

FDC1004 4-Channel Capacitance-to-Digital Converter for Capacitive Sensing Solutions

1 Features

- Input Range: ± 15 pF
- Measurement Resolution: 0.5 fF
- Maximum Offset Capacitance: 100 pF
- Programmable Output Rates: 100/200/400 S/s
- Maximum Shield Load: 400 pF
- Supply Voltage: 3.3 V
- Temp Range: -40 to 85°C
- Current Consumption:
 - Active: 750 μA
 - Standby: 29 μA
- Interface: I²C
- Number of Channels: 4

2 Applications

- Proximity Wake-up
- Gesture Sensing
- Automotive Door / Kick Sensors
- Automotive Rain Sensor
- Remote and Direct Liquid Level Sensing
- High-resolution Metal Profiling
- Rain / Fog / Ice / Snow Detection
- Material Size Detection
- Material Stack Height

3 Description

Capacitive sensing with grounded capacitor sensors is a very low-power, low-cost, high-resolution contactless sensing technique that can be applied to a variety of applications ranging from proximity detection and gesture sensing to material analysis and remote liquid level sensing. The sensor in a capacitive sensing system is any metal or conductor, allowing for low cost and highly flexible system design.

The FDC1004 is a high-resolution, 4-channel capacitance-to-digital converter for implementing capacitive sensing solutions. Each channel has a full scale range of ± 15 pF and can handle a sensor offset capacitance of up to 100 pF, which can be either programmed internally or can be an external capacitor for tracking environmental changes over time and temperature. The large offset capacitance capability allows for the use of remote sensors.

The FDC1004 also includes shield drivers for sensor shields, which can reduce EMI interference and help focus the sensing direction of a capacitive sensor. The small footprint of the FDC1004 allows for use in space-constrained applications. The FDC1004 is available in a 10-pin WSON package and features an I²C interface for interfacing to an MCU.

Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE (NOM)
FDC1004	WSON	3.0 mm x 3.0 mm

(1) For all available packages, see the orderable addendum at the end of the datasheet.

4 Typical Application

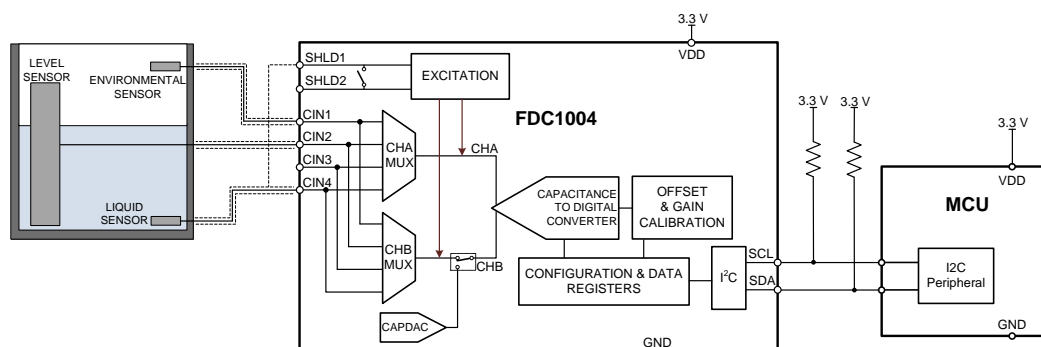


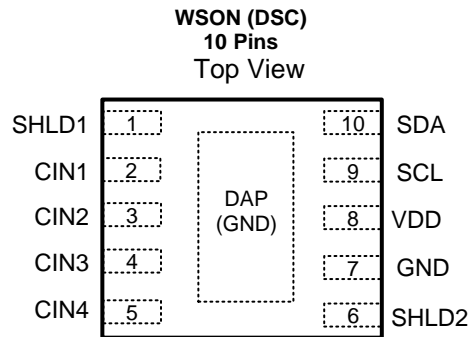
Table of Contents

1 Features	1	8.3 Feature Description	9
2 Applications	1	8.4 Device Functional Modes	10
3 Description	1	8.5 Programming	12
4 Typical Application	1	8.6 Register Maps	15
5 Revision History	2	9 Applications and Implementation	19
6 Pin Configuration and Functions	3	9.1 Application Information	19
7 Specifications	4	9.2 Typical Application	19
7.1 Absolute Maximum Ratings	4	9.3 Do's and Don'ts	21
7.2 Handling Ratings	4	9.4 Initialization Set Up	21
7.3 Recommended Operating Conditions	4	10 Power Supply Recommendations	21
7.4 Thermal Information	4	11 Layout	21
7.5 Electrical Characteristics	5	11.1 Layout Guidelines	21
7.6 I ² C Interface Voltage Level	5	11.2 Layout Example	21
7.7 I ² C Interface Timing	6	12 Device and Documentation Support	22
7.8 Typical Characteristics	7	12.1 Trademarks	22
8 Detailed Description	9	12.2 Electrostatic Discharge Caution	22
8.1 Overview	9	12.3 Glossary	22
8.2 Functional Block Diagram	9	13 Mechanical, Packaging, and Orderable Information	22

5 Revision History

Changes from Original (August 2014) to Revision A	Page
• Added Parameter not tested in production	5
• Changed CINx to CINn throughout	9
• Added note for Applications and Implementation section.	19

6 Pin Configuration and Functions



Pin Functions

PIN		TYPE ⁽¹⁾	DESCRIPTION
NAME	NO.		
SHLD1	1	A	Capacitive Input Active AC Shielding.
CIN1	2	A	Capacitive Input. The measured capacitance is connected between the CIN1 pin and GND. If not used, this pin should be left as an open circuit.
CIN2	3	A	Capacitive Input. The measured capacitance is connected between the CIN2 pin and GND. If not used, this pin should be left as an open circuit.
CIN3	4	A	Capacitive Input. The measured capacitance is connected between the CIN3 pin and GND. If not used, this pin should be left as an open circuit.
CIN4	5	A	Capacitive Input. The measured capacitance is connected between the CIN4 pin and GND. If not used, this pin should be left as an open circuit.
SHLD2	6	A	Capacitive Input Active AC Shielding.
GND	7	G	Ground
VDD	8	P	Power Supply Voltage. This pin should be decoupled to GND, using a low impedance capacitor, for example in combination with a 1-μF tantalum and a 0.1-μF multilayer ceramic.
SCL	9	I	Serial Interface Clock Input. Connects to the master clock line. Requires pull-up resistor if not already provided elsewhere in the system.
SDA	10	I/O	Serial Interface Bidirectional Data. Connects to the master data line. Requires a pull-up resistor if not provided elsewhere in the system.
DAP ⁽²⁾	-	N/A	Connect to GND

(1) P=Power, G=Ground, I=Input, O=Output, A=Analog

(2) There is an internal electrical connection between the exposed Die Attach Pad (DAP) and the GND pin of the device. Although the DAP can be left floating, for best performance the DAP should be connected to the same potential as the device's GND pin. Do not use the DAP as the primary ground for the device. The device GND pin must always be connected to ground.

7 Specifications

7.1 Absolute Maximum Ratings⁽¹⁾

		MIN	MAX	UNIT
Input voltage	VDD	–0.3	6	V
	SCL, SDA	–0.3	6	V
	at any other pin	–0.3	VDD+0.3	V
Input current	at any pin		3	mA
Junction temperature ⁽²⁾			150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) The maximum power dissipation is a function of $T_{J(MAX)}$, $R_{\theta JA}$, and the ambient temperature, T_A . The maximum allowable power dissipation at any ambient temperature is $P_{D(MAX)} = (T_{J(MAX)} - T_A) / R_{\theta JA}$. All numbers apply for packages soldered directly onto a PC board.

7.2 Handling Ratings

			MIN	MAX	UNIT
T_{STG}	Storage Temperature		–65	150	°C
$V_{(ESD)}$	Electrostatic discharge ⁽¹⁾	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins ⁽²⁾	–1000	1000	V
		Charged device model (CDM), per JEDEC specification -500 500 JESD22-C101, all pins ⁽³⁾	–250	250	V

- (1) Electrostatic discharge (ESD) to measure device sensitivity and immunity to damage caused by assembly line electrostatic discharges in to the device.
- (2) Level listed above is the passing level per ANSI, ESDA, and JEDEC JS-001. JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (3) Level listed above is the passing level per EIA-JEDEC JESD22-C101. JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

Over operating temperature range (unless otherwise noted)

	MIN	NOM	MAX	UNIT
Supply voltage (VDD-GND)	3	3.3	3.6	V
Temperature	–40		85	°C

7.4 Thermal Information

THERMAL METRIC ⁽¹⁾		FDC1004	UNIT
		WS0N	
		10 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	46.8	°C/W

- (1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, [SPRA953](#).

7.5 Electrical Characteristics

Over recommended operating temperature range, $V_{DD} = 3.3\text{ V}$, for $T_A = 25^\circ\text{C}$ (unless otherwise noted).

PARAMETER		TEST CONDITION	MIN	TYP	MAX	UNIT
POWER SUPPLY						
I _{DD}	Supply current	Conversion mode; Digital input to VDD or GND		750	950	μA
		Standby; Digital input to VDD or GND		29	70	μA
CAPACITIVE INPUT						
ICR	Input conversion range			±15		pF
C _{OMAX}	Max input offset capacitance	per channel, Series resistance at C _{IN} n n=1.4 = 0 Ω		100		pF
RES	Effective resolution ⁽¹⁾	Sample rate = 100S/s ⁽²⁾		16		bit
EON	Output noise	Sample rate = 100S/s ⁽²⁾		33.2		aF/√Hz
ERR	Absolute error	after offset calibration		±6		fF
Tc _{OFF}	Offset deviation over temperature	-40°C < T < 85°C		30		fF
G _{ERR}	Gain rror			0.07		% of FS
tcG	Gain drift vs. temperature	-40°C < T < 85°C		2.1		ppm of FSR/°C
PSRR	DC power supply rejection	3 V < V _{DD} < 3.6 V		11		fF/V
CAPDAC						
FR _{CAPDAC}	Full-scale range			96.875		pF
RES _{CAPDAC}	Resolution			5		bit
TcCOFF _{CAP DAC}	Offset drift vs. temperature	-40°C < T < 85°C		1		ppm of FS/°C
EXCITATION						
f	Frequency			25		kHz
V _{AC}	AC voltage across capacitance			2.4		V _{pp}
V _{DC}	Average DC voltage across capacitance			1.2		V
SHIELD						
DRV	Driver capability	f = 25 kHz, SHLDn to GND, n = 1,2		400		pF

(1) Effective resolution is the ratio of converter full scale range to RMS measurement noise.

(2) No external capacitance connected.

7.6 I²C Interface Voltage Level

Over recommended operating free-air temperature range, $V_{DD} = 3.3\text{ V}$, for $T_A = T_J = 25^\circ\text{C}$ (unless otherwise noted).

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V_{IH}	Input high voltage		$0.7 \cdot V_{DD}$			V
V_{IL}	Input low voltage				$0.3 \cdot V_{DD}$	V
V_{OL}	Output low voltage	Sink current 3 mA			0.4	V
HYS	Hysteresis ⁽¹⁾		$0.1 \cdot V_{DD}$			V

(1) This parameter is specified by design and/or characterization and is not tested in production.

7.7 I²C Interface Timing

Over recommended operating free-air temperature range, $V_{DD} = 3.3\text{ V}$, for $T_A = T_J = 25^\circ\text{C}$ (unless otherwise noted).

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
f_{SCL}	Clock frequency ⁽¹⁾	10		400	kHz
t_{LOW}	Clock low time ⁽¹⁾	1.3			μs
t_{HIGH}	Clock high time ⁽¹⁾	0.6			μs
$t_{HD;STA}$	Hold time (repeated) START condition ⁽¹⁾	0.6			μs
$t_{SU;STA}$	Set-up time for a repeated START condition ⁽¹⁾	0.6			μs
$t_{HD;DAT}$	Data hold time ⁽¹⁾⁽²⁾	0			ns
$t_{SU;DAT}$	Data setup time ⁽¹⁾	100			ns
t_f	SDA fall time ⁽¹⁾	$IL \leq 3\text{mA}; CL \leq 400\text{pF}$		300	ns
$t_{SU;STO}$	Set-up time for STOP condition ⁽¹⁾	0.6			μs
t_{BUF}	Bus free time between a STOP and START condition ⁽¹⁾	1.3			μs
$t_{VD;DAT}$	Data valid time ⁽¹⁾			0.9	ns
$t_{VD;ACK}$	Data valid acknowledge time ⁽¹⁾			0.9	ns
t_{SP}	Pulse width of spikes that must be suppressed by the input filter ⁽¹⁾			50	ns

(1) This parameter is specified by design and/or characterization and is not tested in production.

(2) The FDC1004 provides an internal 300 ns minimum hold time to bridge the undefined region of the falling edge of SCL.

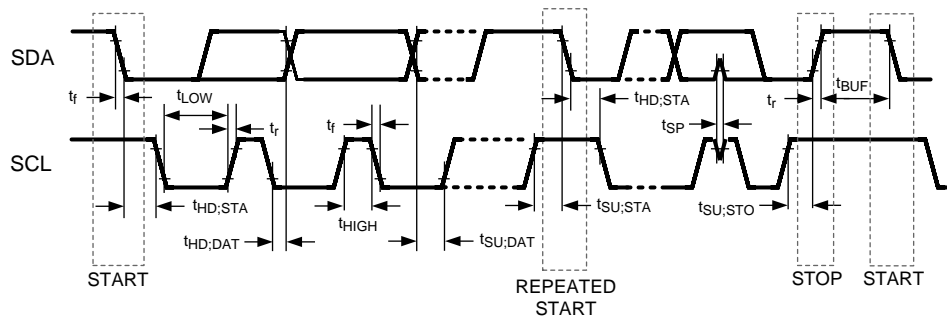


Figure 1. I²C Timing

7.8 Typical Characteristics

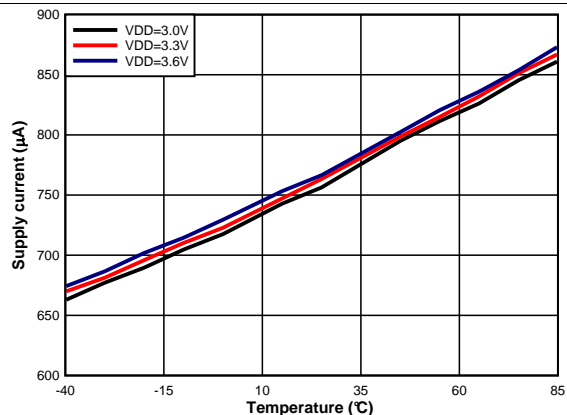


Figure 2. Active Conversion Mode Supply Current vs. Temperature

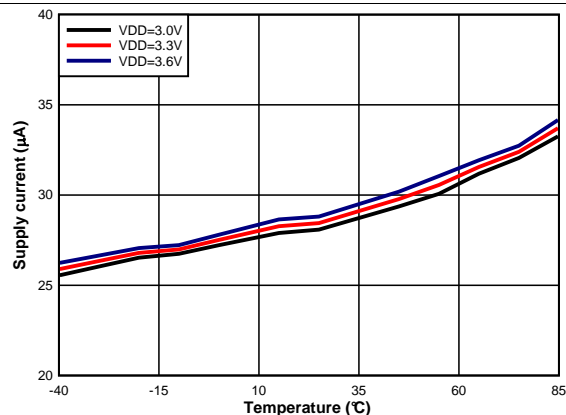


Figure 3. Stand-by Mode Supply Current vs. Temperature

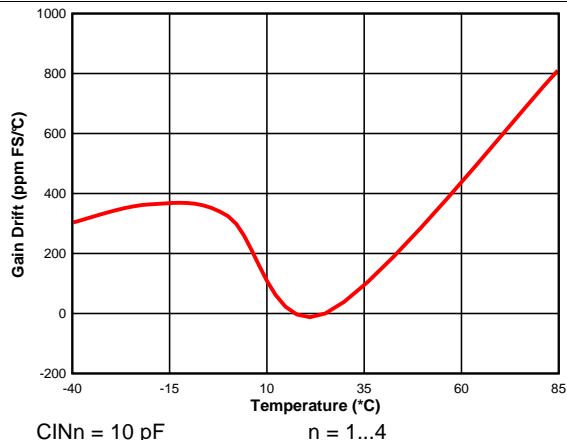


Figure 4. Gain Drift vs. Temperature

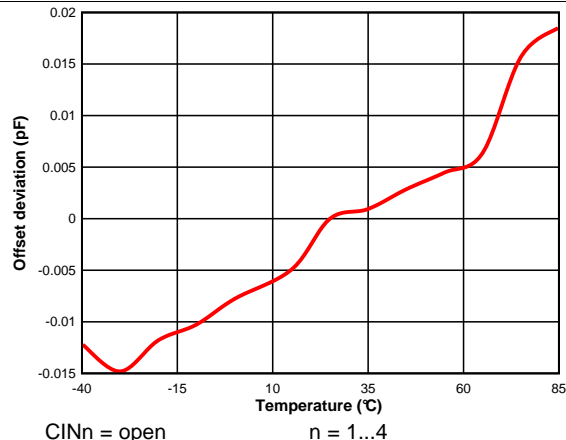


Figure 5. Offset Drift vs. Temperature

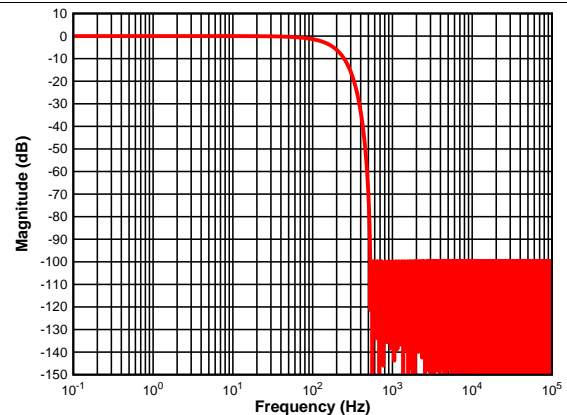


Figure 6. Frequency Response 100S/s

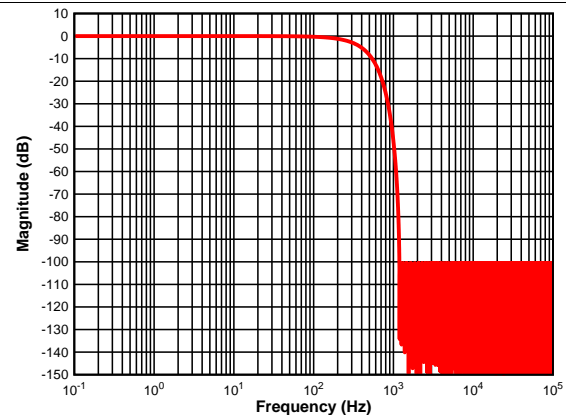


Figure 7. Frequency Response 200S/s

Typical Characteristics (continued)

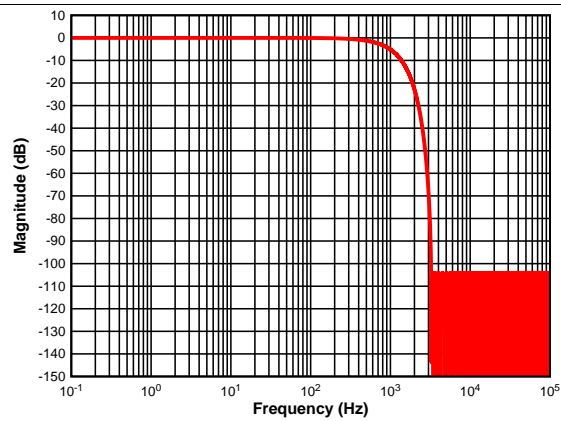


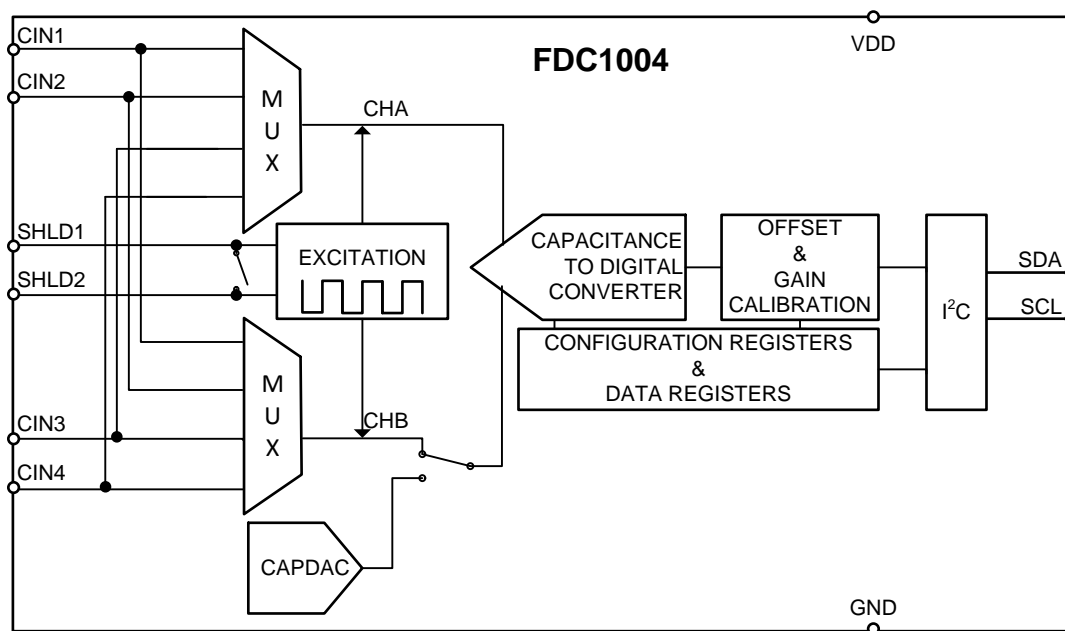
Figure 8. Frequency Response 400S/s

8 Detailed Description

8.1 Overview

The FDC1004 is a high-resolution, 4-channel capacitance-to-digital converter for implementing capacitive sensing solutions. Each channel has a full scale range of ± 15 pF and can handle a sensor offset capacitance of up to 100 pF, which can be either programmed internally or can be an external capacitor for tracking environmental changes over time and temperature. The large offset capacitance capability allows for the use of remote sensors. The FDC1004 also includes shield drivers for sensor shields, which can reduce EMI interference and help focus the sensing direction of a capacitive sensor. The small footprint of the FDC1004 allows for use in space-constrained applications.

8.2 Functional Block Diagram



8.3 Feature Description

8.3.1 The Shield

The FDC1004 measures capacitance between CINn and ground. That means any capacitance to ground on signal path between the FDC1004 CINn pins and sensor is included in the FDC1004 conversion result.

In some applications, the parasitic capacitance of the sensor connections can be larger than the capacitance of the sensor. If that parasitic capacitance is stable, it can be treated as a constant capacitive offset. However, the parasitic capacitance of the sensor connections can have significant variation due to environmental changes (such as mechanical movement, temperature shifts, humidity changes). These changes are seen as drift in the conversion result and may significantly compromise the system accuracy.

To eliminate the CINn parasitic capacitance to ground, the FDC1004 SHLDx signals can be used for shielding the connection between the sensor and CINn. The SHLDx output is the same signal waveform as the excitation of the CINn pin; the SHLDx is driven to the same voltage potential as the CINn pin. Therefore, there is no current between CINn and SHLDx pins, and any capacitance between these pins does not affect the CINn charge transfer. Ideally, the CINn to SHLD capacitance does not have any contribution to the FDC1004 result.

In differential measurements, SHLD1 is assigned to CHn and SHLD2 is assigned to CHm, where $n < m$. For instance in the measurement CIN2 – CIN1, where CHA = CIN2 and CHB = CIN1 (see [Table 4](#)), SHLD1 is assigned to CIN1 and SHLD2 is assigned to CIN2.

Feature Description (continued)

In a single ended configuration, such as CINn vs. GND, SHLD1 is internally shorted to SHLD2. In a single ended configuration, such as CINn vs. GND with CAPDAC enabled, SHLD1 is assigned to the selected channel, SHLD2 is floating.

For best results, locate the FDC1004 as close as possible to the capacitive sensor. Minimize the connection length between the sensor and FDC1004 CINn pins and between the sensor ground and the FDC1004 GND pin. Shield the PCB traces to the CINn pins and connect the shielding to the FDC1004 SHLDx pins. In addition, if a shielded cable is used to connect the FDC1004 to the sensor, the shield should be connected to the appropriate SHLDx pin.

In applications where only one SHLDx pin is used, the unused SHLDx pin can be left unconnected.

8.3.2 The CAPDAC

The FDC1004 full-scale input range is ± 15 pF. The part can accept a higher capacitance on the input and the common-mode or offset (constant component) capacitance can be balanced by the programmable on-chip CAPDACs. The CAPDAC can be viewed as a negative capacitance connected internally to the CINn pin. The relation between the input capacitance and output data can be expressed as $DATA = (CINn - CAPDAC)$, $n = 1...4$. The CAPDACs have a 5-bit resolution, monotonic transfer function, are well matched to each other, and have a defined temperature coefficient.

8.3.3 Capacitive System Offset Calibration

The capacitive offset can be due to many factors including the initial capacitance of the sensor, parasitic capacitances of board traces, and the capacitance of any other connections between the sensor and the FDC.

The parasitic capacitances of the FDC1004 are calibrated out at production. If there are other sources of offset in the system, it may be necessary to calibrate the system capacitance offset in the application. Any offset in the capacitance input larger than $\frac{1}{2}$ LSB of the CAPDAC should first be removed using the on-chip CAPDACs. Any residual offset of approximately 1 pF can then be removed by using the capacitance offset calibration register. The offset calibration register is reloaded by the default value at power-on or after reset. Therefore, if the offset calibration is not repeated after each system power-up, the calibration coefficient value should be stored by the host controller and reloaded as part of the FDC1004 setup.

8.3.4 Capacitive Gain Calibration

The gain is factory calibrated up to ± 15 pF in the production for each part individually. The factory gain coefficient is stored in a one-time programmable (OTP) memory.

The gain can be temporarily changed by setting the Gain Calibration Register (registers 0x11 to 0x14) for the appropriate CINn pin, although the factory gain coefficient will be restored after power-up or reset.

The part is tested and specified for use only with the default factory calibration coefficient. Adjusting the Gain calibration can be used to normalize the capacitance measurement of the CINn input channels.

8.4 Device Functional Modes

8.4.1 Single Ended Measurement

The FDC1004 can be used for interfacing to a single-ended capacitive sensor. In this configuration the sensor should be connected to the input CINn ($n = 1..4$) pins of the FDC1004 and GND. The capacitance-to-digital convertor (without using the CAPDAC, CAPDAC = 0pF) measures the positive (or the negative) input capacitance in the range of 0 pF to 15 pF. The CAPDAC can be used for programmable shifting of the input range. In this case it is possible to measure input capacitance in the range of 0 pF to ± 15 pF which are on top of an offset capacitance up to 100 pF. In single ended measurements with CAPDAC disabled SHLD1 is internally shorted to SHLD2 (see [Figure 9](#)); if CAPDAC is enabled SHLD2 is floating (see [Figure 10](#)). The single ended mode is enabled when the CHB register of the Measurements configuration registers (see [Table 4](#)) are set to b100 or b111.

Device Functional Modes (continued)

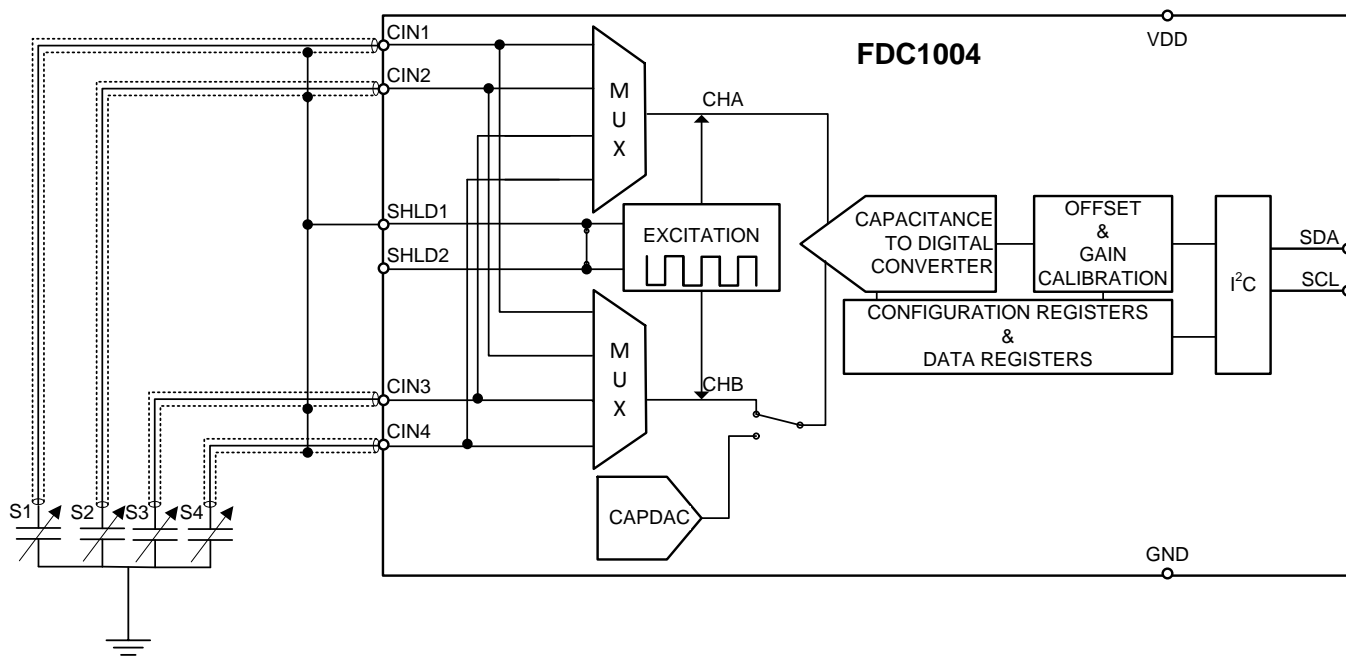


Figure 9. Single-Ended Configuration with CAPDAC Disabled

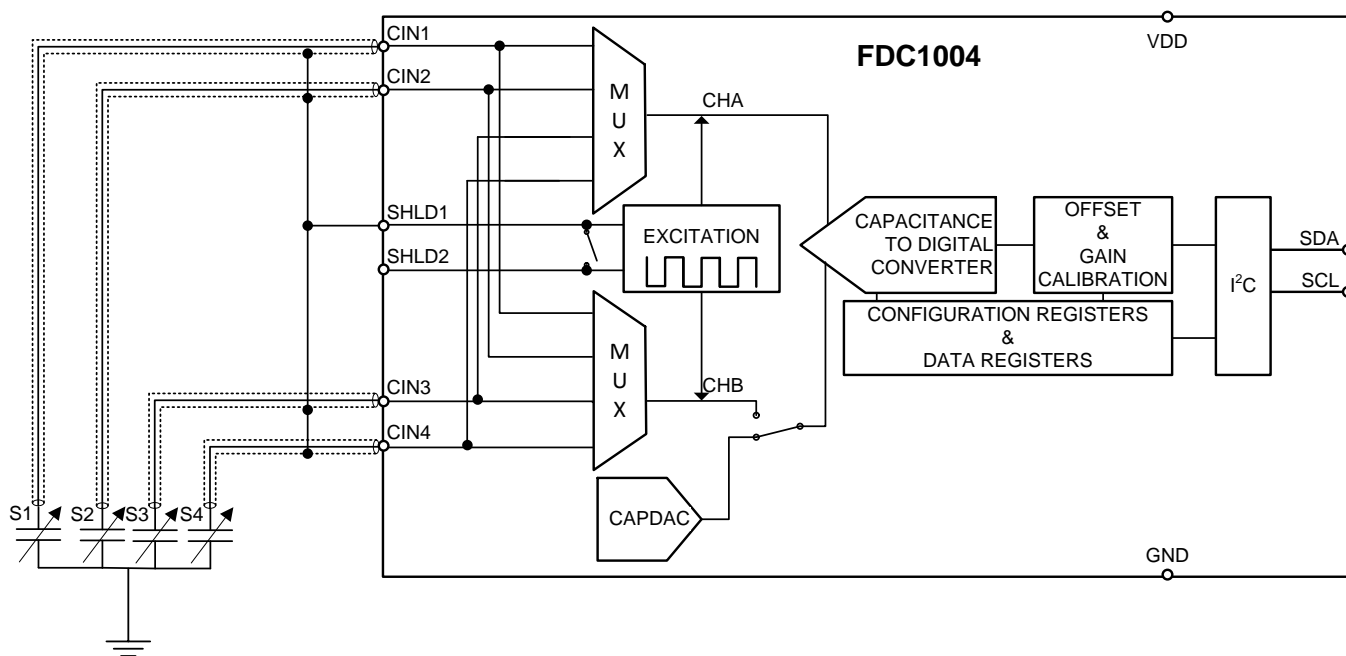


Figure 10. Single-Ended Configuration with CAPDAC Enabled

8.4.2 Differential Measurement

When the FDC1004 is used for interfacing to a differential capacitive sensor, each of the two input capacitances must be less than 115 pF. In this configuration the CAPDAC is disabled. The absolute value of the difference between the two input capacitances should be kept below 15 pF to avoid introducing errors in the measurement. In differential measurements, SHLD1 is assigned to CH_n and SHLD2 is assigned to CH_m, where $n < m$. For instance in the measurement $CIN2 - CIN1$, where $CHA = CIN2$ and $CHB = CIN1$ (see Table 4), SHLD1 is

Device Functional Modes (continued)

assigned to CIN1 and SHDL2 is to CIN2. In the picture below a couple of differential sensors made with S1 versus S3 and S2 versus S4 is shown. S1 and S2 are alternatively connected to CHA and the S3 and S4 are alternatively connected to CHB, the shield signals are connected as explained in previous paragraph. The FDC1004 will perform a differential measurement when CHB field of the Measurements Configuration Registers (refer to [Table 4](#)) is less than to b100.

This configuration is very useful in applications where environment conditions need to be tracked. The differential measurement between the main electrode and the environment electrode makes the measurement independent of the environment conditions.

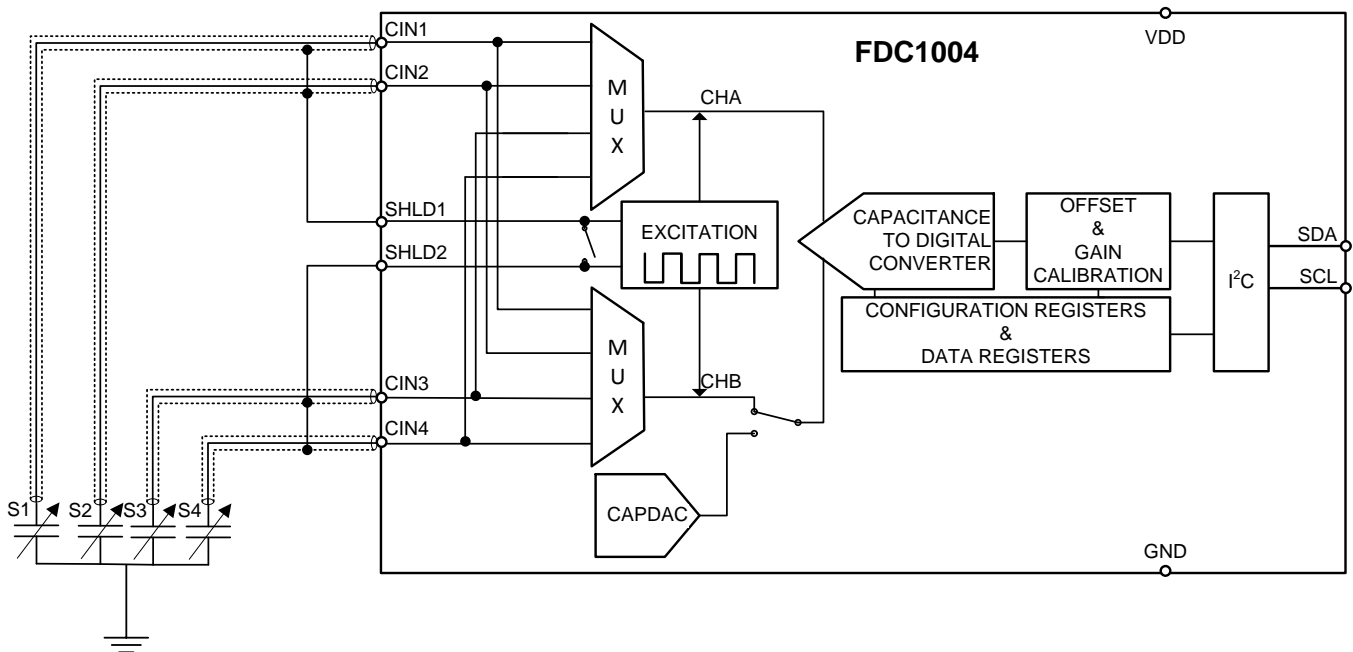


Figure 11. Differential Configuration

8.5 Programming

The FDC1004 operates only as a slave device on the two-wire bus interface. Every device on the bus must have a unique address. Connection to the bus is made via the open-drain I/O lines, SDA, and SCL. The SDA and SCL pins feature integrated spike-suppression filters and Schmitt triggers to minimize the effects of input spikes and bus noise. The FDC1004 supports fast mode frequencies 10 kHz to 400 kHz. All data bytes are transmitted MSB first.

8.5.1 Serial Bus Address

To communicate with the FDC1004, the master must first address slave devices via a slave address byte. The slave address byte consists of seven address bits and a direction bit that indicates the intent to execute a read or write operation. The seven bit address for the FDC1004 is (MSB first): b101 0000.

8.5.2 Read/Write Operations

Access a particular register on the FDC1004 by writing the appropriate value to the Pointer Register. The pointer value is the first byte transferred after the slave address byte with the R/W bit low. Every write operation to the FDC1004 requires a value for the pointer register. When reading from the FDC1004, the last value stored in the pointer by a write operation is used to determine which register is read by a read operation. To change the pointer register for a read operation, a new value must be written to the pointer. This transaction is accomplished by issuing the slave address byte with the R/W bit low, followed by the pointer byte. No additional data is

Programming (continued)

required. The master can then generate a START condition and send the slave address byte with the R/W bit high to initiate the read command. Note that register bytes are sent MSB first, followed by the LSB. A write operation in a read only registers such as MANUFACTURER ID or SERIAL ID returns a NACK after each data byte; read/write operation to unused address returns a NACK after the pointer; a read/write operation with incorrect I²C address returns a NACK after the I²C address.

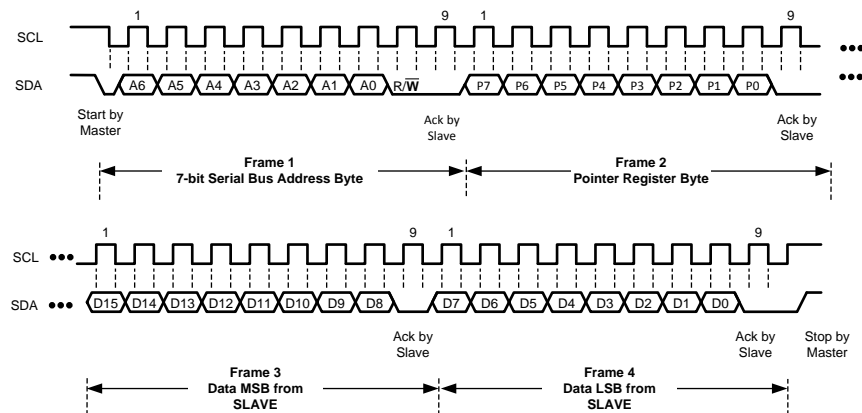


Figure 12. Write Frame

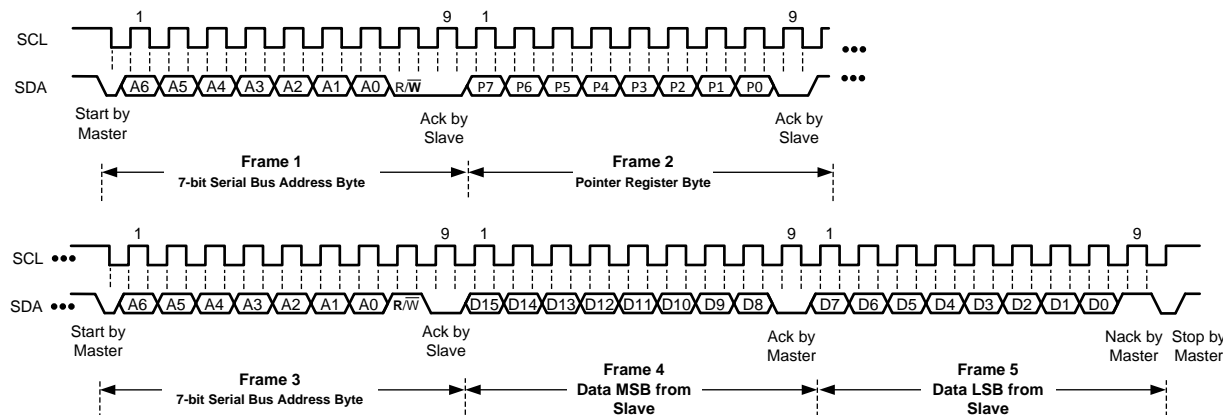


Figure 13. Read Frame

8.5.3 Device Usage

The basic usage model of the FDC1004 is to simply follow these steps:

1. Configure measurements (for details, refer to [Measurement Configuration](#)).
2. Trigger a measurement set (for details, refer to [Triggering Measurements](#)).
3. Wait for measurement completion (for details, refer to [Wait for Measurement Completion](#)).
4. Read measurement data (for details, refer to [Read of Measurement Result](#)).

8.5.3.1 Measurement Configuration

Configuring a measurement involves setting the input channels and the type of measurement (single-ended or differential).

The FDC1004 can be configured with up to 4 separate measurements, where each measurement can be any valid configuration (that is, a specific channel can be used in multiple measurements). There is a dedicated configuration register for each of the 4 possible measurements (e.g MEAS_CONF1 in register 0x08 configures measurement 1, MEAS_CONF2 in register 0x09 configures measurement 2, ...). Configuring only one measurement is fine, and it can be any one of the 4 possible measurement configuration.

Programming (continued)

1. Setup the input channels for each measurement. Determine which of the 4 measurement configuration registers to use (registers 0x08 to 0x0A) and set the following:
 - (a) For single-ended measurement:
 - (a) Select the positive input pin for the measurement by setting the CHA field (bits[15:13]).
 - (b) Set CAPDAC (bits[9:5]) if the channel offset capacitance is more than 15pF.
 - (b) For a differential measurement:
 - (a) Select the positive input pin for the measurement by setting the CHA field (bits[15:13]).
 - (b) Select the negative input pin for the measurement by setting the CHB field (bits[12:10]). Note that the CAPDAC setting has no effect for a differential measurement.
2. Determine the appropriate sample rate. The sample rate sets the resolution of the measurement. Lower the sample rate higher is the resolution of the measurement.

8.5.3.2 Triggering Measurements

For a single measurement, trigger the desired measurement (i.e. which one of the configured measurements) when needed by:

1. Setting REPEAT (Register 0x0C:bit[8]) to 0.
2. Setting the corresponding MEAS_x field (Register 0x0C:bit[7:4]) to 1.
 - For example, to trigger a single measurement of Measurement 2 at a rate of 100S/s, set Address 0x0C to 0x0540.

Note that, at a given time, only one measurement of the configured measurements can be triggered in this manner (i.e. MEAS_1 and MEAS_2 cannot both be triggered in a single operation).

The FDC1004 can also trigger a new measurement on the completion of the previous measurement (repeated measurements). This is setup by:

1. Setting REPEAT (Register 0x0C:bit[8]) to 1.
2. Setting the corresponding MEAS_x field (Register 0x0C:bit[7:4]) to 1.

When the FDC1004 is setup for repeated measurements, multiple configured measurements (up to a maximum of 4) can be performed in this manner, but Register 0x0C must be written in a single transaction.

8.5.3.3 Wait for Measurement Completion

Wait for the triggered measurements to complete. When the measurements are complete, the corresponding DONE_x field (Register 0x0C:bits[3:0]) will be set to 1.

8.5.3.4 Read of Measurement Result

Read the result of the measurement from the corresponding registers:

- 0x00/0x01 for Measurement 1
- 0x02/0x03 for Measurement 2
- 0x04/0x05 for Measurement 3
- 0x06/0x07 for Measurement 4

The measurement results span 2 register addresses; both registers must be read to have a complete conversion result. The lower address (e.g. 0x00 for Measurement 1) must be read first, then the upper address read afterwards (for example, 0x01 for Measurement 1).

Once the measurement read is complete, the corresponding DONE_x field (Register 0x0C:bits[3:0]) will return to 0.

If an additional single triggered measurement is desired, simply perform the Trigger, Wait, Read steps again.

If the FDC1004 is setup for repeated measurements (Register 0x0C:bit[8]) = 1, the FDC1004 will continuously measure until the REPEAT field (Register 0x0C:bit[8]) is set to 0, even if the results are not read back.

8.6 Register Maps

Table 1. Register Map

Pointer	Register Name	Reset Value	Description
0x00	MEAS1_MSB	0x0000	MSB portion of Measurement 1
0x01	MEAS1_LSB	0x0000	LSB portion of Measurement 1
0x02	MEAS2_MSB	0x0000	MSB portion of Measurement 2
0x03	MEAS2_LSB	0x0000	LSB portion of Measurement 2
0x04	MEAS3_MSB	0x0000	MSB portion of Measurement 3
0x05	MEAS3_LSB	0x0000	LSB portion of Measurement 3
0x06	MEAS4_MSB	0x0000	MSB portion of Measurement 4
0x07	MEAS4_LSB	0x0000	LSB portion of Measurement 4
0x08	CONF_MEAS1	0x1C00	Measurement 1 Configuration
0x09	CONF_MEAS2	0x1C00	Measurement 2 Configuration
0x0A	CONF_MEAS3	0x1C00	Measurement 3 Configuration
0x0B	CONF_MEAS4	0x1C00	Measurement 4 Configuration
0x0C	FDC_CONF	0x0000	Capacitance to Digital Configuration
0x0D	OFFSET_CAL_CIN1	0x0000	CIN1 Offset Calibration
0x0E	OFFSET_CAL_CIN2	0x0000	CIN2 Offset Calibration
0x0F	OFFSET_CAL_CIN3	0x0000	CIN3 Offset Calibration
0x10	OFFSET_CAL_CIN4	0x0000	CIN4 Offset Calibration
0x11	GAIN_CAL_CIN1	0x4000	CIN1 Gain Calibration
0x12	GAIN_CAL_CIN2	0x4000	CIN2 Gain Calibration
0x13	GAIN_CAL_CIN3	0x4000	CIN3 Gain Calibration
0x14	GAIN_CAL_CIN4	0x4000	CIN4 Gain Calibration
0xFE	Manufacturer ID	0x5449	ID of Texas Instruments
0xFF	Device ID	0x1004	ID of FDC1004 device

Registers from 0x15 to 0xFD are reserved and should not be written to.

8.6.1 Registers

The FDC1004 has an 8-bit pointer used to address a given data register. The pointer identifies which of the data registers should respond to a read or write command on the two-wire bus. This register is set with every write command. A write command must be issued to set the proper value in the pointer before executing a read command. The power-on reset (POR) value of the pointer is 0x00.

8.6.1.1 Capacitive Measurement Registers

The capacitance measurement registers are 24-bit result registers in binary format (the 8 LSBs D[7:0] are always 0x00). The result of the acquisition is always a 24 bit value, while the accuracy is related to the selected conversion time (refer to [Electrical Characteristics](#)). The data is encoded in a Two's complement format. The result of the measurement can be calculated by the following formula:

$$\text{Capacitance (pf)} = \text{Two's Complement (measurement [23:0])} / 2^{19} + C_{\text{offset}}$$

where

- C_{offset} is based on the CAPDAC setting. (1)

Table 2. Measurement Registers Description (0x00, 0x02, 0x04, 0x06)

Field Name	Bits	Description
MSB_MEASn ⁽¹⁾	[15:0]	Most significant 16 bits of Measurement n (read only)

(1) MSB_MEAS1 = register 0x00, MSB_MEAS2 = register 0x02, MSB_MEAS3 = register 0x04, MSB_MEAS4 = register 0x06

Table 3. Measurement Registers Description (0x01, 0x03, 0x05, 0x07)

Field Name	Bits	Description
LSB_MEASn ⁽¹⁾	[15:8]	Least significant 8 bits of Measurement n (read only)
	[7:0]	Reserved Reserved, always 0 (read only)

(1) LSB_MEAS1 = register 0x01, LSB_MEAS2 = register 0x03, LSB_MEAS3 = register 0x05, LSB_MEAS4 = register 0x07

8.6.2 Measurement Configuration Registers

These registers configure the input channels and CAPDAC setting for a measurement.

Table 4. Measurement Configuration Registers Description (0x08, 0x09, 0x0A, 0x0B)

Field Name	Bits	Description
CHA ⁽¹⁾⁽²⁾	[15:13]	Positive input channel capacitive to digital converter
		b000 CIN1
		b001 CIN2
		b010 CIN3
CHB ⁽¹⁾⁽²⁾	[12:10]	Negative input channel capacitive to digital converter
		b000 CIN1
		b001 CIN2
		b010 CIN3
		b011 CIN4
		b100 CAPDAC
CAPDAC	[9:5]	Offset Capacitance
		b00000 0pF (minimum programmable offset)
		----- Configure the single-ended measurement capacitive offset: C _{offset} = CAPDAC x 3.125pF
RESERVED	[04:00]	b11111 96.875pF (maximum programmable offset)
		Reserved, always 0 (read only)

- (1) It is not permitted to configure a measurement where the CHA field and CHB field hold the same value (for example, if CHA=b010, CHB cannot also be set to b010).
- (2) It is not permitted to configure a differential measurement between CHA and CHB where CHA > CHB (for example, if CHA=b010, CHB cannot be b001 or b000).

8.6.3 FDC Configuration Register

This register configures measurement triggering and reports measurement completion.

Table 5. FDC Register Description (0x0C)

Field Name	Bits	Description
RST	[15]	Reset
		0 Normal operation 1 Software reset: write a 1 to initiate a device reset; after completion of reset this field will return to 0
RESERVED	[14:12]	Reserved Reserved, always 0 (read only)
RATE	[11:10]	Measurement Rate
		b00 Reserved
		b01 100S/s
		b10 200S/s
RESERVED	[9]	Reserved Reserved, always 0 (read only)
REPEAT	[8]	Repeat Measurements
		0 Repeat disabled 1 Repeat enabled, all the enabled measurement are repeated
MEAS_1	[7]	Initiate Measurements
		0 Measurement 1 disabled 1 Measurement 1 enabled
MEAS_2	[6]	Initiate Measurements
		0 Measurement 2 disabled 1 Measurement 2 enabled

Table 5. FDC Register Description (0x0C) (continued)

Field Name	Bits	Description
MEAS_3	[5] Initiate Measurements	0 Measurement 3 disabled
		1 Measurement 3 enabled
MEAS_4	[4] Initiate Measurements	0 Measurement 4 disabled
		1 Measurement 4 enabled
DONE_1	[3] Measurement Done	0 Measurement 1 not completed
		1 Measurement 1 completed
DONE_2	[2] Measurement Done	0 Measurement 2 not completed
		1 Measurement 2 completed
DONE_3	[1] Measurement Done	0 Measurement 3 not completed
		1 Measurement 3 completed
DONE_4	[0] Measurement Done	0 Measurement 4 not completed
		1 Measurement 4 completed

8.6.4 Offset Calibration Registers

These registers configure a digitized capacitance value in the range of -16 pF to 16 pF (max residual offset 250 aF) that can be added to each channel in order to remove parasitic capacitance due to external circuitry. In addition to the offset calibration capacitance which is a fine-tune offset capacitance, it is possible to support a larger offset by using the CAPDAC (for up to 100 pF). These 16-bit registers are formatted as a fixed point number, where the first 5 bits represents the integer portion of the capacitance in Two's complement format, and the remaining 11 bits represent the fractional portion of the capacitance.

Table 6. Offset Calibration Registers Description (0x0D, 0x0E, 0x0F, 0x10)

Field Name	Bits	Description
OFFSET_CALn ⁽¹⁾	[15:11] Integer part	Integer portion of the Offset Calibration of Channel CINn
	[10:0] Decimal part	Decimal portion of the Offset Calibration of Channel CINn

(1) OFFSET_CAL1 = register 0x0D, OFFSET_CAL2 = register 0x0E, OFFSET_CAL3 = register 0x0F, OFFSET_CAL4 = register 0x10

8.6.5 Gain Calibration Registers

These registers contain a gain factor correction in the range of 0 to 4 that can be applied to each channel in order to remove gain mismatch due to the external circuitry. This 16-bit register is formatted as a fixed point number, where the 2 MSBs of the GAIN_CALn register correspond to an integer portion of the gain correction, and the remaining 14 bits represent the fractional portion of the gain correction. The result of the conversion represents a number without dimensions.

The Gain can be set according to the following formula:

$$\text{Gain} = \text{GAIN_CAL}[15:0]/2^{14}$$

Table 7. Gain Calibration Registers Description (0x11, 0x12, 0x13, 0x14)

Field Name	Bits	Description
GAIN_CALn ⁽¹⁾	[15:14] Integer part	Integer portion of the Gain Calibration of Channel CINn
	[13:0] Decimal part	Decimal portion of the Gain Calibration of Channel CINn

(1) GAIN_CAL1 = register 0x11, GAIN_CAL2 = register 0x12, GAIN_CAL3 = register 0x13, GAIN_CAL4 = register 0x14

8.6.6 Manufacturer ID Register

This register contains a factory-programmable identification value that identifies this device as being manufactured by Texas Instruments. This register distinguishes this device from other devices that are on the same I²C bus. The manufacturer ID reads 0x5449.

FDC1004

SNOSCY5A – AUGUST 2014 – REVISED OCTOBER 2014

www.ti.com
Table 8. Manufacturer ID Register Description (0xFE)

Field Name	Bits	Description
MANUFACTURER ID	[15:0] Manufacturer ID	0x5449h Texas instruments ID (read only)

8.6.7 Device ID Register

This register contains a factory-programmable identification value that identifies this device as a FDC1004. This register distinguishes this device from other devices that are on the same I2C bus. The Device ID for the FDC1004 is 0x1004.

Table 9. Device ID Register Description (0xFF)

Field Name	Bits	Description
DEVICE ID	[15:0] Device ID	0x1004 FDC1004 Device ID (read only)

9 Applications and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

9.1.1 Liquid Level Measurement

The FDC1004 can be used to measure liquid level in non-conductive containers. Capacitive sensors can be attached to the outside of the container or be located remotely from the container, allowing for contactless measurements. The working principle is based on a ratiometric measurement; Figure 14 shows a possible system implementation which uses three electrodes. The Level electrode provides a capacitance value proportional to the liquid level. The Reference Environmental electrode and the Reference Liquid electrode are used as references. The Reference Liquid electrode accounts for the liquid dielectric constant and its variation, while the Reference Environmental electrode is used to compensate for any other environmental variations that are not due to the liquid itself. Note that the Reference Environmental electrode and the Reference Liquid electrode are the same physical size (h_{REF}).

For this application, single-ended measurements on the appropriate channels are appropriate, as the tank is grounded.

Use the following formula to determine the liquid level from the measured capacitances:

$$Level = h_{ref} \frac{C_{Lev} - C_{Lev}(0)}{C_{RL} - C_{RE}}$$

where

- C_{RE} is the capacitance of the Reference Environmental electrode,
- C_{RL} is the capacitance of the Reference Liquid electrode,
- C_{Lev} is the current value of the capacitance measured at the Level electrode sensor,
- $C_{Lev}(0)$ is the capacitance of the Level electrode when the container is empty, and
- h_{REF} is the height in the desired units of the Container or Liquid Reference electrodes.

The ratio between the capacitance of the level and the reference electrodes allows simple calculation of the liquid level inside the container itself. Very high sensitivity values (that is, many LSB/mm) can be obtained due to the high resolution of the FDC1004, even when the sensors are located remotely from the container.

9.2 Typical Application

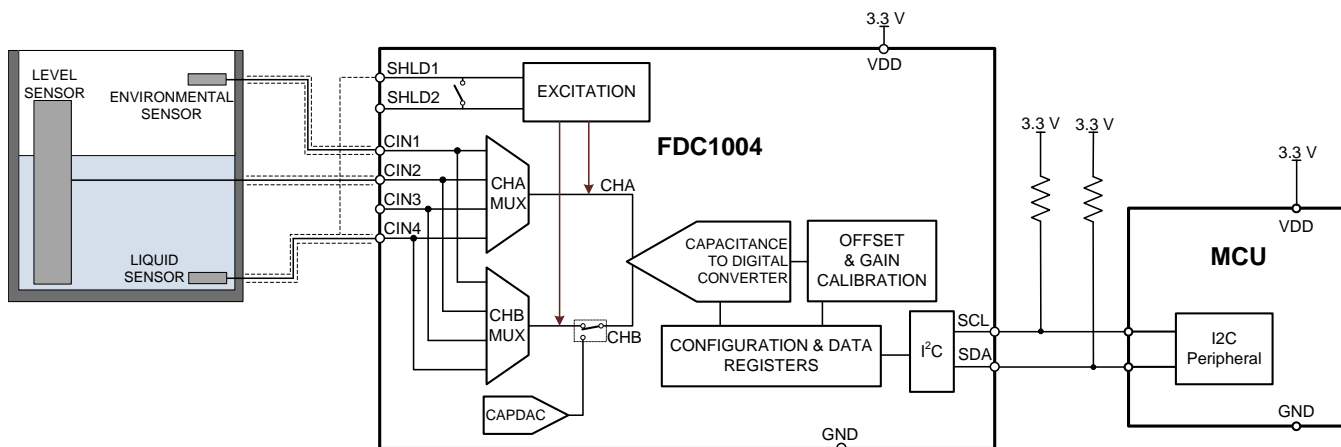


Figure 14. FDC1004 (Liquid Level Measurement)

Typical Application (continued)

9.2.1 Design Requirements

The liquid level measurement should be independent of the liquid, which can be achieved using the 3-electrode design described above. Moreover, the sensor should be immune to environmental interferers such as a human body, other objects, or EMI. This can be achieved by shielding the side of the sensor which does not face the container.

9.2.2 Detailed Design Procedure

In capacitive sensing systems, the design of the sensor plays an important role in determining system performance and capabilities. In most cases the sensor is simply a metal plate that can be designed on the PCB.

The sensor used in this example is implemented with a two-layer PCB. On the top layer, which faces the tank, there are the 3 electrodes (Reference Environmental, Reference Liquid, and Level) with a ground plane surrounding the electrodes. The bottom layer is covered with a shield plane in order to isolate the electrodes from any external interference sources.

Depending on the shape of the container, the FDC1004 can be located on the sensor PCB to minimize the length of the traces between the input channels and the sensors and increase the immunity from EMI sources. In case the shape of the container or other mechanical constraints do not allow having the sensors and the FDC1004 on the same PCB, the traces which connect the channels to the sensor need to be shielded with the appropriate shield. In this design example all of the channels are shielded with SHLD1. For this configuration, the FDC1004 measures the capacitance of the 3 channels versus ground; and so the SHLD1 and SHLD2 pins are internally shorted in the FDC1004 (see [The Shield](#)).

9.2.3 Application Performance Plot

The data shown below has been collected with the FDC1004EVM. A liquid level sensor with 3 electrodes like the one shown in the schematic was connected to the EVM. The plot shows the capacitance measured by the 3 electrodes at different levels of liquid in the tank. The capacitance of the Reference Liquid (the RF trace in the graph below) and Reference Environmental (the RE trace) sensors have a steady value when the liquid is above their height while the capacitance of the level sensor (Level) increases linearly with the height of the liquid in the tank.

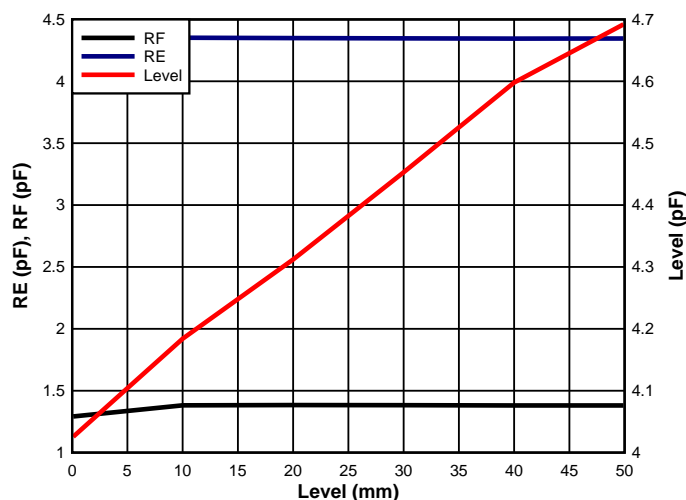


Figure 15. Electrodes' Capacitance vs. Liquid Level

9.3 Do's and Don'ts

Avoid long traces to connect the sensor to the FDC1004. Short traces reduce parasitic capacitances between shield versus input channel and parasitic resistance between input channel versus GND and shield versus GND.

Since the sensor in many cases is simply a metal surface on a PCB, it needs to be protected with solder resist to avoid short circuits and limit any corrosion. Any change in the sensor may result in a change in system performance.

9.4 Initialization Set Up

At power on the device is in stand-by. It stays in this mode until a measurement is triggered.

10 Power Supply Recommendations

The FDC1004 requires a voltage supply within 3 V and 3.6 V. Two multilayer ceramic bypass X7R capacitors of 0.1 μ F and 1 μ F, respectively between VDD and GND pin are recommended. The 0.1- μ F capacitor should be closer to the VDD pin than the 1- μ F capacitor.

11 Layout

11.1 Layout Guidelines

The FDC1004 measures the capacitances connected between the CINn (n=1..4) pins and GND. To get the best result, locate the FDC1004 as close as possible to the capacitive sensor. Minimize the connection length between the sensor and FDC1004 CINn pins and between the sensor ground and the FDC1004 GND pin. If a shielded cable is used for remote sensor connection, the shield should be connected to the SHLDm (m=1...2) pin according to the configured measurement.

11.2 Layout Example

Figure 16 below is optimized for applications where the sensor is not too far from the FDC1004. Each channel trace runs between 2 shield traces. This layout allows the measurements of 4 single ended capacitance or 2 differential capacitance. The ground plane needs to be far from the channel traces, it is mandatory around or below the I2C pin.

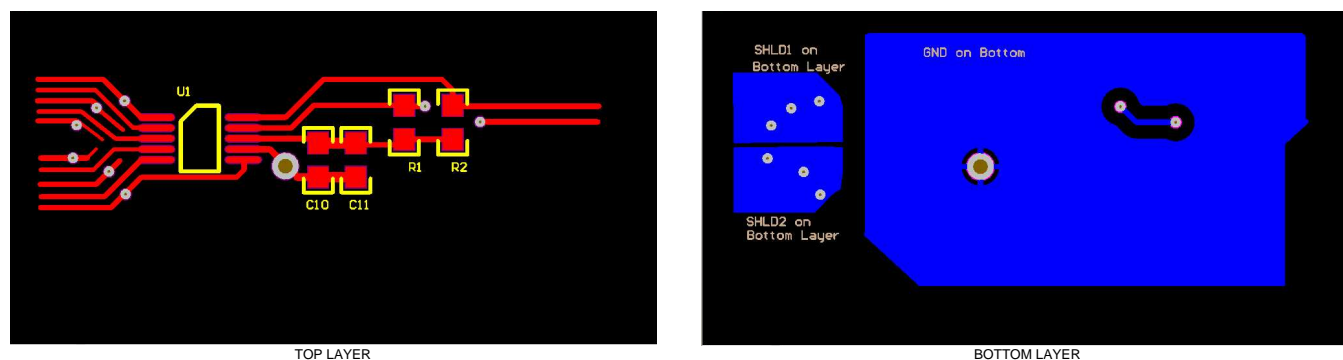


Figure 16. Layout

12 Device and Documentation Support

12.1 Trademarks

All trademarks are the property of their respective owners.

12.2 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

12.3 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
FDC1004DGSR	PREVIEW	VSSOP	DGS	10	3500	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	ZBNX	
FDC1004DGST	PREVIEW	VSSOP	DGS	10	250	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	ZBNX	
FDC1004DSCJ	ACTIVE	WSOP	DSC	10	4500	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	F1004	Samples
FDC1004DSCR	ACTIVE	WSOP	DSC	10	1000	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	F1004	Samples
FDC1004DSCT	ACTIVE	WSOP	DSC	10	250	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	F1004	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

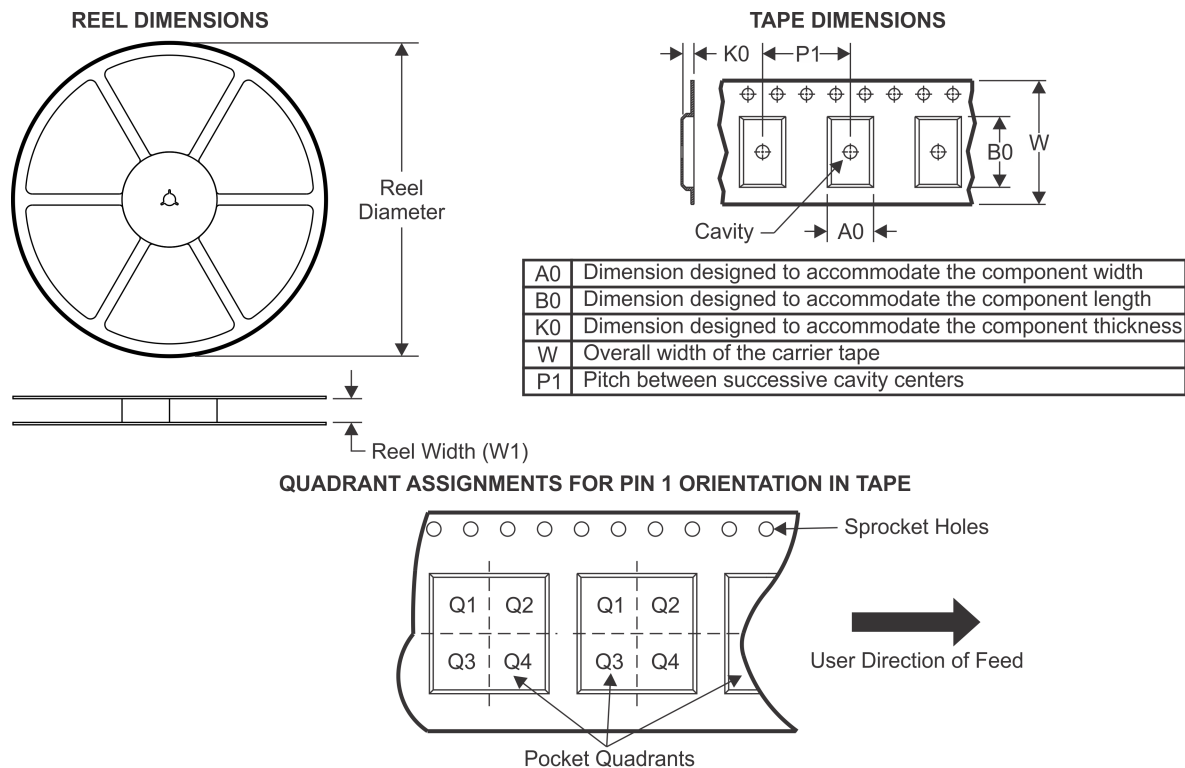
(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

⁽⁶⁾ Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

TAPE AND REEL INFORMATION


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
FDC1004DSCJ	WSO	DSC	10	4500	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q1
FDC1004DSCR	WSO	DSC	10	1000	178.0	12.4	3.3	3.3	1.0	8.0	12.0	Q1
FDC1004DSCT	WSO	DSC	10	250	178.0	12.4	3.3	3.3	1.0	8.0	12.0	Q1

TAPE AND REEL BOX DIMENSIONS

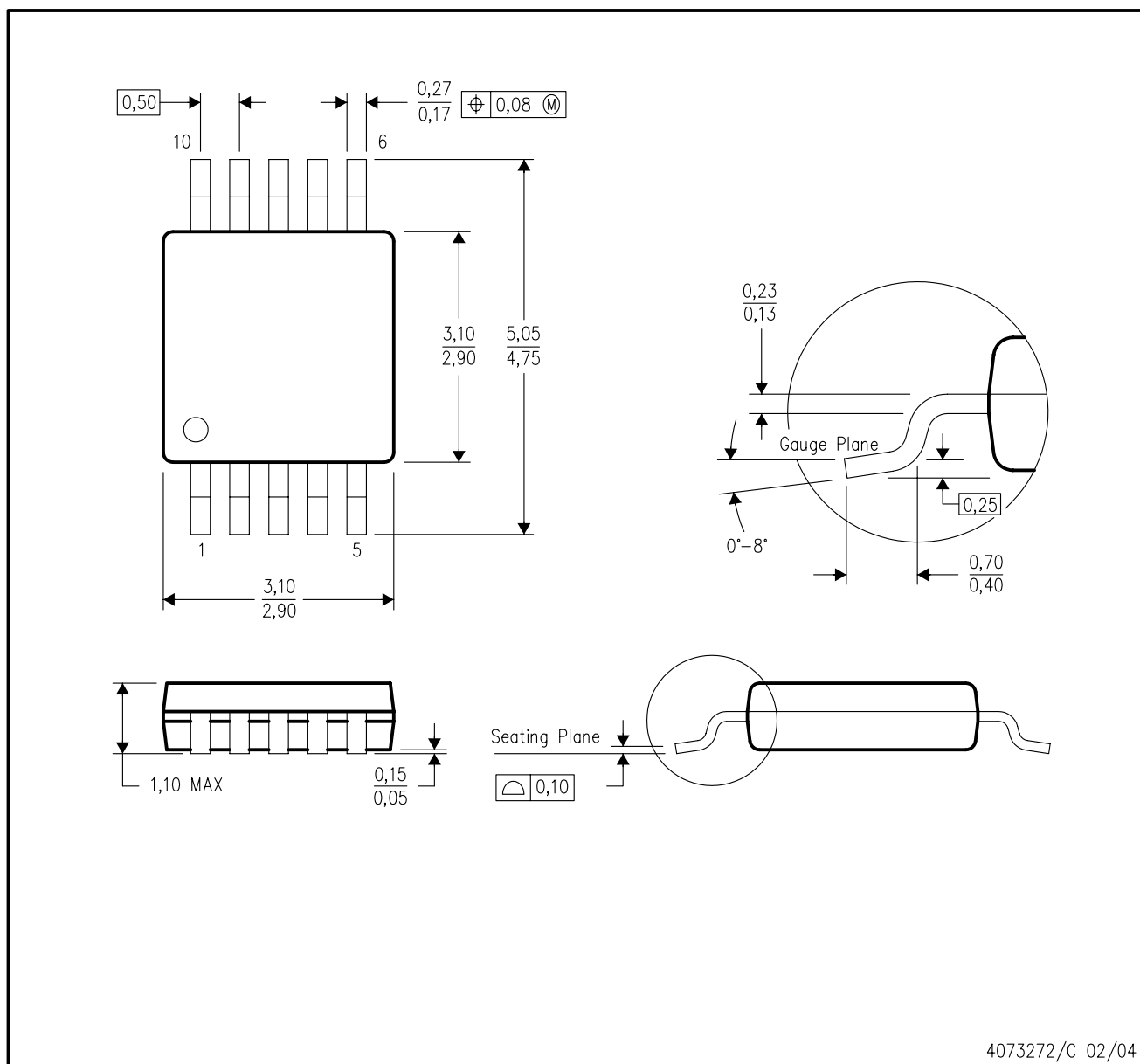


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
FDC1004DSCJ	WSON	DSC	10	4500	367.0	367.0	35.0
FDC1004DSCR	WSON	DSC	10	1000	210.0	185.0	35.0
FDC1004DSCT	WSON	DSC	10	250	210.0	185.0	35.0

DGS (S-PDSO-G10)

PLASTIC SMALL-OUTLINE PACKAGE



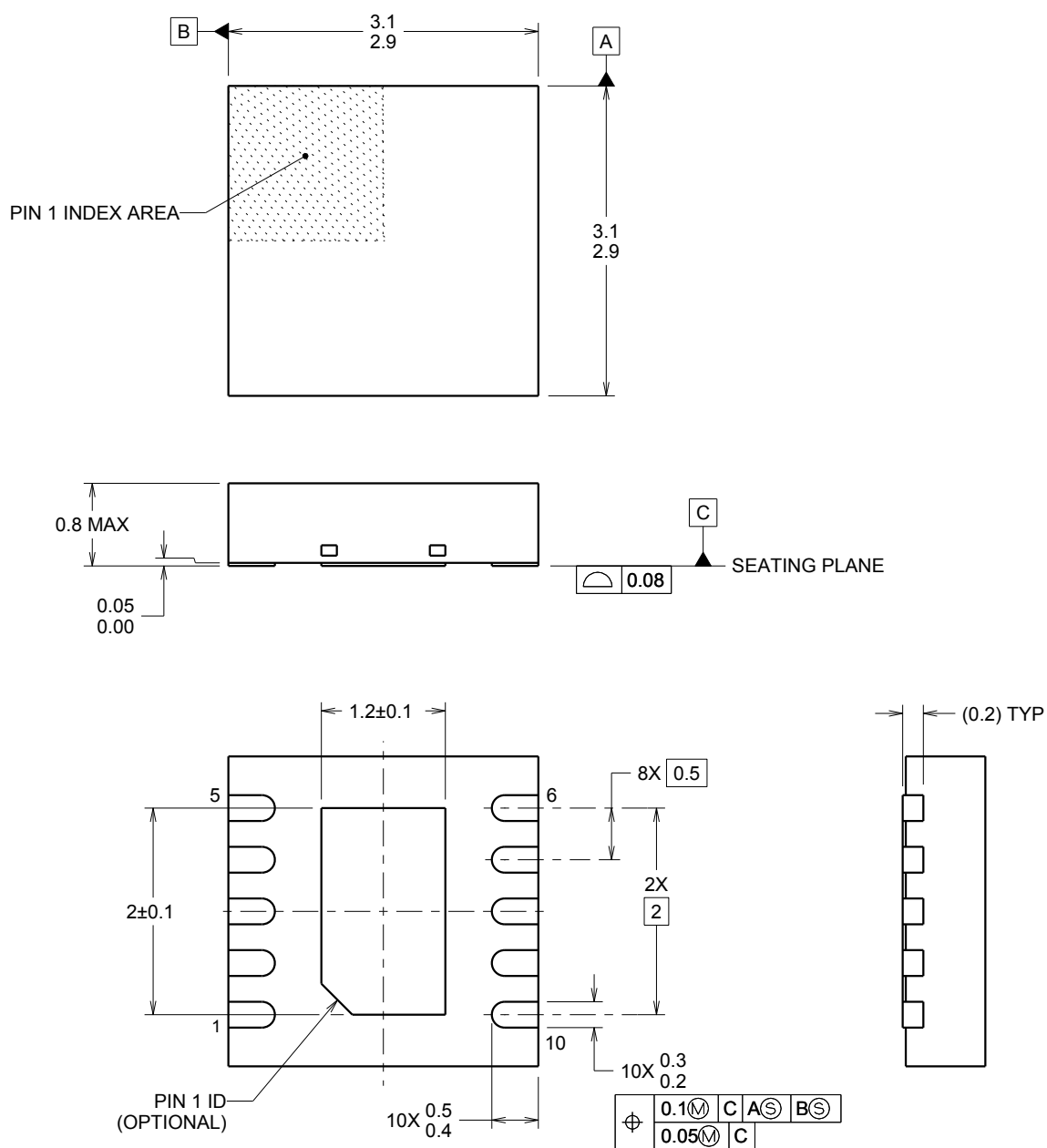
- NOTES:
- All linear dimensions are in millimeters.
 - This drawing is subject to change without notice.
 - Body dimensions do not include mold flash or protrusion.
 - Falls within JEDEC MO-187 variation BA.



PACKAGE OUTLINE

WSON - 0.8 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



4214926/A 07/2014

NOTES:

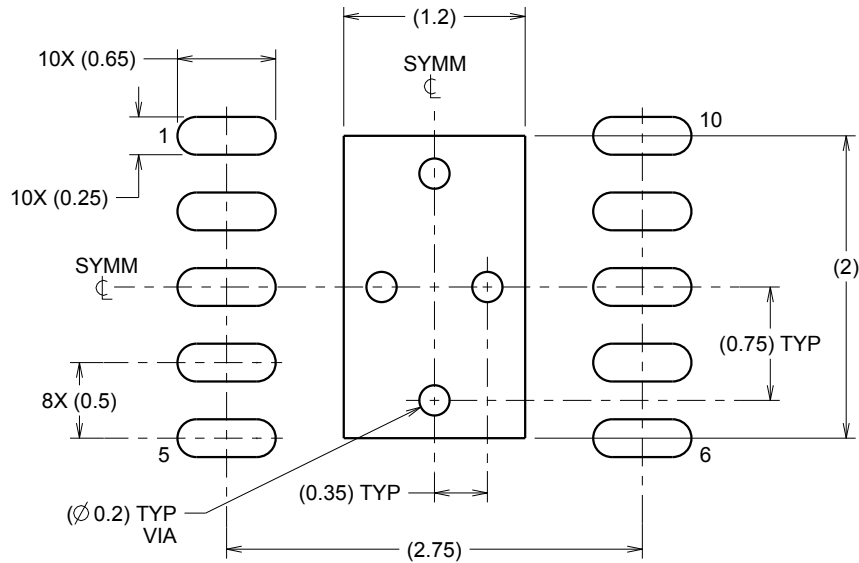
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

EXAMPLE BOARD LAYOUT

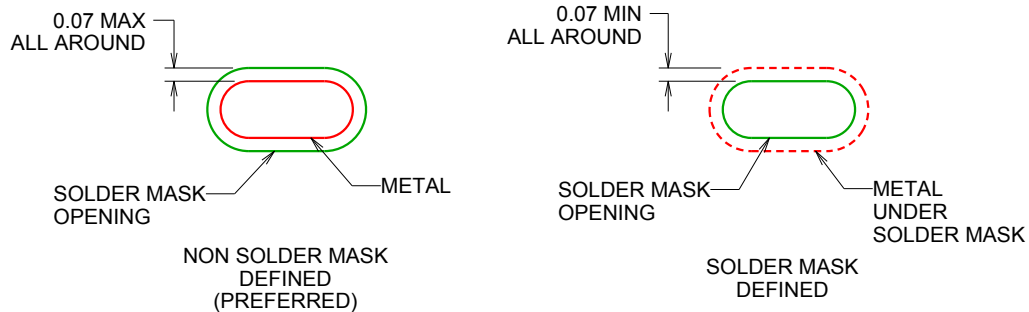
DSC0010B

WSON - 0.8 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



LAND PATTERN EXAMPLE
SCALE:20X



SOLDER MASK DETAILS

4214926/A 07/2014

NOTES: (continued)

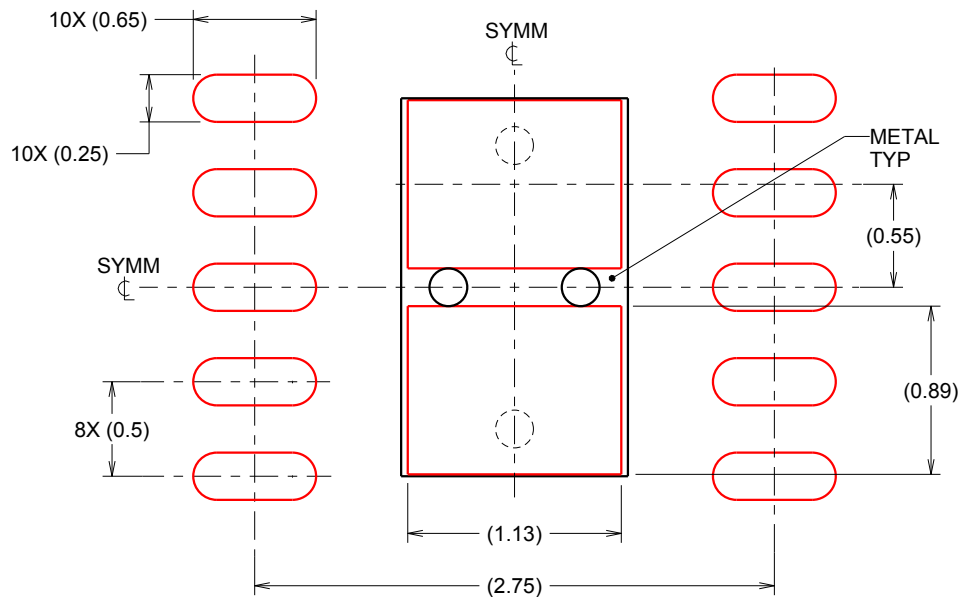
- This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/sluea271).

EXAMPLE STENCIL DESIGN

DSC0010B

WSN - 0.8 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD
84% PRINTED SOLDER COVERAGE BY AREA
SCALE:25X

4214926/A 07/2014

NOTES: (continued)

5. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46, latest issue, and to discontinue any product or service per JESD48, latest issue. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products (also referred to herein as "components") are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its components to the specifications applicable at the time of sale, in accordance with the warranty in TI's terms and conditions of sale of semiconductor products. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by applicable law, testing of all parameters of each component is not necessarily performed.

TI assumes no liability for applications assistance or the design of Buyers' products. Buyers are responsible for their products and applications using TI components. To minimize the risks associated with Buyers' products and applications, Buyers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI components or services are used. Information published by TI regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of significant portions of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI components or services with statements different from or beyond the parameters stated by TI for that component or service voids all express and any implied warranties for the associated TI component or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of TI components in its applications, notwithstanding any applications-related information or support that may be provided by TI. Buyer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Buyer will fully indemnify TI and its representatives against any damages arising out of the use of any TI components in safety-critical applications.

In some cases, TI components may be promoted specifically to facilitate safety-related applications. With such components, TI's goal is to help enable customers to design and create their own end-product solutions that meet applicable functional safety standards and requirements. Nonetheless, such components are subject to these terms.

No TI components are authorized for use in FDA Class III (or similar life-critical medical equipment) unless authorized officers of the parties have executed a special agreement specifically governing such use.

Only those TI components which TI has specifically designated as military grade or "enhanced plastic" are designed and intended for use in military/aerospace applications or environments. Buyer acknowledges and agrees that any military or aerospace use of TI components which have **not** been so designated is solely at the Buyer's risk, and that Buyer is solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI has specifically designated certain components as meeting ISO/TS16949 requirements, mainly for automotive use. In any case of use of non-designated products, TI will not be responsible for any failure to meet ISO/TS16949.

Products

Audio	www.ti.com/audio
Amplifiers	amplifier.ti.com
Data Converters	dataconverter.ti.com
DLP® Products	www.dlp.com
DSP	dsp.ti.com
Clocks and Timers	www.ti.com/clocks
Interface	interface.ti.com
Logic	logic.ti.com
Power Mgmt	power.ti.com
Microcontrollers	microcontroller.ti.com
RFID	www.ti-rfid.com
OMAP Applications Processors	www.ti.com/omap
Wireless Connectivity	www.ti.com/wirelessconnectivity

Applications

Automotive and Transportation	www.ti.com/automotive
Communications and Telecom	www.ti.com/communications
Computers and Peripherals	www.ti.com/computers
Consumer Electronics	www.ti.com/consumer-apps
Energy and Lighting	www.ti.com/energy
Industrial	www.ti.com/industrial
Medical	www.ti.com/medical
Security	www.ti.com/security
Space, Avionics and Defense	www.ti.com/space-avionics-defense
Video and Imaging	www.ti.com/video

TI E2E Community

e2e.ti.com

Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

[Texas Instruments:](#)

[FDC1004DSCT](#) [FDC1004DSCR](#) [FDC1004DSCJ](#)