

Technical Note



Ambient Light Sensor ICs

Digital 16bit Serial Output Type Ambient Light Sensor IC

ronic Components KoH

No.11046EAT13

Descriptions

BH1730FVC

BH1730FVC is a digital Ambient Light Sensor IC for I²C bus interface. This IC is the most suitable to obtain the ambient light data for adjusting LCD backlight power of TV, mobile phone. It is possible to detect very wide range light intensity. (0.008 - 65535 lx).

Features

- 1) I²C bus Interface (f / s Mode Support, Slave address "0101001".)
- 2) There are two outputs that peaks of a spectrum response are in visible light (Type0) and in infrared light (Type1).
- 3) Illuminance to Digital Converter
- 4) Very wide range and High resolution. (0.008 65535 lx)
- 5) Low Current by power down function
- 6) 50Hz / 60Hz light noise reject-function
- 7) Correspond to 1.8V logic input interface
- 8) Light source dependency is little by calculating with Type0 and Type1.
- (ex. Incandescent Lamp. Fluorescent Lamp. Halogen Lamp. White LED. Sun Light) 9) Interrupt function is available.
- Adjustable measurement result for influence of optical window
 (It is possible to detect min. 0.001 lx, max. 100000 lx by using this function.)
- 11) Small measurement variation (+/- 15%)
- 12) Built in power on reset circuit.

Applications

LCD TV, Mobile phone, NOTE PC, Portable game machine, Digital camera, Digital video camera, PDA, LCD display

•Absolute Maximum Ratings

| Parameter | Symbol | Limits | Units |
|--------------------------------------|--|---------|-------|
| Supply Voltage | V _{cc} max | 4.5 | V |
| INT, SDA, DVI, SCL, Terminal Voltage | V _{INT} max, V _{SDA} max, V _{DVI} max, V _{SCL} max | 7 | V |
| Operating Temperature | Topr | -40~70 | °C |
| Storage Temperature | Tstg | -40~100 | °C |
| SDA, INT Sink Current | Imax | 7 | mA |
| Power Dissipation | Pd | 260* | mW |

× 70mm × 70mm × 1.6mm glass epoxy board. Derating in done at 3.47mW/°C for operating above Ta=25°C.

Operating Conditions

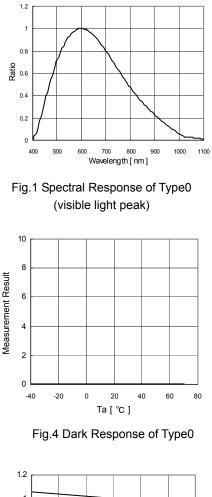
| Parameter | Symbol | Min. | Тур. | Max. | Units |
|------------------------------------|--------|------|------|------|-------|
| VCC Voltage | Vcc | 2.4 | 3.0 | 3.6 | V |
| I ² C Reference Voltage | Vdvi | 1.65 | - | Vcc | V |

●Electrical Characteristics (Vcc = 3.0V, VDVI = 3.0V, Ta = 25°C, unless otherwise noted)

| Min.Typ.Max.Supply CurrentIcc1-150200uA $Ev = 100 \text{ lx} \times 1^{1}$ CONTROL register(00h) = "03h" and the other registers are default.Powerdown CurrentIcc2-0.851.5uANo input Light All registers are default.Peak Wave Length in Type0 $\lambda p0$ -600-nmVisible light responsePeak Wave Length in Type1 $\lambda p1$ -840-nmInfrared light responseADC count value in Type0D1k_0102012001380count $EV = 1000 \text{ lx} \times 1^{1}$ TIMING register(01h) = "DAh" GAIN register(07h) = "00h" | | | , = | Limits | | , í | |
|--|--|--------|---------|--------|----------|----------|--|
| Supply CurrentIcc1-150200uACONTROL register(00h) = "0.3h" and the other registers are default.Powerdown CurrentIcc2-0.851.5uANo input Light and the other registers are default.Peak Wave Length in Type0Ap0-600-nmInfrared light responsePeak Wave Length in Type1Ap1-840-nmInfrared light responseADC count value in Type0D1k_0102012001380countEV = 1000 kR*1ADC count value in Type1D1k_1153180207countTMING register(01h) = "DAh" GAIN register(01h) = "DA | Parameter | Symbol | Min. | Тур. | Max. | Units | Conditions |
| Provention Current Pick Diss F.3 Dr All register are default. Peak Wave Length in Type0 λp0 - 600 - nm Visible light response Peak Wave Length in Type0 λp1 - 840 - nm Mintergister (2nn) = "0.0h" ADC count value in Type0 D1k_0 1020 1200 1380 count EV = 1000 kr ^{3/3} ADC count value in Type0 D1k_1 153 180 207 count Gain register (01h) = "0.0h" ADC count value in Type0 S0_0 0 0 2 count TMINC register (01h) = "0.0h" Dark (0 k) Sensor out in Type0 S0_1 0 0 2 count TIMINC register (01h) = "0.0h" Gain X1 resolution in Type0 rG2 - 0.42 - k/count TIMINC register (01h) = "0.Ah" Gain X128 resolution in Type0 rG2 - 0.42 - k/count TIMINC register (01h) = "0.Ah" **1 Gain X128 resolution in Type0 rG12 - 0.07 - <td>Supply Current</td> <td>lcc1</td> <td>_</td> <td>150</td> <td>200</td> <td>uA</td> <td>CONTROL register(00h) = "03h"</td> | Supply Current | lcc1 | _ | 150 | 200 | uA | CONTROL register(00h) = "03h" |
| Peak Wave Length in Type1 Ap1 - 840 - nm Infrared light response ADC count value in Type0 D1k_0 1020 1200 1380 count EV = 1000 (k **) ADC count value in Type1 D1k_1 153 180 207 count TMINOr register(01h) = "DAh" GAIN register(07h) = "00h" Dark (0 k) Sensor out in Type0 S0_0 0 0 2 count TMINOr register(07h) = "00h" Dark (0 k) Sensor out in Type0 S0_1 0 0 2 count TMINOr register(07h) = "00h" Gain X1 resolution in Type0 rG1 - 0.83 - kx/count TMINOr register(01h) = "DAh" Gain X2 resolution in Type0 rG2 - 0.42 - k/count TMINOr register(01h) = "DAh" Gain X1 resolution in Type0 rG2 - 0.42 - k/count TMINOr register(01h) = "DAh" Gain X128 resolution in Type0 rG12 - 0.007 - k/count TMINOr register(01h) = "DAh" Gain X128 resolution in Type0 rG12 - | Powerdown Current | lcc2 | _ | 0.85 | 1.5 | uA | |
| $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | Peak Wave Length in Type0 | λp0 | _ | 600 | _ | nm | Visible light response |
| ADC count value in Type0D1k_0102012001380countTIMING register(01h) = "DAh" GAIN register(01h) = "OAh" GAIN register(01h) = "OAh" Main Call register(01h) = "OAh" GAIN register(01h) = "OAH" Main Call register(01h) = "OAH" GAIN register(01h) = "OAH" GAIN register(01h) = "OAH" GAIN register(01h) = "OAH" Main Call register(01h) = "OAH" GAIN register(01h) = "OAH" GAIN register(01h) = "OAH" GAIN register(01h) = "OAH" Main Call register(01h) = "OAH" GAIN register(01 | Peak Wave Length in Type1 | λp1 | _ | 840 | _ | nm | C |
| $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | ADC count value in Type0 | D1k_0 | 1020 | 1200 | 1380 | count | TIMING register(01h) = "DAh" GAIN register(07h) = "00h" |
| $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | ADC count value in Type1 | D1k_1 | 153 | 180 | 207 | count | TIMING register(01h) = "DAh" GAIN register(07h) = "00h" |
| | Dark (0 lx) Sensor out in Type0 | S0_0 | 0 | 0 | 2 | count | TIMING register(01h) = "DAh" GAIN register(07h) = "00h" |
| $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | | S0_1 | 0 | 0 | 2 | | TIMING register(01h) = "DAh" GAIN register(07h) = "00h" |
| Gain X64 resolution in Type0rG64-0.014-lx/countTIMING register(01h) = "DAh" **1Gain X128 resolution in Type0rG128-0.007-lx/countTIMING register(01h) = "DAh" **1Measurement Timetmt1-100150msTIMING register(01h) = "DAh" **1Incandescent / Fluorescent ratio by calculating with Type0 and Type1rlF-1-timesEV = 1000 lxINT Output 'L' VoltageVINT0-0.4VIINT = 3 mADVI Input 'L' VoltageVDVL0.4VVSCL, SDA Input 'H' Voltage 1VIH10.7*DVIVDVI ≥ 1.8VSCL, SDA Input 'H' Voltage 2VIH21.26V1.65V ≤ DVI <1.8V | Gain X1 resolution in Type0 | rG1 | _ | 0.83 | _ | | |
| Gain X128 resolution in Type0rG128-0.007-lx/countTIMING register(01h) = "DAh" *1Measurement Timetmt1-100150msTIMING register(01h) = "DAh" *1Incandescent / Fluorescent ratio by calculating with Type0 and Type1rlF-1-timesEV = 1000 lxINT Output 'L' VoltageVINT0-0.4VINT = 3 mADVI Input 'L' VoltageVDVL0.4VSCL, SDA Input 'H' Voltage 1VIH10.7*DVIVDVI \ge 1.8VSCL, SDA Input 'L' Voltage 2VIH21.26V1.65V \le DVI <1.8V | Gain X2 resolution in Type0 | rG2 | — | 0.42 | — | | |
| Measurement Timetmt1-100150msTIMING register(01h) = "DAh"Incandescent / Fluorescent ratio by calculating with Type0 and Type1rIF-1-timesEV = 1000 lxINT Output 'L' VoltageVINT0-0.4VIINT = 3 mADVI Input 'L' VoltageVDVL0.4VSCL, SDA Input 'H' Voltage 1VIH10.7*DVIVDVI \geq 1.8VSCL, SDA Input 'H' Voltage 2VIH21.26V1.65V \leq DVI < 1.8V | Gain X64 resolution in Type0 | rG64 | — | 0.014 | — | | |
| $\begin{array}{ c c c c c c c c c c c c c c c c c c c$ | Gain X128 resolution in Type0 | rG128 | — | 0.007 | — | lx/count | TIMING register(01h) = "DAh" *1 |
| by calculating with Type0 and Type1rlF-1-timesEV = 1000 lxType10-0.4VIINT = 3 mADVI Input 'L' VoltageVDVL0.4VSCL, SDA Input 'H' Voltage 1VIH10.7*DVIVDVI \geq 1.8VSCL, SDA Input 'H' Voltage 2VIH21.26V1.65V \leq DVI < 1.8V | | tmt1 | — | 100 | 150 | ms | TIMING register(01h) = "DAh" |
| DVI Input 'L' VoltageVDVL0.4VSCL, SDA Input 'H' Voltage 1VIH1 $0.7*$ DVIVDVI \geq 1.8VSCL, SDA Input 'H' Voltage 2VIH21.26V1.65V \leq DVI <1.8V | by calculating with Type0 and | rlF | _ | 1 | _ | times | EV = 1000 lx |
| SCL, SDA Input 'H' Voltage 1VIH1 0.7^*DVI V $DVI \ge 1.8V$ SCL, SDA Input 'H' Voltage 2VIH2 1.26 V $1.65V \le DVI < 1.8V$ SCL, SDA Input 'L' Voltage 1VIL1 0.3^*DVI V $DVI \ge 1.8V$ SCL, SDA Input 'L' Voltage 2VIL2DVI-1.26V $1.65V \le DVI < 1.8V$ SCL, SDA, INT Input 'L' Outrage 2VIL2DVI-1.26V $1.65V \le DVI < 1.8V$ SCL, SDA, INT Input 'L' CurrentIIH10 μ AI ² C SCL Clock FrequencyfSCL400kHzI ² C Bus Free TimetBUF 1.3 μ sI ² C Hold Time (repeated) START ConditiontHDSTA 0.6 μ sI ² C Data Hold TimetSUSTA 0.6 μ sI ² C Data Setup TimetSUDAT 100 μ sI ² C 'L' Period of the SCL ClocktLOW 1.3 μ sI ² C 'L' Period of the SCL ClocktHIGH 0.6 μ s | INT Output 'L' Voltage | VINT | 0 | _ | 0.4 | V | IINT = 3 mA |
| SCL, SDA Input 'H' Voltage 2VIH21.26 $ -$ V1.65V \leq DVI <1.8VSCL, SDA Input 'L' Voltage 1VIL1 $ 0.3*DVI$ VDVI \geq 1.8VSCL, SDA Input 'L' Voltage 2VIL2 $ -$ DVI-1.26V1.65V \leq DVI < 1.8V | DVI Input 'L' Voltage | VDVL | Ι | _ | 0.4 | V | |
| SCL, SDA Input 'L' Voltage 1VIL1 $0.3*DVI$ V $DVI \ge 1.8V$ SCL, SDA Input 'L' Voltage 2VIL2 $DVI-1.26$ V $1.65V \le DVI < 1.8V$ SCL, SDA, INT Input 'H' CurrentIIH10 μ ASCL, SDA, INT Input 'L' CurrentIIL10 μ AI ² C SCL Clock FrequencyfSCL400kHzI ² C Bus Free TimetBUF 1.3 μ sI ² C Hold Time (repeated) STARTtHDSTA 0.6 μ sI ² C Set up time for a Repeated START ConditiontSUSTA 0.6 μ sI ² C Data Hold TimetHDDAT0-0.9 μ s1I ² C Data Setup TimetSUDAT100 ns I ² C 'L' Period of the SCL ClocktHOW 1.3 μ s | SCL, SDA Input 'H' Voltage 1 | VIH1 | 0.7*DVI | _ | - | V | DVI \geq 1.8V |
| SCL, SDA Input 'L' Voltage 2VIL2DVI-1.26V1.65V \leq DVI < 1.8VSCL, SDA, INT Input 'H' CurrentIIH10 μ ASCL, SDA, INT Input 'L' CurrentIIL10 μ AI ² C SCL Clock FrequencyfSCL400kHzI ² C Bus Free TimetBUF1.3 μ sI ² C Hold Time (repeated) START ConditiontHDSTA0.6 μ sI ² C Set up time for a Repeated START ConditiontSUSTA0.6 μ sI ² C Data Hold TimetHDDAT0-0.9 μ sI ² C Data Setup TimetSUDAT100nsI ² C 'L' Period of the SCL ClocktLOW1.3 μ s | SCL, SDA Input 'H' Voltage 2 | VIH2 | 1.26 | _ | - | V | $1.65V \leq DVI < 1.8V$ |
| SCL, SDA, INT Input 'H' CurrentIIH10 μA SCL, SDA, INT Input 'L' CurrentIIL10 μA I ² C SCL Clock FrequencyfSCL400kHzI ² C Bus Free TimetBUF1.3 μs I ² C Hold Time (repeated) START ConditiontHDSTA0.6 μs I ² C Set up time for a Repeated START ConditiontSUSTA0.6 μs I ² C Set up time for STOP ConditiontSUSTA0.6 μs I ² C Data Hold TimetHDDAT0-0.9 μs I ² C Data Setup TimetSUDAT100nsI ² C 'L' Period of the SCL ClocktLOW1.3 μs | SCL, SDA Input 'L' Voltage 1 | VIL1 | _ | _ | 0.3*DVI | V | DVI \geq 1.8V |
| SCL, SDA, INT Input 'L' CurrentIIL $ -$ 10 μA I ² C SCL Clock FrequencyfSCL $ -$ 400kHzI ² C Bus Free TimetBUF1.3 $ \mu s$ I ² C Hold Time (repeated) START ConditiontHDSTA0.6 $ \mu s$ I ² C Set up time for a Repeated START ConditiontSUSTA0.6 $ \mu s$ I ² C Set up time for STOP ConditiontSUSTA0.6 $ \mu s$ I ² C Data Hold TimetHDDAT0 $ \mu s$ I ² C Data Setup TimetSUDAT100 $ n s$ I ² C 'L' Period of the SCL ClocktLOW1.3 $ \mu s$ | SCL, SDA Input 'L' Voltage 2 | VIL2 | _ | — | DVI-1.26 | V | $1.65V \leq DVI < 1.8V$ |
| I^2C SCL Clock FrequencyfSCL400kHz I^2C Bus Free TimetBUF1.3 μ s I^2C Hold Time (repeated) START ConditiontHDSTA0.6 μ s I^2C Set up time for a Repeated START ConditiontSUSTA0.6 μ s I^2C Set up time for STOP ConditiontSUSTA0.6 μ s I^2C Set up time for STOP ConditiontSUSTO0.6 μ s I^2C Data Hold TimetHDDAT0-0.9 μ s I^2C Data Setup TimetSUDAT100ns I^2C 'L' Period of the SCL ClocktLOW1.3 μ s I^2C 'H' Period of the SCL ClocktHIGH0.6 μ s | SCL, SDA, INT Input 'H' Current | IIH | _ | _ | 10 | μA | |
| I^2C Bus Free TimetBUF1.3 μ s I^2C Hold Time (repeated) START ConditiontHDSTA0.6 μ s I^2C Set up time for a Repeated START ConditiontSUSTA0.6 μ s I^2C Set up time for STOP ConditiontSUSTO0.6 μ s I^2C Data Hold TimetHDDAT0-0.9 μ s I^2C Data Setup TimetSUDAT100ns I^2C 'L' Period of the SCL ClocktLOW1.3 μ s | SCL, SDA, INT Input 'L' Current | IIL | _ | _ | 10 | μA | |
| I^2C Hold Time (repeated) START ConditiontHDSTA 0.6 $ \mu$ s I^2C Set up time for a Repeated START ConditiontSUSTA 0.6 $ \mu$ s I^2C Set up time for STOP ConditiontSUSTO 0.6 $ \mu$ s I^2C Set up time for STOP ConditiontSUSTO 0.6 $ \mu$ s I^2C Data Hold TimetHDDAT 0 $ 0.9$ μ s I^2C Data Setup TimetSUDAT 100 $ ns$ I^2C 'L' Period of the SCL ClocktLOW 1.3 $ \mu$ s I^2C 'H' Period of the SCL ClocktHIGH 0.6 $ \mu$ s | I ² C SCL Clock Frequency | fSCL | _ | _ | 400 | kHz | |
| ConditionHDSTA 0.6 $ \mu$ sI ² C Set up time for a Repeated START ConditiontSUSTA 0.6 $ \mu$ sI ² C Set up time for STOP ConditiontSUSTO 0.6 $ \mu$ sI ² C Data Hold TimetHDDAT 0 $ 0.9$ μ sI ² C Data Setup TimetSUDAT 100 $ ns$ I ² C 'L' Period of the SCL ClocktLOW 1.3 $ \mu$ s | I ² C Bus Free Time | tBUF | 1.3 | — | - | μs | |
| I^2C Set up time for a Repeated START ConditiontSUSTA 0.6 $ \mu$ s I^2C Set up time for STOP ConditiontSUSTO 0.6 $ \mu$ s I^2C Data Hold TimetHDDAT 0 $ 0.9$ μ s I^2C Data Setup TimetSUDAT 100 $ ns$ I^2C 'L' Period of the SCL ClocktLOW 1.3 $ \mu$ s I^2C 'H' Period of the SCL ClocktHIGH 0.6 $ \mu$ s | | tHDSTA | 0.6 | _ | _ | μs | |
| $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | I ² C Set up time for a Repeated | tSUSTA | 0.6 | _ | - | μs | |
| I^2C Data Setup TimetSUDAT100ns I^2C 'L' Period of the SCL ClocktLOW1.3 μ s I^2C 'H' Period of the SCL ClocktHIGH0.6 μ s | I ² C Set up time for STOP | tSUSTO | 0.6 | _ | _ | μs | |
| I ² C 'L' Period of the SCL ClocktLOW1.3 μ sI ² C 'H' Period of the SCL ClocktHIGH0.6 μ s | I ² C Data Hold Time | tHDDAT | 0 | _ | 0.9 | μs | |
| I^2C 'H' Period of the SCL Clock tHIGH 0.6 – – μ s | I ² C Data Setup Time | tSUDAT | 100 | - | - | ns | |
| | I ² C 'L' Period of the SCL Clock | tLOW | 1.3 | _ | — | μs | |
| I^2C SDA Output 'L' Voltage VOL 0 – 0.4 V IOL = 3 mA | I ² C 'H' Period of the SCL Clock | tHIGH | 0.6 | _ | — | μs | |
| | I ² C SDA Output 'L' Voltage | VOL | 0 | _ | 0.4 | V | IOL = 3 mA |

%1 White LED is used as optical source.

Reference Data



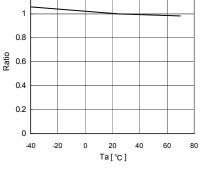


Fig.7 ADC count value in Type0 Temperature Dependency

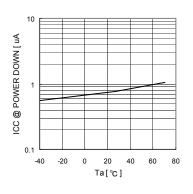


Fig.10 Power down ICC@0Lx Temperature Dependency

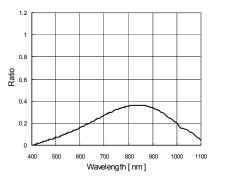


Fig.2 Spectral Response of Type1 (infrared light peak)

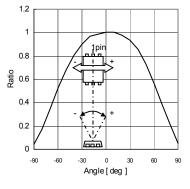


Fig.5 Directional Characteristics 1

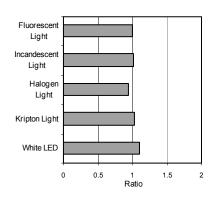


Fig.8 Light Source Dependency in calculation from Type0 and Type1. (Fluorescent Light is set to '1')

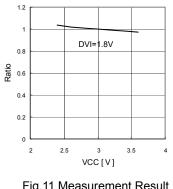


Fig.11 Measurement Result VCC Dependency

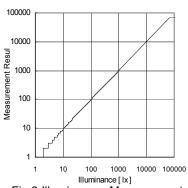


Fig.3 Illuminance -Measurement Result of Type0, Gain 1X, ITIME=DAh

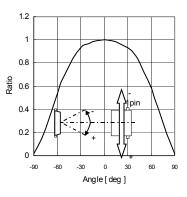


Fig.6 Directional Characteristics 2

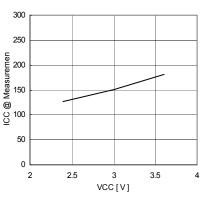
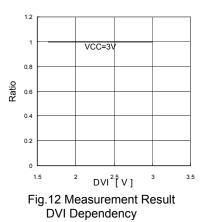
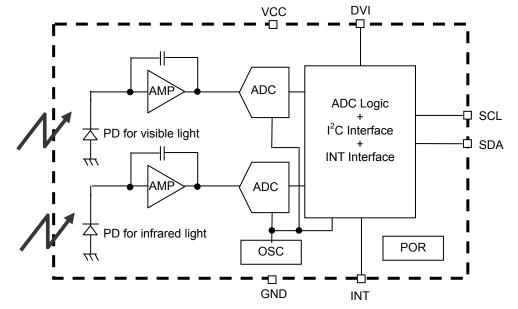


Fig.9 VCC - ICC (During measurement)



Block Diagram



Block Diagram Descriptions

- PD
 - Photo diodes (PD) with peaks in visible light and in infrared light.
- AMP
 - Integration OPAMP for converting from PD current to voltage.
- ADC
 - AD converter for obtainment digital 16bit data.
- ADC Logic + I²C Interface + INT Interface
 - Ambient light calculation logic and I²C Bus Interface and Interrupt function Interface.
- OSC

Internal oscillator (typ. 360kHz). It is clock for internal logic.

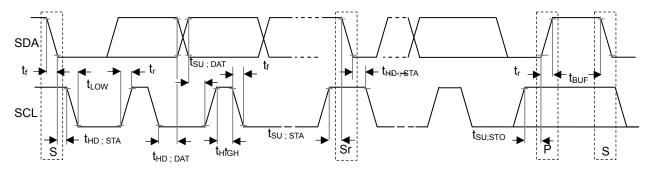
• POR

Power on reset. All register is reset after VCC is supplied. Please refer P14 (Caution of power on reset function).

●I²C Bus Access and Write / Read format

1) I²C Bus interface timing chart

Write measurement command and Read measurement result are done by I²C Bus interface. Please refer the formally specification of I²C Bus interface, and follow the formally timing chart.



2) Main write Format

1. Case of "Write to Command Register"

| ST | Slave Address 0101001 | W 0 | ACK | Data to Command Register 1XXXXXXX | ACK | SP |
|----|--------------------------|--------|-----|--------------------------------------|-----|----|
|----|--------------------------|--------|-----|--------------------------------------|-----|----|

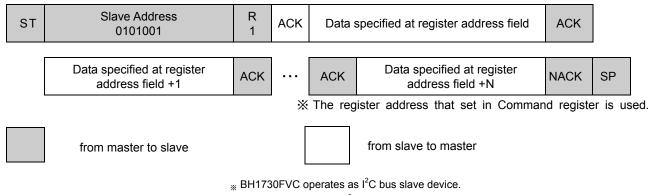
2. Case of "Write to Data Register"

| ST | Slave Address 0101001 | W 0 | ACK | Data | specified at register address field 0XXXXXXX | ACK | |
|----|--|--------|------|------|---|-----|----|
| | Data specified at register address field +1 | ACK | •••• | ACK | Data specified at register address field +N | ACK | SP |

% The register address that set in Command register is used.3. Case of "write to data register after write to Command Register"

| ST | Slave Address 0101001 | W 0 | ACK | | Data to Command Register 1XXXXXXX | ACK | |
|----|---|--------|-----|-----|--|-----|----|
| | Data specified at register address field | ACK | | ACK | Data specified at register address field +N | ACK | SP |

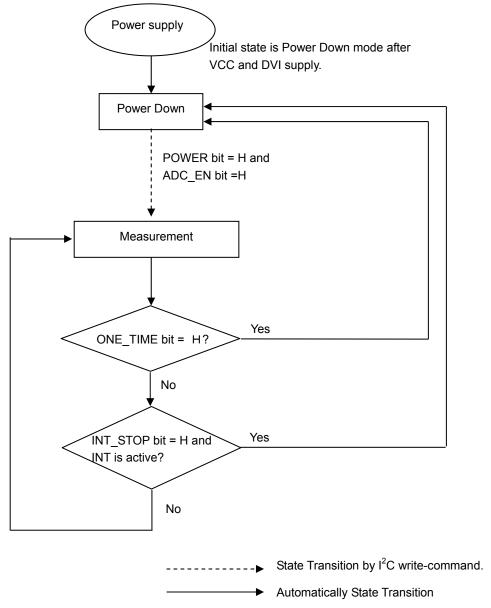
3) Main read Format



* Please refer formality I²C bus specification of NXP semiconductor

BH1730FVC continues to write or read data with address increments until master issues stop condition. Read cycle is $00h - 01h - 02h - 03h - 04h - 05h - 06h - 07h - 12h - 14h - 15h - 16h - 17h - 00h \dots$

Measurement Procedure



• Explanation of Asynchronous reset and Software reset command.

1) Asynchronous reset

All registers are reset and BH1730FVC becomes power down during DVI = 'L'. Initial reset is not necessary, because power on reset function is included in this product.

2) Software reset command All registers are reset and BH1730FVC becomes power down by Software reset command.

●Command set

| Address | Туре | Register name | Register function |
|---------|------|---------------|---|
| | W | COMMAND | Specifies register address or set special command |
| 00h | RW | CONTROL | Operation mode control |
| 01h | RW | TIMING | Light integration time control |
| 02h | RW | INTERRUPT | Interrupt function control |
| 03h | RW | THLLOW | Low byte of low interrupt threshold setting |
| 04h | RW | THLHIGH | High byte of low interrupt threshold setting |
| 05h | RW | THHLOW | Low byte of high interrupt threshold setting |
| 06h | RW | THHHIGH | High byte of high interrupt threshold setting |
| 07h | RW | GAIN | Gain control |
| 12h | R | ID | Part number and Revision ID |
| 14h | R | DATA0LOW | ADC Type0 low byte data register |
| 15h | R | DATA0HIGH | ADC Type0 high byte data register |
| 16h | R | DATA1LOW | ADC Type1 low byte data register |
| 17h | R | DATA1HIGH | ADC Type1 high byte data register |

OCOMMAND

| | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---|-----|-------|--------|---|--------|----------------|---------|---|
| ĺ | CMD | TRANS | ACTION | | ADDRES | SS / Special c | command | |

default value 00h

| Field | Bit | Туре | Description |
|-----------------|-----|------|---|
| CMD | 7 | W | Write 1 |
| | | W | 00 : COMMAND<4:0> is ADDRESS field. |
| TRANSACTION | 0.5 | | 01 : Reserved. |
| TRANSACTION | 6:5 | | 10 : Reserved. |
| | | | 11 : COMMAND<4:0> is Special command field. |
| ADDRESS | | | Specify register address. |
| ADDRE33 | | | Don't specify invalid register address. |
| | | | 00001 : Interrupt output reset. |
| | 4:0 | W | 00010 : Stop manual integration mode. |
| Special command | | | 00011 : Start manual integration mode. |
| | | | 00100 : Software reset |
| | | | Don't input other commands. |

OCONTROL (00h)

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|----|----|------|-------|------|-------|------|-------|
| ום | -0 | ADC_ | ADC_ | ONE_ | DATA_ | ADC_ | POWER |
| KI | ES | INTR | VALID | TIME | SEL | EN | POWER |

default value 00h

| Field | Bit | Туре | Description |
|-----------|-----|------|---|
| RES | 7:6 | RW | Write 00 |
| ADC INTR | 5 | R | 0 : Interrupt is inactive. |
| ADC_INTR | 5 | К | 1 : Interrupt is active. |
| | 4 | R | 0 : ADC data is not updated after last reading. |
| ADC_VALID | 4 | | 1 : ADC data is updated after last reading. |
| ONE_TIME | | RW | 0 : ADC measurement is continuous. |
| | 3 | | 1 : ADC measurement is one time. |
| | | | ADC changes to power down automatically. |
| DATA SEL | 2 | RW | 0 : ADC measurement Type0 and Type1. |
| DATA_SEL | 2 | RVV. | 1 : ADC measurement Type0 only. |
| ADC EN | 1 | RW | 0 : ADC measurement is not started. |
| ADC_EN | I | RVV. | 1 : ADC measurement is started. |
| POWER | 0 | RW | 0 : ADC power down. |
| FUVER | 0 | RVV | 1 : ADC power on. |

OTIMING (01h)

| | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---|---|---|---|---|----|---|---|---|
| ĺ | | | | | ME | | | |

default value DAh

| Field | Bit | Туре | Description |
|-------|-----|------|--|
| ITIME | 7:0 | RW | ADC Light Integration time control. 00000000 : Use manual integration mode. 11111111 : 1 cycle. 2.7ms. 11111110 : 2 cycle. 5.4ms. 11101101 : 19 cycle. 51.3ms. 11011010 : 38 cycle. 102.6ms. 10110110 : 74 cycle. 199.8ms. 01101100 : 148 cycle. 399.6ms. 00000001 : 255 cycle. 688.5ms. Cycle is defined 256-ITIME<7:0>. Integration time is typically cycle*2.7ms. ADC needs additional 2ms for internal calculation. |

OINTERRUPT (02h)

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----|--------------|-----|------------|---|-----|------|---|
| RES | INT_ STOP | RES | INT_ EN | | PER | SIST | |

default value 00h

| Field | Bit | Туре | Description |
|----------|-------|------|---|
| RES | 7 | RW | Write 0. |
| INT_STOP | 6 | RW | 0 : ADC measurement is continuous.1 : ADC measurement is stopped and ADC becomes power down state when interrupt becomes active. |
| RES | 5 | RW | Write 0. |
| INT_EN | 4 | RW | 0 : Interrupt function is invalid.1 : Interrupt function is valid. |
| PERSIST | 3 : 0 | RW | Interrupt persistence function. 0000 : Interrupt becomes active at each measurement end. 0001 : Interrupt status is updated at each measurement end. 0010 : Interrupt status is updated if two consecutive threshold judgments are the same. When set 0011 or more, interrupt status is updated if threshold judgments are the same over consecutive set times. |

OTH_LOW (03h,04h)

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---|---|---|------------|------------|---|---|---|
| | | | Lower thre | shold data | | | |

default value 00h

| Register | Address | Bit | Туре | Description |
|---------------|---------|-----|------|-------------|
| TH lower LSBs | 03h | 7:0 | RW | Lower byte |
| TH lower MSBs | 04h | 7:0 | RW | Upper byte |

OTH_UP (05h,06h)

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---|---|---|------------|-------------|---|---|---|
| | | | Upper thre | eshold data | | | |

default value FFh

| Register | Address | Bit | Туре | Description |
|---------------|---------|-----|------|-------------|
| TH upper LSBs | 05h | 7:0 | RW | Lower byte |
| TH upper MSBs | 06h | 7:0 | RW | Upper byte |

OGAIN (07h)

| ſ | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---|---|---|-----|---|---|---|------|---|
| | | | RES | | | | GAIN | |

default value 00h

| Field | Bit | Туре | Description |
|-------|-----|------|---|
| RES | 7:3 | RW | Write 00000. |
| GAIN | 2:0 | RW | Change ADC resolution. X00 : X1 gain mode X01 : X2 gain mode X10 : X64 gain mode X11 : X128 gain mode |

OPART_ID (12h)

| _ ` | , | | | | | | |
|---------|--------|-------|---|---|-------|--------|---|
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | Part N | umber | | | Revis | ion ID | |

default value 7Xh

| Field | Bit | Туре | Description |
|-------------|-----|------|-------------|
| Part number | 7:4 | R | 0111 |
| Revision ID | 3:0 | R | XXXX |

ODATA0 (14h,15h)

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---|---|---|--------|----------|---|---|---|
| | | | ADC Ty | pe0 data | | | |

default value 00h

| Register | Address | Bit | Туре | Description |
|------------|---------|-----|------|-------------|
| DATA0 LSBs | 14h | 7:0 | R | Lower byte |
| DATA0 MSBs | 15h | 7:0 | R | Upper byte |

ODATA1 (16h,17h)

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---|---|---|--------|----------|---|---|---|
| | | | ADC Ty | pe1 data | | | |

default value 00h

| Register | Address | Bit | Туре | Description |
|------------|---------|-----|------|-------------|
| DATA1 LSBs | 16h | 7:0 | R | Lower byte |
| DATA1 MSBs | 17h | 7:0 | R | Upper byte |

Measurement sequence example from "Write to start measurement" to "Read measurement result"

| | from Master to Slave | | | from Slave to Master | | |
|-----------|-------------------------------------|--------|-----|-------------------------------------|-----|----|
| ① Send "(| Continuous measurement mode" instru | uction | | | | |
| ST | Slave Address 0101001 | W 0 | ACK | Write Command Register 1000_0000 | ACK | |
| <u> </u> | | | | | | |
| | | | | Write CONTROL register | ACK | SP |

2 Wait to complete 1st measurement. TIMING=DAh (typ. 100ms, max.150ms) and GAIN=00h (X1 Gain) at default.

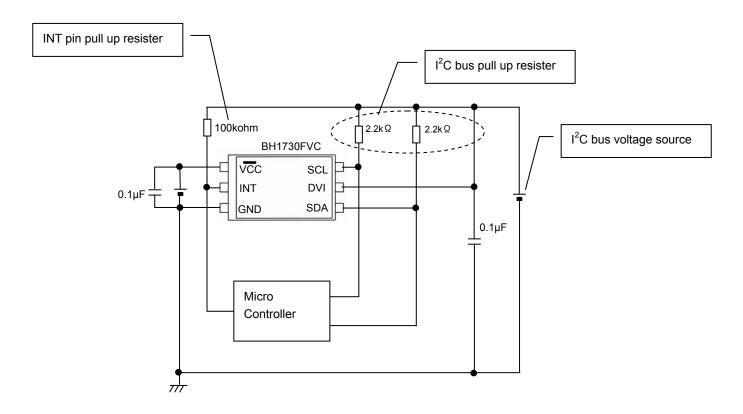
0000_0011

③ Read measurement result

| Cuu III | easurement result. | | | | | |
|---------|--------------------------|--------|-----|-------------------------------------|------|----|
| ST | Slave Address 0101001 | W 0 | ACK | Write Command Register 1001_0100 | ACK | SP |
| | | | | | | |
| ST | Slave Address 0101001 | R 1 | ACK | Read DATA0 LSBs register | ACK | |
| | | | | | | |
| | Read DATA0 MSBs register | | ACK | Read DATA1 LSBs register | ACK | |
| | | | | | | |
| | | | | Read DATA1 MSBs register | NACK | SP |

•Application circuit example

If you don't use INT Pin, please connect to GND or open.



●Lux calculation from DATA0 and DATA1

BH1730FVC has two outputs, DATA0 (14h, 15h) for detecting visible light and infrared light, and DATA1 (16h, 17h) for detecting infrared light. Lux value can be calculated by using these two outputs. The calculation formula depends on the characteristic of optical window. The example of the calculation is shown as follows.

Ex) No optical window or optical window that has flat transmittance from visible light to infrared light.

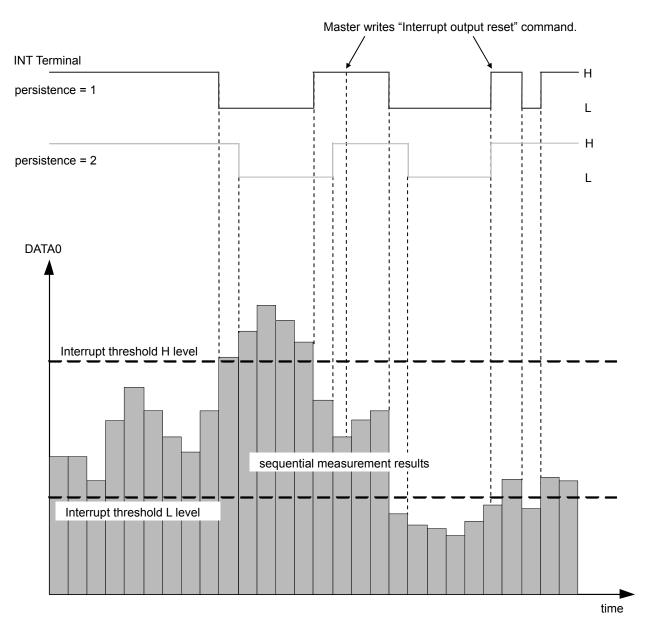
Interrupt function

Interrupt function compares measurement result to preset interrupt threshold level. BH1730FVC uses two threshold level (upper and lower). If measurement result is outside of two threshold, INT pin outputs 'L'. Interrupt threshold is defined at Interrupt threshold registers (03h - 06h).

Interrupt function is able to control by Interrupt opecode. Interrupt persistence is defined at Interrupt opecode lower 4 bits. INT pin is Nch open drain terminal so this terminal should be pull-up to some kind of voltage source by an external resister. Maximum sink current rating of this terminal is 7mA.

INT terminal is high impedance when VCC is supplied.

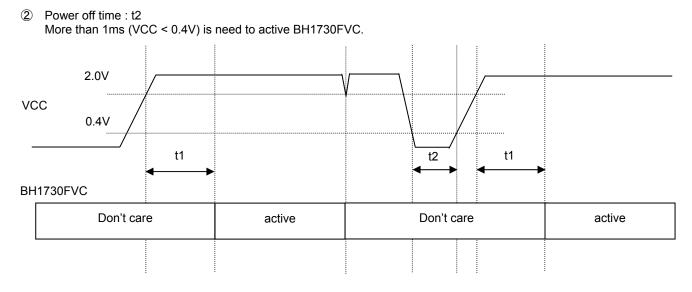
INT terminal becomes inactive by setting "Interrupt output reset" special command. VCC current (approximately 30uA at VCC=3.0V) is consumed during INT terminal is 'L'. So it is recommended to reset INT terminal at once when interrupt is detected.



•Caution of power on reset function

BH1730FVC has power on reset (POR) function. POR is to reset all register and flip flop when VCC Power supplies. There is some cautions about power on and down sequence seeing in below.

 Power on time : t1 More than 2ms is need to active BH1730FVC after VCC supplies more than 2.0V from VCC is less than 0.4V.



*"active state" is that BH1730FVC works and accept I²C bus access correctly.

ALS sensitivity adjustment function

BH1730FVC is possible to change ALS sensitivity. And it is possible to cancel the optical window influence (difference with / without optical window) by using this function. Adjustment is done by changing measurement time. For example, when transmission rate of optical window is 50% (measurement result becomes 0.5 times if optical window is set), influence of optical window is ignored by changing sensor sensitivity from default to 2 times.

Sensitivity can be adjusted by ITIME (01h<7:0>). The measurement time is proportional to "256- ITIME". For example, sensitivity is twice when "256- ITIME" is twice, and the measurement time is twice, too.

The range of adjusting TIMING is below.

| | Min. | Тур. | Max. |
|---------------------------|---------------|-----------|---------------|
| Sensitivity | Default*0.026 | Default | Default*6.711 |
| range of TIMING (binary) | 1111_1111 | 1101_1010 | 0000_0001 |
| range of TIMING (decimal) | 255 | 218 | 1 |
| Measurement time | 2.7ms | 102.6ms | 688.5ms |

It is possible to detect 0.001 lx by using this function at GAIN = x128.

The below formula is to calculate illuminant per 1 count.

Illuminant per 1 count in Type0 at GAIN = x1(lx / count) = 1 / 1.2 * (256 - 218) / (256 - X) 218 : Default value of ITIME (decimal) X : ITIME value (decimal) Illuminant per 1 count in Type0 at GAIN = x128(lx / count) = 1 / 1.2 * (256 - 218) / (256 - X) / 128

218 : Default value of ITIME (decimal)

X : ITIME value (decimal)

128 : Gain value

Illuminant per 1 count in Type0 at GAIN = x1 is as following within adjustable range of ITIME.

| ITIME value | Illuminant per 1count(Ix / count) |
|-------------|-----------------------------------|
| 1111_1111 | 31.67 |
| 1101_1010 | 0.833 |
| 0000_0001 | 0.124 |

Illuminant per 1 count in Type0 at GAIN = x128 is as following within adjustable range of ITIME.

| ITIME value | Illuminant per 1count(Ix / count) |
|-------------|-----------------------------------|
| 1111_1111 | 0.247 |
| 1101_1010 | 0.007 |
| 0000_0001 | 0.001 |

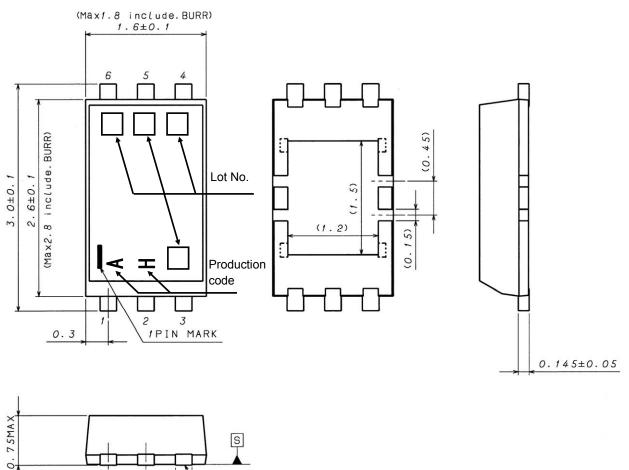
Please take care that about 100,000lx or more cannot be measured even if decreasing the sensitivity.

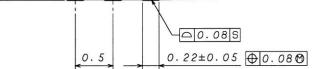
•Terminal Description

| cription | Equivalent Circuit | Function |
|---------------|-----------------------------------|--|
| Terminal Name | Equivalent Circuit | Function |
| vcc | | Power supply terminal |
| INT | | INT Pin output terminal. If you don't use INT Pin, please connect to GND or open. |
| GND | | GND terminal |
| SDA | | I ² C bus Interface SDA terminal |
| DVI | 150kOhm | SDA, SCL reference voltage terminal and asynchronous reset terminal for internal registers. Initial reset is not necessary, because power on reset function is included in this product. DVI terminal is pulled down by 150kOhm while DVI is set 'L' |
| SCL | | I ² C bus Interface SCL terminal |
| | Terminal Name VCC INT GND SDA DVI | Terminal Name Equivalent Circuit VCC INT INT Image: Circuit for the second seco |

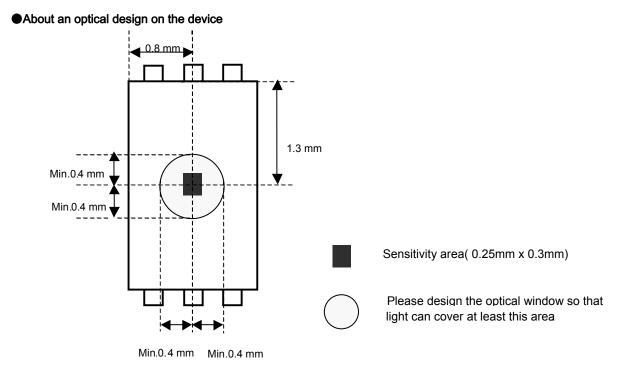
*These values are design-value, not guaranteed.

Package Outlines





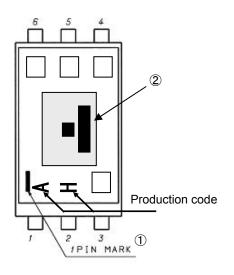
WSOF6 (Unit : mm)

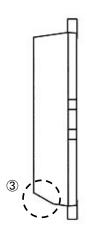


•The method of distinguishing 1pin.

- There is some method of distinguishing 1pin.
- ① Distinguishing by 1Pin marking
- ② Distinguishing by die pattern
- 3 Distinguishing by taper part of 1-3pin side

 $\textcircled{O}(\mbox{by die pattern})$ is the easiest method to distinguish by naked eye.





Notes for use

1) Absolute Maximum Ratings

An excess in the absolute maximum ratings, such as supply voltage (Vccmax), temperature range of operating conditions (Topr), etc., can break down devices, thus making impossible to identify breaking mode such as a short circuit or an open circuit. If any special mode exceeding the absolute maximum ratings is assumed, consideration should be given to take physical safety measures including the use of fuses, etc.

2) GND voltage

Make setting of the potential of the GND terminal so that it will be maintained at the minimum in any operating state. Furthermore, check to be sure no terminals are at a potential lower than the GND voltage including an actual electric transient.

3) Short circuit between terminals and erroneous mounting

In order to mount ICs on a set PCB, pay thorough attention to the direction and offset of the ICs. Erroneous mounting can break down the ICs. Furthermore, if a short circuit occurs due to foreign matters entering between terminals or between the terminal and the power supply or the GND terminal, the ICs can break down.

- 4) Operation in strong electromagnetic field Be noted that using ICs in the strong electromagnetic field can malfunction them.
- 5) Inspection with set PCB

On the inspection with the set PCB, if a capacitor is connected to a low-impedance IC terminal, the IC can suffer stress. Therefore, be sure to discharge from the set PCB by each process. Furthermore, in order to mount or dismount the set PCB to/from the jig for the inspection process, be sure to turn OFF the power supply and then mount the set PCB to the jig. After the completion of the inspection, be sure to turn OFF the power supply and then dismount it from the jig. In addition, for protection against static electricity, establish a ground for the assembly process and pay thorough attention to the transportation and the storage of the set PCB.

6) Input terminals

In terms of the construction of IC, parasitic elements are inevitably formed in relation to potential. The operation of the parasitic element can cause interference with circuit operation, thus resulting in a malfunction and then breakdown of the input terminal. Therefore, pay thorough attention not to handle the input terminals; such as to apply to the input terminals a voltage lower than the GND respectively, so that any parasitic element will operate. Furthermore, do not apply a voltage to the input terminals when no power supply voltage is applied to the IC. In addition, even if the power supply voltage is applied, apply to the input terminals a voltage lower than the guaranteed value of electrical characteristics.

7) Thermal design

Perform thermal design in which there are adequate margins by taking into account the power dissipation (Pd) in actual states of use.

8) Treatment of package

Dusts or scratch on the photo detector may affect the optical characteristics. Please handle it with care.

9) Rush current

When power is first supplied to the CMOS IC, it is possible that the internal logic may be unstable and rush current may flow instantaneously. Therefore, give special consideration to power coupling capacitance, power wiring, width of GND wiring, and routing of connections.

10) The exposed central pad on the back side of the package

There is an exposed central pad on the back side of the package. But please do it non connection. (Don't solder, and don't do electrical connection.) Please mount by Footprint dimensions described in the Jisso Information for WSOF6I. This pad is GND level, therefore there is a possibility that LSI malfunctions and heavy-current is generated.

BH1730FVC

3.0±0.1

0.

0.75MA>

(1.2)

Ď

1PIN MARK

S

0.08 S

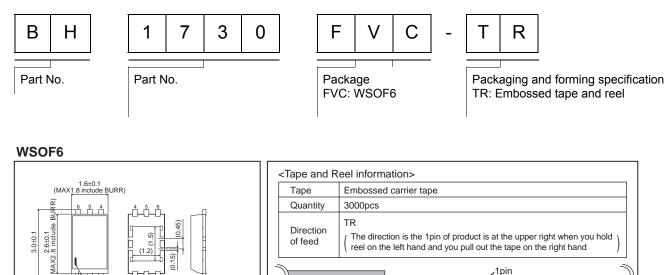
0.22±0.05 ⊕ 0.08 ₪

15) 0

0.145±0.05

(Unit : mm)

Ordering part number



Direction

Reel

of feed

The direction is the 1pin of product is at the upper right when you hold reel on the left hand and you pull out the tape on the right hand

1pin

0

11

*Order quantity needs to be multiple of the minimum quantity.

Direction of feed

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