

Introduction

The PIC18F04/05/14/15Q40 devices you have received conform functionally to the current device data sheet (DS40002236E), except for the anomalies described in this document.

The silicon issues discussed in the following pages are for silicon revisions with the Device and Revision IDs listed in the table below.

The errata described in this document will be addressed in future revisions of the PIC18F04/05/14/15Q40 silicon.

Note: This document summarizes all silicon errata issues from all revisions of silicon, previous as well as current.

Table 1. Silicon Device Identification

Part Number	Device ID	Revision ID		
		D1	D3	E0
PIC18F04Q40	0x7640	0xA0C1	0xA0C3	0xA0D0
PIC18F05Q40	0x7600	0xA0C1	0xA0C3	0xA0D0
PIC18F14Q40	0x7620	0xA0C1	0xA0C3	0xA0D0
PIC18F15Q40	0x75E0	0xA0C1	0xA0C3	0xA0D0

 **Important:** Refer to the **Device/Revision ID** section in the current “**PIC18FXXQ40 Family Programming Specification**” (DS40002185) for more detailed information on Device Identification and Revision IDs for your specific device.

Table 2. Silicon Issue Summary

Module	Feature	Item No.	Issue Summary	Affected Revisions		
				D1	D3	E0
Analog-to-Digital Converter with Computation	ADCC	1.1.1	Double Sample Conversions	X	X	
Electrical Specifications	ADC Offset Error	1.2.1	ADC Offset Error specification lowered in ECH, ECM and ECL modes	X		
I ² C	I ² C	1.3.1	I ² C Start and/or Stop flags may be set When I ² C is enabled	X		
		1.3.2	MDR bit is not cleared after Bus Timeout	X	X	X
		1.3.3	Bus Timeout not detected properly when External Host Clock stretches	X	X	X
		1.3.4	Clock Stretch Disable not working properly	X	X	X
		1.3.5	Bus Timeout causes false Start/ Stop	X	X	X
Universal Asynchronous Receiver Transmitter	UART	1.4.1	UART TXDE signal may go low before the STOP bit has been entirely transmitted	X	X	X
		1.4.2	Asynchronous 9-bit UART Address mode address mismatch	X	X	
Signal Measurement Timer	SMT	1.5.1	Reset Bit	X	X	
PIC18 CPU	FSR Shadow Registers	1.6.1	FSR Shadow Registers are not writable	X	X	
ICSP™	Low-Voltage Programming (LVP)	1.7.1	Low Voltage Programming is not possible when VDD is below BORV while BOR is enabled	X	X	X
Instruction Set	PUSHL Instruction	1.8.1	The PUSHL instruction incorrectly executes	X	X	X

Note: Only those issues indicated in the last column apply to the current silicon revision.

1. Silicon Errata Issues

NOTICE

This document summarizes all silicon errata issues from all revisions of silicon, previous and current. Only the issues indicated by the bold font in the following tables apply to the current silicon revision.

1.1 Module: Analog-to-Digital Converter with Computation (ADCC)

1.1.1 Double Sample Conversions

When enabling a Double Sample Conversion (DSEN = 1) with no precharge time (ADPRE = 0) and no Acquisition time (ADACQ = 0), the maximum number of cycles of acquisition time is inserted prior to the second conversion. The first conversion will be performed as expected with no precharge time and no Acquisition time. It is only between the first and second conversions where a maximum number of cycles of Acquisition time is performed unexpectedly.

Work around

Method 1:

Disable Double Sample Conversion (DSEN = 0) and perform two single conversions back to back.

Method 2:

If adding acquisition time is acceptable, then select no precharge time along with the desired Acquisition time.

Affected Silicon Revisions

D1	D3	E0
X	X	

1.2 Module: Electrical Specifications

1.2.1 ADC Offset Error Specification Lowered in ECH, ECM and ECL Modes

When operating the device using an external clock source as the system clock in ECH, ECM or ECL mode, the ADC Offset Error (AD04: E_{OFF}) is updated to 12 Least Significant bits.

Work around

To meet the specified ADC Offset Error limit of 6 Least Significant bits, do not operate the device using the system clock in ECH, ECM or ECL mode when using the ADC.

Affected Silicon Revisions

D1	D3	E0
X		

1.3 Module: Inter-Integrated Circuit (I²C)

1.3.1 The I²C Start and/or Stop Flags May Be Set When I²C Is Enabled

When I²C is enabled, erroneous Start and/or Stop conditions may be detected. This can generate erroneous I²C interrupts if enabled.

Work around

Use the following procedure to correctly detect the Start and Stop conditions:

1. Disable the Start and Stop conditions interrupt functions.
2. Enable the I²C module.
3. Wait 250 ns + six instruction cycles (F_{Osc}/4).
4. Clear the Start and Stop conditions interrupt flags.
5. Enable the Start and Stop conditions interrupt functions if used.

```

I2CxPIEbits.SCIE = 0;          // Disable Start condition interrupt
I2CxPIEbits.PCIE = 0;          // Disable Stop condition interrupt
I2CxCON0bits.EN = 1;          // Enable I2C
Delay();                      // Wait for 250 ns + 6 instruction cycles (FOSC/4)
I2CxPIRbits.SCIF = 0;          // Clear the Start condition interrupt flags
I2CxPIRbits.PCIF = 0;          // Clear the Stop condition interrupt flags
I2CxPIEbits.SCIE = 1;          // Enable Start condition interrupt if used
I2CxPIEbits.PCIE = 1;          // Enable Stop condition interrupt if used

```

Affected Silicon Revisions

D1	D3	E0
X		

1.3.2 MDR Bit Is Not Cleared after Bus Time-Out

In the Host mode of the I²C module, when a bus time-out occurs during clock stretching and TOREC = 1, the MDR bit will not be cleared and a Stop will not be transmitted on the bus.

Work around

Force a Stop on the bus by setting the P bit upon bus time-out in Host mode. Forcing a Stop on the bus clears the MDR bit.

Affected Silicon Revisions

D1	D3	E0
X	X	X

1.3.3 Bus Time-Out Not Detected Properly When External Host Clock Stretches

When the module is operating in Client mode and an external Host device is clock stretching after the 8th SCL clock and a bus time-out occurs, the bus time-out is not detected properly. When the external Host times out before the Client and releases SCL to generate a Stop condition, the module continues to stretch SDA as if to generate an ACK and hangs the bus, and a Stop is never seen on the bus.

Work around

Reset the module by toggling the EN bit.

Affected Silicon Revisions

D1	D3	E0
X	X	X

1.3.4 Clock Stretch Disable Not Working Properly

When the CSD bit is set between a Start condition and the 8th falling SCL edge, the I²C module enters a state where the module clock stretches indefinitely after the next Start until a bus time-out occurs.

Work around

Force a reset of the module by toggling the EN bit.

Affected Silicon Revisions

D1	D3	E0
X	X	X

1.3.5 Bus Time-Out Causes False Start/Stop

When the module is operating in Client mode and an external Host device is clock stretching, and a bus time-out occurs in the Client, the Client releases SDA and goes into the idle state. After the external Host generates a Stop condition on the bus by releasing SCL, the module can erroneously drive a low pulse on the SDA line, which acts as a false Start and Stop on the bus.

Work around

None.

Affected Silicon Revisions

D1	D3	E0
X	X	X

1.4 Module: Universal Asynchronous Receiver Transmitter (UART)

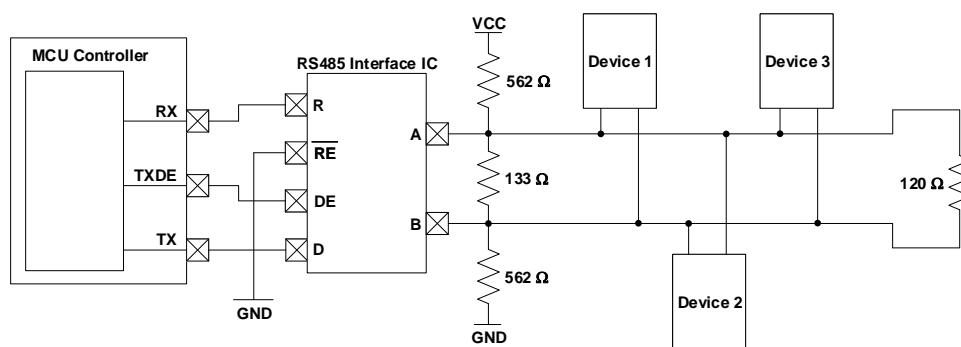
1.4.1 UART TXDE Signal May Go Low Before the STOP Bit Has Been Entirely Transmitted

The UART Transmit Drive Enable (TXDE) signal could potentially transition into a low state before the UART STOP bit has been entirely transmitted due to the effects of parasitic capacitance on the TX line. In some applications, this could result in communication being prematurely terminated due to the TXDE signal going low before the STOP bit has had enough time to settle.

Work around

To ensure that the STOP bit settles into its final logic state before the TXDE signal transitions low, a biasing circuit can be implemented. A biasing circuit allows the TX line to either be driven high or low, rather than being left in a floating tri-state mode where prolonged rise or fall times could lead to communication being disrupted. This bias circuit should only be implemented on one end of the serial bus, and a termination resistor should be used on the other end. The figure below shows an example of a bias circuit that can be used to achieve this.

Please note that the resistor values used in this circuit are recommendations and that the actual resistor values required may vary based on the application.



Affected Silicon Revisions

D1	D3	E0
X	X	X

1.4.2 Asynchronous 9-bit UART Address Mode Address Mismatch

In Asynchronous 9-bit UART Address mode, there is the possibility that a false address mismatch may occur even when the address of both devices match, or that a false address match may occur when there is an address mismatch between the devices.

Work around

None. Do not use the UART modules in Asynchronous 9-bit Address Mode.

Affected Silicon Revisions

D1	D3	E0
X	X	

1.5 Module: Signal Measurement Timer (SMT)

1.5.1 Reset Bit

If the SMT clock prescaler is set to any value other than '00', setting the RST bit will cause the module to stop working. The RST bit will remain at the value '1', the counter will not increment, and no interrupts will be generated. The problem is cleared by turning the module off and on or by performing a device reset.

Work around

Method 1:

Do not set the RST bit; manual reset is usually not required for typical operation because the measurement logic will reset the counter automatically.

Method 2:

Write zero to the counter manually. Either disable the module or the clock before using this method.

Method 3:

Use 1:1 prescaler (PS = 00).

Method 4:

Use the CLKREF subsystem to provide a prescaled clock and set PS = 00.

Affected Silicon Revisions

D1	D3	E0
X	X	

1.6 Module: PIC18 Core

1.6.1 FSR Shadow Registers Are Not Writable

Writing to the FSR Shadow Registers does not result in accurate values being stored in the registers. Consequently, reading the FSR Shadow Registers after they have been written will return inaccurate data.

Work around

Writes to the FSR shadow registers can be performed safely using the following steps:

1. Save regular FSR2 value into RAM.
2. Write the regular FSR2 with the targeted value minus the computed offset (IR[6:0] + 1, see below).
3. Write the shadow FSRxL (data doesn't matter); this will clock the shadow FSR with the FSR computed offset value.

4. Decrement FSR2 value by 1 since FSRxH increments the address by 1 (IR[6:0]).
5. Write FSRxH.
6. Restore the regular FSR2 from the stored RAM value.

The FSR shadow should have the value desired and the regular FSR should have the original value.

Affected Silicon Revisions

D1	D3	E0
X	X	

1.7 Module: Low-Voltage In-Circuit Serial Programming™ (LVP)

1.7.1 Low-Voltage Programming Not Possible

Low-Voltage Programming is not possible when V_{DD} is below the selected BORV voltage level while BOR is enabled.

Work around

Method 1:

Disable BOR to use Low-Voltage Programming.

Method 2:

Raise V_{DD} above the selected BORV level while using Low-Voltage Programming.

Affected Silicon Revisions

D1	D3	E0
X	X	X

1.8 Module: Instruction Set

1.8.1 The `PUSHL` Instruction Incorrectly Executes

The `PUSHL` instruction of the PIC18 Extended Instruction Set incorrectly executes when FSR2 is loaded with certain values.

Work around

Do not use `PUSHL` when FSR2 is loaded with any of the following values:

- 0xDB
- 0xDC
- 0xDE
- 0xE3
- 0xE4
- 0xE6
- 0xEB
- 0xEC
- 0xEE

Affected Silicon Revisions

D1	D3	E0
X	X	X

2. Data Sheet Clarifications

The following typographic corrections and clarifications are to be noted for the latest version of the device data sheet (DS40002236E):

Note:

Corrections are shown in **bold**. Where possible, the original bold text formatting has been removed for clarity.

2.1 None

There are no known data sheet clarifications as of this publication date.

3. Appendix A: Revision History

Doc. Rev.	Date	Comments
F	03/2025	Added silicon errata issue 1.8.1; updated DS revision letter.
E	06/2023	Added silicon revision E0. Added silicon errata 1.3.2, 1.3.3, 1.3.4 and 1.7.1.
D	05/2022	Added silicon revision D3.
C	04/2022	Updated the flash memory cell endurance specification data sheet clarification. Added silicon errata 1.6.1
B	02/2022	Added silicon errata 1.1.1, 1.4.1 and 1.5.1.
A	01/2021	Initial document release.

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