte Sector

Sector	Column Address (Byte)					
	Main Field	Spare Field				
1st Sector	0 to 511	4,096 to 4,111				
2nd Sector	512 to 1,023	4,112 to 4,127				
3rd Sector	1,024 to 1,535	4,128 to 4,143				
4th Sector	1,536 to 2,047	4,144 to 4,159				
5th Sector	2,048 to 2,559	4,160 to 4,175				
6th Sector	2,560 to 3,071	4,176 to 4,191				
7th Sector	3,072 to 3,583	4,192 to 4,207				
8th Sector	3,584 to 4,095	4,208 to 4,223				

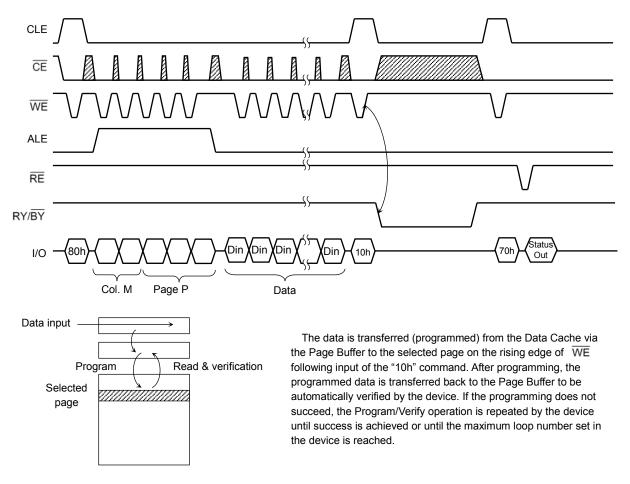
Note) The ECC parity code generated by internal ECC is stored in column addresses 4224-4351 and the user cannot access to these specific addresses.

While using the Partial Page Program, the user must program the data to main field and spare field simultaneously by the definition of sector.



Auto Page Program Operation

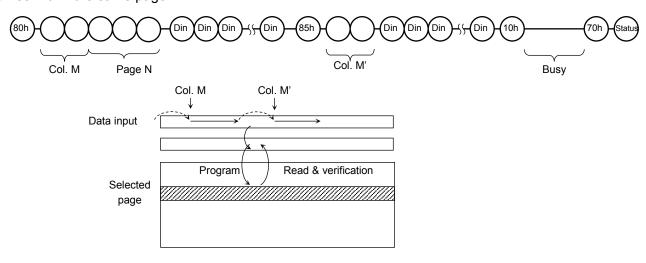
The device carries out an Automatic Page Program operation when it receives a "10h" Program command after the address and data have been input. The sequence of command, address and data input is shown below (Refer to the detailed timing chart).



Random Column Address Change in Auto Page Program Operation

The column address can be changed by the 85h command during the data input sequence of the Auto Page Program operation.

Two address input cycles after the 85h command are recognized as a new column address for the data input. After the new data is input to the new column address, the 10h command initiates the actual data program into the selected page automatically. The Random Column Address Change operation can be repeated multiple times within the same page.



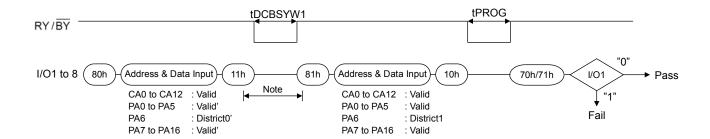


Multi Page Program

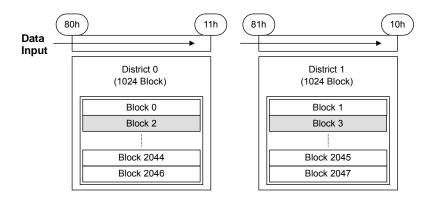
The device has a Multi Page Program, which enables even higher speed program operation compared to Auto Page Program. The sequence of command, address and data input is shown below (Refer to the detailed timing chart).

Although two districts are programmed simultaneously, pass/fail is not available for each page by "70h" command when the program operation completes. Status bit of I/O 1 is set to "1" when any of the pages fails. Limitation in addressing with Multi Page Program is shown below.

Multi Page Program



NOTE: Any command between 11h and 81h is prohibited except 70h and FFh.



The 71h command Status description is as below.

	STATUS	C	OUTPUT
I/O1	Chip Status : Pass/Fail	Pass: 0	Fail: 1
I/O2	District 0 Chip Status : Pass/Fail	Pass: 0	Fail: 1
I/O3	District 1 Chip Status : Pass/Fail	Pass: 0	Fail: 1
I/O4	Not Used		Invalid
I/O5	Not Used		Invalid
I/O6	Ready/Busy	Ready: 1	Busy: 0
I/O7	Ready/Busy	Ready: 1	Busy: 0
I/O8	Write Protect	Protect: 0	Not Protect: 1

I/O1 describes Pass/Fail condition of district 0 and 1(OR data of I/O2 and I/O3). If one of the districts fails during multi page program operation, it shows "Fail".

I/O2 to 3 shows the Pass/Fail condition of each district.



Internal addressing in relation with the Districts

To use Multi Page Program operation, the internal addressing should be considered in relation with the District.

- The device consists of 2 Districts.
- Each District consists of 1024 erase blocks.
- The allocation rule is follows.

```
District 0: Block 0, Block 2, Block 4, Block 6,..., Block 2046 District 1: Block 1, Block 3, Block 5, Block 7,..., Block 2047
```

Address input restriction for the Multi Page Program operation

There are following restrictions in using Multi Page Program;

(Restriction)

Maximum one block should be selected from each District.

Same page address (PA0 to PA5) within two districts has to be selected.

For example:

```
(80) [District 0, Page Address 0x00000] (11) (81) [District 1, Page Address 0x00040] (10) (80) [District 0, Page Address 0x00001] (11) (81) [District 1, Page Address 0x00041] (10)
```

(Acceptance)

There is no order limitation of the District for the address input.

For example, following operation is accepted;

```
(80) [District 0] (11) (81) [District 1] (10)
```

(80) [District 1] (11) (81) [District 0] (10)

It requires no mutual address relation between the selected blocks from each District.

Operating restriction during the Multi Page Program operation

(Restriction)

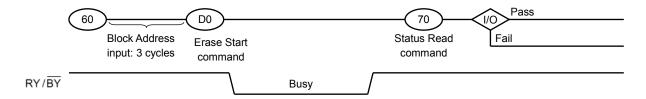
The operation has to be terminated with "10h" command.

Once the operation is started, no commands other than the commands shown in the timing diagram is allowed to be input except for Status Read command and reset command.



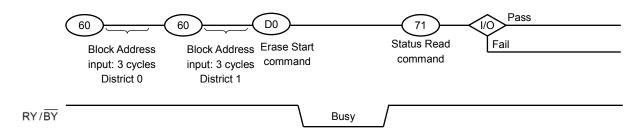
Auto Block Erase

The Auto Block Erase operation starts on the rising edge of $\overline{\mathrm{WE}}$ after the Erase Start command "D0h" which follows the Erase Setup command "60h". This two-cycle process for Erase operations acts as an extra layer of protection from accidental erasure of data due to external noise. The device automatically executes the Erase and Verify operations.



Multi Block Erase

The Multi Block Erase operation starts by selecting two block addresses before D0h command as in below diagram. The device automatically executes the Erase and Verify operations and the result can be monitored by checking the status by 71h status read command. For details on 71h status read command, refer to section "Multi Page Program".



Internal addressing in relation with the Districts

To use Multi Block Erase operation, the internal addressing should be considered in relation with the District.

- The device consists of 2 Districts.
- · Each District consists of 1024 erase blocks.
- The allocation rule is follows.

District 0: Block 0, Block 2, Block 4, Block 6, \cdots , Block 2046 District 1: Block 1, Block 3, Block 5, Block 7, \cdots , Block 2047

Address input restriction for the Multi Block Erase

There are following restrictions in using Multi Block Erase;

(Restriction)

Maximum one block should be selected from each District.

For example;

(60) [District 0] (60) [District 1] (D0)

(Acceptance)

There is no order limitation of the District for the address input.

For example, following operation is accepted;

(60) [District 1] (60) [District 0] (D0)

It requires no mutual address relation between the selected blocks from each District.

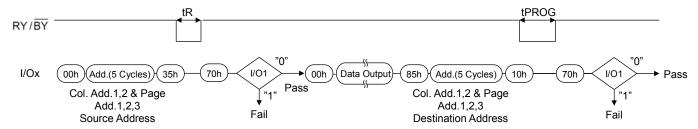
Make sure to terminate the operation with D0h command. If the operation needs to be terminated before D0h command input, input the FFh reset command to terminate the operation.



READ FOR COPY-BACK WITH DATA OUTPUT TIMING GUIDE

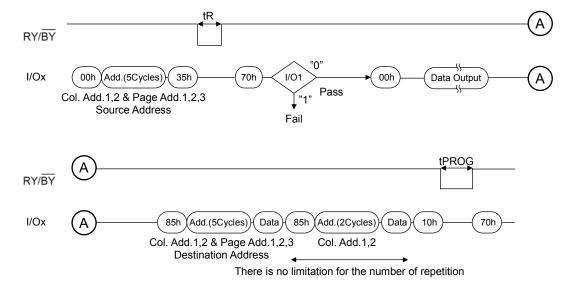
Copy-Back operation is a sequence execution of Read for Copy-Back and of copy-back program with the destination page address. A read operation with "35h" command and the address of source page moves the whole 4224 bytes data into the internal data buffer. Bit errors are checked by sequential reading the data or by reading the status in read after read busy time (tR) to check if uncorrectable error occurs. In the case where there is no bit error or no uncorrectable error, the data don't need to be reloaded. Therefore Copy-Back program operation is initiated by issuing Page-Copy Data-Input command (85h) with destination page address. Actual programming operation begins after Program Confirm command (10h) is issued. Once the program process starts, the Status Read command (70h) may be entered to read the status register. The system controller can detect the completion of a program cycle by monitoring the RY/BY output, or the Status Bit (I/O7) of the Status Register. When the Copy-Back Program is complete, the Write Status Bit (I/O1) may be checked. The command register remains in Status Read mode until another valid command is written to the command register. During copy-Back program, data modification is possible using random data input command (85h) as shown below.

Page Copy-Back Program Operation



NOTE: 1. Copy-Back Program operation is allowed only within the same district.

Page Copy-Back Program Operation with Random Data Input





ID Read

The device contains ID codes which can be used to identify the device type, the manufacturer, and features of the device. The ID codes can be read out under the following timing conditions:

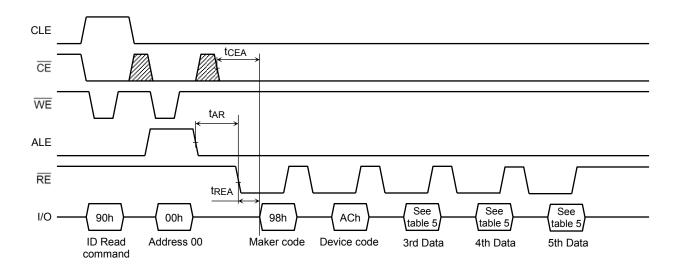


Table 5. Code table

	Description	I/O8	1/07	I/O6	I/O5	1/04	I/O3	I/O2	I/O1	Hex Data
1st Data	Maker Code	1	0	0	1	1	0	0	0	98h
2nd Data	Device Code	1	0	1	0	1	1	0	0	ACh
3rd Data	Chip Number, Cell Type	1	0	0	1	0	0	0	0	90h
4th Data	Page Size, Block Size	0	0	1	0	0	1	1	0	26h
5th Data	District Number	1	1	1	1	0	1	1	0	F6h

3rd Data

	Description	I/O8	1/07	I/O6	I/O5	I/O4	I/O3	I/O2	I/O1
Internal Chip Number	1 2 4 8							0 0 1 1	0 1 0 1
Cell Type	2 level cell 4 level cell 8 level cell 16 level cell					0 0 1 1	0 1 0 1		
Reserved		1	0	0	1				



4th Data

	Description	I/O8	1/07	I/O6	I/O5	I/O4	I/O3	I/O2	I/O1
Page Size (without redundant area)	1 KB 2 KB 4 KB 8 KB							0 0 1 1	0 1 0 1
Block Size (without redundant area)	64 KB 128 KB 256 KB 512 KB			0 0 1 1	0 1 0				
I/O Width	x8 x16		0 1						
Reserved		0				0	1		

5th Data

	Description	I/O8	1/07	I/O6	I/O5	I/O4	I/O3	I/O2	I/O1
District Number	1 District 2 District 4 District 8 District					0 0 1 1	0 1 0 1		
ECC engine on chip	With ECC engine	1							
Reserved			1	1	1			1	0



Status Read

The device automatically implements the execution and verification of the Program and Erase operations. The Status Read function is used to monitor the Ready/Busy status of the device, determine the result (pass /fail) of a Program or Erase operation, and determine whether the device is in Protect mode. The device status is output via the I/O port using $\overline{\rm RE}$ after a "70h" command input. The Status Read can also be used during a Read operation to monitor the Ready/Busy status and to find out the ECC result (pass/fail).

The resulting information is outlined in Table 6.

Table 6. Status output table

	Definition	Page Program	Block Erase	Read
I/O1	Chip Status Pass: 0 Fail: 1	Pass/Fail	Pass/Fail	Pass/Fail(Uncorrectable)
I/O2	Not Used	Invalid	Invalid	Invalid
I/O3	Not Used	0	0	0
1/04	Chip Read Status Normal or uncorrectable: 0 Recommended to rewrite: 1	0	0	Normal or uncorrectable / Recommended to rewrite
I/O5	Not Used	0	0	0
1/06	Ready/Busy Ready: 1 Busy: 0	Ready/Busy	Ready/Busy	Ready/Busy
1/07	Ready/Busy Ready: 1 Busy: 0	Ready/Busy	Ready/Busy	Ready/Busy
I/O8	Write Protect Not Protected :1 Protected: 0	Write Protect	Write Protect	Write Protect

The Pass/Fail status on I/O1 is only valid during a Program/Erase/Read operation when the device is in the Ready state.



ECC Status Read

The ECC Status Read function is used to monitor the Error Correction Status. The device can correct up to 8bit errors.

ECC can be performed on the NAND Flash main and spare areas. The ECC Status Read function can also show the number of errors in a sector as a result of an ECC check in during a read operation.

8	7	6	5	4	3	2	I/O1
Sector Information				ECC S	Status		

ECC Status

I/O4 to I/O1	ECC Status
0000	No Error
0001	1bit error(Correctable)
0010	2bit error(Correctable)
0011	3bit error(Correctable)
0100	4bit error(Correctable)
0101	5bit error(Correctable)
0110	6bit error(Correctable)
0111	7bit error(Correctable)
1000	8bit error(Correctable)
1111	Uncorrectable Error

Sector Information

I/O8 to I/O5	Sector Information
0000	1st Sector (Main and Spare area)
0001	2nd Sector (Main and Spare area)
0010	3rd Sector (Main and Spare area)
0011	4th Sector (Main and Spare area)
0100	5th Sector (Main and Spare area)
0101	6th Sector (Main and Spare area)
0110	7th Sector (Main and Spare area)
0111	8th Sector (Main and Spare area)
Other	Reserved

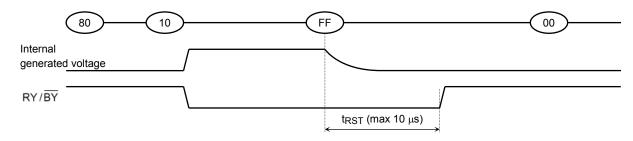


Reset

The Reset mode stops all operations. For example, in case of a Program or Erase operation, the internally generated voltage is discharged to 0 volt and the device enters the Wait state.

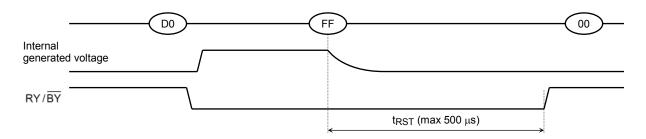
The response to a "FFh" Reset command input during the various device operations is as follows:

When a Reset (FFh) command is input during Program operation

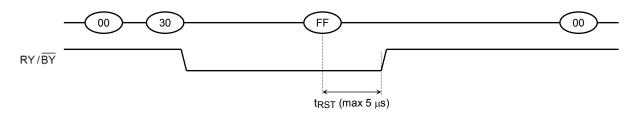




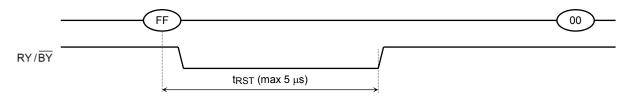
When a Reset (FFh) command is input during Erase operation



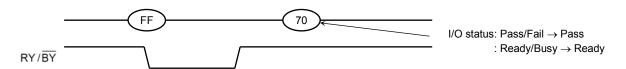
When a Reset (FFh) command is input during Read operation



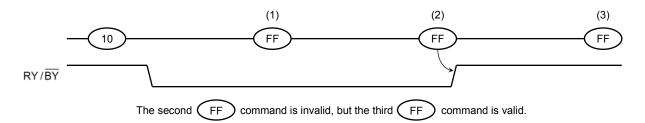
When a Reset (FFh) command is input during Ready



When a Status Read command (70h) is input after a Reset



When two or more Reset commands are input in succession





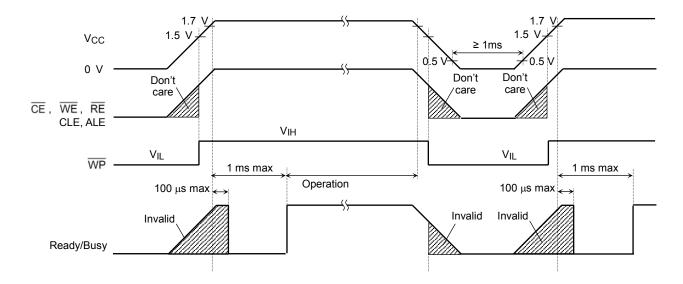
APPLICATION NOTES AND COMMENTS

(1) Power-on/off sequence

The timing sequence shown in the figure below is necessary for the power-on/off sequence.

The device internal initialization starts after the power supply reaches an appropriate level in the power on sequence. During the initialization the device Ready/Busy signal indicates the Busy state as shown in the figure below. In this time period, the acceptable commands are FFh or 70h.

The \overline{WP} signal is useful for protecting against data corruption at power-on/off.



(2) Power-on Reset

The following sequence is necessary because some input signals may not be stable at power-on.



(3) Prohibition of unspecified commands

The operation commands are listed in Table 3. Input of a command other than those specified in Table 3 is prohibited. Stored data may be corrupted if an unknown command is entered during the command cycle.

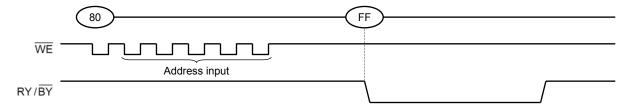
(4) Restriction of commands while in the Busy state

During the Busy state, do not input any command except 70h,71h and FFh.

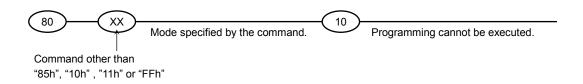


(5) Acceptable commands after Serial Input command "80h"

Once the Serial Input command "80h" has been input, do not input any command other than the Column Address Change in Serial Data Input command "85h", Auto Program command "10h", Multi Page Program command "11h" or the Reset command "FFh".

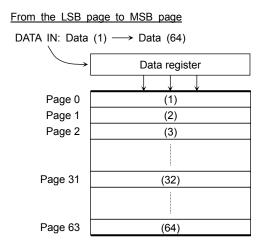


If a command other than "85h", "10h", "11h" or "FFh" is input, the Program operation is not performed and the device operation is set to the mode which the input command specifies.



(6) Addressing for program operation

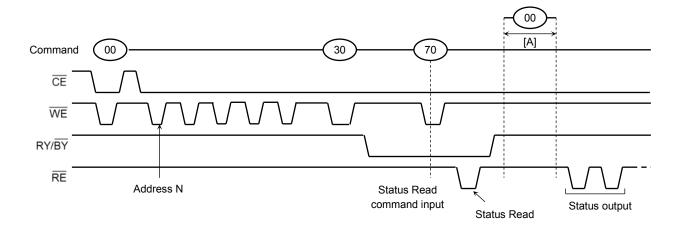
Within a block, the pages must be programmed consecutively from the LSB (least significant bit) page of the block to MSB (most significant bit) page of the block. Random page address programming is prohibited.



Ex.) Random page program (Prohibition) DATA IN: Data (1) Data register Page 0 Page 1 Page 2 (32) Page 2 (3) Page 31 (1) Page 63 (64)

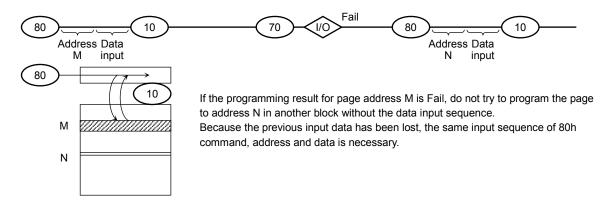


(7) Status Read during a Read operation



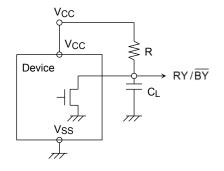
The device status can be read out by inputting the Status Read command "70h" in Read mode. Once the device has been set to Status Read mode by a "70h" command, the device will not return to Read mode unless the Read command "00h" is input during [A]. If the Read command "00h" is input during [A], Status Read mode is reset, and the device returns to Read mode. In this case, data output starts automatically from address N and address input is unnecessary.

(8) Auto programming failure

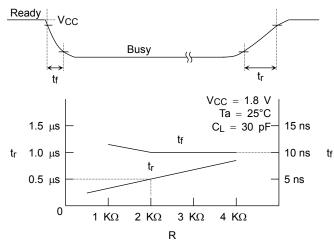


(9) RY / \overline{BY} : termination for the Ready/Busy pin (RY / \overline{BY})

A pull-up resistor needs to be used for termination because the $\ \mathrm{RY}\,/\,\overline{\mathrm{BY}}\$ buffer consists of an open drain circuit.



This data may vary from device to device. We recommend that you use this data as a reference when selecting a resistor value.

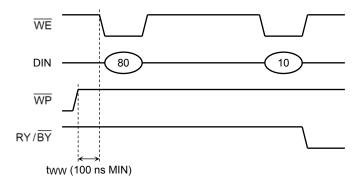




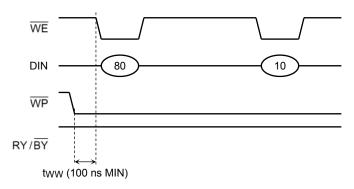
(10) Note regarding the $\overline{\mathrm{WP}}$ signal

The Erase and Program operations are automatically reset when \overline{WP} goes Low. The operations are enabled and disabled as follows:

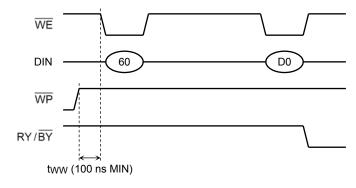
Enable Programming



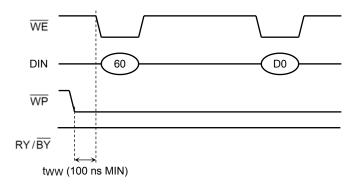
Disable Programming



Enable Erasing



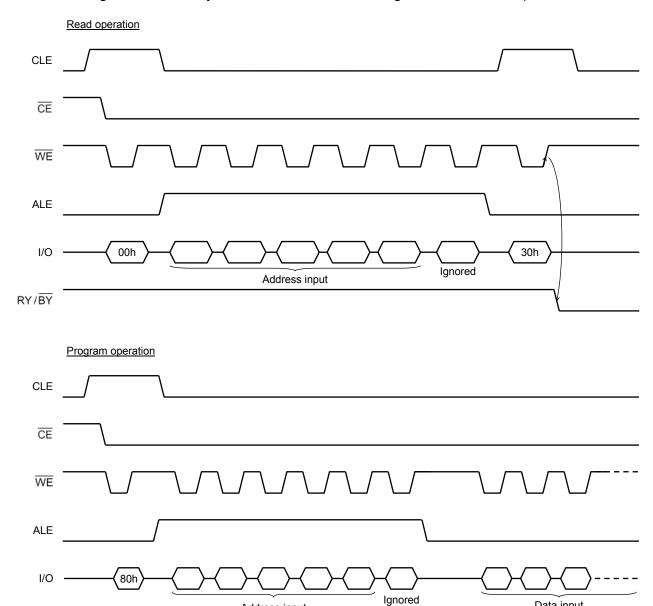
Disable Erasing





When six address cycles are input (11)

Although the device may read in a sixth address, it is ignored inside the chip.



Address input

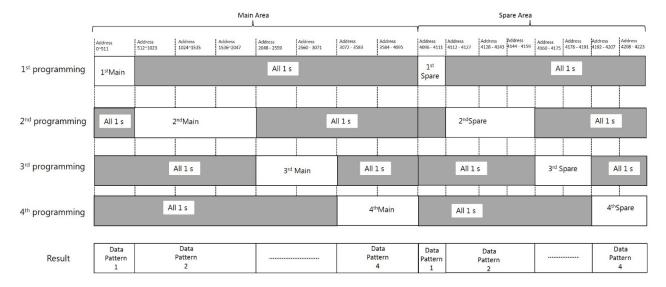
Data input



(12) Several programming cycles on the same page (Partial Page Program)

ECC Parity Code is generated during program operation on Main area (512 byte) + Spare area (16byte). While using the Partial Page Program, the user must program the data to main field and spare field simultaneously by the definition of sector in section "ECC & Sector definition for ECC".

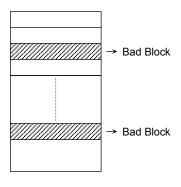
For example, each segment can be programmed individually as follows:





(13) Invalid blocks (bad blocks)

The device occasionally contains unusable blocks. Therefore, the following issues must be recognized:



Please do not perform an erase operation to bad blocks. It may be impossible to recover the bad block information if the information is erased.

Check if the device has any bad blocks after installation into the system. Refer to the test flow for bad block detection. Bad blocks which are detected by the test flow must be managed as unusable blocks by the system.

A bad block does not affect the performance of good blocks because it is isolated from the bit lines by select gates.

The number of valid blocks over the device lifetime is as follows:

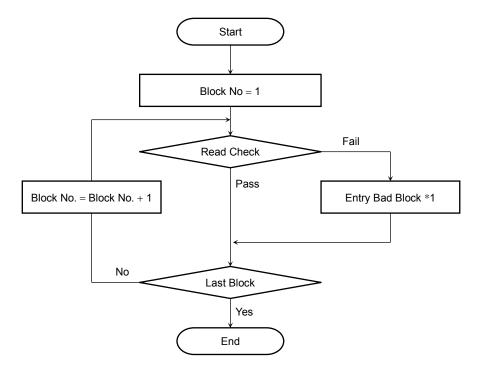
	MIN	TYP.	MAX	UNIT
Valid (Good) Block Number	2008	_	2048	Blocks

Bad Block Test Flow

Regarding invalid blocks, bad block mark is in whole pages.

Please read one column of any page in each block. If the data of the column is 00 (Hex), define the block as a bad block.

For Bad Block Test Flow, during Read Check, regardless of Status Read result (ECC Pass or Fail), use the read data value to make judgement for Bad Block.



^{*1:} No erase operation is allowed to detected bad blocks.



(14) Failure phenomena for Program, Erase and Read operations

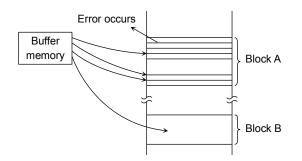
The device may fail during a Program, Erase or Read operation.

The following possible failure modes should be considered when implementing a highly reliable system.

FAILURE MODE		DETECTION AND COUNTERMEASURE SEQUENCE		
Block	Erase Failure	Status Read after Erase → Block Replacement		
Page	Programming Failure	Status Read after Program → Block Replacement		
Read	9bit Failure (uncorrectable error)	Check the ECC correction status by Status Read or ECC Status Read and take appropriate measures such as rewrite in consideration of Wear Leveling before uncorrectable ECC error occurs.		

- ECC: Error Correction Code. 8 bit correction per 528Bytes is executed in a device.
- Block Replacement

Program



When an error happens in Block A, try to reprogram the data into another Block (Block B) by loading from an external buffer. Then, prevent further system accesses to Block A (by creating a bad block table or by using another appropriate scheme).

Erase

When an error occurs during an Erase operation, prevent future accesses to this bad block (by creating a table within the system or by using another appropriate scheme).

(15) Do not turn off the power before write/erase operation is complete. Avoid using the device when the battery is low. Power shortage and/or power failure before write/erase operation is complete will cause loss of data and/or damage to data.



(16) Reliability Guidance

This reliability guidance is intended to notify some guidance related to using NAND Flash with 8 bit ECC for each 512 bytes. NAND Flash memory cells are gradually worn out and the reliability level of memory cells is degraded by repeating Write and Erase operation of '0' data in each block. For detailed reliability data, please refer to the reliability note for each product.

Although random bit errors may occur during use, it does not necessarily mean that a block is bad. Generally, a block should be marked as bad when a program status failure or erase status failure is detected.

The reliability of NAND Flash memory cells during the actual usage on system level depends on the usage and environmental conditions. TOSHIBA MEMORY adopts the checker pattern data, 0x55 & 0xAA for alternative Write/Erase cycles, for the reliability test.

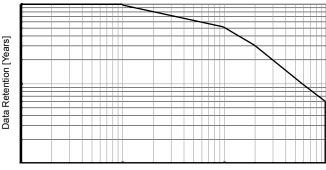
Write/Erase Endurance

Write/Erase endurance failures may occur in a cell, page, or block, and are detected by doing a Status Read after either an Auto Program or Auto Block Erase operation. The cumulative bad block count will increase along with the number of Write/Erase cycles.

Data Retention

The data in NAND Flash memory may change after a certain amount of storage time. This is due to charge loss or charge gain. After block erasure and reprogramming, the block may become usable again. Data Retention time is generally influenced by the number of Write/Erase cycles and temperature.

Here is the combined characteristics image of Write/Erase Endurance and Data Retention.



Write/Erase Endurance [Cycles]

Read Disturb

A Read operation may disturb the data in NAND Flash memory. The data may change due to charge gain. Usually, bit errors occur on other pages in the block, not the page being read. After a large number of read cycles (between block erases), a tiny charge may build up and can cause a cell to be soft programmed to another state. After block erasure and reprogramming, the block may become usable again. Read Disturb capability is generally influenced by the number of Write/Erase cycles.



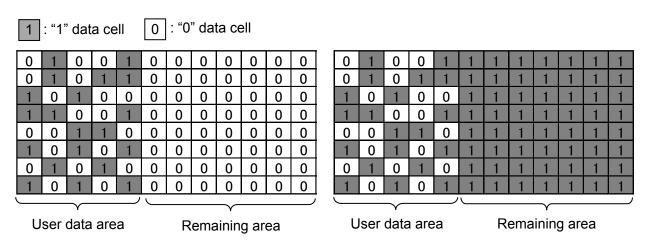
(17) NAND Management

NAND Management such as Bad Block Management, ECC treatment and Wear Leveling, but not limited to these treatments, should be recognized and incorporated in the system design.

ECC treatment for read data is mandatory against random bit errors, and host should monitor ECC status to take appropriate measures such as rewrite in consideration of Wear Leveling before uncorrectable Error occurs. To realize robust system design, generally it is necessary to prevent the concentration of Write/Erase cycles at the specific blocks by adopting Wear Leveling which manages to distribute Write/Erase cycles evenly among NAND Flash memory. And also it is necessary to avoid dummy '0' data write, e.g. '0' data padding, which accelerate block endurance degradation.

Continuous Write and Erase cycling with high percentage of '0' bits in data pattern can lead to faster block endurance degradation.

Example: NAND cell array with '0' data padding



(a) Accelerate block endurance degradation by fixed dummy "0" data write

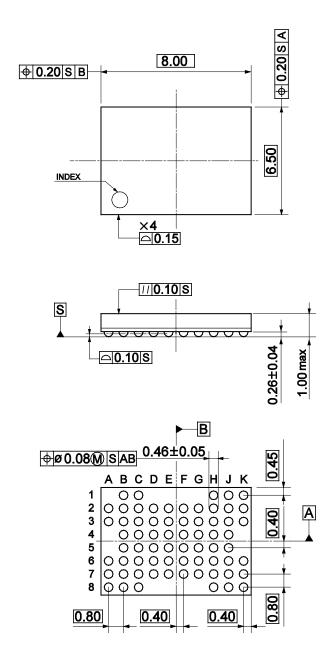
(b) "1" data for Remaining area (Recommended)



Package Dimensions

P-VFBGA67-0608-0.80-001

Unit: mm



Weight: 0.095 g (typ.)



Revision History

Date	Rev.	Description
2013-03-15	0.10	Preliminary version
2013-07-05	1.00	Deleted TENTATIVE notation. Clarification for the Package Weight.
2018-06-01	1.10	Corrected typo, and described some notes.
		Attached Reliability Guidance and NAND Management.
		Changed "RESTRICTIONS ON PRODUCT USE".



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